Operating Systems

Petr Ročkai

Organisation

- lectures only, no seminar
- written exam at the end
 - multiple choice
 - free-form questions
- 1 online test mid-term, 1 before exam
 - mainly training for the exam proper

Mid-Term and End-Term Tests

- 24 hours to complete, 2 attempts possible
- 10 questions, picked from review questions
 - mid-term first 24, end-term second 24
- you need to pass either mid-term or end-term
- 7 out of 10 required for mid-term, 8 of 10 for end-term
- preliminary mid-term date: 18th of April, 4pm

Study Materials

- this course is undergoing a major update
- lecture slides will be in the IS
 - they will be added as we go
- you can also use slides from previous years
 - they are already in study materials
 - but: not everything is covered in those

Books

- there are a few good OS books
- you are encouraged to get and read them
- A. Tanenbaum: Modern Operating Systems
- A. Silberschatz et al.: Operating System Concepts
- L. Skočovský: Principy a problémy OS UNIX
- · W. Stallings: Operating Systems, Internals and Design
- many others, feel free to explore

Topics

- 1. Anatomy of an OS
- 2. System Libraries and APIs
- 3. The Kernel
- 4. File Systems
- 5. Basic Resources and Multiplexing
- 6. Concurrency and Locking

Topics (cont'd)

- 7. Device Drivers
- 8. Network Stack
- 9. Command Interpreters & User Interfaces
- 10. Users and Permissions
- 11. Virtualisation & Containers
- 12. Special-Purpose Operating Systems

Related Courses

- PB150/PB151 Computer Systems
- PB153 Operating Systems and their Interfaces
- PA150 Advanced OS Concepts
- PV062 File Structures
- PB071 Principles of Low-level programming
- PB173 Domain-specific Development in C/C++

Organisation of the Semester

- generally, one lecture = one topic
- 30th of March is a state holiday
- a 50-minute review in the last lecture
- online mid-term first week in April

Part 1: Semester Overview

2. System Libraries and APIs

- POSIX: Portable Operating System Interface
- UNIX: (almost) everything is a file
- the least common denominator of programs: C
- user view: objects, archives, shared libraries
- compiler, linker

3. The Kernel

- privileged CPU mode
- the boot process
- boundary enforcement
- kernel designs: micro, mono, exo, ...
- system calls

4. File Systems

- · why and how
- abstraction over shared block storage
- directory hierarchy
- everything is a file revisited
- i-nodes, directories, hard & soft links

5. Basic Resources and Multiplexing

- virtual memory, processes
- sharing CPUs & scheduling
- processes vs threads
- interrupts, clocks

6. Concurrency and Locking

- inter-process communication
- · accessing shared resources
- mutual exclusion
- deadlocks and deadlock prevention

7. Device Drivers

- user vs kernel drivers
- interrupts &c.
- GPU
- PCI &c.
- block storage
- network devices, wifi
- USB
- bluetooth

8. Network Stack

- TCP/IP
- name resolution
- socket APIs
- firewalls and packet filters
- network file systems

9. Command Interpreters & User Interfaces

- interactive systems
- history: consoles and terminals
- text-based terminals, RS-232
- bash and other Bourne-style shells, POSIX
- graphical: X11, Wayland, OS X, Windows, Android, iOS

Operating Systems 18/746 Semester Overview

10. Users and Permissions

- multi-user systems
- isolation, ownership
- file system permissions
- capabilities

11. Virtualisation & Containers

- resource multiplexing redux
- isolation redux
- multiple kernels on a single system
- type 1 and type 2 hypervisors
- virtio

12. Special-Purpose Operating Systems

- · general-purpose vs special-purpose
- embedded systems
- real-time systems
- high-assurance systems (seL4)

Part 2: Anatomy of an OS

What is an OS?

- the software that makes the hardware tick
- and makes other software easier to write

Also

- catch-all phrase for low-level software
- an abstraction layer over the machine
- but the boundaries are not always clear

What is **not** (part of) an OS?

- firmware: (very) low level software
 - much more hardware-specific than an OS
 - often executes on auxiliary processors
- application software
 - runs on top of an operating system
 - this is what you got the computer for
 - eg. games, spreadsheets, photo editing, ...

Operating Systems: Examples

- Microsoft Windows
- Apple macOS & iOS
- Google Android
- Linux
- FreeBSD, OpenBSD
- MINIX
- many, many others

What does an OS do?

- interact with the user
- manage and multiplex hardware
- manage other software
- · organises and manages data
- provides services for other programs
- enforces security

What is an OS made of?

- · the kernel
- system libraries
- system daemons / services
- user interface
- system utilities

Basically every OS has those.

The Kernel

- lowest level of an operating system
- executes in privileged mode
- · manages all the other software
 - including other OS components
- enforces isolation and security
- provides low-level services to programs

System Libraries

- form a layer above the OS kernel
- provide higher-level services
 - use kernel services behind the scenes
 - easier to use than the kernel interface
- typical example: libc
 - provides C functions like printf
 - also known as msvcrt on Windows

System Daemons

- programs that run in the background
- they either directly provide services
 - but daemons are different from libraries
 - we will learn more in later lectures
- or perform maintenance or periodic tasks
- or perform tasks requested by the kernel

User Interface

- mediates user-computer interaction
- the main shell is typically part of the OS
 - command line on UNIX or DOS
 - graphical interfaces with a desktop and windows
 - but also buttons on your microwave oven
- also building blocks for application UI
 - buttons, tabs, text rendering, OpenGL...
 - provided by system libraries and/or daemons

System Utilities

- · small programs required for OS-related tasks
- e.g. system configuration
 - things like the registry editor on Windows
 - or simple text editors
- filesystem maintenance, daemon management, ...
 - programs like ls/dir or newfs or fdisk
- · also bigger programs, like file managers

Optional Components

- bundled application software
 - web browser, media player, ...
- (3rd-party) software management
- a programming environment
 - eg. a C compiler & linker
 - C header files &c.
- source code

Programming Interface

- kernel provides system calls
 - ABI: Application Binary Interface
 - defined in terms of machine instructions
- system libraries provide APIs
 - Application Programming Interface
 - symbolic / high-level interfaces
 - typically defined in terms of C functions
 - system calls also available as an API

Message Passing

- APIs do not always come as C functions
- message-passing interfaces are possible
 - based on inter-process communication
 - possible even across networks
- form of API often provided by system daemons
 - may be also wrapped by C APIs

General-Purpose Operating Systems

- suitable for use in most situations
- flexible but complex and big
- run on both servers and clients
- cut down versions run on smartphones
- support variety of hardware

Special-Purpose Operating Systems

- embedded devices
 - limited budget
 - small, slow, power-constrained
 - hard or impossible to update
- real-time systems
 - must react to real-world events
 - often safety-critical
 - robots, autonomous cars, space probes, ...

Size and Complexity

- operating systems are usually large and complex
- typically 100K and more lines of code
- 10+ million is quite possible
- many thousand man-years of work
- special-purpose systems are much smaller

Portability

- some OS tasks require close HW cooperation
 - virtual memory and CPU setup
 - platform-specific device drivers
- · but many do not
 - scheduling algorithms
 - memory allocation
 - all sorts of management
- porting: changing a program to run in a new environment
 - for an OS, typically new hardware

Hardware Platform

- CPU instruction set (ISA)
- busses, IO controllers
 - PCI, USB, Ethernet, ...
- firmware, power management

Examples

- x86 (ISA) PC (platform)
- ARM Snapdragon, i.MX 6, ...
- m68k Amiga, Atari, ...

Platform & Architecture Portability

- an OS typically supports many platforms
 - Android on many different ARM SoC's
- quite often also different CPU ISAs
 - long tradition in UNIX-style systems
 - NetBSD runs on 15 different ISAs
 - many of them comprise 6+ different platforms
- special-purpose systems are usually less portable

Code Re-Use

- it makes a lot of sense to re-use code
- majority of OS code is HW-independent
- this was not always the case
 - pioneered by UNIX, which was written in C
 - typical OS of the time was in machine language
 - porting was basically "writing again"

Application Portability

- applications care more about the OS than about HW
 - apps are written in high-level languages
 - and use system libraries extensively
- it is enough to port the OS to new/different HW
 - most applications can be simply recompiled
- still a major hurdle (cf. Itanium)

Application Portability (2)

- same application can often run on many OSes
- · especially within the POSIX family
- but same app can run on Windows, macOS, UNIX, ...
 - Java, Qt (C++)
 - web applications (HTML, JavaScript)
- many systems provide the same set of services
 - differences are mostly in programming interfaces
 - high-level libraries and languages can hide those

Abstraction

- instruction sets abstract over CPU details
- compilers abstract over instruction sets
- operating systems abstract over hardware
- portable runtimes abstract over operating systems
- applications sit on top of the abstractions

Abstraction Costs

- · more complexity
- · less efficiency
- leaky abstractions

Abstraction Benefits

- easier to write and port software
- fewer constraints on HW evolution

Abstraction Trade-Offs

- powerful hardware allows more abstraction
- embedded or real-time systems not so much
 - the OS is smaller & less portable
 - same for applications
 - more efficient use of resources

Kernel Revisited

- bugs in the kernel are very bad
 - system crashes, data loss
 - critical security problems
- bigger kernel means more bugs
- third-party drivers inside the kernel?

Monolithic Kernels

- lot of code in the kernel
- less abstraction, less isolation
- faster and more efficient

Microkernels

- move as much as possible out of kernel
- more abstraction, more isolation
- slower and less efficient

Paradox?

- real-time & embedded systems often use microkernels
- isolation is good for reliability
- efficiency also depends on the workload
 - throughput vs latency
- real-time does not necessarily mean fast

Review Questions

- 1. What are the roles of an operating system?
- 2. What are the basic components of an OS?
- 3. What is an operating system kernel?
- 4. What is an Application Programming Interface?

Part 3: System Libraries and APIs

Programming Interfaces

- kernel system call interface
- system libraries / APIs
- inter-process protocols
- command-line utilities (scripting)

Lecture Overview

- 1. The C Programming Language
- 2. System Libraries
 - what is a library?
 - header files & libraries
- 3. Compiler & Linker
 - object files, executables
- 4. File-based APIs

Sidenote: UNIX and POSIX

- · we will mostly use those terms interchangeably
- it is a family of operating systems
 - started in late 60s / early 70s
- POSIX is a specification
 - a document describing what the OS should provide
 - including programming interfaces

We will assume POSIX unless noted otherwise

Part 3.1: The C Programming Language

Programming Languages

- · there are many different languages
 - C, C++, Java, C#, ...
 - Python, Perl, Ruby, ...
 - ML, Haskell, Agda, ...
- but C has a special place in most OSes

C: The Least Common Denominator

- except for assembly, C is the "bare minimum"
- you can almost think of C as portable assembly
- it is very easy to call C functions
- and to use C data structures

You can use C libraries in almost every language

The Language of Operating Systems

- many (most) kernels are written in C
- this usually extends to system libraries
- and sometimes to almost the entire OS
- non-C operating systems provide C APIs

Part 3.2: System Libraries

(System) Libraries

- mainly C functions and data types
- interfaces defined in header files
- definitions provided in libraries
 - static libraries (archives): libc.a
 - shared (dynamic) libraries: libc.so
- on Windows: msvcrt.lib and msvcrt.dll
- there are (many) more besides libc / msvcrt

Declaration: what but not how

```
int sum( int a, int b );
```

Definition: how is the operation done?

```
int sum( int a, int b )
{
    return a + b;
}
```

Library Files

- /usr/lib on most Unices
 - may be mixed with application libraries
 - especially on Linux-derived systems
 - also /usr/local/lib for user/app libraries
- on Windows: C:\Windows\System32
 - user libraries often bundled with programs

Static Libraries

- stored in libfile.a, or file.lib (Windows)
- · only needed for compiling (linking) programs
- the code is copied into the executable
- the resulting executable is also called static
 - and is easier to work with for the OS
 - but also more wasteful

Shared (Dynamic) Libraries

- required for running programs
- linking is done at execution time
- less code duplication
- can be upgraded separately
- but: dependency problems

Header Files

- on UNIX: /usr/include
- contains prototypes of C functions
- and definitions of C data structures
- required to compile C and C++ programs

Header Example 1 (from unistd.h)

```
int execv(char *, char **);
pid_t fork(void);
int pipe(int *);
ssize_t read(int, void *, size_t);
```

(and many more prototypes)

```
struct timeval
    time t tv sec;
           tv usec;
};
int gettimeofday(timeval *, timezone *);
int settimeofday(timeval *, timezone *);
```

The POSIX C Library

- libc the C runtime library
- contains ISO C functions
 - printf, fopen, fread
- and a number of POSIX functions
 - open, read, gethostbyname, ...
 - C wrappers for system calls

System Calls: Numbers

- system calls are performed at machine level
- which syscall to perform is decided by a number
 - e.g. SYS_write is 4 on OpenBSD
 - numbers defined by sys/syscall.h
 - different for each OS

System Calls: the syscall function

- there is a C function called syscall
 - prototype: int syscall(int number, ...)
- this implements the low-level syscall sequence
- it takes a syscall number and syscall parameters
 - this is a bit like printf
 - first parameter decides what other parameters there are
- (more about how syscall() works next week)

System Calls: Wrappers

- using syscall() directly is inconvenient
- libc has a function for each system call

```
- SYS_write int write( int, char *, size_t )
```

- SYS open int open(char *, int)
- and so on and so forth
- those wrappers use syscall() internally

Portability

- libraries provide an abstraction layer over OS internals
- they are responsible for application portability
 - along with standardised filesystem locations
 - and user-space utilities to some degree
- higher-level languages rely on system libraries

NeXT and Objective C

- the NeXT OS was built around Objective C
- system libraries had ObjC APIs
- in API terms, ObjC is very different from C
 - also very different from C++
 - traditional OOP features (like Smalltalk)
- this has been partly inherited into macOS
 - evolving into Swift

System Libraries: UNIX

- the math library libm
 - implements math functions like sin and exp
- thread library libpthread
- terminal access: libcurses
- cryptography: libcrypto (OpenSSL)
- the C++ standard library libstdc++ or libc++

System Libraries: Windows

- msvcrt, dll the ISO C functions
- kernel32.dll basic OS APIs
- gdi32.dll Graphics Device Interface
- user32.dll standard GUI elements

Documentation

- manual pages on UNIX
 - try e.g. man 2 write on aisa.fi.muni.cz
 - section 2: system calls
 - section 3: library functions (man 3 printf)
- MSDN for Windows
 - https://msdn.microsoft.com
- you can learn a lot from those sources

Part 3.3: Compiler & Linker

C Compiler

- many POSIX systems ship with a C compiler
- the compiler takes a C source file as input
 - a text file with a . c suffix
- · and produces an object file as its output
 - binary file with machine code in it
 - but cannot be directly executed

Object Files

- contain native machine (executable) code
- along with static data
 - e.g. string literals used in the program
- possibly split into a number of sections
 - text, .rodata, .data and so on
- and metadata
 - list of symbols (function names) and their addresses

Object File Formats

- a.out earliest UNIX object format
- COFF Common Object File Format
 - adds support for sections over a . out
- PE Portable Executable (MS Windows)
- Mach-O Mach Microkernel Executable (macOS)
- ELF Executable and Linkable Format (all modern Unices)

Archives (Static Libraries)

- static libraries on UNIX are called archives
- this is why they get the .a suffix
- they are like a zip file full of object files
- plus a table of symbols (function names)

Linker

- object files are incomplete
- they can refer to symbols that they do not define
 - the definitions can be in libraries
 - or in other object files
- a linker puts multiple object files together
 - to produce a single executable
 - or maybe a shared library

Symbols vs Addresses

- we use symbolic names to call functions &c.
- but the call machine instruction needs an address
- the executable will eventually live in memory
- data and instructions need to be given addresses
- what a linker does is assign those addresses

Resolving Symbols

- the linker processes one object file at a time
- it maintains a symbol table
 - mapping symbols (names) to addresses
 - dynamically updated as more objects are processed
- objects can only use symbols already in the table
- resolving symbols = finding their addresses

Executable

- finished image of a program to be executed
- usually in the same format as object files
- but already complete, with symbols resolved
 - but: may use shared libraries
 - in that case, some symbols remain unresolved

Shared Libraries

- each shared library only needs to be in memory once
- shared libraries use symbolic names (like object files)
- there is a "mini linker" in the OS to resolve those names
 - usually known as a runtime linker
 - resolving = finding the addresses
- shared libraries can use other shared libraries
 - they can form a DAG (Directed Acyclic Graph)

Addresses Revisited

- when you run a program, it is loaded into memory
- parts of the program refer to other parts of the program
 - this means they need to know where it will be loaded
 - this is a responsibility of the linker
 - shared libraries use position-independent code
 - works regardless of the base address it is loaded at
 - we won't go into detail on how this is achieved

Compiler, Linker &c.

