

COMPUTER ORGANIZATION AND DESIGN The Hardware/Software Interface



#### **Chapter 2**

# Instructions: Language of the Computer

#### **Instruction Set**

- The repertoire of instructions of a computer
- Different computers have different instruction sets
  - But with many aspects in common
- Early computers had very simple instruction sets
  - Simplified implementation
- Many modern computers also have simple instruction sets

#### **The MIPS Instruction Set**

- Used as the example throughout the book
- Stanford MIPS commercialized by MIPS Technologies (<u>www.mips.com</u>)
- Large share of embedded core market
  - Applications in consumer electronics, network/storage equipment, cameras, printers, …
- Typical of many modern ISAs
  - See MIPS Reference Data tear-out card, and Appendixes B and E

#### **Arithmetic Operations**

- Add and subtract, three operands
   Two sources and one destination
  - add a, b, c # a gets b + c
- All arithmetic operations have this form
  - Design Principle 1: Simplicity favours regularity
    - Regularity makes implementation simpler
    - Simplicity enables higher performance at lower cost

#### **Arithmetic Example**

C code:

$$f = (g + h) - (i + j);$$

Compiled MIPS code:

add t0, g, h # temp t0 = g + h add t1, i, j # temp t1 = i + j sub f, t0, t1 # f = t0 - t1



### **Register Operands**

- Arithmetic instructions use register operands
- MIPS has a 32 × 32-bit register file
  - Use for frequently accessed data
  - Numbered 0 to 31
  - 32-bit data called a "word"
- Assembler names
  - \$t0, \$t1, ..., \$t9 for temporary values
  - \$s0, \$s1, ..., \$s7 for saved variables
  - Design Principle 2: Smaller is faster
    - c.f. main memory: millions of locations

#### **Register Operand Example**

C code: f = (g + h) - (i + j);
f, ..., j in \$s0, ..., \$s4
Compiled MIPS code: add \$t0, \$s1, \$s2 add \$t1, \$s3, \$s4 sub \$s0, \$t0, \$t1



### **Memory Operands**

- Main memory used for composite data
  - Arrays, structures, dynamic data
- To apply arithmetic operations
  - Load values from memory into registers
  - Store result from register to memory
- Memory is byte addressed
  - Each address identifies an 8-bit byte
- Words are aligned in memory
  - Address must be a multiple of 4
- MIPS is Big Endian
  - Most-significant byte at least address of a word
  - *c.f.* Little Endian: least-significant byte at least address

### **Memory Operand Example 1**

- C code:
  - g = h + A[8];
    - g in \$s1, h in \$s2, base address of A in \$s3
- Compiled MIPS code:
  - Index 8 requires offset of 32
    - 4 bytes per word

#### **Memory Operand Example 2**

C code: A[12] = h + A[8];h in \$s2, base address of A in \$s3 Compiled MIPS code: Index 8 requires offset of 32 lw \$t0, 32(\$s3) # load word add \$t0, \$s2, \$t0 sw \$t0, 48(\$s3) # store word

### **Registers vs. Memory**

- Registers are faster to access than memory
- Operating on memory data requires loads and stores
  - More instructions to be executed
- Compiler must use registers for variables as much as possible
  - Only spill to memory for less frequently used variables
  - Register optimization is important!

#### **Immediate Operands**

- Constant data specified in an instruction addi \$s3, \$s3, 4
- No subtract immediate instruction
  - Just use a negative constant addi \$s2, \$s1, -1
- Design Principle 3: Make the common case fast
  - Small constants are common
  - Immediate operand avoids a load instruction

#### **The Constant Zero**

- MIPS register 0 (\$zero) is the constant 0
  - Cannot be overwritten
- Useful for common operations
  - E.g., move between registers add \$t2, \$s1, \$zero



#### **Unsigned Binary Integers**

Given an n-bit number

$$x = x_{n-1}^{-1} 2^{n-1} + x_{n-2}^{-2} 2^{n-2} + \dots + x_1^{-2} 2^{1} + x_0^{-2} 2^{0}$$

- Range: 0 to +2<sup>n</sup> 1
- Example
  - 0000 0000 0000 0000 0000 0000 0000 1011<sub>2</sub> = 0 + ... +  $1 \times 2^3$  +  $0 \times 2^2$  +  $1 \times 2^1$  +  $1 \times 2^0$ 
    - $= 0 + \dots + 8 + 0 + 2 + 1 = 11_{10}$
- Using 32 bits
  - 0 to +4,294,967,295

#### **2s-Complement Signed Integers**

Given an n-bit number

$$x = -x_{n-1}^{}2^{n-1} + x_{n-2}^{}2^{n-2} + \dots + x_1^{}2^1 + x_0^{}2^0$$

Range: 
$$-2^{n-1}$$
 to  $+2^{n-1} - 1$ 

#### Example

#### Using 32 bits

■ -2,147,483,648 to +2,147,483,647

#### **2s-Complement Signed Integers**

- Bit 31 is sign bit
  - I for negative numbers
  - 0 for non-negative numbers
- –(–2<sup>n 1</sup>) can't be represented
- Non-negative numbers have the same unsigned and 2s-complement representation
- Some specific numbers
  - 0: 0000 0000 ... 0000
  - −1: 1111 1111 ... 1111
  - Most-negative: 1000 0000 ... 0000
  - Most-positive: 0111 1111 ... 1111

#### **Signed Negation**

Complement and add 1

• Complement means  $1 \rightarrow 0, 0 \rightarrow 1$ 

$$x + \overline{x} = 1111...111_{2} = -1$$
  
 $\overline{x} + 1 = -x$ 

Example: negate +2 +2 = 0000 0000 ... 0010<sub>2</sub> -2 = 1111 1111 ... 1101<sub>2</sub> + 1 = 1111 1111 ... 1110<sub>2</sub>

### **Sign Extension**

- Representing a number using more bits
  - Preserve the numeric value
- In MIPS instruction set
  - addi: extend immediate value
  - Ib, Ih: extend loaded byte/halfword
  - beq, bne: extend the displacement
- Replicate the sign bit to the left
  - c.f. unsigned values: extend with 0s
- Examples: 8-bit to 16-bit
  - +2: 0000 0010 => 0000 0000 0000 0010
  - -2: 1111 1110 => 1111 1111 1111 1110

