Digital Signal Processing

The Discrete Fourier Transform (2)

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- Zero padding
 - A method to improve DFT spectral estimation
 - Involves addition of zero-valued data samples to an original DFT input sequence to increase total number of input data samples
 - Investigating zero-padding technique illustrates
 DFT's property of frequency-domain sampling
 - When we sample a continuous time-domain function, having a CFT, and take DFT of those samples, the DFT results in a frequency-domain sampled approximation of the CFT
 - The more points in DFT, the better DFT output approximates CFT

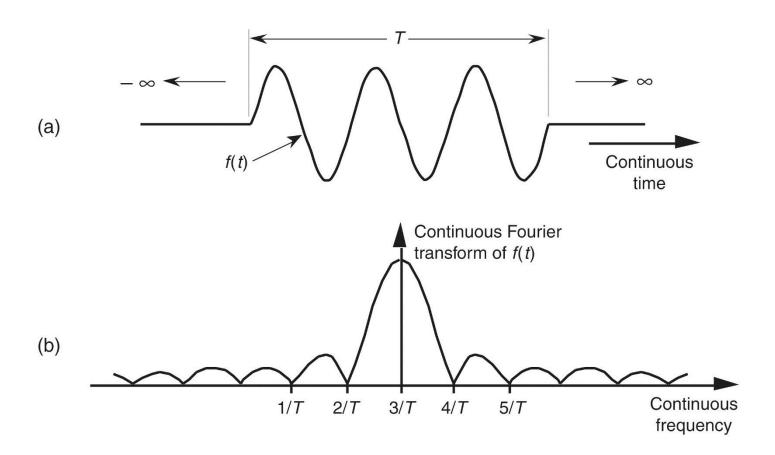


Figure 3-20 Continuous Fourier transform: (a) continuous time-domain f(t) of a truncated sinusoid of frequency 3/T; (b) continuous Fourier transform of f(t).

- Fig. 3-20
 - Because CFT is taken over an infinitely wide time interval, CFT has continuous resolution
 - Suppose we want to use a 16-point DFT to approximate CFT of f(t) in Fig. 3-20(a)
 - 16 discrete samples of f(t) are shown on left side of Fig. 3-21(a)
 - Applying those time samples to a 16-point DFT results in discrete frequency-domain samples, the positive frequencies of which are represented on right side of Fig. 3-21(a)
 - DFT output comprises samples of Fig. 3-20(b)'s CFT

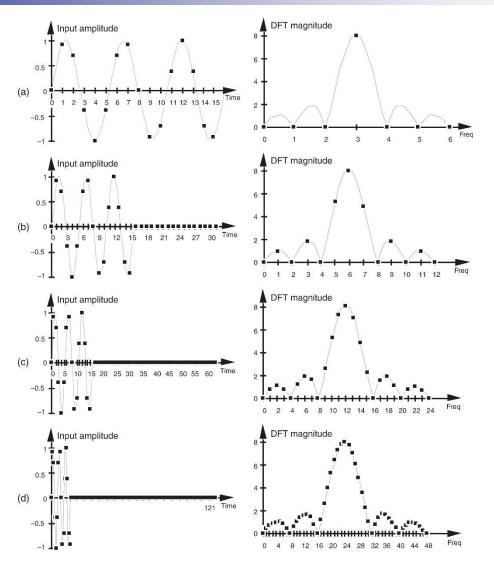


Figure 3-21 DFT frequency-domain sampling: (a) 16 input data samples and N = 16; (b) 16 input data samples, 16 padded zeros, and N = 32; (c) 16 input data samples, 48 padded zeros, and N = 64; (d) 16 input data samples, 112 padded zeros, and N = 128.

- Fig. 3-21
 - If we append 16 zeros to input sequence and take a 32-point DFT, we get output shown on right side of (b)
 - DFT frequency sampling is increased by a factor of two
 - Adding 32 more zeros and taking a 64-point DFT, we get output shown on right side of (c)
 - 64-point DFT output shows true shape of CFT
 - Adding 64 more zeros and taking a 128-point DFT, we get output shown on right side of (d)
 - DFT frequency-domain sampling characteristic is obvious now

- Fig. 3-21
 - Although zero-padded DFT output bin index of main lobe changes as N increases, zero-padded DFT output frequency associated with main lobe remains the same
 - If we perform zero padding on L nonzero input samples to get a total of N time samples for an Npoint DFT, zero-padded DFT output bin center frequencies are related to original f_s by

center frequency of the *m*th bin =
$$\frac{m f_s}{N}$$

Fig. no.	Main lobe peak located at <i>m</i> =	L =	N =	Frequency of main lobe peak relative to f_s
3-21(a)	3	16	16	3f _s / 16
3-21(b)	6	16	32	$6f_{s}/32 = 3f_{s}/16$
3-21(c)	12	16	64	$12f_{\rm s} / 64 = 3f_{\rm s} / 16$
3-21(d)	24	16	128	$24f_{\rm s}$ / $128 = 3f_{\rm s}$ / 16