- the C compiler is usually called cc
- the linker is known as 1d
- the archive (static library) manager is ar
- the runtime linker is often known as ld. so

Part 3.4: File-Based APIs

Everything is a File

- part of the UNIX design philosophy
- directories are files
- devices are files
- pipes are files
- network connections are (almost) files

Why is Everything a File

- re-use the comprehensive file system API
- re-use existing file-based command-line tools
- bugs are bad simplicity is good
- want to print? cat file.txt > /dev/ulpt0
 - (reality is a little more complex)

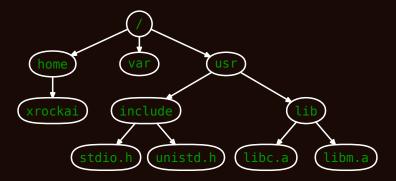
What is a Filesystem?

- a set of files and directories
- usually lives on a single block device
 - but may also be virtual
- directories and files form a tree
 - directories are internal nodes
 - files are leaf nodes

File Paths

- filesystems use paths to point at files
- a string with / as a directory delimiter
 - the delimiter is \ on Windows
- a leading / indicates the filesystem root
- e.g. /usr/include

The File Hierarchy



Operating Systems 95/746 System Libraries and APIs

The Role of Files and Filesystems

- very central in Plan9
- · central in most UNIX systems
 - cf. Linux pseudo-filesystems
 - /proc provides info about all processes
 - /sys gives info about the kernel and devices
- somewhat reduced in Windows
- quite suppressed in Android (and more on iOS)

The Filesystem API

- you open a file (using the open() syscall)
- you can read() and write() data
- you close() the file when you are done
- you can rename() and unlink() files
- you can use mkdir() to create directories

File Descriptors

- the kernel keeps a table of open files
- the file descriptor is an index into this table
- you do everything using file descriptors
- non-Unix systems have similar concepts
 - descriptors are called handles on Windows

Regular files

- these contain sequential data (bytes)
- may have inner structure but the OS does not care
- there is metadata attached to files
 - like when were they last modified
 - who can and who cannot access the file
- you read() and write() files

Directories

- a list of files and other directories
 - internal nodes of the filesystem tree
 - directories give names to files
- · can be opened just like files
 - but read() and write() is not allowed
 - files are created with open() or creat()
 - directories with mkdir()
 - directory listing with opendir() and readdir()

Mounts

- UNIX joins all file systems into a single hierarchy
- the root of one filesystem becomes a directory in another
 - this is called a mount point
- Windows uses drive letters instead (C:, D: &c.)

Devices

- block and character devices are (special) files
- block devices are accessed one block at a time
 - a typical block device would be a disk
 - includes USB mass storage, flash storage, etc
 - you can create a file system on a block device
- · character devices are more like normal files
 - terminals, tapes, serial ports, audio devices

Pipes

- pipes are a simple communication device
- one program can write() data to the pipe
- another program can read() that same data
- each end of the pipe gets a file descriptor
- a pipe can live in the filesystem (named pipe)

Sockets

- the socket API comes from early BSD Unix
- socket represents a (possible) network connection
- sockets are more complicated than normal files
 - establishing connections is hard
 - messages get lost much more often than file data
- you get a file descriptor for an open socket
- you can read() and write() to sockets

Socket Types

- sockets can be internet or unix domain
 - internet sockets connect to other computers
 - Unix sockets live in the filesystem.
- sockets can be stream or datagram
 - stream sockets are like files
 - you can write a continuous stream of data
 - datagram sockets can send individual messages

Review Questions

- 5. What is a shared (dynamic) library?
- 6. What does a linker do?
- 7. What is a symbol in an object file?
- 8. What is a file descriptor?

Part 4: The Kernel

Lecture Overview

- 1. privileged mode
- 2. booting
- 3. kernel architecture
- 4. system calls
- 5. kernel-provided services

Reminder: Software Layering

- the kernel
- system libraries
- system services / daemons
- utilities
- application software

Part 4.1: Privileged Mode

CPU Modes

- CPUs provide a privileged (supervisor) and a user mode
- this is the case with all modern general-purpose CPUs
 - not necessarily with micro-controllers
- x86 provides 4 distinct privilege levels
 - most systems only use ring 0 and ring 3
 - Xen paravirtualisation uses ring 1 for hosted kernels

Privileged Mode

- many operations are restricted in user mode
 - this is how user programs are executed
 - also most of the operating system
- software running in privileged mode can do ~anything
 - most importantly it can program the MMU
 - the kernel runs in this mode

Memory Management Unit

- · is a subsystem of the processor
- takes care of address translation
 - user software uses virtual addresses
 - the MMU translates them to physical addresses
- the mappings can be managed by the OS kernel

Paging

- · physical memory is split into frames
- virtual memory is split into pages
- pages and frames have the same size (usually 4KiB)
- frames are places, pages are the content
- page tables map between pages and frames

Swapping Pages

- RAM used to be a scarce resource
- paging allows the OS to move pages out of RAM
 - a page (content) can be written to disk
 - and the frame can be used for another page
- not as important with contemporary hardware
- useful for memory mapping files (cf. next lecture)

Look Ahead: Processes

- process is primarily defined by its address space
 - address space meaning the valid virtual addresses
- this is implemented via the MMU
- when changing processes, a different page table is loaded
 - this is called a context switch
- the page table defines what the process can see

Memory Maps

- different view of the same principles
- the OS maps physical memory into the process
- multiple processes can have the same RAM area mapped
 - this is called shared memory
- often, a piece of RAM is only mapped in a single process

Page Tables

- the MMU is programmed using translation tables
 - those tables are stored in RAM
 - they are usually called page tables
- and they are fully in the management of the kernel
- the kernel can ask the MMU to replace the page table
 - this is how processes are isolated from each other

Kernel Protection

- kernel memory is usually mapped into all processes
 - this substantially improves performance on many CPUs
 - well, until Meltdown hit us, anyway
- · kernel pages have a special 'supervisor' flag set
 - code executing in user mode cannot touch them
 - else, user code could tamper with kernel memory

Part 4.2: Booting

Starting the OS

- upon power on the system is in a default state
 - mainly because RAM is volatile
- the entire platform needs to be initialised
 - this is first and foremost the CPU
 - and the console hardware (keyboard, monitor, ...)
 - then the rest of the devices

Boot Process

- the process starts with a built-in hardware init
- when ready, the hardware hands off to the firmware
 - this was BIOS on 16 and 32 bit systems
 - replaced with EFI on current amd64 platforms
- the firmware then loads a bootloader
- the bootloader loads the kernel

Boot Process (cont'd)

- the kernel then initialises device drivers
- · and the root filesystem
- then it hands off to the init process
- at this point, the user space takes over

User-mode Initialisation

- init mounts the remaining file systems
- the init process starts up user-mode system services
- then it starts application services
- and finally the login process

After Log-In

- the login process initiates the user session
- · loads desktop modules and application software
- drops the user in a (text or graphical) shell
- now you can start using the computer.

CPU Init

- this depends on both architecture and platform
- on x86, the CPU starts in 16-bit mode
- on legacy systems, BIOS & bootloader stay in this mode
- the kernel then switches to protected mode during its boot

Bootloader

- historically limited to tens of kilobytes of code
- the bootloader locates the kernel on disk
 - it often allows the operator to choose different kernels
 - limited understanding of file systems
- then it loads the kernel image into RAM
- and hands off control to the kernel

Modern Booting on x86

- on modern system, the bootloader runs in protected mode
 - or even the long mode on 64-bit CPUs
- the firmware understands the FAT filesystem
 - it can load files from there into memory
 - this vastly simplifies the boot process

Booting ARM

- on ARM boards, there is no unified firmware interface
- U-boot is as close as one gets to unification
- the bootloader needs low-level hardware knowledge
- this makes writing bootloaders for ARM quite tedious
- current U-boot can use the EFI protocol from PCs

Part 4.3: Kernel Architecture

Architecture Types

- monolithic kernels (Linux, *BSD)
- microkernels (Mach, L4, QNX, NT, ...)
- hybrid kernels (macOS)
- type 1 hypervisors (Xen)
- exokernels, rump kernels

Microkernel

- handles memory protection
- (hardware) interrupts
- task / process scheduling
- message passing
- everything else is separate

Monolithic kernels

- all that a microkernel does
- plus device drivers
- file systems, volume management
- a network stack
- data encryption, ...

Microkernel Redux

- we need a lot more than a microkernel provides
- in a "true" microkernel OS, there are many modules
- each device driver runs in a separate process
- the same for file systems and networking
- those modules / processes are called servers

Hybrid Kernels

- based around a microkernel
- and a gutted monolithic kernel
- the monolithic kernel is a big server
 - takes care of stuff not handled by the microkernel
 - easier to implement than true microkernel OS
 - strikes middle ground on performance

Micro vs Mono

- microkernels are more robust
- monolithic kernels are more efficient
 - less context switching
- what is easier to implement is debatable
 - in the short view, monolithic wins
- hybrid kernels are a compromise

Exokernels

- smaller than a microkernel
- much fewer abstractions
 - applications only get block storage
 - networking is much reduced
- only research systems exist

Type 1 Hypervisors

- also known as bare metal or native hypervisors
- they resemble microkernel operating systems
 - or exokernels, depending on the viewpoint
- the "applications" for a hypervisor are operating systems
 - hypervisor can use coarser abstractions than an OS
 - entire storage devices instead of a filesystem

Unikernels

- kernels for running a single application
 - makes little sense on real hardware
 - but can be very useful on a hypervisor
- bundle applications as virtual machines
 - without the overhead of a general-purpose OS

Exo vs Uni

- an exokernel runs multiple applications
 - includes process-based isolation
 - but abstractions are very bare-bones
- unikernel only runs a single application
 - provides more-or-less standard services
 - e.g. standard hierarchical file system
 - socket-based network stack / API

Part 4.4: System Calls

Reminder: Kernel Protection

- kernel executes in privileged mode of the CPU
- kernel memory is protected from user code

But: Kernel Services

- user code needs to ask kernel for services
- how do we switch the CPU into privileged mode?
- cannot be done arbitrarily (security)

System Calls

- hand off execution to a kernel routine
- pass arguments into the kernel
- obtain return value from the kernel
- all of this must be done safely

Trapping into the Kernel

- there are a few possible mechanisms
- details are very architecture-specific
- in general, the kernels sets a fixed entry address
 - an instruction can change the CPU into privileged mode
 - while at the same time jumping to this address

Trap Example: x86

- there is an int instruction on those CPUs
- this is called a software interrupt
 - interrupts are normally a hardware thing
 - interrupt handlers run in privileged mode
- it is also synchronous
- the handler is set in IDT (interrupt descriptor table)

Software Interrupts

- those are available on a range of CPUs
- generally not very efficient for system calls
- extra level of indirection
 - the handler address is retrieved from memory
 - a lot of CPU state needs to be saved

Aside: SW Interrupts on PCs

- those are used even in real mode
 - legacy 16-bit mode of 80x86 CPUs
 - BIOS (firmware) routines via int 0x10 & 0x13
 - MS-DOS API via int 0x21
- and on older CPUs in 32-bit protected mode
 - Windows NT uses int 0x2e
 - Linux uses int 0x80

Trap Example: amd64 / x86_64

- sysenter and syscall instructions
 - and corresponding sysexit / sysret
- the entry point is stored in a machine state register
- there is only one entry point
 - unlike with software interrupts
- quite a bit faster than interrupts

Which System Call?

- often there are many system calls
 - there are more than 300 on 64-bit Linux
 - about 400 on 32-bit Windows NT
- but there is only a handful of interrupts
 - and only one sysenter address

Reminder: System Call Numbers

- each system call is assigned a number
- available as SYS write &c. on POSIX systems
- for the "universal" int syscall(int sys, ...)
- this number is passed in a CPU register

System Call Sequence

- first, libc prepares the system call arguments
- and puts the system call number in the correct register
- then the CPU is switched into privileged mode
- this also transfers control to the syscall handler

System Call Handler

- the handler first picks up the system call number
- and decides where to continue
- you can imagine this as a giant switch statement

```
switch ( sysnum )
{
    case SYS_write: return syscall_write();
    case SYS_read: return syscall_read();
    /* many more */
}
```

System Call Arguments

- · each system call has different arguments
- how they are passed to the kernel is CPU-dependent
- on 32-bit x86, most of them are passed in memory
- on amd64 Linux, all arguments go into registers
 - 6 registers available for arguments

Part 4.5: Kernel Services

What does a Kernel Do?

- memory & process management
- task (thread) scheduling
- device drivers
 - SSDs, GPUs, USB, bluetooth, HID, audio, ...
- file systems
- networking

Additional Services

- inter-process communication
- timers and time keeping
- process tracing, profiling
- security, sandboxing
- cryptography

Reminder: Microkernel Systems

- the kernel proper is very small
- it is accompanied by servers
- in "true" microkernel systems, there are many servers
 - each device, filesystem, etc. is separate
- in hybrid systems, there is one, or a few
 - a "superserver" that resembles a monolithic kernel

Kernel Services

- we usually don't care which server provides what
 - each system is different
 - for services, we take a monolithic view
- the services are used through system librares
 - they abstract away many of the details
 - e.g. whether a service is a system call or an IPC call

User-Space Drivers in Monolithic Systems

- not all device drivers are part of the kernel
- case in point: printer drivers
- also some USB devices (not the USB bus though)
- · part of the GPU/graphics stack
 - memory and output management in kernel
 - most of OpenGL in user space

Review Questions

- 9. What CPU modes are there and how are they used?
- 10. What is the memory management unit?
- 11. What is a microkernel?
- 12. What is a system call?

Part 5: File Systems

Lecture Overview

- 1. Filesystem Basics
- 2. The Block Layer
- 3. Virtual Filesystem Switch
- 4. The UNIX Filesystem
- 5. Advanced Features

Part 5.1: Filesystem Basics

What is a File System?

- a collection of files and directories
- (mostly) hierarchical
- usually exposed to the user
- usually persistent (across reboots)
- file managers, command line, etc.

What is a (Regular) File?

- a sequence of bytes
- and some basic metadata
- · owner, group, timestamp
- the OS does not care about the content
- text, images, video, source code are all the same
- executables are somewhat special

What is a Directory?

- a list of name file mappings
- an associative container if you will
 - semantically, the value types are not homogeneous
 - syntactically, they are just i-nodes
- one directory = one component of a path
 - /usr/local/bin

What is an i-node?

- an anonymous, file-like object
- could be a regular file
 - or a directory
 - or a special file
 - or a symlink

Files are Anonymous

- this is the case with UNIX
 - not all file systems work like this
- there are pros and cons to this approach
 - e.g. open files can be unlinked
- names are assigned via directory entries

What Else is a Byte Sequence?

