

# Meta-learning for Periodic Algorithm Selection in Time- changing Data

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Masaryk U. – Advanced Machine Learning  
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# Outline

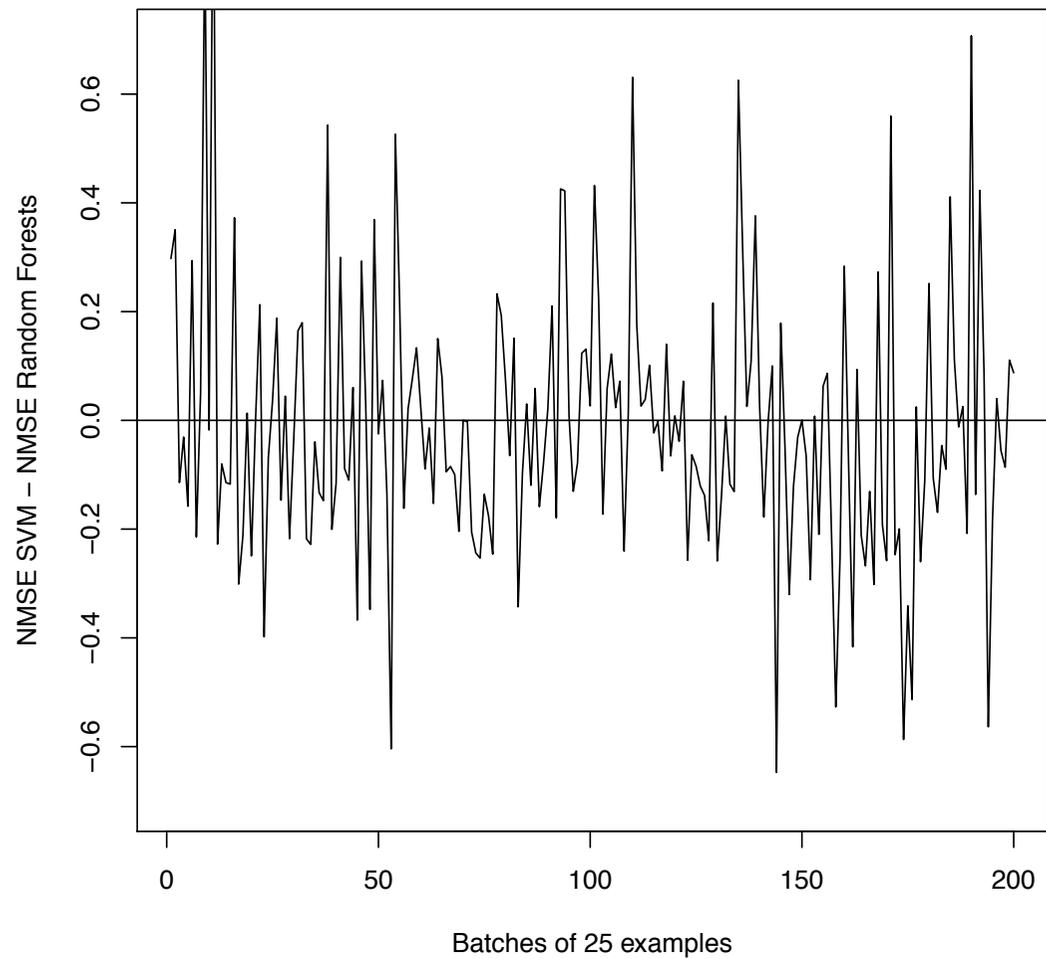
- Introduction
- MetaStream
- Experiments
- Results
- Meta-data issues
- Conclusions and Future Work

# Context

- Dynamic real-world systems generate data continuously
  - Underlying distribution naturally changes over time
    - Concept drift: gradual or abrupt
- Different performance of learning algorithms for different instants of time
- No-free Lunch Theorem (Wolpert, 1996)
  - Any learning algorithm cannot always be the best for all possible learning tasks