- Zero padding
 - DFT magnitude expressions

$$M_{real} = A_o N / 2$$
 and $M_{complex} = A_o N$

don't apply if zero padding is used

- To perform zero padding on L nonzero samples of a sinusoid whose frequency is located at a bin center to get a total of N input samples, replace N with L above
- To perform both zero padding and windowing on input, do not apply window to entire input including appended zero-valued samples
 - Window function must be applied only to original nonzero time samples; otherwise padded zeros will zero out and distort part of window function, leading to erroneous results

- Discrete-time Fourier transform (DTFT)
 - DTFT is continuous Fourier transform of an Lpoint discrete time-domain sequence
 - On a computer we can't perform DTFT because it has an infinitely fine frequency resolution
 - But we can approximate DTFT by performing an N-point DFT on an L-point discrete time sequence where N > L
 - Done by zero-padding original time sequence and taking DFT

- Zero padding
 - Zero padding does not improve our ability to resolve, to distinguish between, two closely spaced signals in frequency domain
 - E.g., main lobes of various spectra in Fig. 3-21 do not change in width, if measured in Hz, with increased zero padding
 - To improve our true spectral resolution of two signals, we need more nonzero time samples
 - To realize F_{res} Hz spectral resolution, we must collect $1/F_{res}$ seconds, worth of nonzero time samples for our DFT processing

- Two types of processing gain associated with DFTs
 - 1) DFT's processing gain
 - Using DFT to detect signal energy embedded in noise
 - DFT can pull signals out of background noise
 - This is due to inherent correlation gain that takes place in any N-point DFT
 - 2) integration gain
 - Possible when multiple DFT outputs are averaged

- Processing gain of a single DFT
 - A DFT output bin can be treated as a bandpass filter (band center = mf_s/N) whose gain can be increased and whose bandwidth can be reduced by increasing the value of N
 - Maximum possible DFT output magnitude increases as number of points (N) increases

$$M_{real} = A_o N / 2$$
 and $M_{complex} = A_o N$

- Also, as N increases, DFT output bin main lobes become narrower
- Decreasing a bandpass filter's bandwidth is useful in energy detection because frequency resolution improves in addition to filter's ability to minimize amount of background noise that resides within its passband

13

-40

100

= 80

Bin power in dB first 32 outputs of a 64-point DFT when -5 input tone is at center (a) -10of DFT's m = 20th bin -15-20 because tone's -2510 15 original signal power is DFT bin number below average noise DFT of a spectral tone Bin power in dB power level, it is (a constant-frequency -5 SNR difficult to detect when sinewave) added to -10(b) -15N = 64random noise. -20Output power levels -25are normalized so that -30 if we quadruple the the highest bin output -35 20 80 100 120 number of input power is set to 0 dB DFT bin number samples (N = 256), the Bin power in dB tone power is raised SNR -10above average (c) background noise power as shown for *m* -30

Figure 3-22 Single DFT processing gain: (a) N = 64; (b) N = 256; (c) N = 1024.

300

DFT bin number

400

500

200

- Signal-to-noise ratio (SNR)
 - DFT's output signal-power level over the average output noise-power level
 - DFT's output SNR increases as N gets larger because a DFT bin's output noise standard deviation (rms) value is proportional to \sqrt{N} , and DFT's output magnitude for the bin containing signal tone is proportional to N
 - For real inputs, if N > N', an N-point DFT's output SNR_N increases over N'-point DFT SNR_N by:

$$SNR_N = SNR_{N'} + 10\log_{10}(N/N')$$

If we increase a DFT's size from N' to N = 2N', DFT's output SNR increases by 3 dB

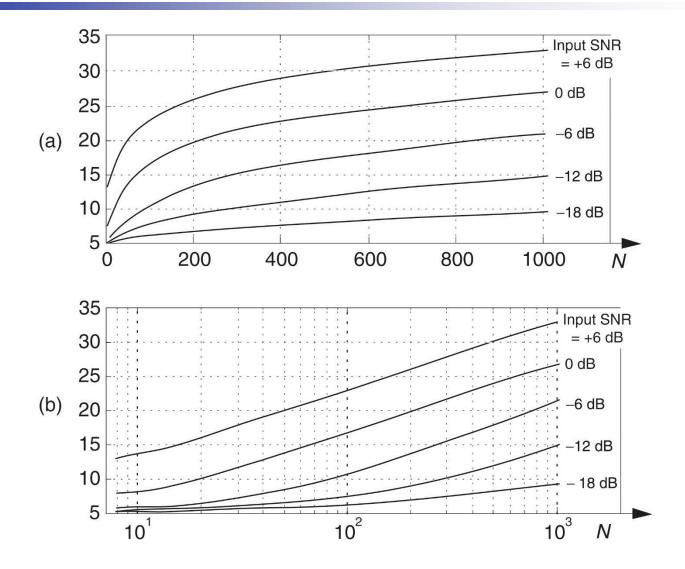


Figure 3-23 DFT processing gain versus number of DFT points N for various input signal-to-noise ratios: (a) linear N axis; (b) logarithmic N axis.