- characters coming from a keyboard
- bytes stored on a magnetic tape
- audio data coming from a microphone
- pixels coming from a webcam
- data coming on a TCP connection

Writing Byte Sequences

- sending data to a printer
- playing back audio
- writing text to a terminal (emulator)
- sending data over a TCP stream

Special Files

- many things look somewhat like files
- · let's exploit that and unify them with files
- recall part 2 on APIs: "everything is a file"
 - the API is the same for special and regular files
 - not the implementation though

File System Types

- fat16, fat32, vfat, exfat (DOS, flash media)
- ISO 9660 (CD-ROMs)
- UDF (DVD-ROM)
- NTFS (Windows NT)
- HFS+ (macOS)
- ext2, ext3, ext4 (Linux)
- ufs, ffs (BSD)

Multi-User Systems

- file ownership
- file permissions
- disk quotas

Ownership & Permissions

- · we assume a discretionary model
- whoever creates a file is its owner
- ownership can be transferred
- the owner decides about permissions
 - basically read, write, execute

Disk Quotas

- disks are big but not infinite
- bad things happen when the file system fills up
 - denial of service
 - programs may fail and even corrupt data
- quotas limits the amount of space per user

Part 5.2: The Block Layer

Disk-Like Devices

- disk drives provide block-level access
- read and write data in 512-byte chunks
 - or also 4K on big modern drives
- a big numbered array of blocks

Aside: Disk Addressing Schemes

- CHS: Cylinder, Head, Sector
 - structured adressing used in (very) old drives
 - exposes information about relative seek times
 - useless with variable-length cylinders
 - 10:4:6 CHS = 1024 cylinders, 16 heads, 63 sectors
- LBA: Logical Block Addessing
 - linear, unstructured address space
 - started as 22, later 28, ... now 48 bit

Block-Level Access

- · disk drivers only expose linear addressing
- one block (sector) is the minimum read/write size
- many sectors can be written "at once"
 - sequential access is faster than random
 - maximum throughput vs IOPS

Aside: Access Times

- block devices are slow (compared to RAM)
 - RAM is slow (compared to CPU)
- we cannot treat drives as an extension of RAM
 - not even fastest modern flash storage
 - latency: HDD 3–12 ms, SSD 0.1 ms, RAM 70 ns

Block Access Cache

- caching is used to hide latency
 - same principle between CPU and RAM
- files recently accessed are kept in RAM
 - many cache management policies exist
- implemented entirely in the OS
 - many devices implement their own caching
 - but the amount of fast memory is usually limited

Write Buffers

- the write equivalent of the block cache
- data is kept in RAM until it can be processed
- must synchronise with caching
 - other users may be reading the file

I/O Scheduler (Elevator)

- reads and writes are requested by users
- access ordering is crucial on a mechanical drive
 - not as important on an SSD
 - but sequential access is still much preferred
- requests are queued (recall, disks are slow)
 - but they are not processed in FIFO order

RAID

- hard drives are also unreliable
 - backups help, but take a long time to restore
- RAID = Redundant Array of Inexpensive Disks
 - live-replicate same data across multiple drives
 - many different configurations
- the system stays online despite disk failures

RAID Performance

- RAID affects the performance of the block layer
- often improved reading throughput
 - data is recombined from multiple channels
- write performance is more mixed
 - may require a fair amount of computation
 - more data needs to be written for redundancy

Block-Level Encryption

- symmetric & length-preserving
- encryption key is derived from a passphrase
- · also known as "full disk encryption"
- incurs a small performance penalty
- very important for security / privacy

Storing Data in Blocks

- splitting data into fixed-size chunks is unnatural
- there is no permission system for individual blocks
 - this is unlike virtual (paged) memory
 - it'd be really inconvenient for users
- processes are not persistent, but block storage is

Filesystem as Resource Sharing

- usually only 1 or few disks per computer
- many programs want to store persistent data
- file system allocates space for the data
 - which blocks belong to which file
- different programs can write to different files
 - no risk of trying to use the same block

Filesystem as Abstraction

- allows the data to be organised into files
- enables the user to manage and review data
- files have arbitrary & dynamic size
 - blocks are transparently allocated & recycled
- structured data instead of a flat block array

Part 5.3: Virtual Filesystem Switch

Virtual File System Layer

- many different filesystems
- the OS wants to treat them all alike
- VFS provides an internal, in-kernel API
- filesystem syscalls are hooked up to VFS

VFS in OOP terms

- VFS provides an abstract class, filesystem
- each filesystem implementation derives filesystem
 - e.g. class iso9660 : public filesystem
- · each actual file system gets an instance
 - /home, /usr, /mnt/usbflash each one
 - the kernel uses the abstract interface to talk to them

The filesystem Class

```
struct handle { /* ... */ };
struct filesystem
{
    virtual int open( const char * path ) = 0;
    virtual int read( handle file, ... ) = 0;
    /* ... */
}
```

Filesystem-Specific Operations

- open: look up the file for access
- read, write self-explanatory
- seek: move the read/write pointer
- sync: flush data to disk
- mmap: memory-mapped IO
- select: IO readiness notification

Standard IO

- the usual way to use files
- open the file
 - operations to read and write bytes
- data has to be buffered in user space
 - and then copied to/from kernel space
- not very efficient

Memory-mapped IO

- uses virtual memory (cf. last lecture)
- treat a file as if it was swap space
- the file is mapped into process memory
 - page faults indicate that data needs to be read
 - dirty pages cause writes
- available as the mmap system call

Sync-ing Data

- recall that the disk is very slow
- waiting for each write to hit disk is inefficient
- but if data is held in RAM, what if power is cut?
 - the sync operation ensures the data has hit disk
 - often used in database implementations

Filesystem-Agnostic Operations

- handling executables
- fcntl handling
- special files
- management of file descriptors
- file locks

Executables

- memory mapped (like mmap)
- may be paged in lazily
- executables must be immutable while running
- but can be still unlinked from the directory

The fcntl Syscall

- mostly operations relating to file descriptors
 - synchronous vs asynchronous access
 - blocking vs non-blocking
 - close on exec: more on this in a later lecture
- also one of the several locking APIs

Special Files

- device nodes, pipes, sockets, ...
- only metadata for special files lives on disk
 - this includes permissions & ownership
 - type and properties of the special file
- they are just different kind of an i-node
- open, read, write, etc. bypass the filesystem

File Locking

- multiple programs writing the same file is bad
 - operations will come in randomly
 - the resulting file will be a mess
- file locks fix this problem
 - multiple APIs: fcntl vs flock
 - differences on networked filesystems

Mount Points

- recall that there is only a single directory tree
- but there are multiple disks and filesystems
- file systems can be joined at directories
- root of one becomes a subdirectory of another

Part 5.4: The UNIX Filesystem

Superblock

- holds toplevel information about the filesystem
- locations of i-node tables
- locations of i-node and free space bitmaps
- block size, filesystem size

I-Nodes

- recall that i-node is an anonymous file
 - or a directory, or a special
- i-nodes only have numbers
- directories tie names to i-nodes

I-Node Allocation

- often a fixed number of i-nodes
- i-nodes are either used or free
- free i-nodes may be stored in a bitmap
- alternatives: B-trees

I-Node Content

- exact content of an i-node depends on its type
- regular file i-nodes contain a list of data blocks
 - both direct and indirect (via a data block)
- symbolic links contain the target path
- special devices describe what device they represent

Attaching Data to I-Nodes

- a few direct block addresses in the i-node
 - eg. 10 refs, 4K blocks, max. 40 kilobytes
- indirect data blocks
 - a block full of addresses of other blocks
 - one indirect block approx. 2 MiB of data
- extents: a contiguous range of blocks

Fragmentation

- internal not all blocks are fully used
 - files are of variable size, blocks are fixed
 - a 4100 byte file needs 2 4 KiB blocks
- external free space is non-contiguous
 - happens when many files try to grow at once
 - this means new files are also fragmented

Fragmentation Problems

- performance: can't use fast sequential IO
 - programs often read files sequentially
 - fragmention random IO on the device
- metadata size: can't use long extents
- internal: waste of disk space

Directories

- uses data blocks (like regular files)
- but the blocks hold name i-node maps
- modern file systems use hashes or trees
- the format of directory data is filesystem-specific

File Name Lookup

- we often need to find a file based on a path
- each component means a directory search
- directories can have many thousands entries

Old-Style Directories

- unsorted sequential list of entries
- new entries are simply appended at the end
- unlinking can create holes
- lookup in large directories is very inefficient

Hash-Based Directories

- only need one block read on average
- often the most efficient option
- extendible hashing
 - directories can grow over time
 - gradually allocates more blocks

Tree-Based Directories

- self-balancing search trees
- optimised for block-level access
- B trees, B+ trees, B* trees
- logarithmic number of reads
 - this is worst case, unlike hashing

Hard Links

- multiple names can refer to the same i-node
 - names are given by directory entries
 - we call such multiple-named files hard links
 - it's usually forbidden to hard-link directories
- hard links cannot cross device boundaries
 - i-node numbers are only unique within a filesystem

Soft Links (Symlinks)

- they exist to lift the one-device limitation
- soft links to directories are OK
 - this can cause loops in the filesystem
- the soft link i-node contains a path
 - the meaning can change when paths change
- dangling link: points to a non-existent path

Free Space

- similar problem to i-node allocation
 - but regards data blocks
- goal: quickly locate data blocks to use
 - also: keep data of a single file close together
 - also: minimise external fragmentation
- usually bitmaps or B-trees

File System Consistency

- what happens if power is cut?
- data buffered in RAM is lost
- the IO scheduler can re-order disk writes
- the file system can become corrupt

Journalling

- also known as an intent log
- write down what was going to happen synchronously
- fix the actual metadata based on the journal
- has a performance penalty at run-time
 - reduces downtime by making consistency checks fast
 - may also prevent data loss

Part 5.5: Advanced Features

What Else Can Filesystems Do?

- transparent file compression
- file encryption
- block de-duplication
- snapshots
- checksums
- redundant storage

File Compression

- use one of the standard compression algorithms
 - must be fairly general-purpose (i.e. not JPEG)
 - and of course lossless
 - e.g. LZ77, LZW, Huffman Coding, ...
- quite challenging to implement
 - the length of the file changes (unpredictably)
 - efficient random access inside the file

File Encryption

- use symmetric encryption for individual files
 - must be transparent to upper layers (applications)
 - symmetric crypto is length-preserving
 - encrypted directories, inheritance, &c.
- a new set of challenges
 - key and passphrase management

Block De-duplication

- sometimes the same data block appears many times
 - virtual machine images are a common example
 - also containers and so on
- · some filesystems will identify those cases
 - internally point many files to the same block
 - copy on write to preserve illusion of separate files

Snapshots

- it is convenient to be able to copy entire filesystems
 - but this is also expensive
 - snapshots provide an efficient means for this
- snapshot is a frozen image of the filesystem
 - cheap, because snapshots share storage
 - easier than de-duplication
 - again implemented as copy-on-write

Checksums

- hardware is unreliable
 - individual bytes or sectors may get corrupted
 - this may happen without the hardware noticing
- the filesystem may store checksums along with metadata
 - and possibly also file content
 - this protects the integrity of the filesystem
- beware: not cryptographically secure

Redundant Storage

- like filesystem-level RAID
- data and metadata blocks are replicated
 - may be between multiple local block devices
 - but also across a cluster / many computers
- drastically improves fault tolerance

Review Questions

- 13. What is a block device?
- 14. What is an IO scheduler?
- 15. What does memory-mapped IO mean?
- 16. What is an i-node?

Part 6: Basic Resources & Multiplexing

Lecture Overview

- 1. processes and virtual memory
- 2. thread scheduling
- 3. interrupts and clocks

Part 6.1: Processes and Virtual Memory

Prehistory: Batch Systems

- first computers ran one program at a time
- programs were scheduled ahead of time
- we are talking punch cards &c.
- and computers that took an entire room

History: Time Sharing

- "mini" computers could run programs interactively
- teletype terminals, screens, keyboards
- multiple users at the same time
- hence, multiple programs at the same time

Processes: Early View

- process is an executing program
- there can be multiple processes
- various resources belong to a process
- each process belongs to a particular user

Process Resources

- memory (address space)
- processor time
- open files (descriptors)
 - also working directory
 - also network connections

Process Memory Segments

- program text: contains instructions
- data: static and dynamic data
 - with a separate read-only section
- stack memory: execution stack
 - return addresses
 - automatic variables

Process Memory

- each process has its own address space
- this means processes are isolated from each other
- requires that the CPU has an MMU
- implemented via paging (page tables)

Process Switching

- switching processes means switching page tables
- physical addresses do not change
- but the mapping of virtual addresses does
- large part of physical memory is not mapped
 - could be completely unallocated (unused)
 - or belong to other processes

Paging and TLB

- address translation is slow
- recently-used pages are stored in a TLB
 - short for Translation Look-aside Buffer
 - very fast hardware cache
- the TLB needs to be flushed on process switch
 - this is fairly expensive (microseconds)

Processor Time Sharing

- CPU time is sliced into time shares
- time shares (slices) are like memory frames
- process computation is like memory pages
- processes are allocated into time shares

Multiple CPUs

- execution of a program is sequential
- instructions depend on results of previous instructions
- one CPU = one instruction sequence
- physical limits on CPU speed multiple cores

Threads

- how to use multiple cores in one process?
- threads: a new unit of CPU scheduling
- each thread runs sequentially
- one process can have multiple threads

What is a Thread?

- thread is a sequence of instructions
- different threads run different instructions
 - as opposed to SIMD or many-core units (GPUs)
- each thread has its own stack
- multiple threads can share an address space

Modern View of a Process

- in a modern view, process is an address space
- threads are the right scheduling abstraction
- process is a unit of memory management
- thread is a unit of computation
- old view: one process = one thread

Memory Segment Redux

- one (shared) text segment
- a shared read-write data segment
- a read-only data segment
- one stack for each thread

Fork

- how do we create new processes?
- by fork-ing existing processes
- fork creates an identical copy of a process
- execution continues in both processes
 - each of them gets a different return value

Lazy Fork

- paging can make fork quite efficient
- we start by copying the page tables
- · initially, all pages are marked read-only
- · the processes start out sharing memory

Lazy Fork: Faults

- the shared memory becomes copy on write
- fault when either process tries to write
 - remember the memory is marked as read-only
- the OS checks if the memory is supposed to be writable
 - if yes, it makes a copy and allows the write

Init

- on UNIX, fork is the only way to make a process
- but fork splits existing processes into 2
- the first process is special
- it is directly spawned by the kernel on boot

Process Identifier

- processes are assigned numeric identifiers
- also known as PID (Process ID)
- those are used in process management
- used calls like kill or setpriority

Process vs Executable

- process is a dynamic entity
- executable is a static file
- an executable contains an initial memory image
 - this sets up memory layout
 - and content of the text and data segments

Exec

- on UNIX, processes are created via fork
- how do we run programs though?
- exec: load a new executable into a process
 - this completely overwrites process memory
 - execution starts from the entry point
- running programs: fork + exec

Part 6.2: Thread Scheduling

What is a Scheduler?

- scheduler has two related tasks
 - plan when to run which thread
 - actually switch threads and processes
- · usually part of the kernel
 - even in micro-kernel operating systems

Switching Threads

- threads of the same process share an address space
 - a partial context switch is needed
 - only register state has to be saved and restored
- no TLB flushing lower overhead

Fixed vs Dynamic Schedule

- fixed schedule = all processes known in advance
 - only useful in special / embedded systems
 - can conserve resources
 - planning is not part of the OS
- most systems use dynamic scheduling
 - what to run next is decided periodically

Preemptive Scheduling

- tasks (threads) just run as if they owned the CPU
- the OS forcibly takes the CPU away from them
 - this is called preemption
- pro: a faulty program cannot block the system
- somewhat less efficient than cooperative

Cooperative Scheduling

- threads (tasks) cooperate to share the CPU
- · each thread has to explicitly yield
- this can be very efficient if designed well
- but a bad program can easily block the system

Scheduling in Practice

- cooperative on Windows 3.x for everything
- cooperative for threads on classic Mac OS
 - but preemptive for processes
- preemptive on pretty much every modern OS
 - including real-time and embedded systems

Waiting and Yielding

- threads often need to wait for resources or events
 - they could also use software timers
- a waiting thread should not consume CPU time
- such a thread will yield the CPU
- it is put on a list and later woken up by the kernel

Run Oueues

- runnable (not waiting) threads are queued
- could be priority, round-robin or other queue types
- scheduler picks threads from the run queue
- preempted threads are put back

Priorities

- what share of the CPU should a thread get?
- priorities are static and dynamic
- dynamic priority is adjusted as the thread runs
 - this is done by the system / scheduler
- a static priority is assigned by the user

Fairness

- equal (or priority-based) share per thread
- what if one process has many more threads?
- what if one user has many more processes?
- what if one user group has many more active users?

Fair Share Scheduling

- we can use a multi-level scheduling scheme
- CPU is sliced fairly first among user groups
- then among users
- then among processes
- and finally among threads

Scheduling Strategies

- first in, first served (batch systems)
- earliest deadline first (realtime)
- round robin
- fixed priority preemptive
- fair share scheduling (multi-user)

Interactivity

- throughput vs latency
- latency is more important for interactive workloads
 - think phone or desktop systems
 - but also web servers
- throughput is more important for batch systems
 - think render farms, compute grids, simulation

Reducing Latency

- shorter time slices
- more willingness to switch tasks (more preemption)
- dynamic priorities
- priority boost for foreground processes

Maximising Throughput

- longer time slices
- reduce context switches to minimum
- · cooperative multitasking

Multi-Core Schedulers

- traditionally one CPU, many threads
- nowadays: many threads, many CPUs (cores)
- more complicated algorithms
- more complicated & concurrent-safe data structures

Scheduling and Caches

- threads can move between CPU cores
 - important when a different core is idle
 - and a runnable thread is waiting for CPU
- but there is a price to pay
 - thread / process data is extensively cached
 - caches are typically not shared by all cores

Core Affinity

- modern schedulers try to avoid moving threads
- threads are said to have an affinity to a core
- an extreme case is pinning
 - this altogether prevents the thread to be migrated
- practically, this practice improves throughput
 - even if nominal core utilisation may be lower

NUMA Systems

- non-uniform memory architecture
 - different memory is attached to different CPUs
 - each symmetric block within a NUMA is called a node
- migrating a process to a different node is expensive
 - thread vs node ping-pong can kill performance
 - threads of one process should live on one node

Part 6.3: Interrupts and Clocks

Interrupt

- a way for hardware to request attention
- CPU mechanism to divert execution
- partial (CPU state only) context switch
- switch to privileged (kernel) CPU mode

Hardware Interrupts

- asynchronous, unlike software interrupts
- triggered via bus signals to the CPU
- IRQ = interrupt request
 - just a different name for hardware interrupts
- PIC = programmable interrupt controller

Interrupt Controllers

- PIC: simple circuit, typically with 8 input lines
 - peripherals connect to the PIC with wires
 - PIC delivers prioritised signals to the CPU
- APIC: advanced programmable interrupt controller
 - split into a shared IO APIC and per-core local APIC
 - typically 24 incoming IRQ lines
- OpenPIC, MPIC: similar to APIC, used by e.g. Freescale

Timekeeping

- PIT: programmable interval timer
 - crystal oscillator + divider
 - IRQ line to the CPU
- local APIC timer: built-in, per-core clock
- HPET: high-precision event timer
- RTC: real-time clock

Timer Interrupt

- generated by the PIT or the local APIC
- the OS can set the frequency
- a hardware interrupt happens on each tick
- this creates an opportunity for bookkeeping
- and for preemptive scheduling

Timer Interrupt and Scheduling

- measure how much time the current thread took
- if it ran out of its slice, preempt it
 - pick a new thread to execute
 - perform a context switch
- · those checks are done on each tick
 - rescheduling is usually less frequent

Timer Interrupt Frequency

- typical is 100 Hz
- this means a 10 ms scheduling slice (quantum)
- 1 kHz is also possible
 - harms throughput but improves latency

Tickless Kernels

- the timer interrupt wakes up the CPU
- this can be inefficient if the system is idle
- alternative: use one-off timers
 - allows the CPU to sleep longer
 - this improves power efficiency on light loads

Tickless Scheduling

- slice length (quantum) becomes part of the planning
- if a core is idle, wake up on next software timer
 - synchronisation of software timers
- · other interrupts are delivered as normal
 - network or disk activity
 - keyboard, mice, ...

