BKM_DATS: Databázové systémy9. Query Processing andRelational Algebra

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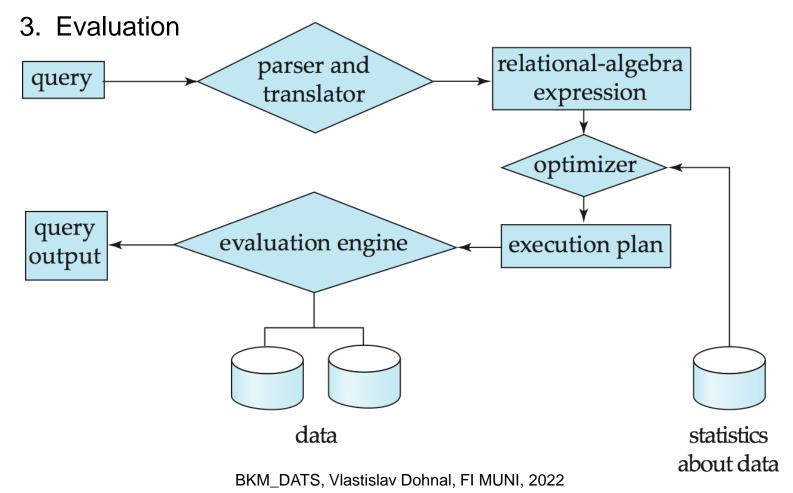
Query Processing

Overview

- Evaluation of Expressions
- Measures of Query Cost
- Evaluation algorithms
 - □ Sorting
 - Join Operation

Basic Steps in Query Processing

- 1. Parsing and translation
- 2. Optimization



Basic Steps in Query Processing (Cont.)

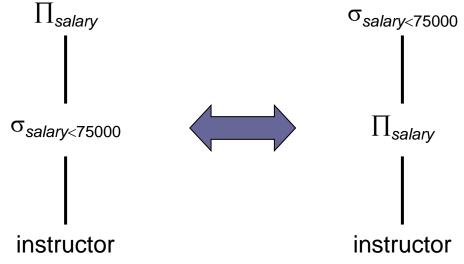
- Parsing and translation
 - □ Translate the SQL query into its internal form.
 - This is then translated into relational algebra.
 - Parser checks syntax, verifies relations
- Optimization
 - Generate a query-evaluation plan and choose algorithms for evaluating individual operations
- Evaluation
 - □ The query-execution engine takes a query-evaluation plan, executes that plan, and returns the answers to the query.

Basic Steps in Query Processing (Cont.)

- □ Example of query:
 - List salary of all instructors that earn less than \$75,000.
- □ SQL query
 - □ SELECT salary FROM instructor WHERE salary < 75000
- Conversion to rel. algebra
 - $\Box \prod_{salary}(\sigma_{salary<75000}(instructor))$

Basic Steps: Optimization

- A relational-algebra expression may have many equivalent expressions:
 - $\Box \prod_{salary}(\sigma_{salary<75000}(instructor))$
 - $\Box \sigma_{salary < 75000}(\prod_{salary}(instructor))$
- For a relational-algebra expression, an expression tree is created

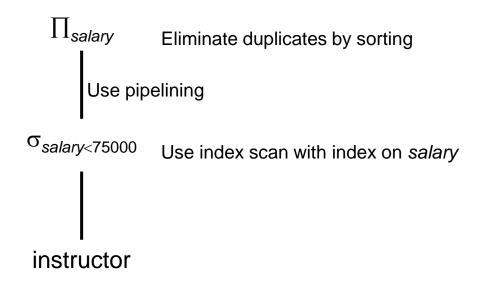


Basic Steps: Optimization (Cont.)

- Each relational algebra operation can be evaluated using one of several different algorithms
 - Correspondingly, a relational-algebra expression can be evaluated in many ways.
- Annotated expression specifying detailed evaluation strategy is called an execution-plan or evaluation-plan.
 - □ E.g., to find instructors with salary < 75000
 - <u>use an index on salary</u>, or
 - □ perform <u>complete relation scan</u> and discard instructors with salary \ge 75000

Basic Steps: Optimization (Cont.)