- Integration gain due to averaging multiple DFTs
 - Theoretically, we could get very large DFT processing gains by increasing DFT size
 - Problem is that the number of necessary DFT multiplications increases proportionally to N²
 - Larger DFTs become very computationally intensive
 - Because addition is easier and faster to perform than multiplication, we can average outputs of multiple DFTs to obtain further processing gain and signal detection sensitivity

- DFT of a rectangular function
 - One of the most prevalent and important computations encountered in DSP
 - Seen in sampling theory, window functions, discussions of convolution, spectral analysis, and in design of digital filters

DFT_{rect. function} =
$$\frac{\sin(x)}{\sin(x/N)}$$
, or $\frac{\sin(x)}{x}$, or $\frac{\sin(Nx/2)}{\sin(x/2)}$

- DFT of a general rectangular function
 - A general rectangular function x(n) is defined as
 N samples containing K unity-valued samples

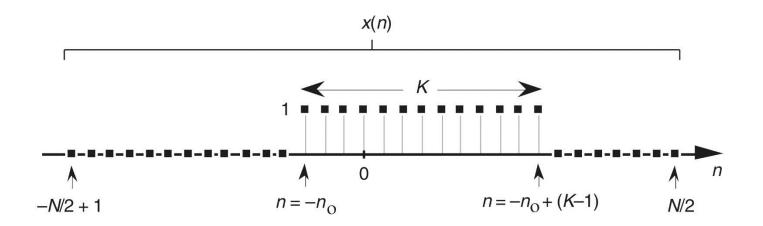


Figure 3-24 Rectangular function of width K samples defined over N samples where K < N.

$$X(m) = \sum_{n=-(N/2)+1}^{N/2} x(n) e^{-j2\pi nm/N}$$

$$= \sum_{n=-n_o}^{-n_o+(K-1)} 1 \cdot e^{-j2\pi nm/N}$$

$$\xrightarrow{q=2\pi m/N}$$

$$X(q) = \sum_{n=-n_o}^{-n_o+(K-1)} e^{-jqn}$$

$$= e^{-jq(-n_o)} + e^{-jq(-n_o+1)} + e^{-jq(-n_o+2)} + \dots + e^{-jq(-n_o+(K-1))}$$

$$= e^{-jq(-n_o)} e^{-j0q} + e^{-jq(-n_o)} e^{-j1q} + e^{-jq(-n_o)} e^{-j2q} + \dots + e^{-jq(-n_o)} e^{-jq(K-1)}$$

$$= e^{jq(n_o)} \cdot [e^{-j0q} + e^{-j1q} + e^{-j2q} + \dots + e^{-jq(K-1)}]$$

$$X(q) = e^{jq(n_o)} \sum_{n=-\infty}^{K-1} e^{-jpq}$$

$$X(q) = e^{jq(n_o)} \sum_{p=0}^{K-1} e^{-jpq}$$

$$geometric series$$

$$\sum_{p=0}^{K-1} e^{-jpq} = \frac{1 - e^{-jqK}}{1 - e^{-jq}}$$

$$= \frac{e^{-jqK/2} (e^{jqK/2} - e^{-jqK/2})}{e^{-jq/2} (e^{jq/2} - e^{-jq/2})}$$

$$= e^{-jq(K-1)/2} \cdot \frac{(e^{jqK/2} - e^{-jqK/2})}{(e^{jq/2} - e^{-jq/2})}$$
Euler's equation
$$\frac{\sin(\phi) = (e^{j\phi} - e^{-j\phi})/2j}{2j \sin(qK/2)} \Rightarrow e^{-jq(K-1)/2} \cdot \frac{2j \sin(qK/2)}{2j \sin(q/2)}$$

$$\sum_{p=0}^{K-1} e^{-jpq} = e^{-jq(K-1)/2} \cdot \frac{\sin(qK/2)}{\sin(q/2)}$$

$$X(q) = e^{jq(n_o)} \sum_{p=0}^{K-1} e^{-jpq}$$

$$\xrightarrow{\sum_{p=0}^{K-1} e^{-jpq} = e^{-jq(K-1)/2}} \cdot \frac{\sin(qK/2)}{\sin(q/2)}$$

$$= e^{jq(n_o)} \cdot e^{-jq(K-1)/2} \cdot \frac{\sin(qK/2)}{\sin(q/2)}$$

$$= e^{jq(n_o - (K-1)/2)} \cdot \frac{\sin(qK/2)}{\sin(q/2)}$$

$$\xrightarrow{q=2\pi n/N} X(m) = e^{j(2\pi n/N)(n_o - (K-1)/2)} \cdot \frac{\sin(2\pi nK/2N)}{\sin(2\pi n/2N)}$$

$$\xrightarrow{\text{General form of the Dirichlet kemel}} X(m) = e^{j(2\pi n/N)(n_o - (K-1)/2)} \cdot \frac{\sin(\pi nK/N)}{\sin(\pi n/N)}$$