### **Representing Instructions**

- Instructions are encoded in binary
  - Called machine code
- MIPS instructions
  - Encoded as 32-bit instruction words
  - Small number of formats encoding operation code (opcode), register numbers, ...
  - Regularity!
- Register numbers
  - \$t0 \$t7 are reg's 8 15
  - \$t8 \$t9 are reg's 24 25
  - \$s0 \$s7 are reg's 16 23

#### **MIPS R-format Instructions**

ор	rs	rt	rd	shamt	funct
6 bits	5 bits	5 bits	5 bits	5 bits	6 bits

- Instruction fields
  - op: operation code (opcode)
  - rs: first source register number
  - rt: second source register number
  - rd: destination register number
  - shamt: shift amount (00000 for now)
  - funct: function code (extends opcode)

#### **R-format Example**

ор	rs	rt	rd	shamt	funct
6 bits	5 bits	5 bits	5 bits	5 bits	6 bits

#### add \$t0, \$s1, \$s2

special	\$s1	\$s2	\$tO	0	add
0	17	18	8	0	32
000000	10001	10010	01000	00000	100000

#### $0000001000110010010000000100000_2 = 02324020_{16}$



#### Hexadecimal

Base 16

- Compact representation of bit strings
- 4 bits per hex digit

0	0000	4	0100	8	1000	С	1100
1	0001	5	0101	9	1001	d	1101
2	0010	6	0110	а	1010	е	1110
3	0011	7	0111	b	1011	f	1111

#### Example: eca8 6420

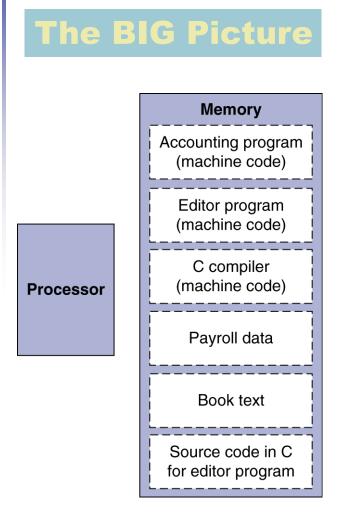
1110 1100 1010 1000 0110 0100 0010 0000

### **MIPS I-format Instructions**

ор	rs	rt	constant or address
6 bits	5 bits	5 bits	16 bits

- Immediate arithmetic and load/store instructions
  - rt: destination or source register number
  - Constant: -2<sup>15</sup> to +2<sup>15</sup> 1
  - Address: offset added to base address in rs
- Design Principle 4: Good design demands good compromises
  - Different formats complicate decoding, but allow 32-bit instructions uniformly
  - Keep formats as similar as possible

## **Stored Program Computers**



- Instructions represented in binary, just like data
- Instructions and data stored in memory
- Programs can operate on programs
  - e.g., compilers, linkers, ...
- Binary compatibility allows compiled programs to work on different computers
  - Standardized ISAs

#### **Logical Operations**

#### Instructions for bitwise manipulation

Operation	С	Java	MIPS
Shift left	<<	<<	s]]
Shift right	>>	>>>	srl
Bitwise AND	&	&	and, andi
Bitwise OR			or, ori
Bitwise NOT	~	~	nor

Useful for extracting and inserting groups of bits in a word



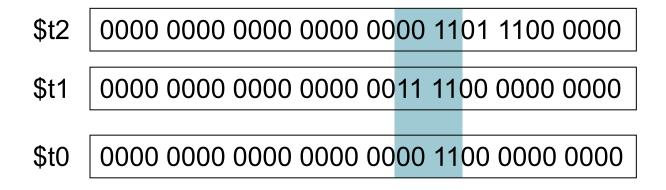
#### **Shift Operations**

ор	rs	rt	rd	shamt	funct	
6 bits	5 bits	5 bits	5 bits	5 bits	6 bits	

- shamt: how many positions to shiftShift left logical
  - Shift left and fill with 0 bits
  - s11 by *i* bits multiplies by 2<sup>i</sup>
- Shift right logical
  - Shift right and fill with 0 bits
  - srl by *i* bits divides by 2<sup>*i*</sup> (unsigned only)

#### **AND Operations**

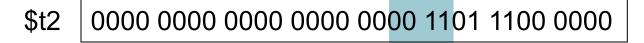
Useful to mask bits in a word
Select some bits, clear others to 0 and \$t0, \$t1, \$t2



#### **OR Operations**

Useful to include bits in a word
Set some bits to 1, leave others unchanged

or \$t0, \$t1, \$t2



\$t0 0000 0000 0000 000 00<mark>11 11</mark>01 1100 0000



#### **NOT Operations**

Useful to invert bits in a word
Change 0 to 1, and 1 to 0
MIPS has NOR 3-operand instruction
a NOR b == NOT ( a OR b )
nor \$t0, \$t1, \$zero Register

Register 0: always read as zero

\$t1 0000 0000 0000 00011 1100 0000 0000

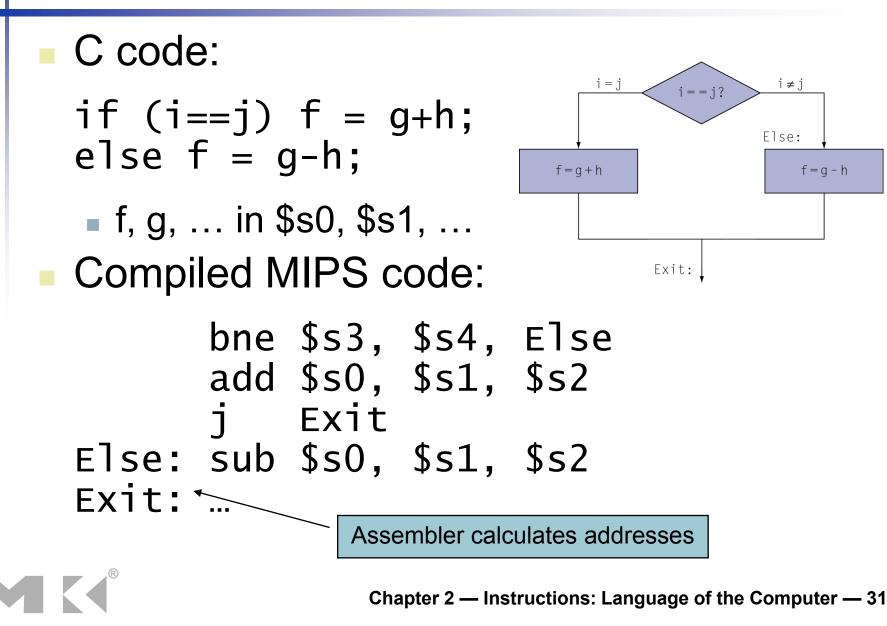
\$t0 | 1111 1111 1111 1100 0011 1111 1111