Other Interrupts

- serial port
 - data is available on the port
- network hardware
 - data is available in a packet queue
- · keyboards, mice
 - user pressed a key, moved the mouse
- USB devices in general

Interrupt Routing

- not all CPU cores need to see all interrupts
- APIC can be told how to deliver IRQs
 - the OS can route IRQs to CPU cores
- multi-core systems: IRQ load balancing
 - useful to spread out IRQ overhead
 - especially useful with high-speed networks

Review Questions

- 17. What is a thread and a process?
- 18. What is a (thread, process) scheduler?
- 19. What do fork and exec do?
- 20. What is an interrupt?

Part 7: Concurrency and Locking

Lecture Overview

- 1. Inter-Process Communication
- 2. Synchronisation
- 3. Deadlocks

What is Concurrency?

- events that can happen at the same time
- it is not important if it does, only that it can
- events can be given a happens-before partial order
- they are concurrent if unordered by happens-before

Why Concurrency?

- problem decomposition
 - different tasks can be largely independent
- reflecting external concurrency
 - serving multiple clients at once
- performance and hardware limitations
 - higher throughput on multicore computers

Parallel Hardware

- hardware is inherently parallel
- software is inherently sequential
- something has to give
 - hint: it's not going to be hardware

Part 7.1: Inter-Process Communication

Reminder: What is a Thread

- thread is a sequence of instructions
- each instruction happens-before the next
 - or: happens-before is a total order on the thread
- basic unit of scheduling

Reminder: What is a Process

- the basic unit of resource ownership
 - primarily memory, but also open files &c.
- may contain one or more threads
- processes are isolated from each other
 - IPC creates gaps in that isolation

I/O vs Communication

- take standard input and output
 - imagine process A writes a file
 - later, process B reads that file
- communication happens in real time
 - between two running threads / processes
 - automatic: without user intervention

Direction

- bidirectional communication is typical
 - this is analogous to a conversation
- but unidirectional communication also makes sense
 - e.g. sending commands to a child process
 - do acknowledgments count as communication?

Communication Example

- network services are a typical example
- take a web server and a web browser
- the browser sends a request for a web page
- the server responds by sending data

Files

- it is possible to communicate through files
- multiple processes can open the same file
- one can write data and another can process it
 - the original program picks up the results
 - typical when using programs as modules

A File-Based IPC Example

- files are used e.g. when you run cc file.c
 - it first runs a preprocessor: cpp -o file.i file.c
 - then the compiler proper: ccl -o file.o file.i
 - and finally a linker: ld file.o crt.o -lc
- the intermediate files may be hidden in /tmp
 - and deleted when the task is completed

Directories

- communication by placing files or links
- typical use: a spool directory
 - clients drop files into the directory for processing
 - a server periodically picks up files in there
- · used for e.g. printing and email

Pipes

- a device for moving bytes in a stream
 - note the difference from messages
- one process writes, the other reads
- the reader blocks if the pipe is empty
- the writer blocks if the pipe buffer is full

UNIX and Pipes

- pipes are used extensively in UNIX
- pipelines built via the shell's | operator
- e.g. ls | grep hello.c
- most useful for processing data in stages

Sockets

- similar to, but more capable than pipes
- allows one server to talk to many clients
- each connection acts like a bidirectional pipe
- could be local but also connected via a network

Shared Memory

- memory is shared when multiple threads can access it
 - happens naturally for threads of a single process
 - the primary means of inter-thread communication
- many processes can map same piece of physical memory
 - this is the more traditional setting
 - hence also allows inter-process communication

Message Passing

- communication using discrete messages
- we may or may not care about delivery order
- we can decide to tolerate message loss
- often used across a network

Part 7.2: Synchronisation

Shared Variables

- structured view of shared memory
- typical in multi-threaded programs
- e.g. any global variable in a program
- but may also live in memory from malloc

Shared Heap Variable

```
void *thread( int *x ) { *x = 7; }
int main()
{
    pthread_t id;
    int *x = malloc( sizeof( int ) );
    pthread_create( &id, NULL, thread, x );
}
```

Race Condition: Example

- consider a shared counter, i
- and the following two threads

```
int i = 0;
void thread1() { i = i + 1; }
void thread2() { i = i - 1; }
```

What is the value of i after both finish?

Race on a Variable

- memory access is not atomic
- take x = x + 1

```
a_0 \leftarrow load \times | b_0 \leftarrow load \times 
a_1 \leftarrow a_0 + 1 | b_1 \leftarrow b_0 + 1
store a_1 \times | store b_1 \times
```

Critical Section

- any section of code that must not be interrupted
- the statement x = x + 1 could be a critical section
- what is a critical section is domain-dependent
 - another example could be a bank transaction
 - or an insertion of an element into a linked list

Race Condition: Definition

- (anomalous) behaviour that depends on timing
- typically among multiple threads or processes
- an unexpected sequence of events happens
- recall that ordering is not guaranteed

Races in a Filesystem

- the file system is also a shared resource
- and as such, prone to race conditions
- e.g. two threads both try to create the same file
 - what happens if they both succeed?
 - if both write data, the result will be garbled

Mutual Exclusion

- only one thread can access a resource at once
- ensured by a mutual exclusion device (a.k.a mutex)
- a mutex has 2 operations: lock and unlock
- lock may need to wait until another thread unlocks

Semaphore

- somewhat more general than a mutex
- allows multiple interchangeable instances of a resource
 - that many threads can enter the critical section
- · basically an atomic counter

Monitors

- a programming language device (not OS-provided)
- internally uses standard mutual exclusion
- data of the monitor is only accessible to its methods
- only one thread can enter the monitor at any given time

Condition Variables

- what if the monitor needs to wait for something?
- imagine a bounded queue implemented as a monitor
 - what happens if it becomes full?
 - the writer must be suspended
- condition variables have wait and signal operations

Spinlocks

- a spinlock is the simplest form of a mutex
- the lock method repeatedly tries to acquire the lock
 - this means it is taking up processor time
 - also known as busy waiting
- spinlocks between threads on the same CPU are very bad
 - but can be very efficient between CPUs

Suspending Mutexes

- these need cooperation from the OS scheduler
- when lock acquisition fails, the thread sleeps
 - it is put on a waiting queue in the scheduler
- unlocking the mutex will wake up the waiting thread
- needs a system call slow compared to a spinlock

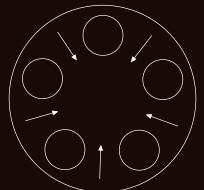
Condition Variables Revisited

- same principle as a suspending mutex
- the waiting thread goes into a wait queue
- the signal method moves the thread back to a run queue
- the busy-wait version is known as polling

Barrier

- sometimes, parallel computation proceeds in phases
 - all threads must finish phase 1
 - before any can start phase 2
- this is achieved with a barrier
 - blocks all threads until the last one arrives
 - waiting threads are usually suspended

Dining Philosophers



Readers and Writers

Read-Copy-Update

- the fastest lock is no lock
- RCU allows readers to work while updates are done
 - make a copy and update the copy
 - point new readers to the updated copy
- when is it safe to reclaim memory?

Part 7.3: Deadlocks

Shared Resources

- hardware comes in a limited number of instances
- many devices can only do one thing at a time
- think printers, DVD writers, tape drives, ...
- we want to use the devices efficiently sharing

Network-based Sharing

- sharing is not limited to processes on one computer
- printers and scanners can be network-attached
- all computers on network may need to coordinate access
 - this could lead to multi-computer deadlocks

Locks as Resources

- we explored locks in the previous section
- locks (mutexes) are also a form of resource
 - a mutex can be acquired (locked) and released
 - a locked mutex belongs to a particular thread
- locks are proxy (stand-in) resources

Preemptable Resources

- sometimes, held resources can be taken away
- this is the case with e.g. physical memory
 - a process can be swapped to disk if need be
- preemtability may also depend on context
 - maybe paging is not available

Non-preemptable Resources

- those resources cannot be (easily) taken away
- think photo printer in the middle of a page
- · or a DVD burner in the middle of writing
- non-preemptable resources can cause deadlocks

Resource Acquisition

- a process needs to request access to a resource
- this is called an acquisition
- when the request is granted, it can use the device
- after it is done, it must release the device
 - this makes it available for other processes

Waiting

- what to do if we wish to acquire a busy resource?
- unless we don't really need it, we have to wait
- this is the same as waiting for a mutex
- the thread is moved to a wait queue

Resource Deadlock

- two resources, A and B
- two processes, P and Q
- P acquires A, Q acquires B
- P tries to acquire B but has to wait for Q
- Q tries to acquire A but has to wait for P

Deadlock Conditions

- 1. mutual exclusion
- 2. hold and wait condition
- 3. non-preemtability
- 4. circular wait

Deadlock is only possible if all 4 are present.

Non-Resource Deadlocks

- not all deadlocks are due to resource contention
- imagine a message-passing system
- process A is waiting for a message
- process B sends a message to A and waits for reply
- the message is lost in transit

Example: Pipe Deadlock

- recall that both the reader and writer can block
- what if we create a pipe in each direction?
- process A writes data and tries to read a reply
 - it blocks because the opposite pipe is empty
- process B reads the data but waits for more deadlock

Deadlocks: Do We Care?

- deadlocks can be very hard to debug
- they can also be exceedingly rare
- we may find the risk of a deadlock acceptable
- just reboot everything if we hit a deadlock
 - also known as the ostrich algorithm

Deadlock Detection

- we can at least try to detect deadlocks
- usually by checking the circular wait condition
- · keep a graph of who owns what and who waits for what
- if there is a loop in the graph deadlock

Deadlock Recovery

- if a preemptable resource is involved, reassign it
- otherwise, it may be possible to do a rollback
 - this needs elaborate checkpointing mechanisms
- all else failing, kill some of the processes
 - the devices may need to be re-initialised

Deadlock Avoidance

- we can possibly deny acquisitions to avoid deadlocks
- we need to know the maximum resources for each process
- avoidance relies on safe states
 - worst case all processes ask for maximum resources
 - safe means we can avoid a deadlock in the worst case

Deadlock Prevention

- deadlock avoidance is typically impractical
- there are 4 conditions for deadlocks to exist
- · we can try attacking those conditions
- if we can remove one of them, deadlocks are prevented

Prevention via Spooling

- this attacks the mutual exclusion property
- multiple programs could write to a printer
- the data is collected by a spooling daemon
- which then sends the jobs to the printer in sequence

Prevention via Reservation

- we can also try removing hold-and-wait
- for instance, we can only allow batch acquisition
 - the process must request everything at once
 - this is usually impractical
- alternative: release and re-acquire

Prevention via Ordering

- this approach eliminates circular waits
- we impose a global order on resources
- a process can only acquire resources in this order
 - must release + re-acquire if the order is wrong
- it is impossible to form a cycle this way

Livelock

- in a deadlock, no progress can be made
- but it's not much better if processes go back and forth
 - for instance releasing and re-acquiring resources
 - they make no useful progress
 - they additionally consume resources
- this is as livelock and is just as bad as a deadlock

Starvation

- starvation happens when a process can't make progress
- generalisation of both deadlock and livelock
- · for instance, unfair scheduling on a busy system
- also recall the readers and writers problem

Review Questions

- 21. What is a mutex?
- 22. What is a deadlock?
- 23. What are the conditions for a deadlock to form?
- 24. What is a race condition?

Part 8: Device Drivers

Lecture Overview

- 1. Drivers, IO and Interrupts
- 2. System and Expansion Busses
- 3. Graphics
- 4. Persistent Storage
- 5. Networking and Wireless

Part 8.1: Drivers, IO and Interrupts

Input and Output

- we will mostly think in terms of IO
- peripherals produce and consume data
- input reading data produced by a device
- output sending data to a device

What is a Driver?

- piece of software that talks to a device
- usually quite specific / unportable
 - tied to the particular device
 - and also to the operating system
- often part of the kernel

Kernel-mode Drivers

- · they are part of the kernel
- running with full kernel privileges
 - including unrestricted hardware access
- no or minimal context switching overhead
 - fast but dangerous

Microkernels

- drivers are excluded from microkernels
- but the driver still needs hardware access
 - this could be a special memory region
 - it may need to react to interrupts
- in principle, everything can be done indirectly
 - but this may be quite expensive, too

User-mode Drivers

- many drivers can run completely in user space
- this improves robustness and security
 - driver bugs can't bring the entire system down
 - nor can they compromise system security
- possibly at some cost to performance

Drivers in Processes

- user-mode drivers typically run in their own process
- this means context switches
 - every time the device demands attention (interrupt)
 - every time another process wants to use the device
- the driver needs system calls to talk to the device
 - this incurs even more overhead

In-Process Drivers

- what if a (large portion of) a driver could be a library
- best of both worlds
 - no context switch overhead for requests
 - bugs and security problems remain isolated
- often used for GPU-accelerated 3D graphics

Port-Mapped IO

- early CPUs had very limited address space
 - 16-bit addresses mean 64KB of memory
- peripherals got a separate address space
- special instructions for using those addresses
 - e.g. in and out on x86 processors

Memory-mapped IO

- devices share address space with memory
- more common in contemporary systems
- IO uses the same instructions as memory access
 - load and store on RISC, mov on x86
- allows selective user-level access (via the MMU)

Programmed IO

- input or output is driven by the CPU
- the CPU must wait until the device is ready
- · would usually run at bus speed
 - 8 MHz for ISA (and hence ATA-1)
- PIO would talk to a buffer on the device

Interrupt-driven IO

- peripherals are much slower than the CPU
 - polling the device is expensive
- the peripheral can signal data availability
 - and also readiness to accept more data
- this frees up CPU to do other work in the meantime

Interrupt Handlers

- also known as first-level interrupt handler
- they must run in privileged mode
 - they are part of the kernel by definition
- the low-level interrupt handler must finish quickly
 - it will mask its own interrupt to avoid re-entering
 - and schedule any long-running jobs for later (SLIH)

Second-level Handler

- · does any expensive interrupt-related processing
- can be executed by a kernel thread
 - but also by a user-mode driver
- usually not time critical (unlike first-level handler)
 - can use standard locking mechanisms

Direct Memory Access

- allows the device to directly read/write memory
- this is a huge improvement over programmed IO
- interrupts only indicate buffer full/empty
- the device can read and write arbitrary physical memory
 - opens up security / reliability problems

IO-MMU

- like the MMU, but for DMA transfers
- allows the OS to limit memory access per device
- very useful in virtualisation
- only recently found its way into consumer computers

Part 8.2: System and Expansion Busses

History: ISA (Industry Standard Architecture)

- 16-bit system expansion bus on IBM PC/AT
- programmed IO and interrupts (but no DMA)
- a fixed number of hardware-configured interrupt lines
 - likewise for I/O port ranges
 - the HW settings then need to be typed back for SW
- parallel data and address transmission

MCA. EISA

- MCA: Micro Channel Architecture
 - proprietary to IBM, patent-encumbered
 - 32-bit, software-driven device configuration
 - expensive and ultimately a market failure
- EISA: Enhanced ISA
 - a 32-bit extension of ISA
 - mostly created to avoid MCA licensing costs
 - short-lived and replaced by PCI

VESA Local Bus

- memory mapped IO & DMA on otherwise ISA systems
- tied to the 80486 line of Intel CPUs (and AMD clones)
- primarily for graphics cards
 - but also used with hard drives
- quickly fell out of use with the arrival of PCI

PCI: Peripheral Component Interconnect

- a 32-bit successor to ISA
 - 33 MHz (compared to 8 MHz for ISA)
 - later revisions at 66 MHz, PCI-X at 133 MHz
 - added support for bus-mastering and DMA
- still a shared, parallel bus
 - all devices share the same set of wires