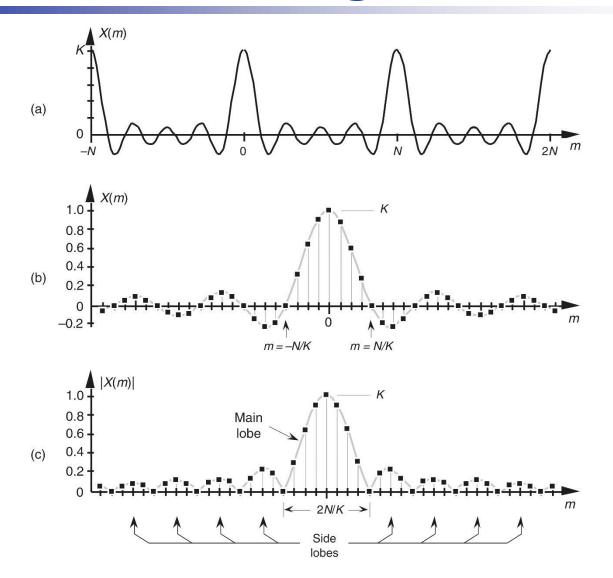


Figure 3-25 The Dirichlet kernel of X(m): (a) periodic continuous curve on which the X(m) samples lie; (b) X(m) amplitudes about the m = 0 sample; (c) |X(m)| magnitudes about the m = 0 sample.

- Dirichlet kernel (DFT of rectangular function)
 - Has a main lobe, centered about m = 0 point
 - Peak amplitude of main lobe is K
 - X(0) = sum of K unity-valued samples = K
 - Main lobe's width = 2N/K

$$X(m) = e^{j(2\pi m/N)(n_o - (K-1)/2)} \cdot \frac{\sin(\pi m K/N)}{\sin(\pi m/N)}$$

$$m_{\text{first zero crossing}} = \frac{\pi N}{\pi K} = \frac{N}{K}$$

- Thus main lobe width is inversely proportional to K
- A fundamental characteristic of Fourier transforms: the narrower the function in one domain, the wider its transform will be in the other domain

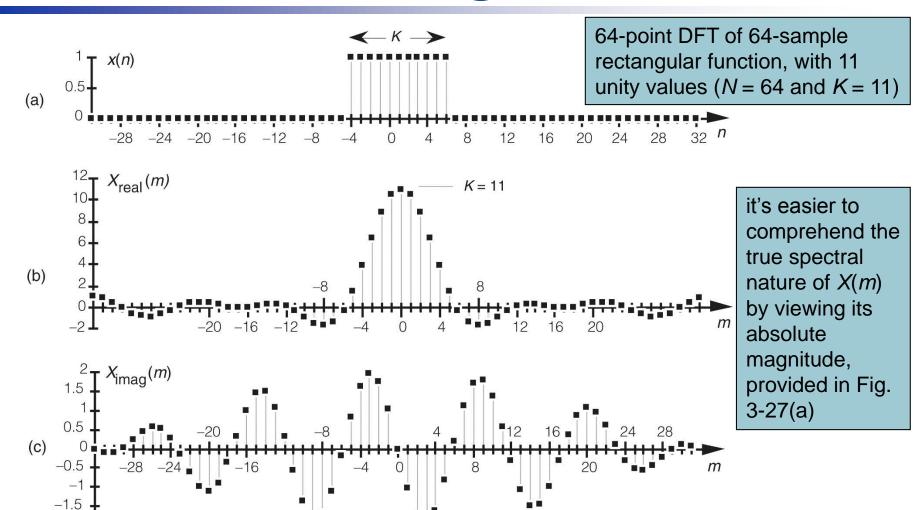


Figure 3-26 DFT of a rectangular function: (a) original function x(n); (b) real part of the DFT of x(n), $X_{\text{real}}(m)$; (c) imaginary part of the DFT of x(n), $X_{\text{imag}}(m)$.