#### **Conditional Operations**

- Branch to a labeled instruction if a condition is true
  - Otherwise, continue sequentially
- beq rs, rt, L1
  - if (rs == rt) branch to instruction labeled L1;
- bne rs, rt, L1
  - if (rs != rt) branch to instruction labeled L1;
- •j L1

unconditional jump to instruction labeled L1

### **Compiling If Statements**



#### **Compiling Loop Statements**

C code:

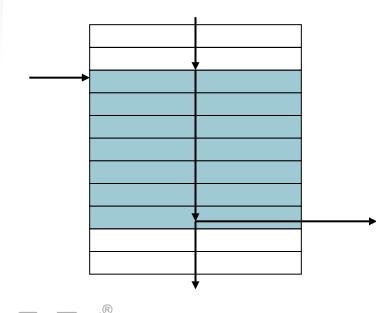
while (save[i] == k) i += 1;

i in \$s3, k in \$s5, address of save in \$s6
 Compiled MIPS code:

Loop: sll \$t1, \$s3, 2 add \$t1, \$t1, \$s6 lw \$t0, 0(\$t1) bne \$t0, \$s5, Exit addi \$s3, \$s3, 1 j Loop Exit: ...

#### **Basic Blocks**

- A basic block is a sequence of instructions with
  - No embedded branches (except at end)
  - No branch targets (except at beginning)



- A compiler identifies basic blocks for optimization
- An advanced processor can accelerate execution of basic blocks

#### **More Conditional Operations**

Set result to 1 if a condition is true Otherwise, set to 0 slt rd, rs, rt if (rs < rt) rd = 1; else rd = 0;</p> slti rt, rs, constant if (rs < constant) rt = 1; else rt = 0;</p> Use in combination with beg, bne slt \$t0, \$s1, \$s2 # if (\$s1 < \$s2) bne \$t0, \$zero, L # branch to L

#### **Branch Instruction Design**

- Why not blt, bge, etc?
- Hardware for <, ≥, … slower than =, ≠</p>
  - Combining with branch involves more work per instruction, requiring a slower clock
  - All instructions penalized!
- beq and bne are the common case
- This is a good design compromise

## Signed vs. Unsigned

- Signed comparison: slt, slti
  - Unsigned comparison: sltu, sltui
- Example

  - slt \$t0, \$s0, \$s1 # signed \_\_1 < +1 ⇒ \$t0 = 1</pre>
  - sltu \$t0, \$s0, \$s1 # unsigned ■ +4,294,967,295 > +1 ⇒ \$t0 = 0

# **Procedure Calling**

#### Steps required

- 1. Place parameters in registers
- 2. Transfer control to procedure
- 3. Acquire storage for procedure
- 4. Perform procedure's operations
- 5. Place result in register for caller
- 6. Return to place of call

# **Register Usage**

- \$a0 \$a3: arguments (reg's 4 7)
- \$v0, \$v1: result values (reg's 2 and 3)
- \$t0 \$t9: temporaries
  - Can be overwritten by callee
- \$s0 \$s7: saved
  - Must be saved/restored by callee
- \$gp: global pointer for static data (reg 28)
- \$sp: stack pointer (reg 29)
- \$fp: frame pointer (reg 30)
- \$ra: return address (reg 31)

## **Procedure Call Instructions**

- Procedure call: jump and link
  - jal ProcedureLabel
    - Address of following instruction put in \$ra
    - Jumps to target address
- Procedure return: jump register
  - jr \$ra
    - Copies \$ra to program counter
    - Can also be used for computed jumps
       e.g., for case/switch statements

### Leaf Procedure Example

- C code: int leaf\_example (int g, h, i, j) { int f; f = (g + h) - (i + j); return f; }
  - Arguments g, ..., j in \$a0, ..., \$a3
  - f in \$s0 (hence, need to save \$s0 on stack)
  - Result in \$v0

#### Leaf Procedure Example

#### MIPS code:

<pre>leaf_example:</pre>				
addi	\$sp,	\$sp,	-4	
SW	\$s0,	0(\$sj	o) (c	
add	\$t0,	\$a0,	\$a1	
add	\$t1,	\$a2,	\$a3	
sub	\$s0,	\$t0,	\$t1	
add	\$v0,	\$s0,	\$zero	
٦w	\$s0,	0(\$s	o)	
addi	\$sp,	\$sp,	4	
jr	\$ra			

Save \$s0 on stack

Procedure body

Result

Restore \$s0

Return

## **Non-Leaf Procedures**

- Procedures that call other procedures
  - For nested call, caller needs to save on the stack:
    - Its return address
    - Any arguments and temporaries needed after the call
  - Restore from the stack after the call

## **Non-Leaf Procedure Example**

```
C code:
int fact (int n)
{
  if (n < 1) return 1;
  else return n * fact(n - 1);
}
```

- Argument n in \$a0
- Result in \$v0

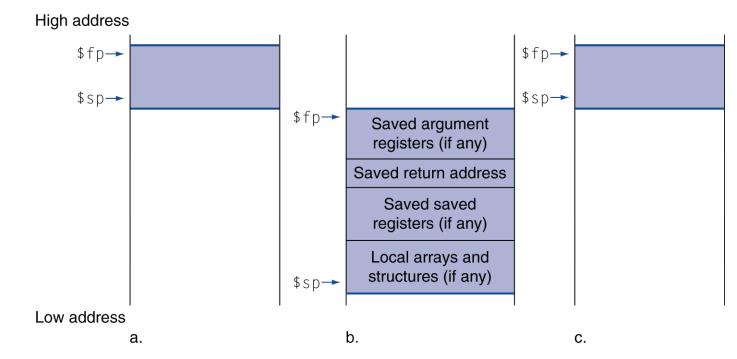
## **Non-Leaf Procedure Example**

#### MIPS code:

fact	t:				
	addi	\$sp,	\$sp, -8	#	adjust stack for 2 items
	SW	\$ra,	4(\$sp)	#	save return address
	SW	\$a0,	0(\$sp)	#	save argument
	slti	\$t0,	\$a0, 1	#	test for n < 1
	beq	\$t0,	\$zero, L1		
	addi	\$∨0,	\$zero, 1	#	if so, result is 1
	addi	\$sp,	\$sp, 8	#	pop 2 items from stack
	jr	\$ra		#	and return
L1:	addi	\$a0,	\$a0, -1	#	else decrement n
	jal	fact		#	recursive call
	٦w	\$a0,	0(\$sp)	#	restore original n
	٦w	\$ra,	4(\$sp)	#	and return address
	addi	\$sp,	\$sp, 8	#	pop 2 items from stack
	mul	\$v0,	\$a0, \$v0	#	multiply to get result
	jr	\$ra		#	and return

