# IA169 System Verification and Assurance

# **Deductive Verification**

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## Validation and Verification

• A general goal of V&V is to prove correct behaviour of algorithms.

## Reminder

- Testing is incomplete.
- Testing can detect errors but cannot prove correctness.

# Conclusion

• Need for another different way of verification.

## **Goal of formal Verification**

• The goal is to show that system behaves correctly with the same level of confidence as it is given with a mathematical proof.

### Requirements

- Formally precise semantics of system behaviour.
- Formally precise definition of system properties to be shown.

#### Methods of formal verification

- Deductive verification
- Model checking
- Abstract interpretation

# Deductive verification

### Program is correct if

- it terminates for a valid input and returns correct output.
- There is a need to show two parts partial correctness and termination.

# Partial correctness (Correctness, Soundness)

• If the computation terminates for valid input values (i.e. values for which the program is defined) the resulting values are correct.

### **Termination** (Completness, Convergence)

• If executed on valid input values, the computation always terminates.

# Serial programs (sequential)

- Input-output-closed and finite programs.
  - All input values are known prior program execution.
  - All output values are stored in output variables.
- Examples: Quick sort, Greater common divider, ...

## **General Principle**

- Program instructions are viewed as state transformers.
- The goal is to show that the mutual relation of input and output values is as expected or given by the specification.
- I.e. to verify the correctness of procedure of transformation of input values to output values.

# Expressing Program Properties

## State of Computation

• State of computation of a program is given by the value of program counter and values of all variables.

#### **Atomic predicates**

- Basic statements about individual states of the computation.
- The validity is deduced purely from the values of variables given by the state of computation.
- Examples of atomic propositions: (x == 0), (x1 >= y3).
- Beware of the scope of variables.

# Set of States

• Can be described with a Boolean combination of atomic predicates.

• Example: 
$$(x == m) \land (y > 0)$$

## Assertion

- For a given program location defines a Boolean expression that should be satisfied with the current values of program variables in the given location.
- Invariant of a program location.

#### Assertions – Proving Correctness

- Assigning properties to individual locations of Control Flow Graph.
- Robert Floyd: Assigning Meanings to Programs (1967)

# Testing

• Assertion violation serves as a test oracle.

#### Run-Time Checking

- Checking location invariants during run-time.
- Improved error localisation as the assertion violated relates to a particular program line.

## **Undetected Errors**

- If the error does not exhibit for given input data.
- If the program behaves non-deterministically (parallelism).

# Hoare Proof System

# Hoare Proof System

# Principle

- Programs = State Transformers.
- Specification = Relation between input and output state of computation.

# Hoare logic

- Designed for showing partial correctness of programs.
- Let P and Q be predicates and S be a program, then
   {P} S {Q}

is the so called *Hoare triple*.

# Intended meaning of $\{P\} S \{Q\}$

• S is a program that transforms any state satisfying *pre-condition* P to a state satisfying *post-condition* Q.

# Pre- and Post- Conditions

# Example

- $\{z = 5\} \ x = z * 2 \ \{x > 0\}$
- Valid triple, though post-condition could be more precise (stronger).
- Example of a stronger post-condition:  $\{x > 5 \land x < 20\}$ .
- Obviously,  $\{x > 5 \land x < 20\} \implies \{x > 0\}.$

# The Weakest Pre-Condition

- P is the weakest pre-condition, if and only if
- $\{P\}S\{Q\}$  is a valid triple and
- $\forall P'$  such that  $\{P'\}S\{Q\}$  is valid,  $P' \implies P$ .
- Edsger W. Dijkstra (1975)

# How to prove $\{P\}$ S $\{Q\}$

- Pick suitable conditions P' a Q'
- Decomposition into three sub-problems:

$$\{\mathsf{P}'\} \mathrel{\mathsf{S}} \{\mathsf{Q}'\} \qquad \mathsf{P} \implies \mathsf{P}' \qquad \mathsf{Q}' \implies \mathsf{Q}$$

- Use axioms and rules of Hoare system to prove  $\{P'\} S \{Q'\}$ .
- $\bullet \ P \implies P' \text{ and } Q' \implies Q \text{ are called proof obligations.}$
- Proof obligations are proven in the standard way.

#### Axiom

Assignment axiom: {φ[x replaced with k]} x := k {φ}

## Meaning

Triple {P}x := y{Q} is an axiom in Hoare system, if it holds that P is equal to Q in which all occurrences of x has been replaced with y.