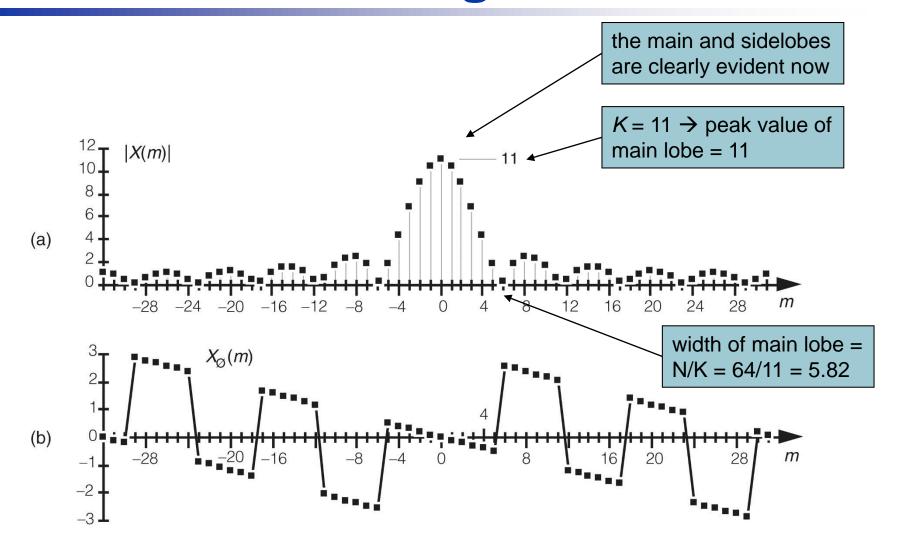
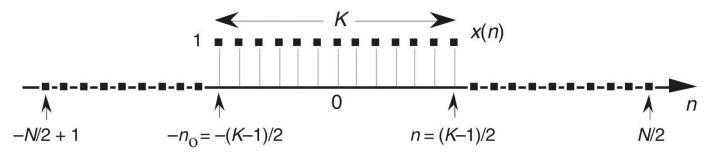


Figure 3-27 DFT of a generalized rectangular function: (a) magnitude |X(m)|; (b) phase angle in radians.

DFT of a symmetrical rectangular function



Rectangular x(n) with K samples centered about n = 0.

Dirichlet kernel

$$X(m) = e^{j(2\pi m/N)(n_o - (K-1)/2)} \cdot \frac{\sin(\pi mK/N)}{\sin(\pi m/N)}$$

$$\xrightarrow{n_o = (K-1)/2} X(m) = e^{j(2\pi m/N)((K-1)/2 - (K-1)/2)} \cdot \frac{\sin(\pi mK/N)}{\sin(\pi m/N)}$$

$$= e^{j(2\pi m/N)(0)} \cdot \frac{\sin(\pi mK/N)}{\sin(\pi m/N)}$$
Symmetrical form of the Dirichlet kernel
$$X(m) = \frac{\sin(\pi mK/N)}{\sin(\pi m/N)}$$

DFT of a symmetrical rectangular function

$$X(m) = \frac{\sin(\pi m K / N)}{\sin(\pi m / N)}$$

- This DFT is itself a real function
 - So it contains no imaginary part or phase term
 - If x(n) is real and even, x(n) = x(-n), then $X_{real}(m)$ is nonzero and $X_{imag}(m)$ is always zero

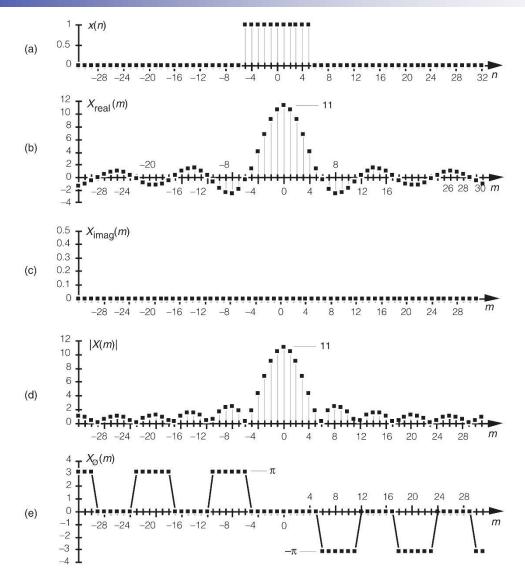


Figure 3-29 DFT of a rectangular function centered about n = 0: (a) original x(n); (b) $X_{\text{real}}(m)$; (c) $X_{\text{imag}}(m)$; (d) magnitude of X(m); (e) phase angle of X(m) in radians.

- Fig. 3-29 (64-point DFT)
 - $X_{\text{real}}(m)$ is nonzero and $X_{\text{imag}}(m)$ is zero
 - Identical magnitudes in Figs. 3-27(a) and 3-29(d)
 - Shifting K unity-valued samples to center merely affects phase angle of X(m), not its magnitude (shifting theorem of DFT)
 - Even though $X_{imag}(m)$ is zero in (c), phase angle of X(m) is not always zero
 - X(m)'s phase angles in (e) are either $+\pi$, zero, or $-\pi$
 - $e^{j\pi} = e^{j(-\pi)} = -1$ we could easily reconstruct $X_{real}(m)$ from |X(m)| and phase angle $X_{\varnothing}(m)$ if we must
 - $X_{\text{real}}(m)$ is equal to |X(m)| with the signs of |X(m)|'s alternate sidelobes reversed

another example of how DFT of a rectangular function is a sampled version of Dirichlet kernel

