## Bi7740: Scientific computing

## Matlab remider

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## Outline

(1) General purpose commands
(2) Arrays

3 Mathematical operations
4. Programming with Matlab

## Help and paths

- doc, help, helpdesk, helpwin, lookfor: different ways of obtaining help
- docopt: (on UNIX) path where the help files reside
- addpath, path, pathtool, rmpath: manage search paths for functions
- lasterr, lastwarn: last error and warning
- type, what, which: list a file, list a directory, locate functions and files


## Creating arrays

- var $=$ [val1 val2 ...] row vector from values
- var $=$ [val1; val2; ...] column vector from values; equivalent to var $=$ [val1 val2 ...]' (' is the transposition operator)
- equally spaced data: <low>: <step>: <high>; is <step> is 1, omit :<step>. Example: 1:2:10, 1:10,1.5:0.1:2.1. last value might not be in the generated sequence
- decreasing sequences: as above, with negative <step>:

20:-5:0

- equally spacing of an interval:
linspace (<first>, <last>, <number_of_values>)
<first> and <last> values will be in the sequence
- logarithmically equally space points: logspace


## Creating 2D arrays - matrices

- var $=$ [a11, a12,...; a21, a22,...; ...] from values
- you can use vector generators, as before, for the rows of the matrix
- zeros ( $\mathrm{m}, \mathrm{n}$ ), ones ( $\mathrm{m}, \mathrm{n}$ ), eye ( m ) : all-zeros, all-ones, or identity matrix with m rows and n columns
- transpose of X : $\mathrm{X}^{\prime}$


## Arrays dimension

- size(a), size(b), size (b, 2)
- length (a): for vectors
- numel (b): total number of elements


## Addressing the elements of an array

- by index: a = 1:3:10; a(1) and b = [1:4;5:8]; b(1,2)
- by index vectors: $a(1: 2), b(1,:), b(2,2$ :end) : end gives the last index in the corresponding dimension of an array
- all elements as a row vector: a (: ), b (: ): column-by-column ordering of matrix elements (column-major)
- you can use single index for n-dimensional arrays too! Pay attention to ordering of elements: b(1:5)


## Extending/reducing arrays

- arrays are dynamical structures, you can add a new value beyond the dimension of the array: $b(3,3)=13$ : Мatlab adds Os to fill-in to the required new dimension
- this operation is expensive: better pre-allocate the array!
- concatenation: [a a], [a;a]: the arrays must be consistent
- general concatenation: cat (. . .)
- delete elements: replace them by empty arrays:
$c=b ; c(3,:)=[]$. You have to keep the shape of the array!


## (Re-)shaping the array

- reshape (b, <new_extent_specification>). The total number of elements must not change!
reshape (b, [1, 2, 2, 3])


## Strings

O $s=1 a b c d e f '$

- s = char('aaa', 'bb', 'c') rows are the strings given


## Basic operators

The arrays must have conforming shapes/sizes, depending on the operation.

- +,-, *, ^ classical matrix operators (addition, subtraction, multiplication, power)
- /: matrix division, related to the inverse (we discussed)
- .*, .^, . / element-wise operations
- scalars are multicast: [11 2 3; 4 5 6 $]$ * 2 and operation is kept element-wise


## Some basic built-in functions for arrays

Usually, the summaries are column-wise - see the help for details

- min(b), min (b, 4), $[m, n]=\min (b) \max (. .$.
- mean(...), median(...), std(...)
- sum(...), prod(...)
- $\operatorname{dot}(\ldots, .):. \operatorname{dot}(a, a)$ is the same as $a * a^{\prime}$


## Random arrays

- rand $(m, n)$ : random uniformly distributed numbers between 0 and 1, in the form of a matrix (or vector, or scalar, depending on $m$ and $n$ )
- randperm ( $n$ ): random permutation of $1: n$ vector
- randperm ( $n, k$ ) random selection of $k$ elements out of $1: n$
- randi (imax, m, n): random uniformly distributed integers between 1 and imax, in the form of a matrix (or vector, or scalar)
- randn (. . . ) : normally distributed random numbers: try hist (randn(1000, 1))


## Relational operators

Check help precedence for precedence of operators!

- relational operators: $<,>,=<, \geq r==, \sim=$
- the result is either logical 1 (true) or logical 0 (false) and has the shape of the operands (after bringing them to compatible shapes)
- example: $\bmod (1: 10,5)<3$
- logical results can be used to address elements of arrays:
$a=r a n d n(4) ; ~ a(a<0.5)$ what happend?


## Logical operators and functions

- AND: x \& y , and ( $\mathrm{x}, \mathrm{y}$ )
- OR: $x$ | $y$, or $(x, y)$
- NOT:~x, not (x)
- XOR: xor $(x, y)$
- all(x), any (x), find(x)


## Conditional branching

```
if <conditional statement 1>
        <block 1>
    [elseif <conditional statement 2>
    <block 2>]
    [else
        <block 3>]
    end
```

One-liner: if <cond> instruction; end

```
switch <expression>
    case value1
        <block 1>
    case {value2, value3,...}
        <block 2>
    otherwise
        <block n>
end
```


## Loops

```
for iterator = sequence
    <block>
end
while <condition_is_true>
    <block>
end
```

- continue skips the rest of the block and jumps to the next iteration (if any)
- break: breaks out of the loop; if it is outside a loop, it terminates the script/function


## Functions

## One visible function per <function_name>.m file.

```
function [<output>] = <name>(<parameters>)
% document your function here
    % process arguments
    if nargin < ...
    end
        <block>
    % prepare the return values
    if nargout...
    . . .
    end
end % or return: not mandatory, but a good practice
```

- usually, the variables created in the functions are local
- use global <variable> to declare that a variable is from the global environment (put globals at the top of the file)
- the file with the function must be in the search path of Matlab


## Anonymous functions

```
<function_name> = @(arguments) <expression>
cube = @(x) x.^3
```

- <expression> must be a single valid Matlab expression
- you can use also variables from the context in which the anonymous function is defined
- anonymous functions can be used as parameters for other functions


## Inline functions

```
<function_name> = inline('mathematical expression ...
        as a string')
square = inline('x .^ 2')
square(1:5)
quad = inline('x .^ 2 + y .^ 2 + dot(x,y)', 'x', 'y')
```

- if you do not provide explicit parameters, they are deduced from the expression and ordered alphabetically in the argument list
- you cannot use $i$ and $j$ as variables
- the inline functions can be used as arguments for other functions


## Functions as arguments

@function_name gives you a function handle, that can be used for calling the function itself.

```
function y = funplot(F, x0, x1)
    x = linspace(x0, x1, 100);
    y = F(x);
    plot(x, y);
return
funplot(@cos, 0, 2*pi)
8 funplot(square, -3, 3)
9 funplot(@(x) x .^ 3, 0, 5)
```


## Subfunctions

In a file "main_function.m":

```
function ...= main_function(...)
end
function ...= subfunction_1(...)
end
function ...= subfunction_2(...)
end
```


## Nested functions

| 1 | function $\ldots=A(\ldots)$ |
| :--- | :--- |
| 2 | function $\ldots=B(\ldots)$ |
| 3 | $\ldots$ |
| 4 | end |
| 5 | $\ldots$ |
| 6 | function $\ldots=C(\ldots)$ |
| 7 | $\ldots$ |
| 8 | end |
| 9 | $\ldots$ |