# Motivation

Difference between SVM and Random Forests

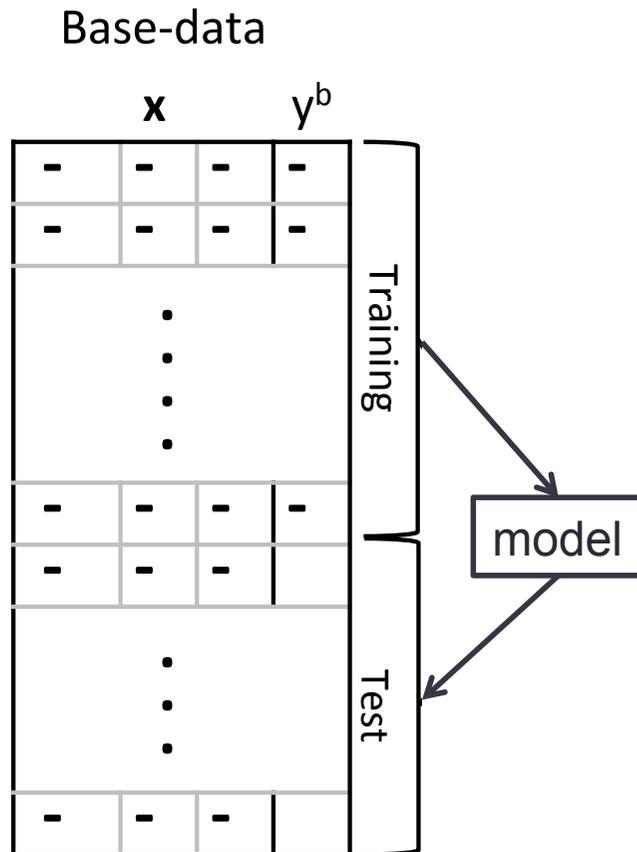


# Problem & Approach

- Periodic algorithm selection for non-stationary environments
- MetaStream: a metalearning approach
  - Meta-model relates data characteristics to base-level model performance