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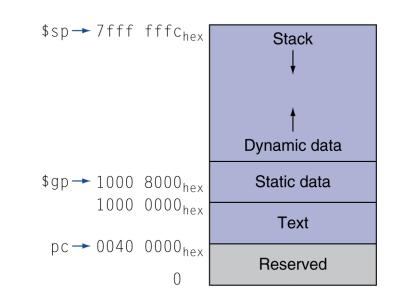
## **Local Data on the Stack**



- Local data allocated by callee
  - e.g., C automatic variables
- Procedure frame (activation record)
  - Used by some compilers to manage stack storage

# **Memory Layout**

- Text: program code
- Static data: global variables
  - e.g., static variables in C, constant arrays and strings
  - \$gp initialized to address allowing ±offsets into this segment
  - Dynamic data: heap
    - E.g., malloc in C, new in Java
- Stack: automatic storage



#### **Character Data**

Byte-encoded character sets ASCII: 128 characters 95 graphic, 33 control Latin-1: 256 characters ASCII, +96 more graphic characters Unicode: 32-bit character set Used in Java, C++ wide characters, … Most of the world's alphabets, plus symbols

UTF-8, UTF-16: variable-length encodings

# **Byte/Halfword Operations**

Could use bitwise operations MIPS byte/halfword load/store String processing is a common case lb rt, offset(rs) lh rt, offset(rs) Sign extend to 32 bits in rt lbu rt, offset(rs) lhu rt, offset(rs) Zero extend to 32 bits in rt sb rt, offset(rs) sh rt, offset(rs)

Store just rightmost byte/halfword

# String Copy Example

```
C code (naïve):
  Null-terminated string
 void strcpy (char x[], char y[])
  { int i;
    i = 0;
    while ((x[i]=y[i])!='\setminus 0')
      i += 1;
  }
  Addresses of x, y in $a0, $a1
  i in $s0
```

# **String Copy Example**

#### MIPS code:

stro	cpy:				
	addi	\$sp,	\$sp, -4	#	adjust stack for 1 item
	SW	\$s0,	0(\$sp)	#	save \$s0
	add	\$s0,	<pre>\$zero, \$zero</pre>		
L1:	add	\$t1,	\$s0, \$a1	#	addr of y[i] in \$t1
	1bu	\$t2,	0(\$t1)	#	$t_{2} = y[i]$
	add	\$t3,	\$s0, \$a0	#	addr of x[i] in \$t3
	sb	\$t2,	0(\$t3)	#	x[i] = y[i]
	beq	\$t2,	\$zero, L2	#	exit loop if y[i] == 0
	addi	\$s0,	\$s0, 1	#	i = i + 1
	j	L1		#	next iteration of loop
L2:	٦w	\$s0,	0(\$sp)	#	restore saved \$s0
	addi	\$sp,	\$sp, 4	#	pop 1 item from stack
	jr	\$ra		#	and return

#### **32-bit Constants**

- Most constants are small
  - 16-bit immediate is sufficient
  - For the occasional 32-bit constant
  - lui rt, constant
    - Copies 16-bit constant to left 16 bits of rt
  - Clears right 16 bits of rt to 0

lui \$s0, 61

0000 0000 0011 1101 0000 0000 0000 0000

ori \$s0, \$s0, 2304 0000 0000 0011 1101 0000 1001 0000 0000



# **Branch Addressing**

Branch instructions specify

- Opcode, two registers, target address
- Most branch targets are near branch
  - Forward or backward

ор	rs	rt	constant or address
6 bits	5 bits	5 bits	16 bits

- PC-relative addressing
  - Target address = PC + offset × 4
  - PC already incremented by 4 by this time

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# **Jump Addressing**

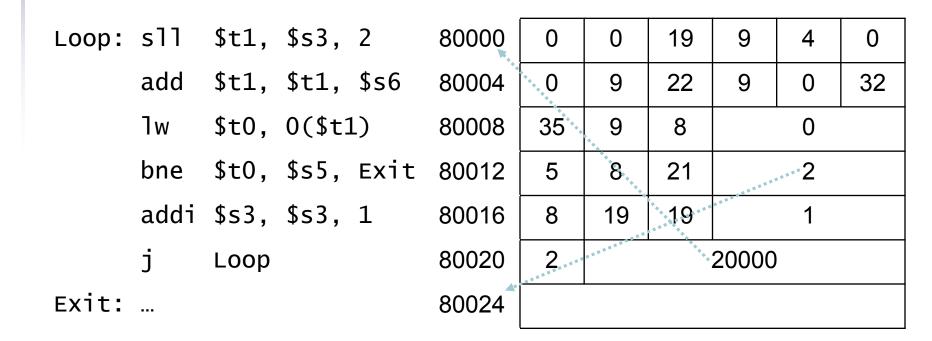
- Jump (j and jal) targets could be anywhere in text segment
  - Encode full address in instruction

ор	address
6 bits	26 bits

- (Pseudo)Direct jump addressing
  - Target address = PC<sub>31...28</sub> : (address × 4)

# **Target Addressing Example**

Loop code from earlier exampleAssume Loop at location 80000



# **Branching Far Away**

If branch target is too far to encode with 16-bit offset, assembler rewrites the code

#### Example

```
beq $s0,$s1, L1
↓
bne $s0,$s1, L2
j L1
L2: ...
```

# **Addressing Mode Summary**

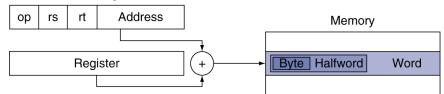
1. Immediate addressing

op rs rt Immediate

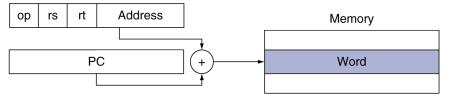
#### 2. Register addressing



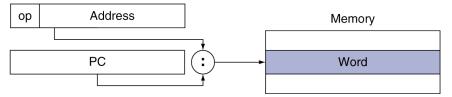
#### 3. Base addressing



#### 4. PC-relative addressing



5. Pseudodirect addressing



# **Synchronization**

Two processors sharing an area of memory

- P1 writes, then P2 reads
- Data race if P1 and P2 don't synchronize
  - Result depends of order of accesses
- Hardware support required
  - Atomic read/write memory operation
  - No other access to the location allowed between the read and write
- Could be a single instruction
  - E.g., atomic swap of register  $\leftrightarrow$  memory
  - Or an atomic pair of instructions