Bus Mastering

- normally, the CPU is the bus master
 - which means it initiates communication
- it's possible to have multiple masters
 - they need to agree on a conflict resolution protocol
- usually used for accessing the memory

DMA (Direct Memory Access)

- the most common form of bus mastering
- the CPU tells the device what and where to write
- the device then sends data directly to RAM
 - the CPU can work on other things in the meantime
 - completion is signaled via an interrupt

Plug and Play

- the ISA system for IRQ configuration was messy
- MCA pioneered software-configured devices
- PCI further improved on MCA with "Plug and Play"
 - each PCI device has an ID it can tell the system
 - allows for enumeration and automatic configuration

PCI IDs and Drivers

- PCI allows for device enumeration
- device identifiers can be paired to device drivers
- this allows the OS to load and configure its drivers
 - or even download / install drivers from a vendor

AGP: Accelerated Graphics Port

- PCI eventually became too slow for GPUs
 - AGP is based on PCI and only improves performance
 - enumeration and configuration stays the same
 - adds a dedicated point-to-point connection
- multiple transfers per clock (up to 8, for 2 GB/s)

PCI Express

- the current high-speed peripheral bus for PC
- builds on / extends conventional PCI
- point-to-point, serial data interconnect
- much improved throughput (up to ~30GB/s)

USB: Universal Serial Bus

- primarily for external peripherals
 - keyboards, mice, printers, ...
 - replaced a host of legacy ports
- later revisions allow high-speed transfers
 - suitable for storage devices, cameras &c.
- device enumeration, capability negotiation

USB Classes

- a set of vendor-neutral protocols
- HID = human-interface device
- mass storage = disk-like devices
- · audio equipment
- printing

Other USB Uses

- ethernet adapters
- usb-serial adapters
- wifi adapters (dongles)
 - there isn't a universal protocol
 - each USB WiFi adapter needs
- bluetooth

ARM Busses

- ARM is typically used in System-on-a-Chip designs
- those use a proprietary bus to connect peripherals
- there is less need for enumeration
 - the entire system is baked into a single chip
- the peripherals can be pre-configured

USB and PCIe on ARM

- USB nor PCIe are exclusive to the PC platform
- most ARM SoC's support USB devices
 - for slow and medium-speed off-SoC devices
 - e.g. used for ethernet on RPi 1
- some ARM SoC's support PCI Express
 - this allows for high-speed off-SoC peripherals

PCMCIA & PC Card

- People Can't Memorize Computer Industry Acronyms
 - PC = Personal Computer, MC = Memory Card
- hotplug-capable notebook expansion bus
- used for memory cards, network adapters, modems
- comes with its own set of drivers (cardbus)

ExpressCard

- an expansion card standard like PCMCIA / PC Card
- based on PCIe and USB
 - can mostly re-use drivers for those standards
- not in wide use anymore
 - last update was in 2009, introducing USB 3 support
 - the industry association disbanded the same year

miniPCIe, mSATA, M.2

- those are physical interfaces, not special busses
- they provide some mix of PCIe, SATA and USB
 - also other protocols like I²C, SMBus, ...
- used mainly for compact SSDs and wireless
 - also GPS, NFC, bluetooth, ...

Part 8.3: Graphics and GPUs

Graphics Cards

- initially just a device to drive displays
- reads pixels from memory and provides display signal
 - basically a DAC with a clock
 - the memory can be part of the graphics card
- evolved acceleration capabilities

Graphics Accelerator

- allows common operations to be done in hardware
- like drawing lines or filled polygons
- the pixels are computed directly in video RAM
- this can save considerable CPU time

3D Graphics

- rendering 3D scenes is computationally intensive
- CPU-based, software-only rendering is possible
 - texture-less in early flight simulators
 - bitmap textures since '95 / '96 (Descent, Quake)
- CAD workstation had 3D accelerators (OpenGL '92)

GPU (Graphical Processing Unit)

- a term coined by nVidia near the end of '90s
- originally a purpose-built hardware renderer
 - based on polygonal meshes and Z buffering
- increasingly more flexible and programmable
- on-board RAM, high-speed connection to system RAM

GPU Drivers

- · split into a number of components
- graphics output / frame buffer access
- memory management is often done in kernel
- geometry, textures &c. are prepared in-process
- front end API: OpenGL, Direct3D, Vulkan, ...

Shaders

- current GPUs are computation devices
- the GPU has its own machine code for shaders
- the GPU driver contains a shader compiler
 - either all the way from a high level language (HLSL)
 - or starting with an intermediate code (SPIR)

Mode Setting

- this part deals with screen configuration and resolution
- including support for e.g. multiple displays
- usually also supports primitive (SW-only) framebuffer
- often done by a kernel with minimum user-level support

Graphics Servers

- multiple apps cannot all drive the graphics card
 - the graphics hardware needs to be shared
 - one option is a graphics server
- provides an IPC-based drawing and/or windowing API
- performs painting on behalf of the applications

Compositors

- a more direct way to share graphics cards
- each application gets its own buffer to paint into
- painting is mostly done by a (context-switched) GPU
- the individual buffers are then composed onto screen
 - composition is also hardware-accelerated

GP-GPU

- general-purpose GPU (CUDA, OpenCL, ...)
- used for computation instead of just graphics
- basically a return of vector processors
- close to CPUs but not part of normal OS scheduling

Part 8.4: Persistent Storage

Drivers

- split into adapter, bus and device drivers
- often a single driver per device type
 - at least for disk drives and CD-ROMs
- bus enumeration and configuration
- data addressing and data transfers

IDE / ATA

- Integrated Drive Electronics
 - disk controller becomes part of the disk
 - standardised as ATA-1 (AT Attachment ...)
- based on the ISA bus, but with cables
- later adapted for non-disk use via ATAPI

ATA Enumeration

- each ATA interface can attach only 2 drives
 - the drives are HW-configured as master/slave
 - this makes enumeration quite simple
 - multiple ATA interfaces were standard
- no need for specific HDD drivers

PIO vs DMA

- original IDE could only use programmed IO
- this eventually became a serious bottleneck
- later ATA revisions include DMA modes
 - up to 160MB/s with highest DMA modes
 - compare 1900MB/s for SATA 3.2

SATA

- serial, point-to-point replacement for ATA
- hardware-level incompatible to (parallel) ATA
 - but SATA inherited the ATA command set
 - legacy mode allows PATA drivers to talk to SATA drives
- hot-swap capable replace drives in a running system

AHCI (Advanced Host Controller Interface)

- vendor-neutral interface to SATA controllers
 - in theory only a single 'AHCI' driver is needed
- an alternative to 'legacy mode'
- NCQ = Native Command Queuing
 - allows the drive to re-order requests
 - another layer of IO scheduling

ATA and SATA Drivers

- the host controller (adapter) is mostly vendor-neutral
- the bus driver will expose the ATA command set
 - including support for command queuing
- device driver uses the bus driver to talk to devices
- partially re-uses SCSI drivers for ATAPI &c.

SCSI (Small Computer System Interface)

- originated with minicomputers in the 80's
- more complicated and capable than ATA
 - ATAPI basically encapsulates SCSI over ATA
- device enumeration, including aggregates
 - e.g. entire enclosures with many drives
- also allows CD-ROM, tapes, scanners (!)

SCSI Drivers

- split into a host bus adapter (HBA) driver
- a generic SCSI bus and command component
 - often re-used in both ATAPI and USB storage
- · and per-device or per-class drivers
 - optical drives, tapes, CD/DVD-ROM
 - standard disk and SSD drives

iSCSI

- basically SCSI over TCP/IP
- entirely software-based
- allows standard computers to serve as block storage
- takes advantage of fast cheap ethernet
- re-uses most of the SCSI driver stack

NVMe: Non-Volatile Memory Express

- a fairly simple protocol for PCIe-attached storage
- optimised for SSD-based devices
 - much bigger and more command queues than AHCI
 - better / faster interrupt handling
- stresses concurrency in the kernel block layer

USB Mass Storage

- an USB device class (vendor-neutral protocol)
 - one driver for the entire class
- typically USB flash drives, but also external disks
- USB 2 is not suitable for high-speed storage
 - USB 3 introduced UAS = USB-Attached SCSI

Tape Drives

- unlike disk drives, only allow sequential access
- needs support for media ejection, rewinding
- can be attached with SCSI, SATA, USB
- parts of the driver will be bus-neutral
- mainly for data backup, capacities 6-15TB

Optical Drives

- mainly used as a read-only distribution medium
- · laser-facilitated reading of a rotating disc
- can be again attached to SCSI, SATA or USB
- conceived for audio playback very slow seek

Optical Disk Writers (Burners)

- behaves more like a printer for optical disks
- drivers are often done in user space
- attached by one of the standard disk busses
- special programs required to burn disks
 - alternative: packet-writing drivers

Part 8.5: Networking and Wireless

Networking

- networks allow multiple computers to exchange data
 - this could be files, streams or messages
- there are wired and wireless networks
- we will only deal with the lowest layers for now
- NIC = Network Interface Card

Ethernet

- specifies the physical media
- on-wire format and collision resolution
- in modern setups, mostly point-to-point links
 - using active packet switching devices
- transmits data in frames (low-level packets)

Addressing

- at this level, only local addressing
 - at most a single LAN segment
- uses baked-in MAC addresses
 - MAC = Media Access Control
- · addresses belong to interfaces, not computers

Transmit Queue

- packets are picked up from memory
- the OS prepares packets into the transmit queue
- · the device picks them up asynchronously
- similar to how SATA queues commands and data

Receive Queue

- data is also queued in the other direction
- the NIC copies packets into a receive queue
- it invokes an interrupt to tell the OS about new items
 - the NIC may batch multiple packets per interrupt
- if the queue is not cleared quickly packet loss

Multi-Queue Adapters

- fast adapters can saturate a CPU
 - e.g. 10GbE cards, or multi-port GbE
- these NICs can manage multiple RX and TX queues
 - each queue gets its own interrupt
 - different queues can be handled by different CPU cores

Checksum and TCP Offloading

- more advanced adapters can offload certain features
- commonly computation of mandatory packet checksums
- but also TCP-related features
- this needs both driver support and TCP/IP stack support

WiFi

- wireless network interface "wireless ethernet"
- shared medium electromagnetic waves in air
- (almost) mandatory encryption
 - otherwise easy to eavesdrop or even actively attack
- a very complex protocol (relative to hardware standards)
 - assisted by firmware running on the adapter

Bluetooth

- a wireless alternative to USB
- allows short-distance radio links with peripherals
 - input (keyboard, mice, game controllers)
 - audio (headsets, speakers)
 - data transmission (e.g. smartphone sync)
 - gadgets (watches, heartrate monitoring, GPS, ...)

Review Questions

- 25. What is memory-mapped IO and DMA?
- 26. What is a system bus?
- 27. What is a graphics accelerator?
- 28. What is a NIC receive queue?

Part 9: Network Stack

Lecture Overview

- 1. Networking Intro
- 2. The TCP/IP Stack
- 3. Using Networks
- 4. Network File Systems

Part 9.1: Networking Intro

Host and Domain Names

- hostname = human readable computer name
- hierarchical system, big-endian: www.fi.muni.cz
- FQDN = fully-qualified domain name
- the local suffix may be omitted (ping aisa)

Network Addresses

- address = machine-friendly and numeric
- IPv4 address: 4 octets (bytes): 192.168.1.1
- IPv6 address: 16 octets
- Ethernet (MAC): 6 octets, c8:5b:76:bd:6e:0b

Network Types

- LAN = Local Area Network
 - Ethernet: wired, up to 10Gb/s
 - WiFi (802.11): wireless, up to 1Gb/s
- WAN = Wide Area Network (the Internet)
 - PSTN, xDSL, PPPoE
 - GSM, 2G (GPRS, EDGE), 3G (UMTS), 4G (LTE)
 - also LAN technologies Ethernet, WiFi

Networking Layers

- 2. Link (Ethernet, WiFi)
- 3. Network (IP)
- 4. Transport (TCP, UDP, ...)
- 7. Application (HTTP, SMTP, ...)

Networking and Operating Systems

- a network stack is a standard part of an OS
- large part of the stack lives in the kernel
 - although this only applies to monolithic kernels
 - microkernels use user-space networking
- another chunk is in system libraries & utilities

Kernel-Side Networking

- device drivers for networking hardware
- network and transport protocol layers
- routing and packet filtering (firewalls)
- networking-related system calls (sockets)
- network file systems (SMB, NFS)

System Libraries

- the socket and related APIs
- host name resolution (a DNS client)
- encryption and data authentication (SSL, TLS)
- certificate handling and validation

System Utilities

- network configuration (ifconfig)
- diagnostics (ping, traceroute)
- packet logging and inspection (tcpdump)
- route management (route, bgpd)

Networking Aspects

- packet format
 - what are the units of communication
- · addressing
 - how are the sender and recipient named
- · packet delivery
 - how a message is delivered

Protocol Nesting

- protocols run on top of each other
- this is why it is called a network stack
- higher levels make use of the lower levels
 - HTTP uses abstractions provided by TCP
 - TCP uses abstractions provided by IP

Packet Nesting

- higher-level packets are just data to the lower level
- an Ethernet frame can carry an IP packet in it
- the IP packet can carry a TCP packet
- the TCP packet can carry an HTTP request

Stacked Delivery

- delivery is, in the abstract, point-to-point
 - routing is mostly hidden from upper layers
 - the upper layer requests delivery to an address
- · lower-layer protocols are usually packet-oriented
 - packet size mismatches can cause fragmentation
- a packet can pass through different low-level domains

Layers vs Addressing

- not as straightforward as packet nesting
 - address relationships are tricky
- special protocols exist to translate addresses
 - DNS for hostname vs IP address mapping
 - ARP for IP vs MAC address mapping

ARP (Address Resolution Protocol)

- finds the MAC that corresponds to an IP
- required to allow packet delivery
 - IP uses the link layer to deliver its packets
 - the link layer must be given a MAC address
- the OS builds a map of IP MAC translations

Ethernet

- link-level communication protocol
- largely implemented in hardware
- the OS uses a well-defined interface
 - packed receive and submit
 - using MAC addresses (ARP is part of the OS)

Packet Switching

- shared media are inefficient due to collisions
- ethernet is typically packet switched
 - a switch is usually a hardware device
 - but also in software (usually for virtualisation)
 - physical connections form a star topology

Bridging

- bridges operate at the link layer (layer 2)
- a bridge is a two-port device
 - each port is connected to a different LAN
 - the bridge joins the LANs by forwarding frames
- can be done in hardware or software
 - brctl on Linux, ifconfig on OpenBSD

Tunneling

- tunnels are virtual layer 2 or 3 devices
- they encapsulate traffic using a higher-level protocol
- tunneling is used to implement Virtual Private Networks
 - a software bridge can operate over an UDP tunnel
 - the tunnel is usually encrypted

PPP (Point-to-Point Protocol)

- a link-layer protocol for 2-node networks
- available over many physical connections
 - phone lines, cellular connections, DSL, Ethernet
 - often used to connect endpoints to the ISP
- supported by most operating systems
 - split between the kernel and system utilities

Wireless

- WiFi is mostly like (slow, unreliable) Ethernet
- needs encryption since anyone can listen
- also authentication to prevent rogue connections
 - PSK (pre-shared key), EAP / 802.11x
- · encryption needs key management

Part 9.2: The TCP/IP Stack

IP (Internet Protocol)

- uses 4 byte (v4) or 16 byte (v6) addresses
 - split into network and host parts
- it is a packet-based protocol
- is a best-effort protocol
 - packets may get lost, reordered or corrupted

IP Networks

- IP networks roughly correspond to LANs
 - hosts on the same network are located with ARP
 - remote networks are reached via routers
- a netmask splits the address into network/host parts
- IP typically runs on top of Ethernet or PPP

Routing

- routers forward packets between networks
- somewhat like bridges but layer 3
- routers act as normal LAN endpoints
 - but represent entire remote IP networks
 - or even the entire Internet

Services and TCP/UDP Port Numbers

- networks are generally used to provide services
 - each computer can host multiple
- different services can run on different ports
- port is a 16-bit number and some ar given names
 - port 25 is SMTP, port 80 is HTTP, ...