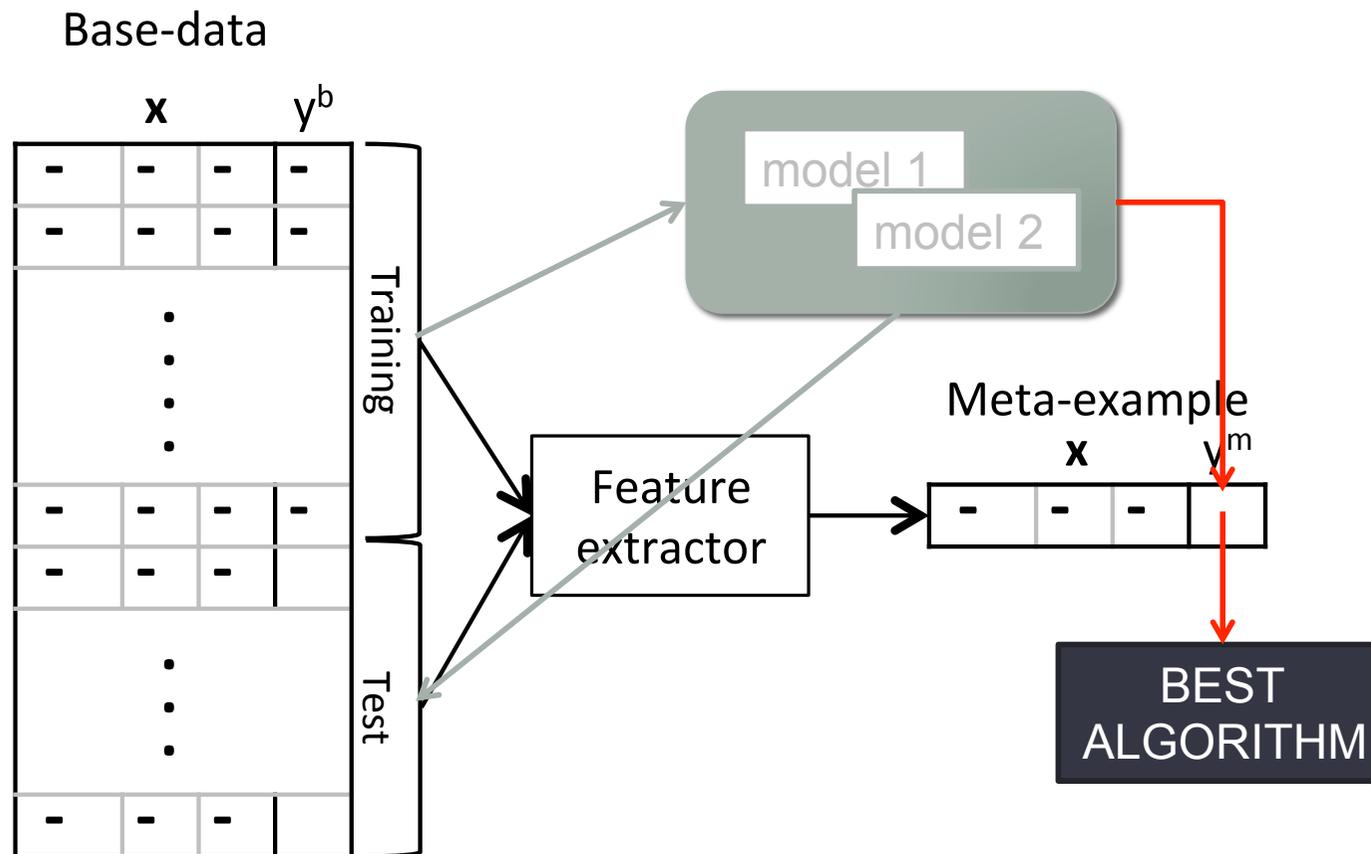


# Base-level

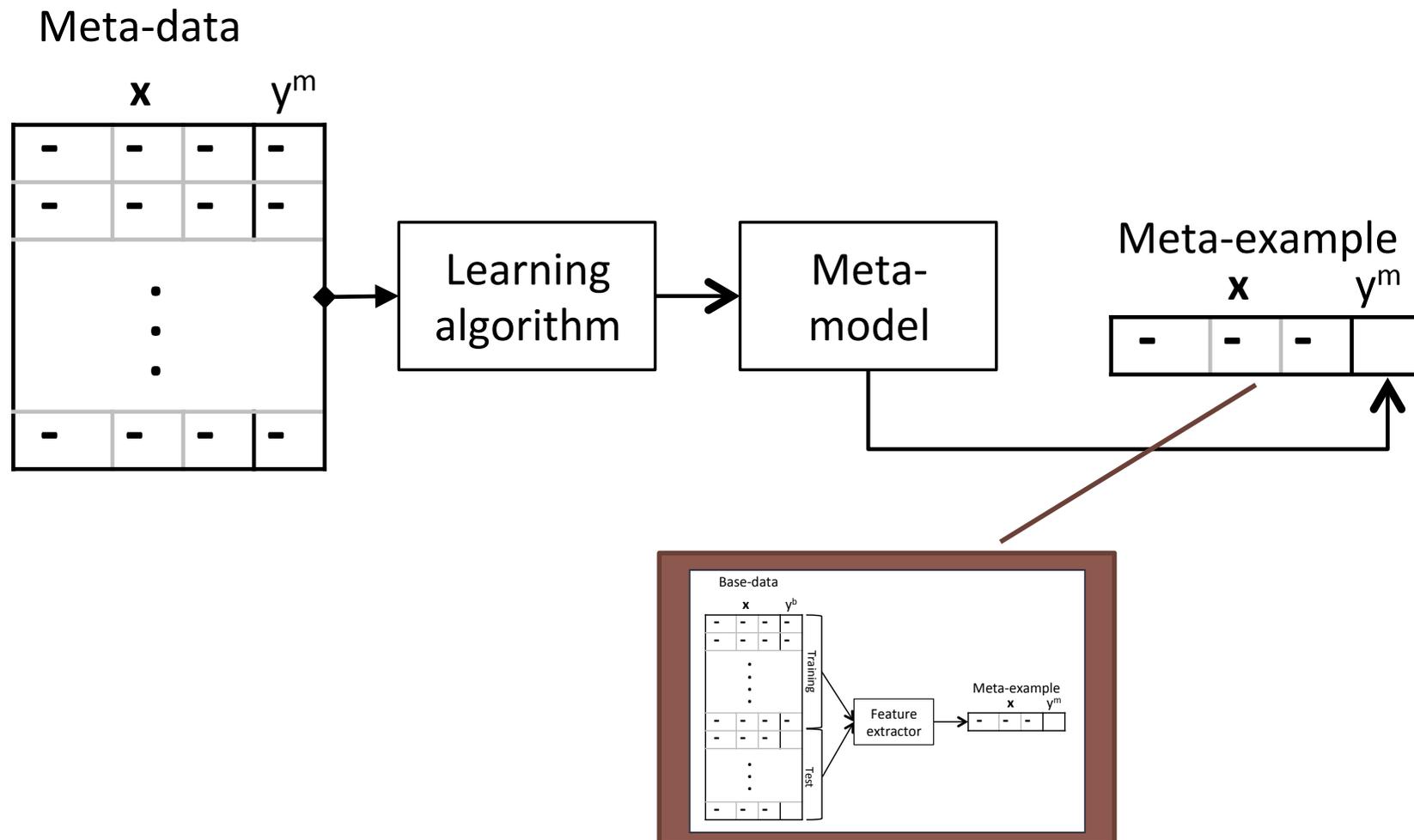


- For each new batch of  $n$  test examples:
  - Induces regression models using most recent training data
  - Predicts target value for test examples
  - Evaluates predictions when true target values become available

# Meta-level: meta-data



# Meta-level: meta-model induction and algorithm prediction



# Experiments: comparison

- Meta-level
  - MetaStream
  - Default class
    - majority class (i.e., regression algorithm) in the meta training data
- Base-level
  - MetaStream and Default
    - i.e., algorithms selected by these methods
  - Ensemble: average predictions of regressors