□ Example of an **evaluation-plan**



Basic Steps: Optimization (Cont.)

Query Optimization

- Amongst all equivalent evaluation plans choose the one with lowest cost.
- Cost is estimated using statistical information from the database catalog
 - □ E.g., number of tuples in each relation, size of tuples, etc.
- □ There is a huge number of possible evaluation plans
 - Optimization uses some heuristics
 - 1. Perform selection early
 - reduce the number of tuples (by using an index, e.g.)
 - 2. Perform projection early
 - reduce the number of attributes
 - 3. Perform most restrictive operations early
 - such as join and selection.

Evaluation of Expressions

□ Alternatives for evaluating an entire expression tree

Materialization

- Evaluate one operation at a time, starting at the lowest-level.
- Use intermediate results materialized into temporary relations to evaluate next-level operations.

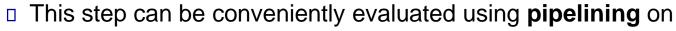
Pipelining

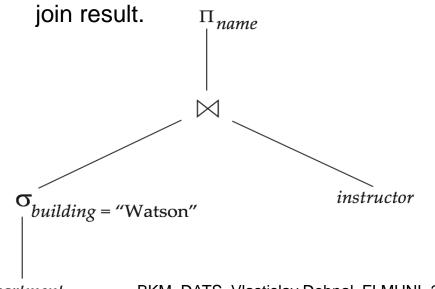
 pass on tuples to parent operations even as an operation is being executed

Evaluation of Expressions (Cont.)

Materialized evaluation

- □ Compute $\sigma_{building=`Watson'}$ (*department*) and store it
- Then read from stored intermediate result and compute its join with *instructor*, store it
- Finally read it and compute the projection on *name* and output it.





Measures of Query Cost

- Cost is generally measured as total elapsed time for answering query
 - Many factors contribute to time cost
 - □ *disk accesses, CPU*, or even network *communication*
- Typically disk access is the predominant cost and is also relatively easy to estimate. Measured by taking into account
 - Number of seeks * average-seek-cost
 - Number of blocks read * average-block-read-cost
 - Number of blocks written * average-block-write-cost
 - Cost to write a block is greater than cost to read a block
 - Data is read back after being written to ensure that the write was successful

Measures of Query Cost (Cont.)

- For simplicity we just use the number of block transfers from disk and the number of seeks as the cost measures
 - \Box t_T time to transfer one block
 - \Box $t_{\rm S}$ time for one seek
 - □ Cost for *b* block transfers plus *S* seeks $b * t_T + S * t_S$
- □ We ignore CPU costs for simplicity
 - Real systems do take CPU cost into account
- We do not include cost to writing output to disk in our cost formulae

Measures of Query Cost (Cont.)

- Several algorithms can reduce disk I/O by using extra buffer space
 - Amount of real memory available to buffer depends on other concurrent queries and OS processes, known only during execution
 - We often use worst case estimates, assuming only the minimum amount of memory needed for the operation is available
- Required data may be buffer resident already, avoiding disk I/O
 - But hard to take into account for cost estimation

Relational Algebra

- Procedural language
- □ Six basic operations
 - Select: σ
 - □ Project: ∏
 - \Box Union: \cup
 - Set difference: –
 - Cartesian product: ×
 - \square Rename: ρ
- Principle:
 - An operation takes one or two relations as input and produce a new relation as a result.
 - □ So, another operation can be applied to this result.
- □ Note: SQL is a declarative language.