## Examples

# Hoare Logic – Example 1

# Example

- Prove that the following program returns value greater than zero if executed for value of 5.
- Program: *out* := *in* \* 2

# Proof

- 1) We built a Hoare triple:  $\{in = 5\} out := in * 2 \{out > 0\}$
- 2) We deduce/guess a suitable pre-condition:  $\{ in*2>0 \}$
- 3) We prove Hoare triple:  $\{in*2>0\} out := in*2 \{out > 0\}$  (axiom)

4) We prove auxiliary statement:  $(in = 5) \implies (in * 2 > 0)$ 

# Rule

• Sequential composition:  $\frac{\{\phi\}S_1\{\chi\}\land\{\chi\}S_2\{\psi\}}{\{\phi\}S_1;S_2\{\psi\}}$ 

# Meaning

• If  $S_1$  transforms a state satisfying  $\phi$  to a state satisfying  $\chi$ and  $S_2$  transforms a state satisfying  $\chi$  to a state satisfying  $\psi$ then the sequence  $S_1$ ;  $S_2$  transforms a state satisfying  $\phi$  to a state satisfying  $\psi$ .

# In the proof

Should {φ}S<sub>1</sub>; S<sub>2</sub>{ψ} be used in the proof, an intermediate condition χ has to be found, and {φ}S<sub>1</sub>{χ} and {χ}S<sub>2</sub>{ψ} have to be proven.

Axiom for skip:  $\{\phi\}$  skip  $\{\phi\}$ 

Axiom for :=:

Composition rule:

Conditional rule:

While rule:

Consequence rule:

 $\{\phi[x:=k]\}x{:=}k\{\phi\}$ 

 $\frac{\{\phi\}S_1\{\chi\}\land\{\chi\}S_2\{\psi\}}{\{\phi\}S_1;S_2\{\psi\}}$ 

 $\frac{\{\phi \land B\}S_1\{\psi\}\land\{\phi\land \neg B\}S_2\{\psi\}}{\{\phi\} \text{if } B \text{ then } S_1 \text{ else } S_2 \text{ fi}\{\psi\}}$ 

 $\frac{\{\phi \land B\}S\{\phi\}}{\{\phi\}\text{while } B \text{ do } S \text{ od } \{\phi \land \neg B\}}$ 

$$\frac{\phi \Longrightarrow \phi', \{\phi'\} S\{\psi'\}, \psi' \Longrightarrow \psi}{\{\phi\} S\{\psi\}}$$

• 
$$r = 1;$$
  
while  $(n \neq 0)$ {  
 $r = r * n;$   
 $n = n - 1;$   
}

```
• { n \ge 0 \land t=n } {P}

r = 1;

while (n \ne 0) {

r = r * n;

n = n - 1;

} {r=t! } {Q}
```

- Reformulation in terms of Hoare logic.
- Note the use of auxiliary variable *t*.

• { 
$$n \ge 0 \land t=n$$
 } {P}  
r = 1;  
{  $n \ge 0 \land t=n \land r = 1$  } {I\_1}  
while  $(n \ne 0)$  {  
r = r \* n;  
n = n - 1;  
} { r=t! } {Q}

• {n 
$$\ge 0 \land t=n \land 1=1$$
} r=1 { n  $\ge 0 \land t=n \land r=1$  }  
• (n  $\ge 0 \land t=n$ )  $\implies$  (n  $\ge 0 \land t=n \land 1=1$ )

• { 
$$n \ge 0 \land t=n$$
 } {P}  
r = 1;  
{  $n \ge 0 \land t=n \land r = 1$  } {I<sub>1</sub>}  
while  $(n \ne 0)$  {  $r=t!/n! \land t \ge n \ge 0$  } { I<sub>2</sub>}  
r = r \* n;  
n = n - 1;  
} {r=t! } {Q}

- $\bullet$  Invariant of a cycle:  $\{I_2\} \equiv \{ \ r{=}t!/n! \ \land \ t \geq n \geq 0 \ \}$
- $\bullet \ \mathsf{I}_1 \implies \mathsf{I}_2 \qquad (\ \mathsf{I}_2 \land \neg(\mathsf{n}{\neq} \mathsf{0}) \ ) \implies \mathsf{Q}$

• { 
$$n \ge 0 \land t=n$$
 } {P}  
r = 1;  
{  $n \ge 0 \land t=n \land r = 1$  } {I\_1}  
while  $(n \ne 0)$  {  $r=t!/n! \land t \ge n \ge 0$  } { {I\_2}  
r = r \* n;  
{  $r=t!/(n-1)! \land t \ge n > 0$  } {I\_3}  
n = n - 1;  
}  
{  $r=t!$  } {Q}

• { 
$$r^*n = t!/(n-1)! \land t \ge n > 0$$
 }  $r=r^*n \{I_3\}$   
•  $I_2 \land (n \ne 0) \implies (r^*n = t!/(n-1)! \land t \ge n > 0$  )

• { 
$$n \ge 0 \land t=n$$
 } {P}  
r = 1;  
{  $n \ge 0 \land t=n \land r = 1$  } {I\_1}  
while  $(n \ne 0)$  {  $r=t!/n! \land t \ge n \ge 0$  } { I\_2}  
r = r \* n;  
{  $r=t!/(n-1)! \land t \ge n > 0$  } {I\_3}  
n = n - 1;  
}  
{  $r=t!$  } {Q}

• { 
$$r = t!/(n-1)! \land t \ge (n-1) \ge 0$$
 }  $n=n-1$  { $I_2$ }  
•  $I_3 \implies (r = t!/(n-1)! \land t \ge (n-1) \ge 0$  )

# Observation

• Hoare logic allowed us to reduce the problem of proving program correctness to a problem of proving a set of mathematical statements with arithmetic operations.