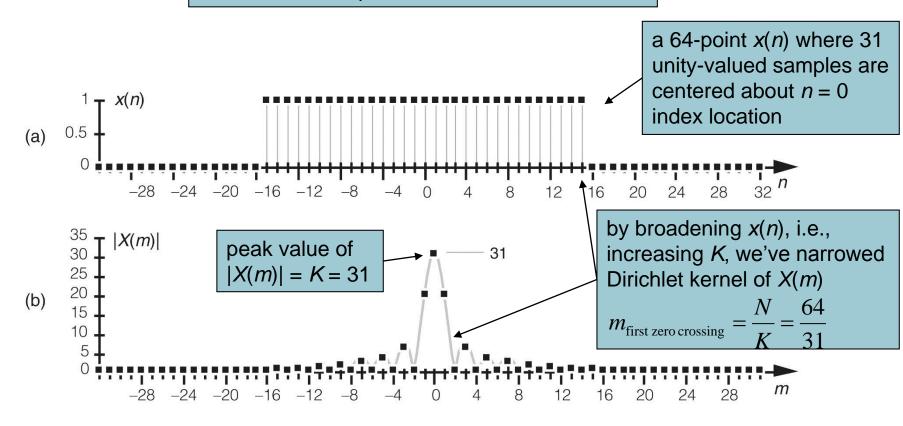


Figure 3-30 DFT of a symmetrical rectangular function with 31 unity values: (a) original x(n); (b) magnitude of X(m).

DFT of an all-ones rectangular function

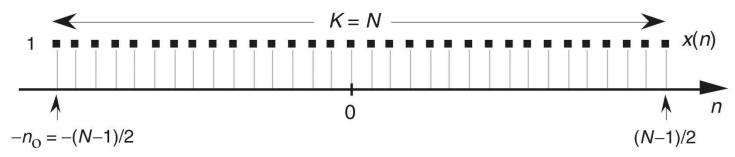


Figure 3-31 Rectangular function with N unity-valued samples.

 $\xrightarrow{\text{Dirichlet kernel (Type 1)}} X(m) = \frac{\sin(\pi m)}{\sin(\pi m/N)}$

$$X(m) = e^{j(2\pi m/N)(n_o - (K-1)/2)} \cdot \frac{\sin(\pi m K/N)}{\sin(\pi m/N)}$$

$$\xrightarrow{K=N \text{ and } \atop n_o = (N-1)/2} X(m) = e^{j(2\pi m/N)((N-1)/2 - (N-1)/2)} \cdot \frac{\sin(\pi m N/N)}{\sin(\pi m/N)}$$

$$= e^{j(2\pi m/N)(0)} \cdot \frac{\sin(\pi m)}{\sin(\pi m/N)}$$
All-onesform of the

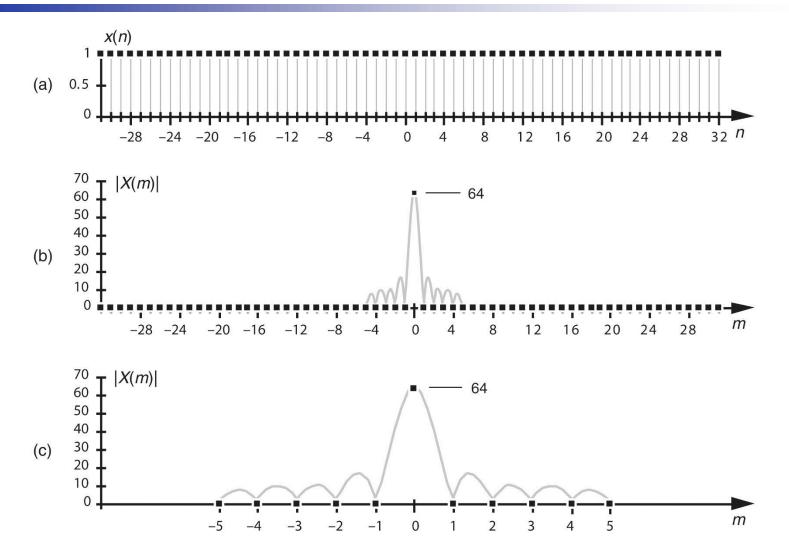


Figure 3-32 All-ones function: (a) rectangular function with N=64 unity-valued samples; (b) DFT magnitude of the all-ones time function; (c) close-up view of the DFT magnitude of an all-ones time function.