# **Synchronization in MIPS**

- Load linked: 11 rt, offset(rs)
- Store conditional: sc rt, offset(rs)
  - Succeeds if location not changed since the 11
    - Returns 1 in rt
  - Fails if location is changed
    - Returns 0 in rt

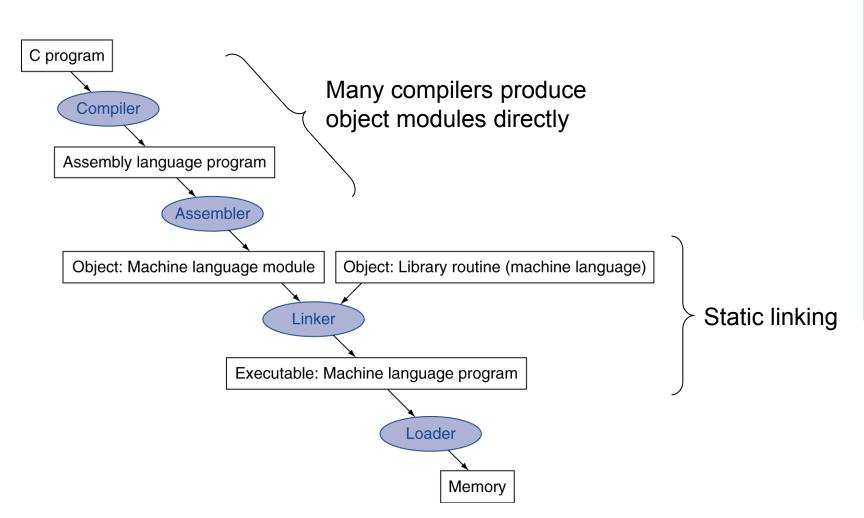
Example: atomic swap (to test/set lock variable)

try: add \$t0,\$zero,\$s4 ;copy exchange value

- 11 \$t1,0(\$s1) ;load linked
- sc \$t0,0(\$s1) ;store conditional
- beq \$t0,\$zero,try ;branch store fails
- add \$s4,\$zero,\$t1 ;put load value in \$s4



### **Translation and Startup**



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#### **Assembler Pseudoinstructions**

- Most assembler instructions represent machine instructions one-to-one
- Pseudoinstructions: figments of the assembler's imagination
  - move \$t0, \$t1  $\rightarrow$  add \$t0, \$zero, \$t1
  - blt \$t0, \$t1,  $L \rightarrow slt$  \$at, \$t0, \$t1 bne \$at, \$zero, L
    - \$at (register 1): assembler temporary

# **Producing an Object Module**

- Assembler (or compiler) translates program into machine instructions
- Provides information for building a complete program from the pieces
  - Header: described contents of object module
  - Text segment: translated instructions
  - Static data segment: data allocated for the life of the program
  - Relocation info: for contents that depend on absolute location of loaded program
  - Symbol table: global definitions and external refs
  - Debug info: for associating with source code

# **Linking Object Modules**

Produces an executable image

- 1. Merges segments
- 2. Resolve labels (determine their addresses)
- 3. Patch location-dependent and external refs
- Could leave location dependencies for fixing by a relocating loader
  - But with virtual memory, no need to do this
  - Program can be loaded into absolute location in virtual memory space

# Loading a Program

- Load from image file on disk into memory
  - 1. Read header to determine segment sizes
  - 2. Create virtual address space
  - Copy text and initialized data into memory
    Or set page table entries so they can be faulted in
  - 4. Set up arguments on stack
  - 5. Initialize registers (including \$sp, \$fp, \$gp)
  - 6. Jump to startup routine
    - Copies arguments to \$a0, ... and calls main
    - When main returns, do exit syscall

# **Dynamic Linking**

- Only link/load library procedure when it is called
  - Requires procedure code to be relocatable
  - Avoids image bloat caused by static linking of all (transitively) referenced libraries
  - Automatically picks up new library versions



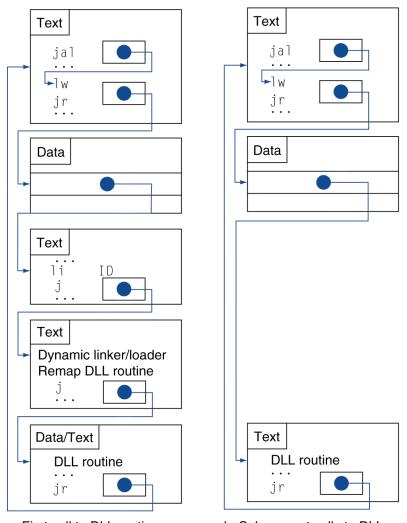
## Lazy Linkage

Indirection table

Stub: Loads routine ID, Jump to linker/loader

Linker/loader code

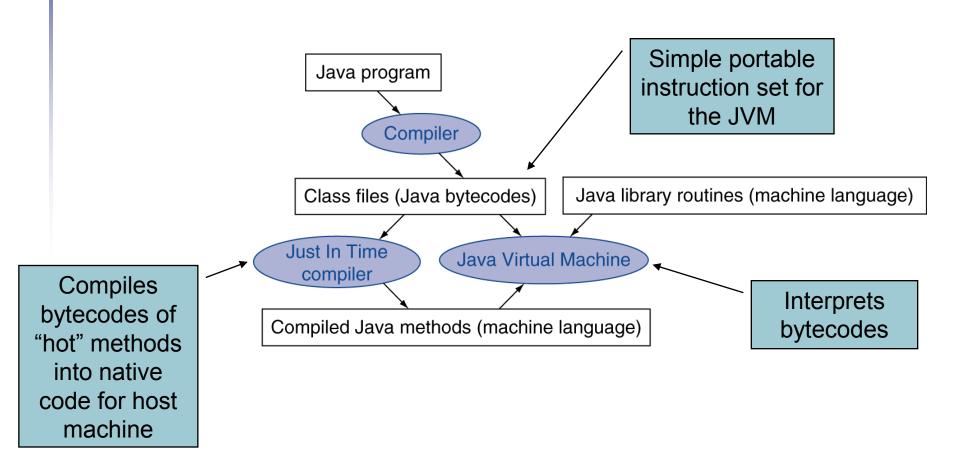
Dynamically mapped code



a. First call to DLL routine

b. Subsequent calls to DLL routine

# **Starting Java Applications**



# **C Sort Example**

Illustrates use of assembly instructions for a C bubble sort function Swap procedure (leaf) void swap(int v[], int k) int temp; temp = v[k]; v[k] = v[k+1];v[k+1] = temp;} v in \$a0, k in \$a1, temp in \$t0