### Notice about correctness's and (in)completeness

- Hoare logic is correct, i.e. if it is possible to deduce  $\{P\}S\{Q\}$  then executing program S from a state satisfying P may terminate only in a state satisfying Q.
- If a proof system is strong enough to express integral arithmetics, it is necessarily incomplete, i.e. there exists claims that cannot be proven or dis-proven using the system.
- Hoare system for proving correctness of programs is incomplete due to the proof obligations generated with the consequence rule.

#### Troubles with Proof Construction

- Often pre- and post- condition must be suitable reformulated for the purpose of the proof.
- It is very difficult to identify loop invariants.

#### Partial Correctness in Practice

- Often reduced to formulation of all the loop invariants, and demonstration that they actually are the loop invariants.
- The proof of being an invariant is often achieved with math induction.

# Well-Founded Domain

- Partially ordered set that does not contain infinitely decreasing sequence of members.
- Examples: (N, <),  $(PowerSet(N), \subseteq)$

### **Proving Termination**

- For every loop in the program a suitable well-founded domain and an expression over the domain is chosen.
- It is shown that the value associated with a location cannot grow along any instruction that is part of the loop.
- It is shown that there exists at least one instruction in the loop that decreases the value of the expression.

# Automating Deductive Verification

# Pre-processing

- Transformation of program to a suitable intermediate language.
- Examples of IL: Boogie (Microsoft Research), Why3 (INRIA)

## Structural Analysis and Construction of the Proof Skeleton

- Identification of Hoare triples, loop invariants and suitable pre- and post-conditions (some of that might be given with the program to be verified).
- Generation of auxiliary proof obligations.

# Solving proof obligations

- Using tools for automated proving.
- May be human-assisted.

#### **Tools for Automated Proving**

- User guides a tool to construct a proof.
- HOL, ACL2, Isabelle, PVS, Coq, ...

### Reduced to the satisfiability problem

- Employ SAT and SMT solvers.
- Z3, ...

# Proof

• A finite sequence of steps that using axioms and rules of a given proof system that transforms assumptions  $\psi$  into the conclusion  $\varphi$ .

# Observation

- For systems with finitely many axioms and rules, proofs may be systematically generated. Hence, for all provable claims the proof can be found in finite time.
- All reasonable proving systems has infinitely many axioms. Consider, e.g. an axiom x = x. This is virtually a shortcut (template) for axioms 1 = 1, 2 = 2, 3 = 3, etc.
- Semi-decidable with dove-tailing approach.

#### Searching for a Proof of Valid Statement

- The number of possible finite sequences of steps of rules and axiom applications is too many (infinitely many).
- In general there is no algorithm to find a proof in a given proof system even for a valid statement.
- Without some clever strategy, it cannot be expected that a tool for automated proof generation will succeed in a reasonable short time.
- The strategy is typically given by an experienced user of the automated proving tool. The user typically has to have appropriate mathematical feeling and education.
- At the end, the tool is used as a mechanical checker for a human constructed proof.

## Theorem Provery

- The goal is find the proof within a given proof system.
- the proof is searched for in two modes:
  - Algorithmic mode Application of rules and axioms
    - Guided by the user of the tool.
    - Application of the general proving techniques, such as deduction, resolution, unification, ....
  - Search mode Looking for new valid statements
    - Employs brute-force approach and various heuristics.

### **Existing Tools**

• The description of system (axioms, rules) as well as the claim to be proven is given in the language of the tool.

## **Possible Outputs**

- a) Proof has been found and checked.
- b) Proof has not been found.
  - The statement is valid, can be proven, but the proof has not yet been found.
  - The statement is valid, but it cannot be proven in the system.
  - The statement is invalid.

### Observation

 In the case that no proof has been found, there is no indication of why it is so.

#### http://rise4fun.com/dafny

# Practicals and Homework - 04

# Practicals

- Dafny (rise4fun.com)
- http://www.doc.ic.ac.uk/~scd/Dafny\_Material/ Exercises\_%20Arithm\_Terms\_Loops.docx

# Homework

• Prove correctness of the following program using Dafny

```
 \begin{array}{l} \mbox{method Count(N: nat, M: int, P: int) returns (R: int) } \\ \mbox{var } a := M; \\ \mbox{var } i := P; \\ \mbox{var } i := 1; \\ \mbox{while } (i <= N) \\ \mbox{a } := a + 3; \\ \mbox{b } i := a + 3; \\ \mbox{b } i := a + 1; \\ \mbox{b } i := i + 1; \\ \mbox{b } R := b; \\ \end{array}
```

• Read and repeat: Jaco van de Pol: Automated verification of Nested DFS