Select and Project Operations: Example

□ Relation *r*

Α

α

α

β

β

В

α

β

β

β

С

1

5

12

23

D

7

7

3

10

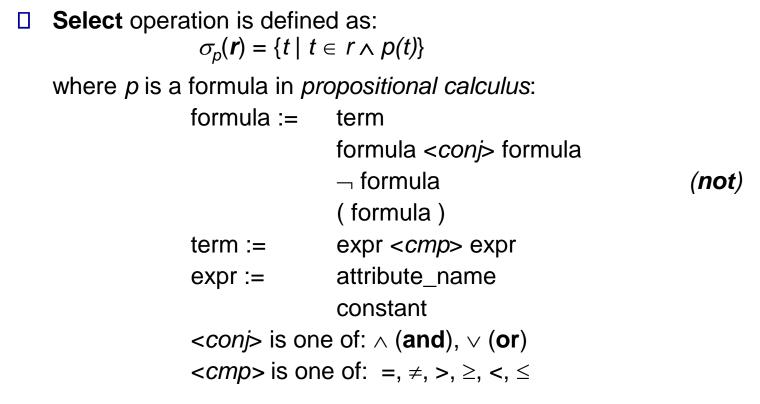
 $\Box \ \sigma_{A=B \land D > 5}(r)$

A	В	С	D
α	α	1	7
β	β	23	10

		11	(م
	I A,C	$(\prime$)

A	С
α	1
α	5
β	12
β	23

Select Operation



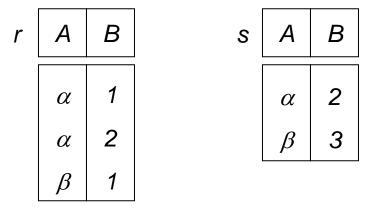
Project operation is defined as: $\prod_{A_1,\dots,A_k} (r)$

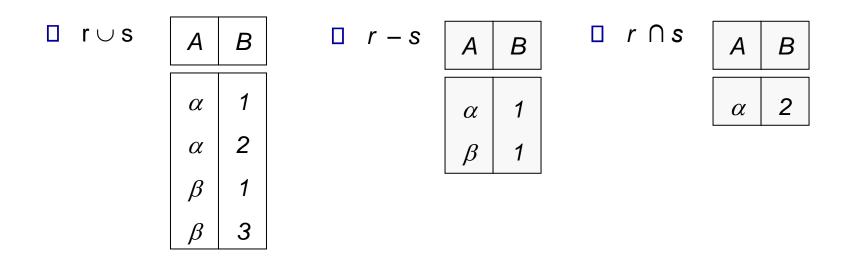
 $=\{t|\exists q\in r: t[A_1]=q[A_1]\wedge\cdots\wedge t[A_k]=q[A_k]\}$

where A_i are attribute names and r is a relation name.

Union, Set Difference, Intersect Operations

□ Relations *r*, *s*:





Cartesian product and Operation Composition

r

- Can build complex expressions using multiple operations
- $\Box \quad \text{Example:} \quad \sigma_{A=C}(r \times s)$
 - Relations:

r

$$\sigma_{A=C}(r \times s) \begin{bmatrix} A & B & C & D & E \\ \\ \alpha & 1 & \alpha & 10 & a \\ \beta & 2 & \beta & 10 & a \\ \beta & 2 & \beta & 20 & b \end{bmatrix}$$

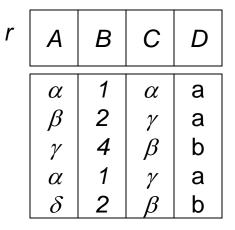
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Example Queries

- Relations
 - customer (customer_name, customer_street, customer_city)
 - □ loan (loan number, branch_name, amount)
 - borrower (<u>customer_name</u>, <u>loan_number</u>)
- Find the names of all customers who have a loan at the Perryridge branch.
 - $\Box \prod_{customer_name} (\sigma_{loan.loan_number} = borrower.loan_number ((\sigma_{branch_name} = 'Perryridge' (loan)) \times borrower))$
 - □ Alternatively, as:
 - Π_{customer_name} (σ_{branch_name = 'Perryridge'} (σ_{borrower.loan_number = loan.loan_number} (borrower × loan)))

Natural-Join Operation: Example

Relations r, s:



S Ε В D 1 а α 3 β а 1 а γ 2 b δ 3 b ϵ

🛛 r 🖂 s

 $\Box \quad r \bowtie s \text{ is defined as:}$

$$\prod_{r.A, r.B, r.C, r.D, s.E} (\sigma_{r.B = s.B \land r.D = s.D} (r \times s))$$