# Experimental setup: base-level

- Regression algorithms:
  - Random Forests (RF)
  - Support Vector Machines (SVM)
  - Classification and Regression Trees (CART)
  - Project Pursuit Regression (PPR)
- Data
  - Travel time prediction (TTP) problem
- Time
  - Training window: 1000 examples
  - Sliding step: 1 example
- Evaluation measure
  - NMSE

# Experimental setup: meta-level data

- Pairwise comparisons of algorithms
  - blocks of 25 base-level examples
  - for every pair of algorithms, which one is the best
    - or tie if difference between base-level NMSE  $< 0.1$
  - ... but no ranking
- Experiments with and without tie meta-examples
  - ... on the training set
- Meta-features
  - possibility of existence of outliers, dispersion gain, skewness, kurtosis, average, variance, minimum, maximum, ...
  - correlation between attribute and target
  - ... for each independent variable

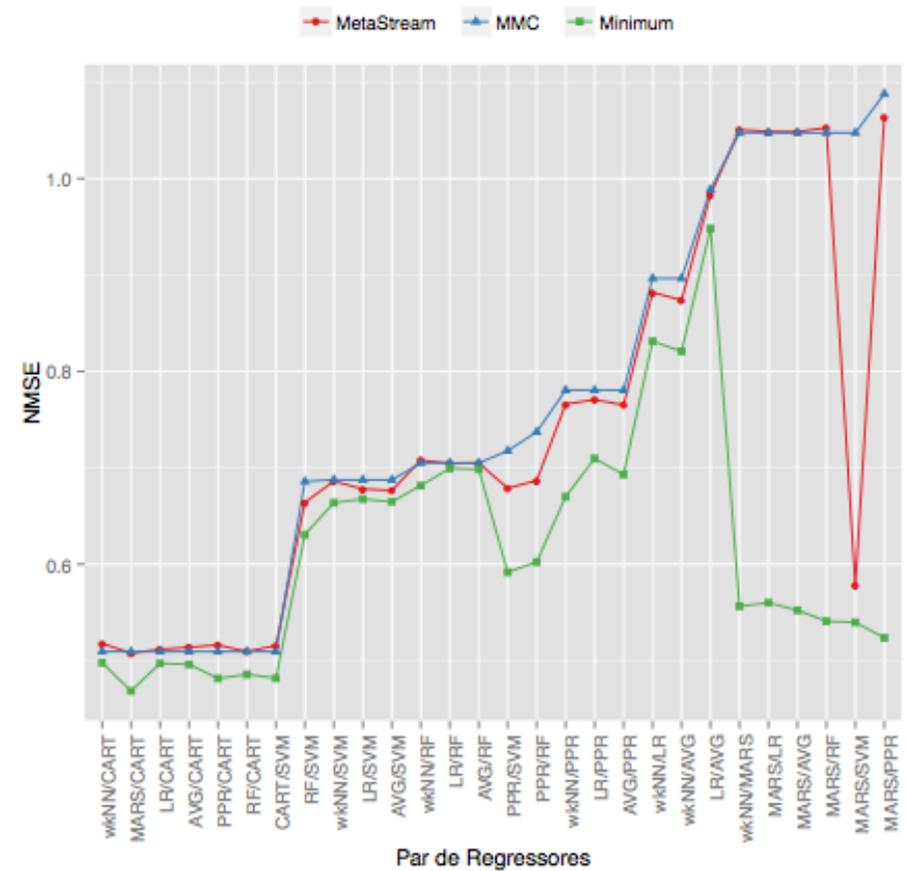
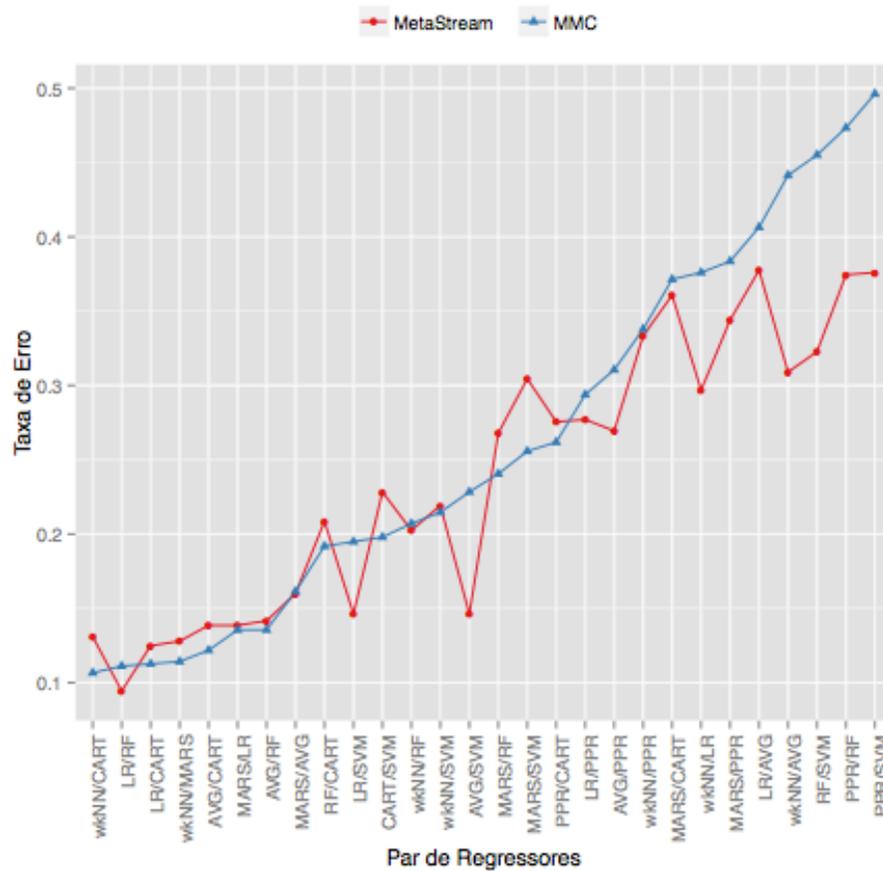