ICMP: Internet Control Message Protocol

- control messages (packets)
 - destination host/network unreachable
 - time to live exceeded
 - fragmentation required
- diagnostic packets, e.g. the ping command
 - echo request and echo reply
 - combine with TTL for traceroute

TCP: Transmission Control Protocol

- a stream-oriented protocol on top of IP
- works like a pipe (transfers a byte sequence)
 - must respect delivery order
 - and also re-transmit lost packets
- must establish connections

TCP Connections

- the endpoints must establish a connection first
- each connection serves as a separate data stream
- a connection is bidirectional
- TCP uses a 3-way handshake: SYN, SYN/ACK, ACK

Sequence Numbers

- TCP packets carry sequence numbers
- these numbers are used to re-assemble the stream
 - IP packets can arrive out of order
- they are also used to acknowledge reception
 - and subsequently to manage re-transmission

Packet Loss and Re-transmission

- packets can get lost for a variety of reasons
 - a link goes down for an extended period of time
 - buffer overruns on routing equipment
- TCP sends acknowledgments for received packets
 - the ACKs use sequence numbers to identify packets

Operating Systems 455/746 Network Stack

UDP: User (Unreliable) Datagram Protocol

- TCP comes with non-trivial overhead
 - and its guarantees are not always required
- UDP is a much simpler protocol
 - a very thin wrapper around IP
 - with minimal overhead on top of IP

Name Resolution

- users do not want to remember numeric addresses
 - phone numbers are bad enough
- host names are used instead
- can be stored in a file, e.g. /etc/hosts
 - not very practical for more than 3 computers
 - but there are millions of computers on the Internet

DNS: Domain Name Service

- hierarchical protocol for name resolution
 - runs on top of TCP or UDP
- domain names are split into parts using dots
 - each domain knows whom to ask for the next bit.
 - the name database is effectively distributed

DNS Recursion

- take www.fi.muni.cz. as an example domain
- resolution starts from the right at root servers
 - the root servers refer us to the cz. servers
 - the cz. servers refer us to muni.cz
 - finally muni.cz. tells us about fi.muni.cz

DNS Recursion Example

Operating Systems 460/746 Network Stack

DNS Record Types

- A is for (IP) Address
- AAAA is for an IPv6 Address
- CNAME is for an alias
- MX is for mail servers
- and many more

Firewalls

- the name comes from building construction
 - a fire-proof barrier between parts of a building
- the idea is to separate networks from each other
 - making attacks harder from the outside
 - limiting damage in case of compromise

Packet Filtering

- packet filtering is how firewalls are usually implemented
- can be done on a router or at an endpoint
- dedicated routers + packet filters are more secure
 - a single such firewall protects the entire network
 - less opportunity for mis-configuration

Operating Systems 463/746 Network Stack

Packet Filter Operation

- packet filters operate on a set of rules
 - the rules are generally operator-provided
- each incoming packet is classified using the rules
- and then dispatched accordingly
 - may be forwarded, dropped, rejected or edited

Packet Flter Examples

- packet filters are often part of the kernel
- the rule parser is a system utility
 - it loads rules from a configuration file
 - and sets up the kernel-side filter
- there are multiple implementations
 - iptables, nftables in Linux
 - pf in OpenBSD, ipfw in FreeBSD

Part 9.3: Using Networks

Sockets Reminder

- the socket API comes from early BSD Unix
- socket represents a (possible) network connection
- you get a file descriptor for an open socket
- you can read() and write() to sockets
 - but also sendmsg() and recvmsg()

Socket Types

- sockets can be internet or unix domain
 - internet sockets work across networks
- stream sockets are like files
 - you can write a continuous stream of data
 - usually implemented using TCP
- datagram sockets send individual messages
 - usually implemented using UDP

Creating Sockets

- a socket is created using the socket() function
- it can be turned into a server using listen()
 - individual connections are established with accept()
- or into a client using connect()

Resolver API

- libc contains a resolver
 - available as gethostbyname (and gethostbyname2)
 - also gethostbyaddr for reverse lookups
- can look in many different places
 - most systems support at least /etc/hosts
 - and DNS-based lookups

Network Services

- servers listen on a socket for incoming connections
 - a client actively establishes a connection to a server
- the network simply transfers data between them
- interpretation of the data is a layer 7 issue
 - could be commands, file transfers, ...

Network Service Examples

- (secure) remote shell sshd
- the internet email suite
 - MTA = Mail Transfer Agent, speaks SMTP
 - SMTP = Simple Mail-Transfer Protocol
- the world wide web
 - web servers provide content (files)
 - clients and servers speak HTTP and HTTPS

Client Software

- the ssh command talks uses the SSH protocol
 - a very useful system utility on virtually all UNIXes
- web browser is the client for world wide web
 - browsers are complex application programs
 - some of them bigger than even operating systems
- email client is also known as a MUA (Mail User Agent)

Part 9.4: Network File Systems

Why Network Filesystems?

- copying files back and forth is impractical
 - and also error-prone (which is the latest version?)
- how about storing data in a central location
- and sharing it with all the computers on the LAN

NAS (Network-Attached Storage)

- a (small) computer dedicated to storing files
- usually running a cut down operating system
 - often based on Linux or FreeBSD
- provides file access to the network
- sometimes additional app-level services
 - e.g. photo management, media streaming, ...

NFS (Network File System)

- the traditional UNIX networked filesystem
- hooked quite deep into the kernel
 - assumes generally reliable network (LAN)
- filesystems are exported for use over NFS
- the client side mounts the NFS-exported volume

NFS History

- originated in Sun Microsystems in the 80s
- v2 implemented in System V, DOS, ...
- v3 appeared in '95 and is still in use
- v4 arrives in 2000, improving security

VFS Reminder

- implementation mechanism for multiple FS types
- · an object-oriented approach
 - open: look up the file for access
 - read, write self-explanatory
 - rename: rename a file or directory

RPC (Remote Procedure Call)

- any protocol for calling functions on remote hosts
 - ONC-RPC = Open Network Computing RPC
 - NFS is based on ONC-RPC (also known as Sun RPC)
- · NFS basically runs VFS operations using RPC
 - this makes it easy to implement on UNIX-like systems

Port Mapper

- ONC-RPC is executed over TCP or UDP
 - but it is more dynamic wrt. available services
- TCP/UDP port numbers are assigned on demand
- portmap translates from RPC services to port numbers
 - the port mapper itself listens on port 111

The NFS Daemon

- also known as nfsd
- provides NFS access to a local file system
- can run as a system service
- or it can be part of the kernel
 - this is more typical for performance reasons

SMB (Server Message Block)

- a network file system from Microsoft
- available in Windows since version 3.1 (1992)
 - originally ran on top of NetBIOS
 - later versions used TCP/IP
- SMB1 accumulated a lot of cruft and complexity

SMB 2.0

- simpler than SMB1 due to fewer retrofits and compat
- better performance and security
- support for symbolic links
- available since Windows Vista (2006)

Review Questions

- 29. What is ARP (Address Resolution Protocol)?
- 30. What is IP (Internet Protocol)?
- 31. What is TCP (Transmission Control Protocol)?
- 32. What is DNS (Domain Name Service)?

Part 10: Shells & User Interfaces

Lecture Overview

- 1. Command Interpreters
- 2. The Command Line
- 3. Graphical Interfaces

Part 10.1: Command Interpreters

Shell

- programming language centered on OS interaction
- rudimentary control flow
- untyped, text-centered variables
- · dubious error handling

Interactive Shells

- almost all shells have an interactive mode
- · the user inputs a single statement on keyboard
- when confirmed, it is immediately executed
- this forms the basis of command-line interfaces

Shell Scripts

- a shell script is an (executable) file
- in simplest form, it is a sequence of commands
 - each command goes on a separate line
 - executing a script is about the same as typing it
- but can use structured programming constructs

Shell Upsides

- very easy to write simple scripts
- first choice for simple automation
- · often useful to save repetitive typing
- definitely not good for big programs

Bourne Shell

- a specific language in the "shell" family
- the first shell with consistent programming support
 - available since 1976.
- still widely used today
 - best known implementation is bash
 - /bin/sh is mandated by POSIX

C Shell

- also known as csh, first released in 1978
- more C-like syntax than sh (Bourne Shell)
 - but not really very C-like at all
- improved interactive mode (over sh from '76)
- also still used today (tcsh)

Korn Shell

- also known as ksh, released in 1983
- middle ground between sh and csh
- basis of the POSIX.2 requirements
- a number of implementations exists

Commands

- typically a name of an executable
 - may also be control flow or a built-in
- the executable is looked up in the filesystem
- the shell doas a fork + exec
 - this means new process for each command
 - process creation is fairly expensive

Built-in Commands

- cd change the working directory
- export for setting up environment
- echo print a message
- exec replace the shell process (no fork)

Variables

- · variable names are made of letters and digits
- using variables is indicated with \$
- setting variables does not use the \$
- all variables are global (except subshells)

VARIABLE="some text" echo \$VARIABLE

Variable Substitution

- variables are substituted as text
- \$foo is simply replaced with the content of foo
- arithmetic is not well supported in most shells
 - or any expression syntax, e.g. relational operators
 - consider z=\$((\$x + \$y)) for addition in bash

Command Substitution

- basically like variable substitution
- written as `command`or \$(command)
 - first executes the command
 - and captures its standard output
 - then replaces \$(command) with the output

Quoting

- whitespace is an argument separator in shell
- multi-word arguments must be quoted
- quotes can be double quotes "" or single ' '
 - double quotes allow variable substitution

Quoting and Substitution

- whitespace from variable substitution must be quoted
 - `foo="hello world"``
 - ls \$foo is different than ls "\$foo"
- bad quoting is a very common source of bugs
- consider also filenames with spaces in them

Special Variables

- \$? is the result of last command
- \$\$ is the PID of the current shell
- \$1 through \$9 are positional parameters
 - \$# is the number of parameters
- \$0 is the name of the shell (argv[0])

Environment

- is like shell variables but not the same
- the environment is passed to all executed programs
 - but a child cannot modify environment of its parent
- variables are moved into the environment by export
- environment variables often act as settings

Important Environment Variables

- \$PATH tells the system where to find programs
- \$HOME is the home directory of the current user
- \$EDITOR and \$VISUAL set which text editor to use
- \$EMAIL is the email address of the current user
- \$PWD is the current working directory

Globbing

- patterns for quickly listing multiple files
- e.g. ls *.c shows all files ending in .c
- * matches any number of characters
- ? matches one arbitrary character
- works on entire paths (ls src/*/*.c)

Conditionals

- allows conditional execution of commands
- if cond; then cmd1; else cmd2; fi
- also elif cond2; then cmd3; fi
- cond is also a command (the exit code is used)

test (evaluating boolean expressions)

- originally an external program, also known as [
 - nowadays built-in in most shells
 - works around lack of expressions in shell
- evaluates its arguments and returns true or false
 - can be used with if and while constructs

test Examples

- test file1 -nt file2 'nt' = newer than
- test 32 -gt 14 'gt' = greater than
- test foo = bar string equality
- combines with variable substitution (test \$y = x)

Loops

- while cond; do cmd; done
 - cond is a command, like in if
- for i in 1 2 3 4; do cmd; done
 - allows globs: for f in *.c; do cmd; done
 - also command substitution
 - for f in `seq 1 10`; do cmd; done

Case Analysis

- selects a command based on pattern matching
- case \$x in *.c) cc \$x;; *) ls \$x;; esac
 - yes, case really uses unbalanced parens
 - the ;; indicates end of a case

Command Chaining

- ; (semicolon): run two commands in sequence
- && run the second command if the first succeeded
- | run the second command if the first failed
- e.g. compile and run: cc file.c && ./a.out

Pipes

- shells can run pipelines of commands
- cmd1 | cmd2 | cmd3
 - all commands are run in parallel
 - output of cmd1 becomes input of cmd2
 - output of cmd2 is processed by cmd3

echo hello world | sed -e s,hello,goodbye,

Functions

- you can also define functions in shell
- mostly a light-weight alternative to scripts
 - no need to export variables
 - but cannot be invoked by non-shell programs
- functions can also set variables

Part 10.2: The Command Line

Interactive Shell

- the shell displays a prompt and waits
- the user types in a command and hits enter
- the command is executed immediately
- output is printed to the terminal

Command Completion

- most shells let you use TAB to auto-complete
 - works at least for command names and file names
 - but "smart completion" is common
- interactive history: hit "up" to recall a command
 - also interactive history search, e.g. C-r in bash

Prompt

- the string printed when shell expects a command
- controlled by the PS1 environment variable
- usually shows at least your username and the hostname
- also: working directory, battery status, time, weather, ...

Job Control

- only one program can run in the foreground (terminal)
- but a running program can be suspended (C-z)
- and resumed in background (bg) or in foreground (fg)
- use & to run a command in background: ./spambot &

Terminal

- can print text and read text from a keyboard
- normally everything is printed on the last line
- the text could contain escape (control) sequences
 - for printing colourful text or clearing the screen
 - also for printing text at a specific coordinate

Full-Screen Terminal Apps

- applications can use the entire terminal screen
- a library abstracts away the low-level control sequences
 - the library is called ncurses for new curses
 - different terminals use different control sequences
- special characters exist to draw frames and separators

UNIX Text Editors

- sed stream editor, non-interactive
- ed line oriented, interactive
- vi visual, screen oriented
- ex line-oriented mode of vi

TUI: Text User Interface

- the program draws a 2D interface on a terminal
- these types of interfaces can be quite comfortable
- they are often easier to program than GUIs
- very low bandwidth requirements for remote use

Part 10.3: Graphical Interfaces

Windowing Systems

- each application runs in its own window
 - or possibly multiple windows
- multiple applications can be shown on screen
- windows can be moved around, resized &c.
 - facilitated by frames around window content
 - generally known as window management

Window-less Systems

- especially popular on smaller screens
- · applications take the entire screen
 - give or take status or control widgets
- task switching via a dedicated screen

A GUI Stack

- graphics card driver, mode setting
- drawing/painting (usually hardware-accelerated)
- multiplexing (e.g. using windows)
- widgets: buttons, labels, lists, ...
- layout: what goes where on the screen

Well-known GUI Stacks

- Windows
- macOS, iOS
- X11
- Wayland
- Android

Portability

- GUI "toolkits" make portability easy
 - Qt, GTK, Swing, HTML5+CSS, ...
 - many of them run on all major platforms
- code portability is not the only issue
 - GUIs come with look and feel guidelines
 - portable applications may fail to fit

Text Rendering

- a surprisingly complex task
- unlike terminals, GUIs use variable pitch fonts
 - brings up issues like kerning
 - hard to predict pixel width of a line
- bad interaction with printing (cf. WYSIWIG)

Bitmap Fonts

- characters are represented as pixel arrays
 - usually just black and white
- traditionally pixel-drawn by hand
 - very time consuming (many letters, sizes, variants)
- the result is **sharp** but **jagged** (not smooth)

Outline Fonts

- Type1, TrueType based on splines
- they can be scaled to arbitrary pixel sizes
- same font can be used for screen and for print
- rasterisation is usually done in software

Hinting, Anti-Aliasing

- screens are low resolution devices
 - typical HD displays have DPI around 100
 - laser printers have DPI of 300 or more
- hinting: deform outlines to better fit a pixel grid
- anti-aliasing: smooth outlines using grayscale

X11 (X Window System)

- a traditional UNIX windowing system
- provides a C API (xlib)
- built-in network transparency (socket-based)
- core protocol version 11 from 1987

X11 Architecture

- X server provides graphics and input
- X client is an application that uses X
- a window manager is a (special) client
- a compositor is another special client

Remote Displays

- application is running on computer A
- the display is not the console of A
 - could be a dedicated graphical terminal
 - could be another computer on a LAN
 - or even across the internet

Remote Display Protocols

- one approach is pushing pixels
 - VNC (Virtual Network Computing)
- X11 uses a custom drawing protocol
- others use high-level abstractions
 - NeWS (PostScript-based)
 - HTML5 + JavaScript

VNC (Virtual Network Computing)

- sends compressed pixel data over the wire
 - can leverage regularities in pixel data
 - can send incremental updates
- and input events in the other direction
- no support for peripherals or file sync

RDP (Remote Desktop Protocol)

- more sophisticated than VNC (but proprietary)
- can also send drawing commands over the wire
 - like X11, but using DirectX drawing
 - also allows remote OpenGL
- support for audio, remote USB &c.

SPICE (Simple Protocol for Indep. Computing Env.)

- open protocol somewhere between VNC and RDP
- can send OpenGL (but only over a local socket)
- two-way audio, USB, clipboard integration
- still mainly based on pushing (compressed) pixels

Remote Desktop Security

- the user needs to be authenticated over network
 - passwords are easy, biometric data less so
- the data stream should be encrypted
 - not part of the X11 or NeWS protocols
 - or even HTTP by default (used for HTML5/JS)

Review Questions

- 33. What is a shell?
- 34. What does variable substitution mean?
- 35. What is an environment variable?
- 36. What belongs into the GUI stack?