- Fig. 3-32
 - Dirichlet kernel of X(m) in (b) is as narrow as it can get
 - Main lobe's first positive zero crossing occurs at m = 64/64 = 1 sample in (b)
 - Peak value of |X(m)| = N = 64
 - x(n) is all ones $\rightarrow |X(m)|$ is zero for all $m \neq 0$
 - The sinc function

All-onesform of the Dirichlet kernel (Type 1)
$$\rightarrow X(m) = \frac{\sin(\pi m)}{\sin(\pi m/N)}$$

- Defines overall DFT frequency response to an input sinusoidal sequence
- Is also amplitude response of a single DFT bin

DFT of an all-ones rectangular function

All-ones form of the Dirichlet kernel (Type1)
$$\rightarrow X(m) = \frac{\sin(\pi m)}{\sin(\pi m/N)}$$

$$\alpha \text{ is small} \rightarrow \sin(\alpha) \approx \alpha$$
All-ones form of the Dirichlet kernel (Type2) (when N is large) $\rightarrow X(m) \approx \frac{\sin(\pi m)}{\pi m/N} = N \cdot \frac{\sin(\pi m)}{\pi m}$
All-ones form of the Dirichlet kernel (Type3) (normalized) $\rightarrow X(m) \approx \frac{\sin(\pi m)}{\pi m}$

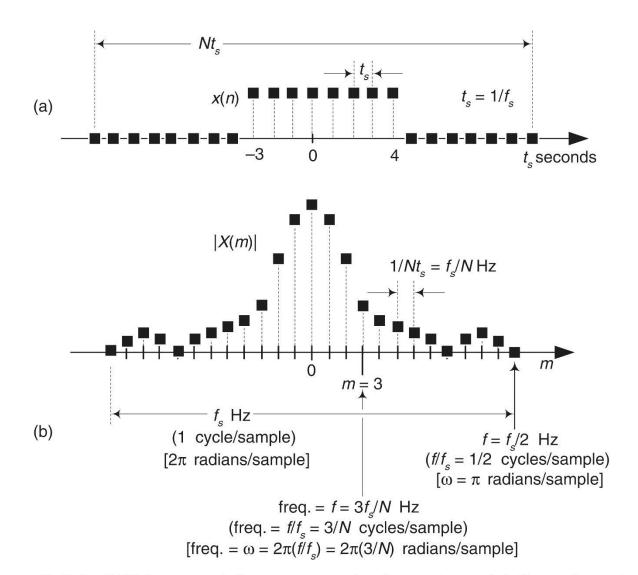


Figure 3-34 DFT time and frequency axis dimensions: (a) time-domain axis uses time index n; (b) various representations of the DFT's frequency axis.

DFT frequency axis representation	Frequency variable	Resolution of X(m)	Repetition interval of X(m)	Frequency axis range
Frequency in Hz	f	f _s /N	f _s	-f _s /2 to f _s /2
Frequency in cycles/sample	f/f _s	1/N	1	-1/2 to 1/2
Frequency in radians/sample	ω	2π/N	2π	-π to π

- Alternate form of DFT of an all-ones rectangular function
 - Using radians/sample frequency notation for DFT axis leads to another prevalent form of DFT of allones rectangular function
 - Letting normalized discrete frequency axis variable be $\omega = 2\pi m/N$, then $\pi m = N\omega/2$

All-onesform of the Dirichlet kernel(Type1)
$$X(m) = \frac{\sin(\pi m)}{\sin(\pi m/N)}$$

All-onesform of the Dirichlet kernel(Type4) $X(\omega) = \frac{\sin(N\omega/2)}{\sin(\omega/2)}$

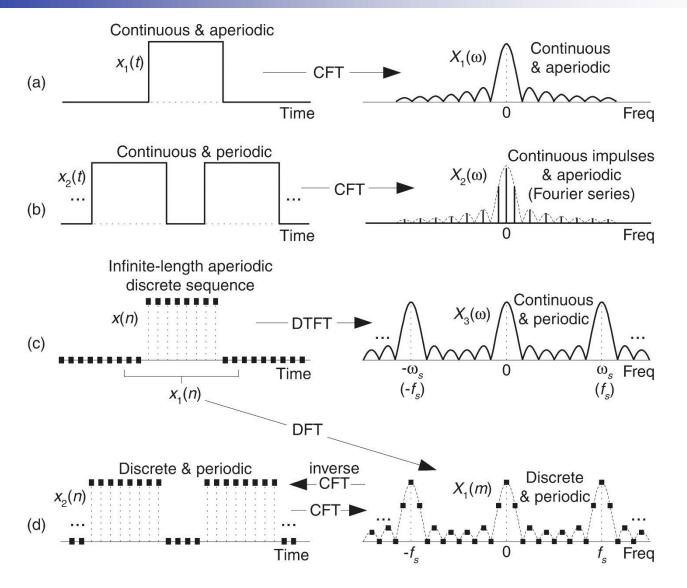


Figure 3-35 Time-domain signals and sequences, and the magnitudes of their transforms in the frequency domain.