#### **The Procedure Swap**



#### The Sort Procedure in C

```
Non-leaf (calls swap)
  void sort (int v[], int n)
  Ł
     int i, j;
     for (i = 0; i < n; i += 1) {
       for (j = i - 1;
             j >= 0 \& v[j] > v[j + 1];
             i -= 1) {
         swap(v,j);
       }
  }
v in $a0, k in $a1, i in $s0, j in $s1
```

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## **The Procedure Body**

M

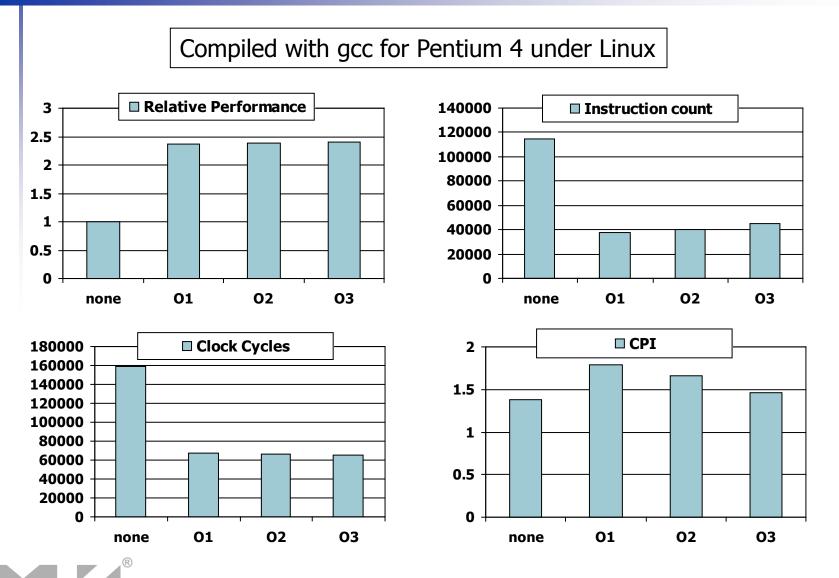
	move	\$s2,	\$a0	#	save \$a0 into \$s2	Move
	move	\$s3,	\$a1	#	save \$a1 into \$s3	params
	move	\$s0,	\$zero	#	i = 0	Outerleen
for1tst:	slt	\$t0,	\$s0, \$s3	#	$t0 = 0 \text{ if } s0 \ge s3 (i \ge n)$	Outer loop
	beq	\$t0,	\$zero, exit1	#	go to exit1 if $s0 \ge s3$ (i \ge n)	
	addi	\$s1,	\$s0, −1	#	j = i - 1	
for2tst:	slti	\$t0,	\$s1, 0	#	t0 = 1  if  s1 < 0 (j < 0)	
	bne	\$t0,	<pre>\$zero, exit2</pre>	#	go to exit2 if \$s1 < 0 (j < 0)	
	s11	\$t1,	\$s1, 2	#	\$t1 = j * 4	Inner loop
	add	\$t2,	\$s2, \$t1	#	t2 = v + (j * 4)	
	٦w	\$t3,	0(\$t2)	#	t3 = v[j]	
	٦w	\$t4,	4(\$t2)	#	t4 = v[j + 1]	
	slt	\$t0,	\$t4, \$t3	#	$t0 = 0 \text{ if } t4 \ge t3$	
	beq	\$t0,	\$zero, exit2	#	go to exit2 if \$t4 ≥ \$t3	
	move	\$a0,	\$s2	#	1st param of swap is v (old \$a0)	Pass
	move	\$a1,	\$s1	#	2nd param of swap is j	params
	jal	swap		#	call swap procedure	& call
	addi	\$s1,	\$s1, -1	#	j -= 1	
	j	for2	tst	#	jump to test of inner loop	Inner loop
exit2:	addi	\$s0,	\$s0, 1	#	i += 1	Outerless
	j	for1	tst	#	jump to test of outer loop	Outer loop
Ô						-

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#### **The Full Procedure**

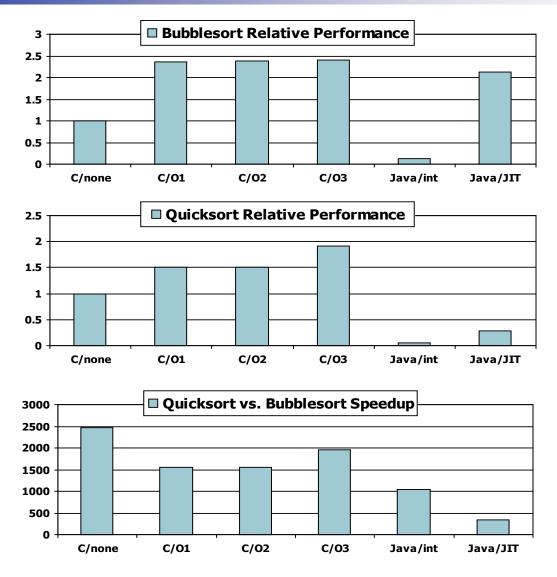
sort:	addi \$sp,\$sp, -20	<pre># make room on stack for 5 registers</pre>
	sw \$ra, 16(\$sp)	# save \$ra on stack
	sw \$s3,12(\$sp)	# save \$s3 on stack
	sw \$s2, 8(\$sp)	# save \$s2 on stack
	sw \$s1, 4(\$sp)	# save \$s1 on stack
	sw \$s0, 0(\$sp)	# save \$s0 on stack
		# procedure body
	exit1: lw \$s0, 0(\$sp)	<pre># restore \$s0 from stack</pre>
	lw \$s1, 4(\$sp)	<pre># restore \$s1 from stack</pre>
	lw \$s2, 8(\$sp)	<pre># restore \$s2 from stack</pre>
	lw \$s3,12(\$sp)	<pre># restore \$s3 from stack</pre>
	lw \$ra,16(\$sp)	<pre># restore \$ra from stack</pre>
	addi \$sp,\$sp, 20	<pre># restore stack pointer</pre>
	jr \$ra	<pre># return to calling routine</pre>

#### **Effect of Compiler Optimization**



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#### **Effect of Language and Algorithm**



#### **Lessons Learnt**

- Instruction count and CPI are not good performance indicators in isolation
- Compiler optimizations are sensitive to the algorithm
- Java/JIT compiled code is significantly faster than JVM interpreted
  - Comparable to optimized C in some cases Nothing can fix a dumb algorithm!