Part 11: Access Control

Lecture Overview

- 1. Multi-User Systems
- 2. File Systems
- 3. Sub-user Granularity

Part 11.1: Multi-User Systems

Users

- originally a proxy for people
- currently a more general abstraction
- user is the unit of ownership
- many permissions are user-centered

Computer Sharing

- computer is a (often costly) resource
- efficiency of use is a concern
 - a single user rarely exploits a computer fully
- · data sharing makes access control a necessity

Ownership

- various objects in an OS can be owned
 - primarily files and processes
- the owner is typically whoever created the object
 - ownership can be transferred
 - usually at the impetus of the original owner

Process Ownership

- each process belongs to some user
- the process acts on behalf of the user
 - the process gets the same privilege as its owner
 - this both constrains and empowers the process
- processes are active participants

File Ownership

- · each file also belongs to some user
- this gives rights to the user (or rather their processes)
 - they can read and write the file
 - they can change permissions or ownership
- files are passive participants

Access Control Models

- owners usually decide who can access their objects
 - this is known as discretionary access control
- in high-security environments, this is not allowed
 - known as mandatory access control
 - a central authority decides the policy

(Virtual) System Users

- users are an useful ownership abstraction
- various system services get their own "fake" users
- this allows them to own files and processes
- and also limit their access to the rest of the OS

Principle of Least Privilege

- entities should have minimum privilege required
 - applies to software components
 - but also to human users of the system
- this limits the scope of mistakes
 - and also of security compromises

Privilege Separation

- different parts of a system need different privilege
- least privilege dictates splitting the system
 - components are isolated from each other
 - they are given only the rights they need
- components communicate using the simplest feasible IPC

Process Separation

- recall that each process runs in its own address space
 - but shared memory can be requested
- each user has a view of the filesystem
 - a lot more is shared by default in the filesystem
 - especially the namespace (directory hierarchy)

Access Control Policy

- there are 3 pieces of information
 - the subject (user)
 - the verb (what is to be done)
 - the object (the file or other resource)
- there are many ways to encode this information

Access Rights Subjects

- in a typical OS those are (possibly virtual) users
 - sub-user units are possible (e.g. programs)
 - roles and groups could also be subjects
- the subject must be named (names, identifiers)
 - easy on a single system, hard in a network

Access Rights Verbs

- the available "verbs" (actions) depend on object type
- a typical object would be a file
 - files can be read, written, executed
 - directories can be searched or listed or changed
- network connections can be established &c.

Access Rights Objects

- anything that can be manipulated by programs
 - although not everything is subject to access control
- could be files, directories, sockets, shared memory, ...
- object names depend on their type
 - file paths, i-node numbers, IP addresses, ...

Subjects in POSIX

- there are 2 types of subjects: users and groups
- each user can belong to multiple groups
- users are split into normal users and root
 - root is also known as the super-user

User Management

- the system needs a database of users
- in a network, user identities often need to be shared
- could be as simple as a text file
 - /etc/passwd and /etc/group on UNIX systems
- · or as complex as a distributed database

User and Group Identifiers

- users and groups are represented as numbers
 - this improves efficiency of many operations
 - the numbers are called uid and gid
- those numbers are valid on a single computer
 - or at most, a local network

Changing Identities

- each process belongs to a particular user
- ownership is inherited across fork()
- super-user processes can use setuid()
- exec() can sometimes change a process owner

Login

- a super-user process manages user logins
- the user types their name and provides credentials
 - upon successful authentication, login calls fork()
 - the child calls setuid() to the user
 - and uses exec() to start a shell for the user

User Authentication

- the user needs to authenticate themselves
- passwords are the most commonly used method
 - the system needs to know the right password
 - user should be able to change their password
- biometric methods are also quite popular

Remote Login

- authentication over network is more complicated
- passwords are easiest, but not easy
 - encryption is needed to safely transmit passwords
 - along with computer authentication
- 2-factor authentication is a popular improvement

Computer Authentication

- how to ensure we send the password to the right party?
 - an attacker could impersonate our remote computer
- usually via asymmetric cryptography
 - a private key can be used to sign messages
 - the server will sign a message establishing its identity

2-factor Authentication

- 2 different types of authentication
 - harder to spoof both at the same time
- there are a few factors to pick from
 - something the user knows (password)
 - something the user has (keys)
 - what the user is (biometric)

Enforcement: Hardware

- all enforcement begins with the hardware
 - the CPU provides a privileged mode for the kernel
 - DMA memory and IO instructions are protected
- the MMU allows the kernel to isolate processes
 - and protect its own integrity

Enforcement: Kernel

- kernel uses hardware facilities to implement security
 - it stands between resources and processes
 - access is mediated through system calls
- file systems are part of the kernel
- user and group abstractions are part of the kernel

Enforcement: System Calls

- the kernel acts as an arbitrator
- a process is trapped in its own address space
- processes use system calls to access resources
 - kernel can decide what to allow
 - based on its access control model and policy

Enforcement: Service APIs

- · userland processes can enforce access control
 - usually system services which provide IPC API
- e.g. via the getpeereid() system call
 - tells the caller which user is connected to a socket
 - user-level access control is rooted in kernel facilities

Part 11.2: File Systems

File Access Rights

- file systems are a case study in access control
- all modern file systems maintain permissions
 - the only extant exception is FAT (USB sticks)
- · different systems adopt different representation

Representation

- file systems are usually object-centric
 - permissions are attached to individual objects
 - easily answers "who can access this file"?
- there is a fixed set of verbs
 - those may be different for files and directories
 - different systems allow different verbs

The UNIX Model

- each file and directory has a single owner
- plus a single owning group
 - not limited to those the owner belongs to
- ownership and permissions are attached to i-nodes

Access vs Ownership

- POSIX ties ownership and access rights
- only 3 subjects can be named on a file
 - the owner (user)
 - the owning group
 - anyone else

Access Verbs in POSIX File Systems

- read: read a file, list a directory
- write: write a file, link/unlink i-nodes to a directory
- execute: exec a program, enter the directory
- execute as owner (group): setuid/setgid

Permission Bits

- basic UNIX permissions can be encoded in 9 bits
- 3 bits per 3 subject designations
 - first comes the owner, then group, then others
 - written as e.g. rwxr-x--- or 0750
- plus two numbers for the owner/group identifiers

Changing File Ownership

- the owner and root can change file owners
- chown and chgrp system utilities
- or via the C API
 - chown(), fchown(), fchownat(), lchown()
 - same set for chgrp

Changing File Permissions

- again available to the owner and to root
- chmod is the user space utility
 - either numeric argument: chmod 644 file.txt
 - or symbolic: chmod +x script.sh
- and the corresponding system call (numeric-only)

setuid and setgid

- special permissions on executable files
- they allow exec to also change the process owner
- · often used for granting extra privileges
 - e.g. the mount command runs as the super-user

Sticky Directories

- file creation and deletion is a directory permission
 - this is problematic for shared directories
 - in particular the system /tmp directory
- in a sticky directory, different rules apply
 - new files can be created as usual
 - only the owner can unlink a file from the directory

Access Control Lists

- ACL is a list of ACE's (access control elements)
 - each ACE is a subject + verb pair
 - it can name an arbitrary user
- ACL is attached to an object (file, directory)
- more flexible than the traditional UNIX system

ACLs and POSIX

- part of POSIX.1e (security extensions)
- most POSIX systems implement ACLs
 - this does not supersede UNIX permission bits
 - instead, they are interpreted as part of the ACL
- file system support is not universal (but widespread)

Device Files

- UNIX represents devices as special i-nodes
 - this makes them subject to normal access control
- the particular device is described in the i-node
 - only a super-user can create device nodes
 - users could otherwise gain access to any device

Sockets and Pipes

- named sockets and pipes are just i-nodes
 - also subject to standard file permissions
- especially useful with sockets
 - a service sets up a named socket in the file system
 - file permissions decide who can talk to the service

Special Attributes

- flags that allow additional restrictions on file use
 - e.g. immutable files (cannot be changed by anyone)
 - append-only files (for logfile integrity protection)
 - compression, copy-on-write controls
- non-standard (Linux chattr, BSD chflags)

Network File System

- NFS 3.0 simply transmits numeric uid and gid
 - the numbering needs to be synchronised
 - can be done via a central user database
- NFS 4.0 uses per-user authentication
 - the user authenticates to the server directly
 - filesystem uid and gid values are mapped

File System Quotas

- storage space is limited, shared by users
 - files take up storage space
 - file ownership is also a liability
- quotas set up limits space use by users
 - exhausted quota can lead to denial of access

Removable Media

- access control at file system level makes no sense
 - other computers may choose to ignore permissions
 - user names or id's would not make sense anyway
- option 1: encryption (for denying reads)
- option 2: hardware-level controls
 - usually read-only vs read-write on the entire medium

The chroot System Call

- each process in UNIX has its own root directory
 - for most, this coincides with the system root
- the root directory can be changed using chroot()
- can be useful to limit file system access
 - e.g. in privilege separation scenarios

Uses of chroot

- chroot alone is not a security mechanism
 - a super-user process can get out easily
 - but not easy for a normal user process
- also useful for diagnostic purposes
- and as lightweight alternative to virtualisation

Part 11.3: Sub-User Granularity

Users are Not Enough

- users are not always the right abstraction
 - creating users is relatively expensive
 - only a super-user can create new users
- you may want to include programs as subjects
 - or rather, the combination user + program

Naming Programs

- users have user names, but how about programs?
- option 1: cryptographic signatures
 - portable across computers but complex
 - establishes identity based on the program itself
- option 2: i-node of the executable
 - simple, local, identity based on location

Program as a Subject

- program: passive (file) vs active (processes)
 - only a process can be a subject
 - but program identity is attached to the file
- rights of a process depend on its program
 - exec() will change privileges

Mandatory Access Control

- delegates permission control to a central authority
- often coupled with security labels
 - classifies subjects (users, processes)
 - and also objects (files, sockets, programs)
- the owner cannot change object permissions

Capabilities

- not all verbs (actions) need to take objects
- e.g. shutting down the computer (there is only one)
- mounting file systems (they can't be always named)
- listening on ports with number less than 1024

Dismantling the root User

- the traditional root user is all-powerful
 - "all or nothing" is often unsatisfactory
 - violates the principle of least privilege
- many special properties of root are capabilities
 - root then becomes the user with all capabilities
 - other users can get selective privileges

Security and Execution

- security hinges on what is allowed to execute
- arbitrary code execution are the worst exploits
 - this allows unauthorized execution of code
 - same effect as impersonating the user
 - almost as bad as stolen credentials

Untrusted Input

- programs often process data from dubious sources
 - think image viewers, audio & video players
 - archive extraction, font rendering, ...
- bugs in programs can be exploited
 - the program can be tricked into executing data

Process as a Subject

- some privileges can be tied to a particular process
 - those only apply during the lifetime of the process
 - often restrictions rather than privileges
 - this is how privilege dropping is done
- processes are identified using their numeric pid
 - restrictions are inherited across fork()

Sandboxing

- tries to limit damage from code execution exploits
- the program drops all privileges it can
 - this is done before it touches any of the input
 - the attacker is stuck with the reduced privileges
 - this can often prevent a successful attack

Untrusted Code

- traditionally, you would only execute trusted code
 - usually based on reputation or other external factors
 - this does not scale to a large number of vendors
- it is common to execute untrusted, even dubious code
 - this can be okay with sufficient sandboxing

API-Level Access Control

- capability system for user-level resources
 - things like contact lists, calendars, bookmarks
 - objects not provided directly by the kernel
- enforcement e.g. via a virtual machine
 - not applicable to execution of native code
 - alternative: an IPC-based API

Android/iOS Permissions

- applications from a store are semi-trusted
- typically single-user computers/devices
- permissions are attached to apps instead of users
- partially virtual users, partially API-level

Review Questions

- 37. What is a user?
- 38. What is the principle of least privilege?
- 39. What is an access control object?
- 40. What is a sandbox?

Part 12: Virtualisation & Containers

Lecture Overview

- 1. Hypervisors
- 2. Containers
- 3. Management

Part 12.1: Hypervisors

What is a Hypervisor

- also known as a Virtual Machine Monitor
- allows execution of multiple operating systems
- like a kernel that runs kernels
- improves hardware utilisation

Motivation

- · OS-level sharing is tricky
 - user isolation is often insufficient
 - only root can install software
- the hypervisor/OS interface is simple
 - compared to OS-application interfaces

Virtualisation in General

- many resources are "virtualised"
 - physical memory by the MMU
 - peripherals by the OS
- makes resource management easier
- enables isolation of components

Hypervisor Types

- type 1: bare metal
 - standalone, microkernel-like
- type 2: hosted
 - runs on top of normal OS
 - usually need kernel support

Type 1 (Bare Metal)

- IBM z/VM
- (Citrix) Xen
- Microsoft Hyper-V
- VMWare ESX

Type 2 (Hosted)

- VMWare (Workstation, Player)
- Oracle VirtualBox
- Linux KVM
- FreeBSD bhyve
- OpenBSD vmm

History

- started with mainframe computers
- IBM CP/CMS: 1968
- IBM VM/370: 1972
- IBM z/VM: 2000

Desktop Virtualisation

- x86 hardware lacks virtual supervisor mode
- software-only solutions viable since late 90s
 - Bochs: 1994
 - VMWare Workstation: 1999
 - QEMU: 2003

Paravirtualisation

- introduced as VMI in 2005 by VMWare
- alternative approach in Xen in 2006
- relies on modification of the guest OS
- near-native speed without HW support

The Virtual x86 Revolution

- 2005: virtualisation extensions on x86
- 2008: MMU virtualisation
- unmodified guest at near-native speed
- most software-only solutions became obsolete

Paravirtual Devices

- special drivers for virtualised devices
 - block storage, network, console
 - random number generator
- faster than software emulation
 - orthogonal to CPU/MMU virtualisation

Virtual Computers

- · usually known as Virtual Machines
- · everything in the computer is virtual
 - either via hardware (VT-x, EPT)
 - or software (QEMU, virtio, ...)
- much easier to manage than actual hardware

Essential Resources

- the CPU and RAM
- persistent (block) storage
- network connection
- a console device

CPU Sharing

- same principle as normal processes
- there is a scheduler in the hypervisor
 - simpler, with different trade-offs
- privileged instructions are trapped

RAM Sharing

- · very similar to standard paging
- software (shadow paging)
- or hardware (second-level translation)
- fixed amount of RAM for each VM

Shadow Page Tables

- the guest system cannot access the MMU
- set up shadow table, invisible to the guest
- guest page tables are sync'd to the sPT by VMM
- the gPT can be made read-only to cause traps

Second-Level Translation

- hardware-assisted MMU virtualisation
- · adds guest-physical to host-physical layer
- greatly simplifies the VMM
- also much faster than shadow page tables

Network Sharing

- usually a paravirtualised NIC
 - transports frames between guest and host
 - usually connected to a SW bridge in the host
 - alternatives: routing, NAT
- a single physical NIC is used by everyone

Virtual Block Devices

- usually also paravirtualised
- often backed by normal files
 - maybe in a special format
 - e.g. based on copy-on-write
- but can be a real block device

Special Resources

- mainly useful in desktop systems
- GPU / graphics hardware
- audio equipment
- printers, scanners, ...

PCI Passthrough

- an anti-virtualisation technology
- based on an IO-MMU (VT-D, AMD-Vi)
- a virtual OS can touch real hardware
 - only one OS at a time, of course

GPUs and Virtualisation

- can be assigned (via VT-d) to a single OS
- or time-shared using native drivers (GVT-g)
- paravirtualised
- shared by other means (X11, SPICE, RDP)

Peripherals

- · useful either via passthrough
 - audio, webcams, ...
- · or standard sharing technology
 - network printers & scanners
 - networked audio servers

Peripheral Passthrough

- virtual PCI, USB or SATA bus
- forwarding to a real device
 - e.g. a single USB stick
 - or a single SATA drive

Suspend & Resume

- the VM can be quite easily stopped
- the RAM of a stopped VM can be copied
 - e.g. to a file in the host filesystem
 - along with registers and other state
- and also later loaded and resumed

Migration Basics

- the stored state can be sent over network
- and resumed on a different host
- as long as the virtual environment is same
- this is known as paused migration

Live Migration

- uses asynchronous memory snapshots
- host copies pages and marks them read-only
- the snapshot is sent as it is constructed
- · changed pages are sent at the end

Live Migration Handoff

- the VM is then paused
- registers and last few pages are sent
- the VM is resumed at the remote end
- usually within a few milliseconds

Memory Ballooning

- how to deallocate "physical" memory?
 - i. e. return it to the hypervisor
- this is often desirable in virtualisation
- needs a special host/guest interface

Part 12.2: Containers

What are Containers?

- OS-level virtualisation
 - e.g. virtualised network stack
 - or restricted file system access
- not a complete virtual computer
- turbocharged processes

Why Containers

- virtual machines take a while to boot
- each VM needs its own kernel
 - this adds up if you need many VMs
- easier to share memory efficiently
- easier to cut down the OS image

Kernel Sharing

- multiple containers share a single kernel
- but not user tables, process tables, ...
- the kernel must explicitly support this
- another level of isolation (process, user, container)

Boot Time

- a light virtual machine takes a second or two
- a container can take under 50ms
- but VMs can be suspended and resumed
- but dormant VMs take up a lot more space

chroot

- the mother of all container systems
- not very sophisticated or secure
- but allows multiple OS images under 1 kernel
- · everything else is shared

chroot-based Containers

- · process tables, network, etc. are shared
- · the superuser must also be shared
- containers have their own view of the filesystem
 - including system libraries and utilities

BSD Jails

- an evolution of the chroot container
- adds user and process table separation
- and a virtualised network stack
 - each jail can get its own IP address
- root in the jail has limited power

Linux VServer

- like BSD jails but on Linux
 - FreeBSD jail 2000, VServer 2001
- not part of the mainline kernel
- jailed root user is partially isolated

Namespaces

- · visibility compartments in the Linux kernel
- virtualizes common resources
 - the filesystem hierarchy (including mounts)
 - process tables
 - networking (IP address)

cgroups

- controls resource allocation in Linux
- a CPU group is a fair scheduling unit
- a memory group sets limits on memory use
- mostly orthogonal to namespaces

LXC

- mainline Linux way to do containers
- based on namespaces and cgroups
- relative newcomer (2008, 7 years after vserver)
- feature set similar to VServer, OpenVZ &c.