Bank Example Queries

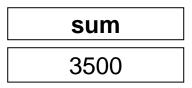
- □ Relations:
 - □ loan (loan_number, branch_name, amount)
 - depositor (customer_name, account_number)
 - borrower (<u>customer_name</u>, <u>loan_number</u>)
- Find the names of all customers who have a loan and an account at the bank.
 - $\Box \quad \prod_{customer_name} (borrower) \cap \prod_{customer_name} (depositor)$
- Find the names of all customers who have a loan at the Perryridge branch.
 - $\square \prod_{customer_name} (\sigma_{branch_name = 'Perryridge'} (loan \bowtie borrower))$
- Find all customers who have a loan at the bank and return his/her name, loan number and the loan amount.
 - $\square \quad \prod_{customer_name, \ loan_number, \ amount} (borrower \bowtie \ loan)$

Aggregate Operation: Example

□ Relation *account*

branch_name	account_number	balance		
Perryridge	A-102	400		
Perryridge	A-201	900		
Brighton	A-217	750		
Brighton	A-215	750		
Redwood	A-222	700		

 $\mathcal{G}_{\text{sum}(\text{balance})}$ (account)



 $\textit{branch_name } G_{\textit{sum}(\textit{balance})} \textit{(account)}$

branch_name	sum
Perryridge	1300
Brighton	1500
Redwood	700

Left Outer Join: Example

L-260

loan				1		borrow	er		
loan_number	branch_name		amount			customer_name		loan_r	number
L-170	Downtown		3000			Jones		L-170	
L-230	Redwo	od	4000			Smith		L-230	
L-260	Perryri	dge	1700			Hayes		L-155	
	Left Outer Join		number	er branch_name		amount	custor	mer_name	
loan 🖂 boi	rrower	L-170		Downtown		3000	Jones	S	
			L-230		Redwood		4000	Smith	1
			L-260		Perryridge		1700	null	
U	□ Right Outer Join loan ⋈ borrower		loan_number		branch_name		amount	custor	mer_name
iuan 🖂 Dui	TOwer	L-170		Downtown		3000	Jones	S	
		L-230		Redwood		4000	Smith	۱	
		L-155		null		null	Haye	S	
			loan_number		branch_name		amount	custor	mer_name
loan <i></i> ⊳⊄ borrower		L-170		Do	Downtown		3000	Jones	5
		L-230		Re	Redwood		4000	Smith	۱

Perryridge

null

1700

null

null

Hayes

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Query Processing Operators

- □ Selection or projection
 - Table scan vs Index scan
- Sorting for ORDER BY or table joins
 - □ In-memory \rightarrow quick sort, ...
 - □ On-disk \rightarrow external merge sort
- Joining tables
 - Nested-loop join
 - Merge-join
 - Hash-join

Selection Operation

- □ **File scan** (table / sequential scan) no index structure is necessary
 - Scan each file block and test all records to see whether they satisfy the selection condition.
 - □ Cost estimate = b_r block transfers + 1 seek

 \Box *b_r* denotes number of blocks containing records from relation *r*

- □ If selection is on a key attribute, can stop on finding matching record
 □ cost = (b_r/2) block transfers + 1 seek
- □ Linear search can be applied regardless of
 - selection condition or
 - ordering of records in the file, or
 - availability of indices
- Note: binary search generally does not make sense since data is not stored consecutively
 - □ except when there is an index available,
 - and binary search requires more seeks than index search

Selections Using Indices

- □ **Index scan** search algorithms that use an index
 - selection condition must be on search-key of index
- □ Now, assume the sequential file is ordered by this key:
- □ Algorithm for primary index & equality on primary key
 - Retrieve a single record that satisfies the corresponding equality condition
 - $\Box \quad Cost = (h_i + 1) * (t_S + t_T)$
 - □ h_i height of index *i* (for hashing h_i =1)
 - □ +1 for reading the actual record