#### **Arrays vs. Pointers**

- Array indexing involves
  - Multiplying index by element size
  - Adding to array base address
- Pointers correspond directly to memory addresses
  - Can avoid indexing complexity

## **Example: Clearing and Array**

<pre>clear1(int array[], int size) int i; for (i = 0; i &lt; size; i += 1) array[i] = 0; }</pre>	int *p;
sw \$zero, 0(\$t2) # array addi \$t0,\$t0,1 # i = 5 slt \$t3,\$t0,\$a1 # \$t3 =	<pre>size = i * 4 = sll \$t1,\$a1,2 # \$t1 = size * 4 add \$t2,\$a0,\$t1 # \$t2 =</pre>
· · · ·	oto loop1 # goto loop2

# **Comparison of Array vs. Ptr**

- Multiply "strength reduced" to shift
  Array version requires shift to be inside loop
  - Part of index calculation for incremented i
  - c.f. incrementing pointer
- Compiler can achieve same effect as manual use of pointers
  - Induction variable elimination
  - Better to make program clearer and safer

#### **ARM & MIPS Similarities**

ARM: the most popular embedded core
Similar basic set of instructions to MIPS

	ARM	MIPS
Date announced	1985	1985
Instruction size	32 bits	32 bits
Address space	32-bit flat	32-bit flat
Data alignment	Aligned	Aligned
Data addressing modes	9	3
Registers	15 × 32-bit	31 × 32-bit
Input/output	Memory mapped	Memory mapped



### **Compare and Branch in ARM**

- Uses condition codes for result of an arithmetic/logical instruction
  - Negative, zero, carry, overflow
  - Compare instructions to set condition codes without keeping the result
- Each instruction can be conditional
  - Top 4 bits of instruction word: condition value
  - Can avoid branches over single instructions

#### **Instruction Encoding**

			27	2	20 19 16			43 0
	ARM	Opx <sup>4</sup>	Op <sup>8</sup>		Rs1⁴	Rd⁴	Opx <sup>8</sup>	Rs2 <sup>4</sup>
Register-register		31	26 25	21 2	20 16	15 1	1 10 6 5	5 0
	MIPS	Op <sup>6</sup>	Rs1	5	Rs2⁵	Rd⁵	Const <sup>5</sup>	Opx <sup>6</sup>
		31 28	27	2	20 19 16	15 12 1	1	0
	ARM	Opx <sup>4</sup>	Op <sup>8</sup>		Rs1 <sup>4</sup>	Rd⁴	Const <sup>11</sup>	2
Data transfer		31	26 25	21 2	20 16	15		0
	MIPS	Op <sup>6</sup>	Rs1	5	Rd⁵		Const <sup>16</sup>	
			27 24 23			2	4	0
	ARM	Opx <sup>4</sup>	Op <sup>4</sup>			Const <sup>2</sup>	•	
Branch		31	26 25	21 2		15		0
	MIPS	Op <sup>6</sup>	Rs1	5	Opx <sup>5</sup> /Rs2 <sup>5</sup>		Const <sup>16</sup>	
		31 28	27 24 23					0
	ARM	Opx <sup>4</sup>	Op <sup>4</sup>			Const <sup>2</sup>	4	Ũ
1. (O. II.								
Jump/Call		31	26 25			26		0
	MIPS	Op <sup>6</sup>				Const <sup>26</sup>		
	Dpcode DRegister Constant							

#### The Intel x86 ISA

Evolution with backward compatibility

- 8080 (1974): 8-bit microprocessor
  - Accumulator, plus 3 index-register pairs
- 8086 (1978): 16-bit extension to 8080
  - Complex instruction set (CISC)
- 8087 (1980): floating-point coprocessor
  - Adds FP instructions and register stack
- 80286 (1982): 24-bit addresses, MMU
  - Segmented memory mapping and protection
- 80386 (1985): 32-bit extension (now IA-32)
  - Additional addressing modes and operations
  - Paged memory mapping as well as segments

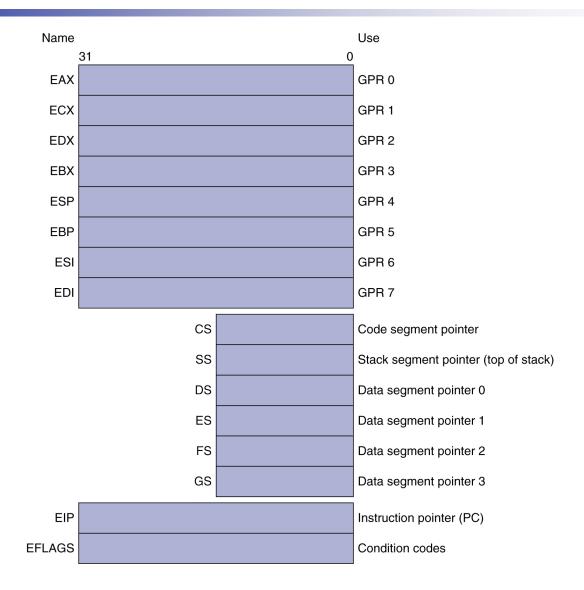
#### The Intel x86 ISA

- Further evolution...
  - i486 (1989): pipelined, on-chip caches and FPU
    - Compatible competitors: AMD, Cyrix, …
  - Pentium (1993): superscalar, 64-bit datapath
    - Later versions added MMX (Multi-Media eXtension) instructions
    - The infamous FDIV bug
  - Pentium Pro (1995), Pentium II (1997)
    - New microarchitecture (see Colwell, The Pentium Chronicles)
  - Pentium III (1999)
    - Added SSE (Streaming SIMD Extensions) and associated registers
  - Pentium 4 (2001)
    - New microarchitecture
    - Added SSE2 instructions