- Fig. 3-35
 - (a) shows an infinite-length continuous-time signal containing a single finite-width pulse
 - Magnitude of its continuous Fourier transform (CFT) is continuous frequency-domain function $X_1(\omega)$
 - continuous frequency variable ω is radians per second
 - If CFT is performed on infinite-length signal of periodic pulses in (b), result is line spectra known as Fourier series $X_2(\omega)$
 - $X_2(\omega)$ Fourier series is a sampled version of continuous spectrum in (a)

- Fig. 3-35
 - (c) shows infinite-length discrete time sequence
 x(n), containing several nonzero samples
 - We can perform a CFT of x(n) describing its spectrum as a continuous frequency-domain function $X_3(\omega)$
 - This continuous spectrum is called a discrete-time Fourier transform (DTFT) defined by

$$X(\omega) = \sum_{n = -\infty}^{\infty} x(n) e^{-j\omega n}$$

• ω frequency variable is measured in radians/sample

- DTFT example
 - Time sequence: $x_o(n) = (0.75)^n$ for $n \ge 0$
 - Its DTFT is

$$X(\omega) = \sum_{n=-\infty}^{\infty} x(n) e^{-j\omega n}$$

$$X_o(\omega) = \sum_{n=0}^{\infty} 0.75^n e^{-j\omega n} = \sum_{n=0}^{\infty} (0.75 e^{-j\omega})^n$$

$$\xrightarrow{\text{geometric series}} X_o(\omega) = \frac{1}{1 - 0.75 e^{-j\omega}} = \frac{e^{j\omega}}{e^{j\omega} - 0.75}$$

• $X_o(\omega)$ is continuous and periodic with a period of 2π , whose magnitude is shown in Fig. 3-36

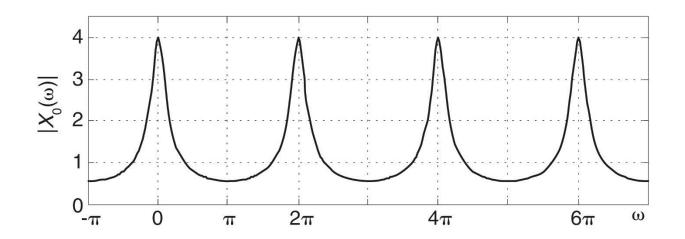


Figure 3-36 DTFT magnitude $|X_{O}(\omega)|$.

Verification of 2π periodicity of DTFT

$$X(\omega + 2\pi k) = \sum_{n = -\infty}^{\infty} x(n) e^{-j(\omega + 2\pi k)n} = \sum_{n = -\infty}^{\infty} x(n) e^{-j\omega n} e^{-j2\pi kn}$$
$$= \sum_{n = -\infty}^{\infty} x(n) e^{-j\omega n} = X(\omega)$$

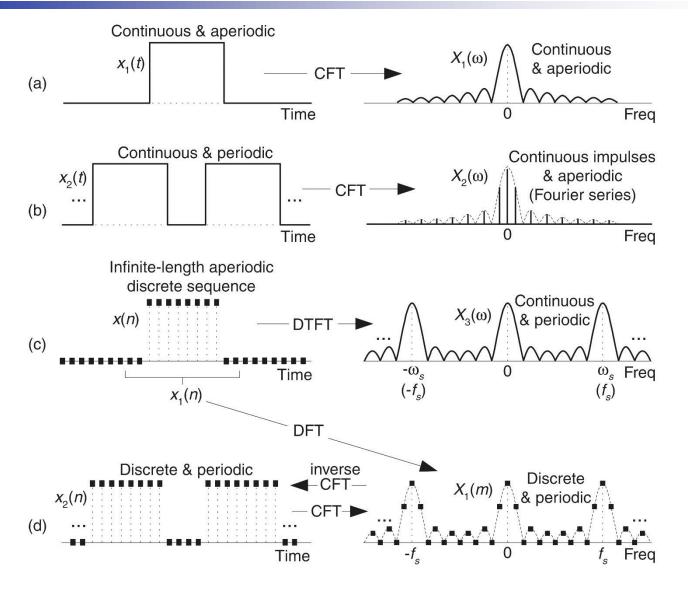


Figure 3-35 Time-domain signals and sequences, and the magnitudes of their transforms in the frequency domain.

- Fig. 3-35 (cont.)
 - Transforms indicated in Figs. (a) through (c) are pencil-and-paper mathematics of calculus
 - In a computer, using only finite-length discrete sequences, we can only approximate CFT (the DTFT) of infinite-length x(n) time sequence in (c)
 - That approximation is DFT, and it's the only Fourier transform tool available
 - Taking DFT of $x_1(n)$, where $x_1(n)$ is a finite-length portion of x(n), we obtain discrete periodic $X_1(m)$ in (d)
 - $X_1(m)$ is a sampled version of $X_3(\omega)$

$$X_1(m) = X_3(\omega)|_{\omega=2\pi m/N} = \sum_{n=0}^{N-1} x_1(n) e^{-j2\pi n m/N}$$

- Fig. 3-35
 - $X_1(m)$ is also exactly equal to CFT of periodic time sequence $x_2(n)$ in (d)
 - The DFT is equal to the continuous Fourier transform (the DTFT) of a periodic time-domain discrete sequence
 - If a function is periodic, its forward/inverse DTFT will be discrete; if a function is discrete, its forward/inverse DTFT will be periodic