□ Algorithm for primary index & equality on non-primary key

- Retrieve multiple records.
- Records will be on consecutive blocks

□ Let b = number of blocks containing all n matching records

$$\Box \quad Cost = h_i^* (t_S + t_T) + t_S + t_T^* b$$

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Selections Using Indices

- □ Algorithm for secondary index & equality on non-primary key
 - Sequential file is not ordered by this search key!
 - Retrieve a single record if the search-key is a candidate key

 $\Box Cost = (h_i + 1) * (t_S + t_T)$

- Retrieve multiple records if search-key is not a candidate key
 - Each of *n* matching records may be on a different block.

$$\Box Cost = (h_i + n)^* (t_S + t_T)$$

Can be very expensive!

Sorting Relations

- We may build an index on the relation, and then use the index to read the relation in the sorted order.
 - May lead to one disk block access for each tuple.
- □ Use a sorting algorithm
 - For relations that fit in memory, techniques like quick-sort can be used.
 - For relations that don't fit in memory, external sort-merge is a good choice.

External Sort-Merge

Let *M* denote memory size (in pages/blocks):

1. Create sorted *runs*. Let *i* be 0 initially.

Repeatedly do the following till the end of the relation:

- (a) Read *M* blocks of relation into memory
- (b) Sort the in-memory blocks
- (c) Write sorted data to run R_i ; increment *i*.

Let the final value of *i* be *N*

2. Merge the runs. (next slide)

External Sort-Merge (Cont.)

2. Merge the runs (N-way merge).

We assume (for now) that N < M.

- 1. Use *N* blocks of memory to buffer input runs, and 1 block to buffer output.
- 2. Read the first block of each run into its buffer page

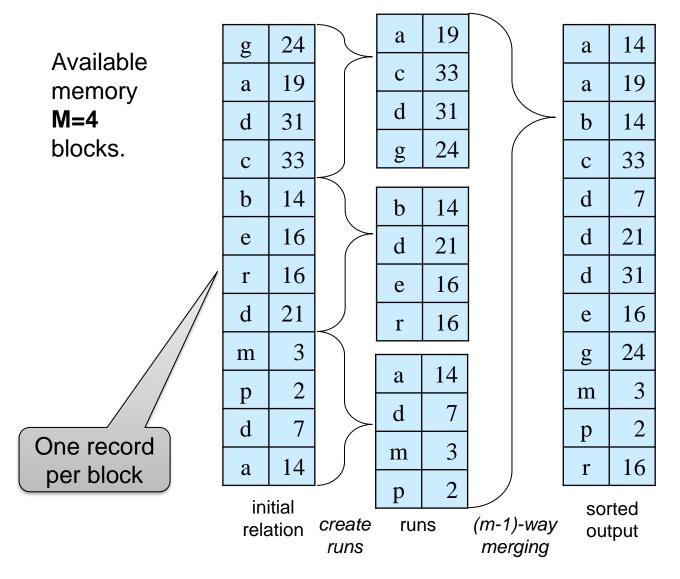
3. repeat

- 1. Select the first record (in sort order) among all buffer pages
- 2. Write the record to the output buffer.
 - If the output buffer is full write it to disk.
- 3. Delete the record from its input buffer page.
 - If the buffer page becomes empty then read the next block (if any) of the run into the buffer.
- 4. **until** all input buffer pages are empty.

External Sort-Merge (Cont.)