#### The Intel x86 ISA

- And further...
  - AMD64 (2003): extended architecture to 64 bits
  - EM64T Extended Memory 64 Technology (2004)
    - AMD64 adopted by Intel (with refinements)
    - Added SSE3 instructions
  - Intel Core (2006)
    - Added SSE4 instructions, virtual machine support
  - AMD64 (announced 2007): SSE5 instructions
     Intel declined to follow, instead...
  - Advanced Vector Extension (announced 2008)
    - Longer SSE registers, more instructions
- If Intel didn't extend with compatibility, its competitors would!
  - Technical elegance ≠ market success

#### **Basic x86 Registers**



#### **Basic x86 Addressing Modes**

#### Two operands per instruction

Source/dest operand	Second source operand
Register	Register
Register	Immediate
Register	Memory
Memory	Register
Memory	Immediate

#### Memory addressing modes

- Address in register
- Address = R<sub>base</sub> + displacement
- Address =  $R_{base}$  + 2<sup>scale</sup> ×  $R_{index}$  (scale = 0, 1, 2, or 3)
- Address =  $R_{base} + 2^{scale} \times R_{index} + displacement$

### x86 Instruction Encoding

a. JE EIP + disp	lacement				
4 4	8				
JE Condi- tion	Displacement				
b. CALL					
8		32			
CALL		Offset			
	[EDI + 45]	•			
6 1 1	8	8			
MOV dw	r/m Postbyte	Displacement			
d. PUSH ESI					
5 3					
	]				
PUSH Reg					
	1				
e. ADD EAX, #6	765				
4 3 1	100	32			
ADD Reg w	Immediate				
· · · ·					
f. TEST EDX, #4	12				
7 1	8	32			
test w	Postbyte	Immediate			

#### Variable length encoding

- Postfix bytes specify addressing mode
- Prefix bytes modify operation
  - Operand length,
    - repetition, locking, ...

## **Implementing IA-32**

- Complex instruction set makes implementation difficult
  - Hardware translates instructions to simpler microoperations
    - Simple instructions: 1–1
    - Complex instructions: 1—many
  - Microengine similar to RISC
  - Market share makes this economically viable
- Comparable performance to RISC
  - Compilers avoid complex instructions

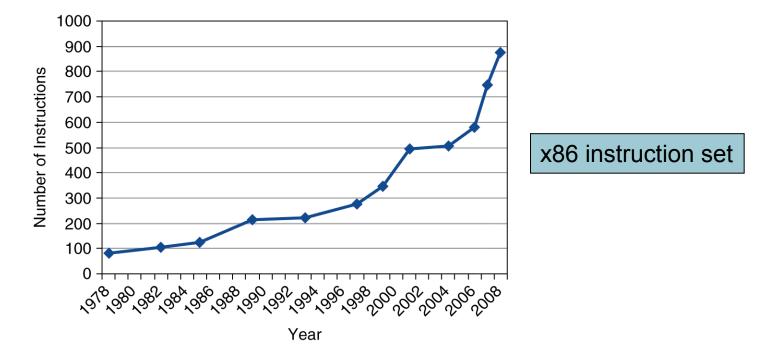
#### Fallacies

- Powerful instruction  $\Rightarrow$  higher performance
  - Fewer instructions required
  - But complex instructions are hard to implement
    - May slow down all instructions, including simple ones
  - Compilers are good at making fast code from simple instructions
- Use assembly code for high performance
  - But modern compilers are better at dealing with modern processors
  - More lines of code ⇒ more errors and less productivity

#### Fallacies

# Backward compatibility $\Rightarrow$ instruction set doesn't change

But they do accrete more instructions



#### **Pitfalls**

- Sequential words are not at sequential addresses
  - Increment by 4, not by 1!
- Keeping a pointer to an automatic variable after procedure returns
  - e.g., passing pointer back via an argument
  - Pointer becomes invalid when stack popped



### **Concluding Remarks**

#### Design principles

- 1. Simplicity favors regularity
- 2. Smaller is faster
- 3. Make the common case fast
- 4. Good design demands good compromises
- Layers of software/hardware
  - Compiler, assembler, hardware
- MIPS: typical of RISC ISAs
  - c.f. x86

## **Concluding Remarks**

- Measure MIPS instruction executions in benchmark programs
  - Consider making the common case fast
  - Consider compromises

Instruction class	MIPS examples	SPEC2006 Int	SPEC2006 FP
Arithmetic	add, sub, addi	16%	48%
Data transfer	lw, sw, lb, lbu, lh, lhu, sb, lui	35%	36%
Logical	and, or, nor, andi, ori, sll, srl	12%	4%
Cond. Branch	beq, bne, slt, slti, sltiu	34%	8%
Jump	j, jr, jal	2%	0%

#### **Exercises**

 Answer the following exercises, and send your answers as a PDF attachment to the email address listed below

xamiri@fi.muni.cz

- Leave body of the email blank
- Deadline is March 25<sup>th</sup>

#### **Exercise 1**

Assume that the stack and the static data segments are empty and that the stack and global pointers start at address 0x7fff fffc and 0x1000 8000, respectively. int my\_global = 100; main() { int x = 10; int y = 20;

```
int z;
z = my_function(x, my_global)
}
int my_function(int x, int y)
{
```

```
return x - y;
```

- 1) Show the contents of the stack and the static data segments after each function call.
- 2) Write MIPS code for the code above.

#### **Exercise 2**

 For the following problems, use the hexadecimal data in the table below.

a. 0x00001000

b. 0xFFFC0000

- 1) If the PC is at address 0x0000000, how many branch (no jump instructions) do you need to get to the addresses in the table above?
- 2) If the PC is at address 0x00000000, how many jump instructions (no jump register instructions or branch instructions) are required to get to the target addresses in the table above?



#### **Exercise 3**

Each entry in the following table has code and also shows the contents of various registers. The notation, "(\$s1)" shows the contents of a memory location pointed to by register \$s1. The assembly code in the table is executed in the cycle shown on parallel processors with a shared memory space. Fill out the table with the value of the registers for each given cycle.

	Broossor 1		Cycle	Processor 1			MEM	Processor 2		
	Processor 1	Processor 2		\$s4	\$t1	\$t0	(\$s1)	\$s4	\$t1	\$t0
			0	2	3	4	99	10	20	30
		try: add \$t0, \$0, \$s4	1							
try: a	add \$t0, \$0, \$s4	ll \$t1, 0(\$s1)	2							
]	ll \$t1, 0(\$s1)		3							
ç	sc \$t0, 0(\$s1)		4							
k	beqz \$t0, try	sc \$t0, 0(\$s1)	5							
	add \$s4, \$0, \$t1	beqz \$t0, try	6							