major  
difference to  
"traditional"  
metalearning

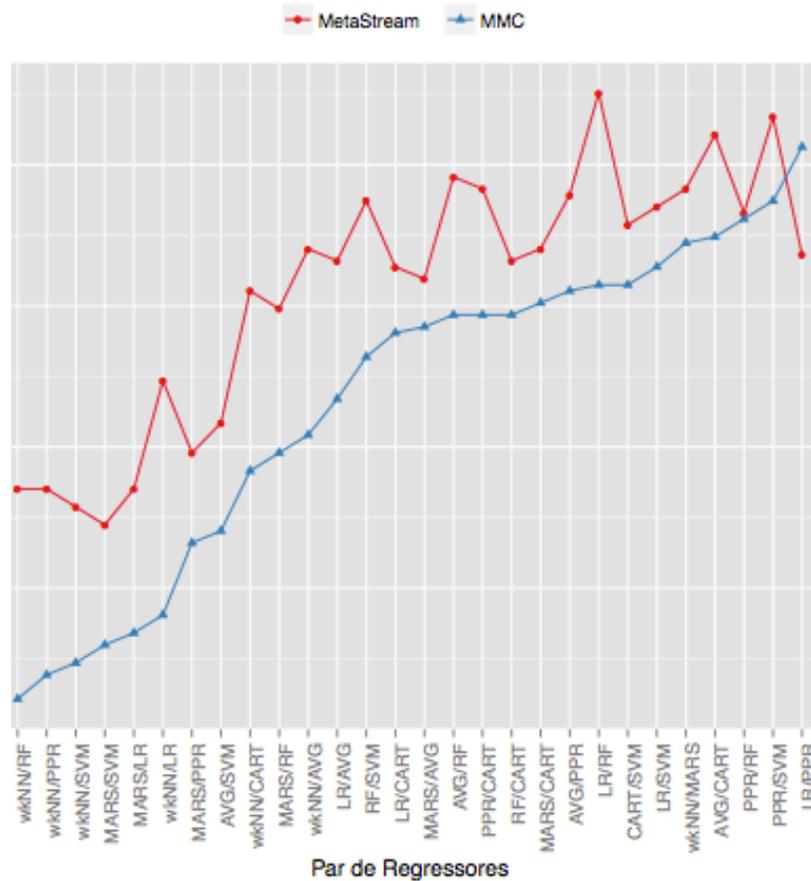
# Experimental setup: meta-level

- Meta-level learning
  - classification task
  - RF
- Meta-model updating strategies:
  - Dynamic: updated for each new meta-example
  - Static: never updated
- Meta-time
  - Sliding window of 300 meta-examples
  - Sliding step of 1 meta-example