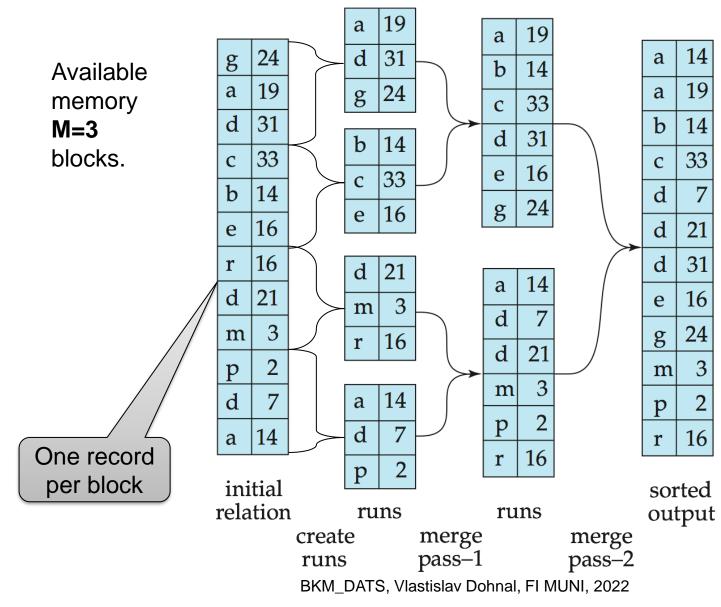
- If $N \ge M$, several merge *passes* are required.
 - □ In each pass, continuous groups of M 1 runs are merged.
 - □ A pass reduces the number of runs by a factor of M-1, and creates runs longer by the same factor.
 - E.g. If M=11, and there are 90 runs, one pass reduces the number of runs to 9, each 10 times the size of the initial runs
 - Repeated passes are performed till all runs have been merged into one.

Example: External Sorting Using Sort-Merge



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Example: External Sorting Using Sort-Merge (2)



34

External Sort-Merge (Cont.)

- Cost analysis:
 - □ Total number of merge passes required: $\lceil \log_{M-1}(b_r/M) \rceil$.
 - Block transfers for initial run creation as well as in each pass is $2b_r$
 - □ for final pass, we don't count write cost
 - we ignore final write cost for all operations since the output of an operation may be sent to the parent operation without being written to disk
 - Thus total number of block transfers for external sorting: $b_r(2 \lceil \log_{M-1}(b_r/M) \rceil + 1)$
 - Seeks: next slide

External Sort-Merge (Cont.)

- Cost in seeks
 - During run generation: one seek to read each run and one seek to write each run
 - $\Box \quad 2 \lceil b_r / M \rceil$
 - During the merge phase
 - Buffer size: b_b (read/write b_b blocks at a time)
 - cannot be larger than (M-1) / "number of runs"
 - □ Need $2 \lceil b_r / b_b \rceil$ seeks for each merge pass
 - except the final one which does not require a write
 - Total number of seeks:

 $2 \left\lceil b_r / M \right\rceil + \left\lceil b_r / b_b \right\rceil (2 \left\lceil \log_{M-1}(b_r / M) \right\rceil - 1)$

Join Operation

- Several different algorithms to implement joins
 - Nested-loop join
 - Block nested-loop join
 - Improved nested-loop join by reading records in blocks
 - Indexed nested-loop join
 - Improved by using an index to look up equal records
 - Merge-join
 - Hash-join
- Choice based on cost estimate
 - □ For each of the variants a cost estimation can be stated.

Nested-Loop Join

- \Box To compute the join $r \bowtie s$
- □ for each tuple t_r in r do begin for each tuple t_s in s do begin test pair (t_r, t_s) to see if they satisfy the equality on shared attributes if they do, add $t_r \cdot t_s$ to the result. end end
- \Box *r* is called the **outer relation** and *s* the **inner relation** of the join.
- Requires no indices and can be used with any kind of join condition.
 - Expensive since it examines every pair of tuples in the two relations.
 - $\Box \quad Cost = n_r * (t_S + t_T) * (n_s * (t_S + t_T))$

```
• where n_r = number of tuples in r
```

Nested-Loop Join (Cont.)

In the worst case, if there is enough memory only to hold <u>one block of each</u> relation, the estimated cost is

 $n_r * b_s + b_r$ block transfers, plus

 $n_r + b_r$ seeks

Example on student and takes

□ *student* (the smaller one) as the outer relation:

□ 5000 * 400 + 100 = 2,000,100 block transfers,

□ 5000 + 100 = 5,100 seeks

□ takes (the larger one) as the outer relation

10000 * 100 + 400 = 1,000,400 block transfers and 10,400 seeks

□ If the smaller relation fits entirely in memory, use that as the inner relation.