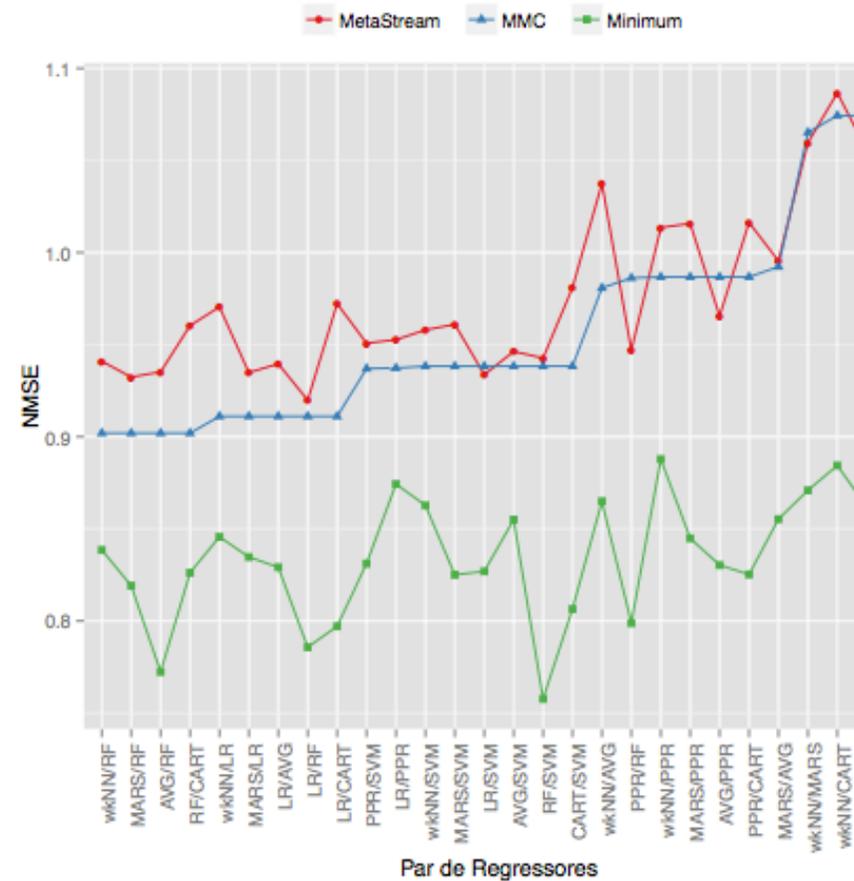
# Sometimes the winner is unclear



# Sometimes MetaStream is worse

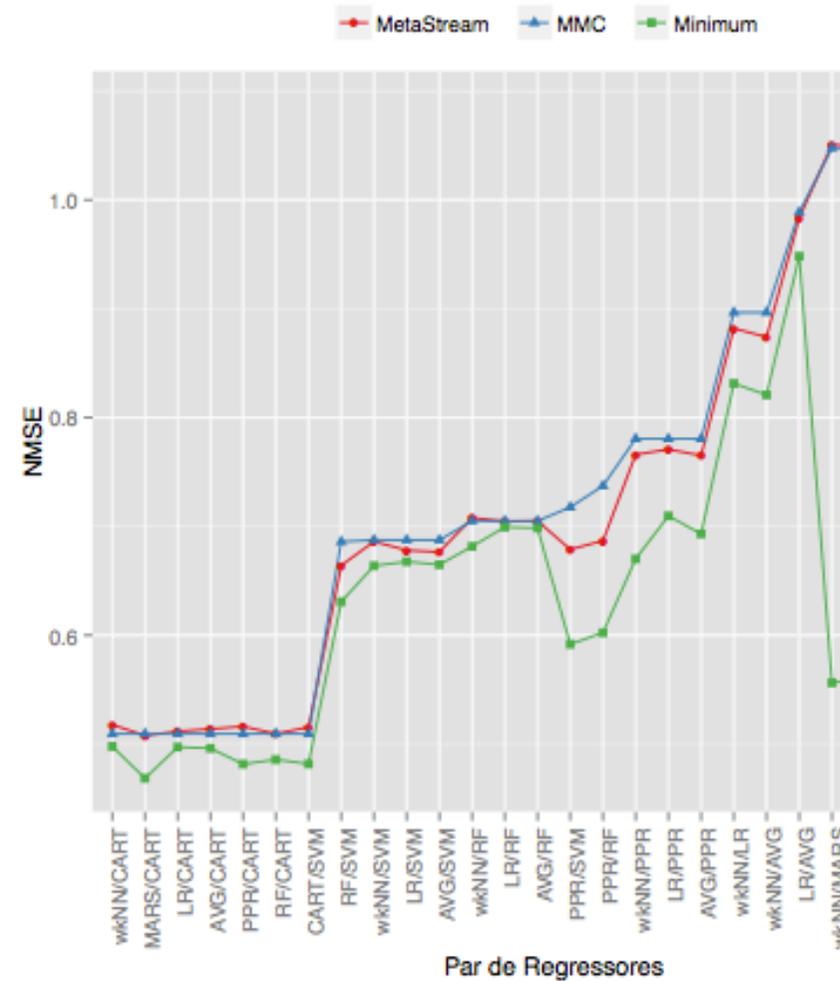
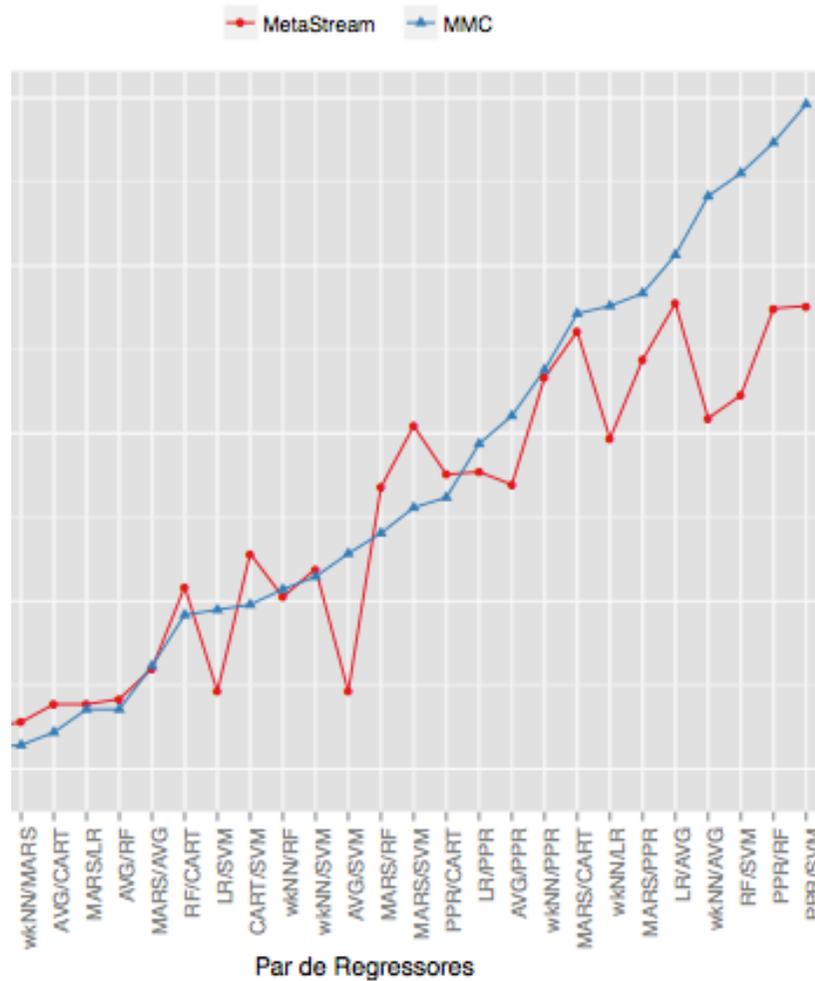


(a) airline LGA meta



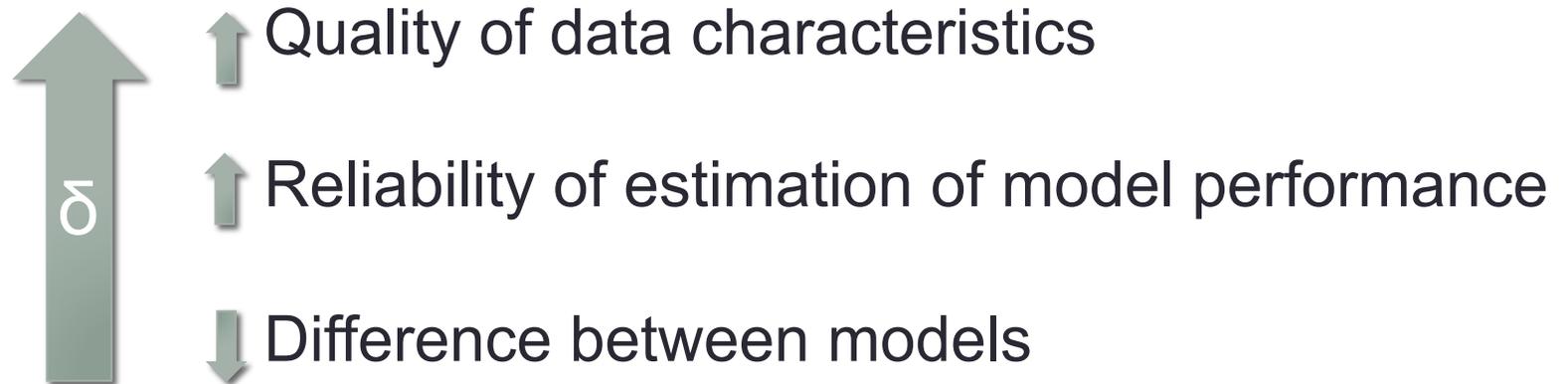
(b) airline LGA base

# Sometimes MetaStream is better



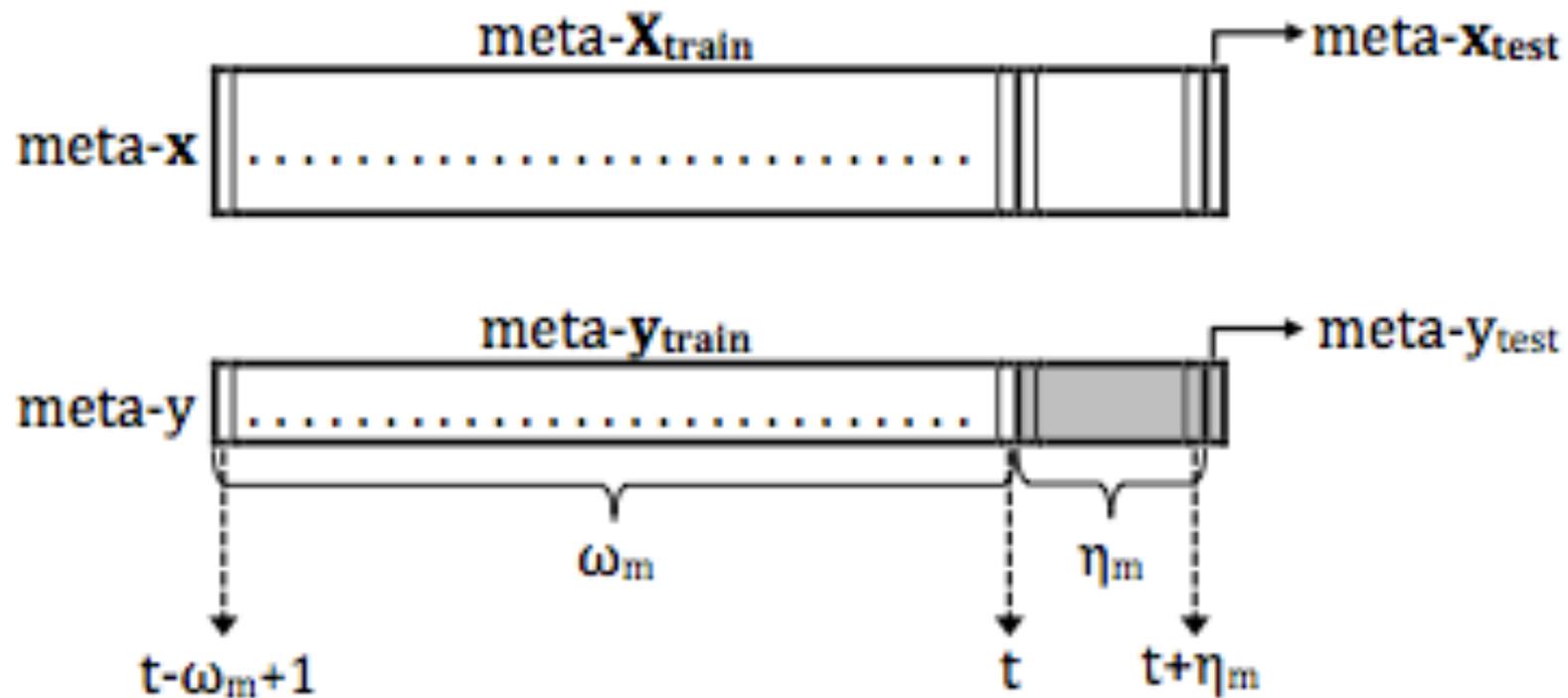
# Meta-data issues

- Quality of the meta-data is sensitive to the size of the test set ( $\delta$ ):





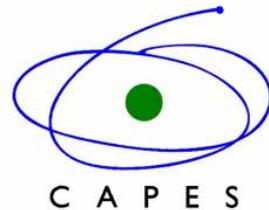
# Meta-features issues: meta level



# Conclusion and Future Work

- MetaStream is a promising approach for periodically selecting algorithms over time
- RF/CART and SVM/CART are the best choices of pairs of algorithms for the data analyzed
  - They achieved the smallest NMSE
- The proposed approach is not domain and algorithm dependent
- As future work, we plan:
  - To investigate meta-features specific for time-changing data
  - To move beyond simple pair of algorithms to multi-class classification

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# References

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