- □ Reduces cost to $b_r + b_s$ block transfers and 2 seeks
- Example: *student* fits entirely in memory

□ the cost estimate is 500 block transfers.

Block nested-loops algorithm (next slide) is preferable.
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 $n_{student}$ =5,000 b_{student}=100 n_{takes}=10,000 $b_{takes} = 400$

```
Block Nested-Loop Join
```

Variant of nested-loop join in which every block of inner relation is paired with every block of outer relation.

```
for each block B_r of r do begin
for each block B_s of s do begin
for each tuple t_r in B_r do begin
for each tuple t_s in B_s do begin
Check if (t_r, t_s) satisfy the join condition
if they do, add t_r \cdot t_s to the result.
end
end
end
```

```
□ Cost: b_r^* (1+b_s) blocks; b_r^* (1+1) seeks
□ For student (outer) and takes (inner):
```

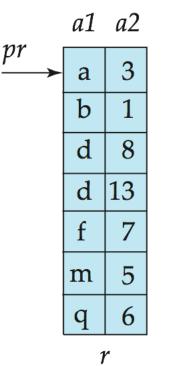
□ 100 + 100 * 400 = 40,100 block transfers

□ 100 + 100 seeks

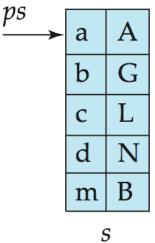
 $n_{student}$ =5,000 b_{student}=100 $n_{takes} = 10,000$ $b_{takes} = 400$

Merge-Join

- 1. Sort both relations on their join attributes
 - □ If not already sorted.
- 2. Merge the sorted relations to join them
 - Join step is similar to the merge stage of the sort-merge algorithm.
 - Main difference is handling of duplicate values in join attribute
 - Every pair with same value on join attribute must be matched



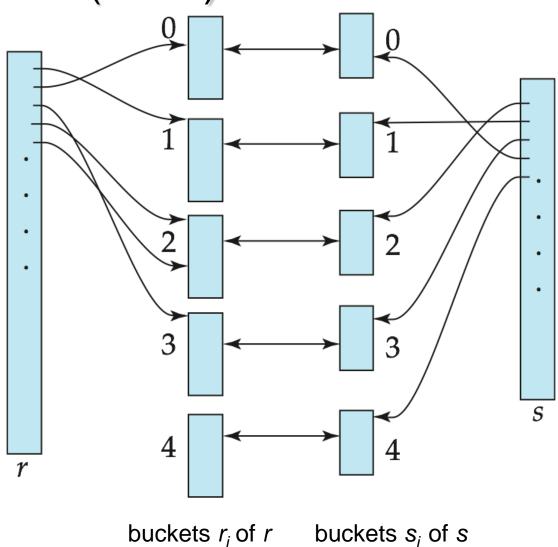
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Hash-Join

- □ A hash function *h* is used to partition tuples of both relations
 - □ JoinAttrs are the common attributes of r and s used in $r \bowtie s$
- $\square h maps JoinAttrs values to \{0, 1, ..., n\}$
 - *r*₀, *r*₁, ..., *r*_n denote buckets of *r* Each tuple *t*_r ∈ *r* is put in bucket *r*_i
 where *i* = *h*(*t*_r[JoinAttrs]).
 - s₀, s₁, ..., s_n denotes buckets of s
 Each tuple t_S ∈ s is put in bucket s_i,
 where i = h(t_S [JoinAttrs]).

Hash-Join (Cont.)



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Hash-Join (Cont.)

- \Box Tuples in r_i need only to be compared with tuples in s_i
 - □ Need not be compared with *s* tuples in any other bucket, since:
 - a tuple of r and a tuple of s that satisfy the join condition will have the same value for the join attributes.
 - If that value is hashed to some value *i*, the tuple of *r* has to be in r_i and the tuple of *s* in s_i .
- □ Cost of hash join is $3(b_r + b_s)$ block transfers
 - □ $3^*(100+400)$ for student \bowtie takes