User-Mode Linux

- halfway between a container and a virtual machine
- an early fully paravirtualised system
- a Linux kernel runs as a process on another Linux
- integrated in Linux 2.6 in 2003

DragonFlyBSD Virtual Kernels

- very similar to User-Mode Linux
- part of DFlyBSD since 2007
- uses standard libc, unlike UML
- paravirtual ethernet, storage and console

User Mode Kernels

- · easier to retrofit securely
 - uses existing security mechanisms
 - for the host, mostly a standard process
- the kernel needs to be ported though
 - analogous to a new hardware platform

Migration

- not widely supported, unlike in hypervisors
- process state is much harder to serialise
 - file descriptors, network connections &c.
- somewhat mitigated by fast shutdown/boot time

Part 12.3: Management

Disk Images

- disk image is the embodiment of the VM
- the virtual OS needs to be installed
- the image can be a simple file
- or a dedicated block device on the host

Snapshots

- making a copy of the image = snapshot
- can be done more efficiently: copy on write
- alternative to OS installation
 - make copies of the freshly installed image
 - and run updates after cloning the image

Duplication

- each image will have a copy of the system
- copy-on-write snapshots can help
 - most of the base system will not change
 - regression as images are updated separately
- · block-level de-duplication is expensive

File Systems

- disk images contain entire file systems
- the virtual disk is of (apparently) fixed size
- sparse images: unwritten area is not stored
- initially only filesystem metadata is allocated

Overcommit

- the host can allocate more resources than it has
- this works as long as not many VMs reach limits
- enabled by sparse images and CoW snapshots
- · also applies to available RAM

Thin Provisioning

- the act of obtaining resources on demand
- the host system can be extended as needed
 - to keep pace with growing guest demands
- alternatively, VMs can be migrated out
- improves resource utilisation.

Configuration

- each OS has its own configuration files
- same methods apply as for physical networks
 - software configuration management
- bundled services are deployed to VMs

Bundling vs Sharing

- · bundling makes deployment easier
- the bundled components have known behaviour
- · but updates are much trickier
- this also prevents resource sharing

Security

- · hypervisors have a decent track record
 - security here means protection of host from guest
 - breaking out is still possible sometimes
- containers are more of a mixed bag
 - many hooks are needed into the kernel

Updates

- each system needs to be updated separately
 - this also applies to containers
- · blocks coming from a common ancestor are shared
 - but updating images means loss of sharing

Container vs VM Updates

- de-duplication may be easier in containers
 - shared file system e.g. link farming
- kernel updates: containers and type 2 hypervisors
 - can be mitigated by live migration
- type 1 hypervisors need less downtime

Docker

- · automated container image management
- mainly a service deployment tool
- containers share a single Linux kernel
 - the kernel itself can run in a VM
- · rides on a wave of bundling resurgence

The Cloud

- public virtualisation infrastructure
- "someone else's computer"
- the guests are not secure against the host
 - entire memory is exposed, including secret keys
 - host compromise is fatal
- the host is mostly secure from the guests

Review Questions

- 41. What is a hypervisor?
- 42. What is paravirtualisation?
- 43. How are VMs suspended and migrated?
- 44. What is a container?

Part 13: Review

What is an OS made of?

- the kernel
- system libraries
- system daemons / services
- user interface
- system utilities

Basically every OS has those.

The Kernel

- lowest level of an operating system
- executes in privileged mode
- manages all the other software
 - including other OS components
- enforces isolation and security
- · provides low-level services to programs

System Libraries

- form a layer above the OS kernel
- provide higher-level services
 - use kernel services behind the scenes
 - easier to use than the kernel interface
- typical example: libc
 - provides C functions like printf
 - also known as msvcrt on Windows

Programming Interfaces

- kernel system call interface
- system libraries / APIs
- inter-process protocols
- command-line utilities (scripting)

(System) Libraries

- mainly C functions and data types
- interfaces defined in header files
- definitions provided in libraries
 - static libraries (archives): libc.a
 - shared (dynamic) libraries: libc.so
- on Windows: msvcrt.lib and msvcrt.dll
- there are (many) more besides libc / msvcrt

Shared (Dynamic) Libraries

- required for running programs
- linking is done at execution time
- less code duplication
- can be upgraded separately
- but: dependency problems

Why is Everything a File

- re-use the comprehensive file system API
- re-use existing file-based command-line tools
- bugs are bad simplicity is good
- want to print? cat file.txt > /dev/ulpt0
 - (reality is a little more complex)

What is a Filesystem?

- a set of files and directories
- usually lives on a single block device
 - but may also be virtual
- directories and files form a tree
 - directories are internal nodes
 - files are leaf nodes

File Descriptors

- the kernel keeps a table of open files
- the file descriptor is an index into this table
- you do everything using file descriptors
- non-Unix systems have similar concepts

Regular files

- these contain sequential data (bytes)
- may have inner structure but the OS does not care
- there is metadata attached to files
 - like when were they last modified
 - who can and who cannot access the file
- you read() and write() files

Privileged CPU Mode

- many operations are restricted in user mode
 - this is how user programs are executed
 - also most of the operating system
- software running in privileged mode can do ~anything
 - most importantly it can program the MMU
 - the kernel runs in this mode

Memory Management Unit

- · is a subsystem of the processor
- takes care of address translation
 - user software uses virtual addresses
 - the MMU translates them to physical addresses
- the mappings can be managed by the OS kernel

What does a Kernel Do?

- memory & process management
- task (thread) scheduling
- device drivers
 - SSDs, GPUs, USB, bluetooth, HID, audio, ...
- file systems
- networking

Kernel Architecture Types

- monolithic kernels (Linux, *BSD)
- microkernels (Mach, L4, QNX, NT, ...)
- hybrid kernels (macOS)
- type 1 hypervisors (Xen)
- exokernels, rump kernels

System Call Sequence

- first, libc prepares the system call arguments
- and puts the system call number in the correct register
- then the CPU is switched into privileged mode
- this also transfers control to the syscall handler

What is an i-node?

- an anonymous, file-like object
- could be a regular file
 - or a directory
 - or a special file
 - or a symlink

Disk-Like Devices

- disk drives provide block-level access
- read and write data in 512-byte chunks
 - or also 4K on big modern drives
- · a big numbered array of blocks

I/O Scheduler (Elevator)

- reads and writes are requested by users
- access ordering is crucial on a mechanical drive
 - not as important on an SSD
 - but sequential access is still much preferred
- requests are queued (recall, disks are slow)
 - but they are not processed in FIFO order

Filesystem as Resource Sharing

- usually only 1 or few disks per computer
- many programs want to store persistent data
- file system allocates space for the data
 - which blocks belong to which file
- different programs can write to different files
 - no risk of trying to use the same block

Filesystem as Abstraction

- allows the data to be organised into files
- enables the user to manage and review data
- files have arbitrary & dynamic size
 - blocks are transparently allocated & recycled
- structured data instead of a flat block array

Memory-mapped IO

- uses virtual memory (cf. last lecture)
- treat a file as if it was swap space
- the file is mapped into process memory
 - page faults indicate that data needs to be read
 - dirty pages cause writes
- available as the mmap system call

Fragmentation

- internal not all blocks are fully used
 - files are of variable size, blocks are fixed
 - a 4100 byte file needs 2 4 KiB blocks
- external free space is non-contiguous
 - happens when many files try to grow at once
 - this means new files are also fragmented

Hard Links

- multiple names can refer to the same i-node
 - names are given by directory entries
 - we call such multiple-named files hard links
 - it's usually forbidden to hard-link directories
- hard links cannot cross device boundaries
 - i-node numbers are only unique within a filesystem

Process Resources

- memory (address space)
- processor time
- open files (descriptors)
 - also working directory
 - also network connections

Process Memory

- each process has its own address space
- this means processes are isolated from each other
- requires that the CPU has an MMU
- implemented via paging (page tables)

Process Switching

- switching processes means switching page tables
- physical addresses do not change
- but the mapping of virtual addresses does
- large part of physical memory is not mapped
 - could be completely unallocated (unused)
 - or belong to other processes

What is a Thread?

- thread is a sequence of instructions
- different threads run different instructions
 - as opposed to SIMD or many-core units (GPUs)
- each thread has its own stack
- multiple threads can share an address space

Fork

- how do we create new processes?
- by fork-ing existing processes
- fork creates an identical copy of a process
- execution continues in both processes
 - each of them gets a different return value

Process vs Executable

- process is a dynamic entity
- executable is a static file
- an executable contains an initial memory image
 - this sets up memory layout
 - and content of the text and data segments

Exec

- on UNIX, processes are created via fork
- how do we run programs though?
- exec: load a new executable into a process
 - this completely overwrites process memory
 - execution starts from the entry point
- running programs: fork + exec

What is a Scheduler?

- · scheduler has two related tasks
 - plan when to run which thread
 - actually switch threads and processes
- usually part of the kernel
 - even in micro-kernel operating systems

Interrupt

- a way for hardware to request attention
- CPU mechanism to divert execution
- partial (CPU state only) context switch
- switch to privileged (kernel) CPU mode

Timer Interrupt

- generated by the PIT or the local APIC
- the OS can set the frequency
- a hardware interrupt happens on each tick
- · this creates an opportunity for bookkeeping
- and for preemptive scheduling

What is Concurrency?

- events that can happen at the same time
- it is not important if it does, only that it can
- events can be given a happens-before partial order
- they are concurrent if unordered by happens-before

Why Concurrency?

- problem decomposition
 - different tasks can be largely independent
- reflecting external concurrency
 - serving multiple clients at once
- performance and hardware limitations
 - higher throughput on multicore computers

Critical Section

- any section of code that must not be interrupted
- the statement x = x + 1 could be a critical section
- · what is a critical section is domain-dependent
 - another example could be a bank transaction
 - or an insertion of an element into a linked list

Race Condition: Definition

- (anomalous) behaviour that depends on timing
- typically among multiple threads or processes
- an unexpected sequence of events happens
- recall that ordering is not guaranteed

Mutual Exclusion

- only one thread can access a resource at once
- ensured by a mutual exclusion device (a.k.a mutex)
- a mutex has 2 operations: lock and unlock
- lock may need to wait until another thread unlocks

Deadlock Conditions

- 1. mutual exclusion
- 2. hold and wait condition
- 3. non-preemtability
- 4. circular wait

Deadlock is only possible if all 4 are present.

Starvation

- starvation happens when a process can't make progress
- generalisation of both deadlock and livelock
- for instance, unfair scheduling on a busy system
- also recall the readers and writers problem

What is a Driver?

- piece of software that talks to a device
- usually quite specific / unportable
 - tied to the particular device
 - and also to the operating system
- often part of the kernel

Drivers and Microkernels

- drivers are excluded from microkernels
- but the driver still needs hardware access
 - this could be a special memory region
 - it may need to react to interrupts
- in principle, everything can be done indirectly
 - but this may be quite expensive, too

Interrupt-driven IO

- peripherals are much slower than the CPU
 - polling the device is expensive
- the peripheral can signal data availability
 - and also readiness to accept more data
- this frees up CPU to do other work in the meantime

Memory-mapped IO

- devices share address space with memory
- more common in contemporary systems
- IO uses the same instructions as memory access
 - load and store on RISC, mov on x86
- allows selective user-level access (via the MMU)

Direct Memory Access

- allows the device to directly read/write memory
- this is a huge improvement over programmed IO
- interrupts only indicate buffer full/empty
- the device can read and write arbitrary physical memory
 - opens up security / reliability problems

GPU Drivers

- · split into a number of components
- graphics output / frame buffer access
- memory management is often done in kernel
- geometry, textures &c. are prepared in-process
- front end API: OpenGL, Direct3D, Vulkan, ...

Storage Drivers

- split into adapter, bus and device drivers
- often a single driver per device type
 - at least for disk drives and CD-ROMs
- bus enumeration and configuration
- data addressing and data transfers

Networking Layers

- 2. Link (Ethernet, WiFi)
- 3. Network (IP)
- 4. Transport (TCP, UDP, ...)
- 7. Application (HTTP, SMTP, ...)

Networking and Operating Systems

- a network stack is a standard part of an OS
- large part of the stack lives in the kernel
 - although this only applies to monolithic kernels
 - microkernels use user-space networking
- another chunk is in system libraries & utilities

Kernel-Side Networking

- device drivers for networking hardware
- network and transport protocol layers
- routing and packet filtering (firewalls)
- networking-related system calls (sockets)
- network file systems (SMB, NFS)

IP (Internet Protocol)

- uses 4 byte (v4) or 16 byte (v6) addresses
 - split into network and host parts
- it is a packet-based protocol
- is a best-effort protocol
 - packets may get lost, reordered or corrupted

TCP: Transmission Control Protocol

- a stream-oriented protocol on top of IP
- works like a pipe (transfers a byte sequence)
 - must respect delivery order
 - and also re-transmit lost packets
- must establish connections

UDP: User (Unreliable) Datagram Protocol

- TCP comes with non-trivial overhead
 - and its guarantees are not always required
- UDP is a much simpler protocol
 - a very thin wrapper around IP
 - with minimal overhead on top of IP

DNS: Domain Name Service

- hierarchical protocol for name resolution
 - runs on top of TCP or UDP
- domain names are split into parts using dots
 - each domain knows whom to ask for the next bit
 - the name database is effectively distributed

NFS (Network File System)

- the traditional UNIX networked filesystem
- hooked quite deep into the kernel
 - assumes generally reliable network (LAN)
- filesystems are exported for use over NFS
- the client side mounts the NFS-exported volume

Shell

- programming language centered on OS interaction
- rudimentary control flow
- untyped, text-centered variables
- · dubious error handling

Interactive Shells

- almost all shells have an interactive mode
- the user inputs a single statement on keyboard
- when confirmed, it is immediately executed
- this forms the basis of command-line interfaces

Shell Scripts

- a shell script is an (executable) file
- in simplest form, it is a sequence of commands
 - each command goes on a separate line
 - executing a script is about the same as typing it
- but can use structured programming constructs

Terminal

- can print text and read text from a keyboard
- normally everything is printed on the last line
- the text could contain escape (control) sequences
 - for printing colourful text or clearing the screen
 - also for printing text at a specific coordinate

A GUI Stack

- graphics card driver, mode setting
- drawing/painting (usually hardware-accelerated)
- multiplexing (e.g. using windows)
- widgets: buttons, labels, lists, ...
- layout: what goes where on the screen

X11 (X Window System)

- a traditional UNIX windowing system
- provides a C API (xlib)
- built-in network transparency (socket-based)
- core protocol version 11 from 1987

Users

- originally a proxy for people
- currently a more general abstraction
- user is the unit of ownership
- many permissions are user-centered

User Management

- the system needs a database of users
- in a network, user identities often need to be shared
- could be as simple as a text file
 - /etc/passwd and /etc/group on UNIX systems
- or as complex as a distributed database

User Authentication

- the user needs to authenticate themselves
- passwords are the most commonly used method
 - the system needs to know the right password
 - user should be able to change their password
- biometric methods are also quite popular

Ownership

- various objects in an OS can be owned
 - primarily files and processes
- the owner is typically whoever created the object
 - ownership can be transferred
 - usually at the impetus of the original owner

Access Control Policy

- there are 3 pieces of information
 - the subject (user)
 - the verb (what is to be done)
 - the object (the file or other resource)
- there are many ways to encode this information

Sandboxing

- tries to limit damage from code execution exploits
- the program drops all privileges it can
 - this is done before it touches any of the input
 - the attacker is stuck with the reduced privileges
 - this can often prevent a successful attack

What is a Hypervisor

- also known as a Virtual Machine Monitor
- allows execution of multiple operating systems
- like a kernel that runs kernels
- isolation and resource sharing

Hypervisor Types

- type 1: bare metal
 - standalone, microkernel-like
- type 2: hosted
 - runs on top of normal OS
 - usually need kernel support

Paravirtual Devices

- special drivers for virtualised devices
 - block storage, network, console
 - random number generator
- faster than software emulation
 - orthogonal to CPU/MMU virtualisation

VM Suspend & Resume

- the VM can be quite easily stopped
- the RAM of a stopped VM can be copied
 - e.g. to a file in the host filesystem
 - along with registers and other state
- and also later loaded and resumed

What are Containers?

- OS-level virtualisation
 - e.g. virtualised network stack
 - or restricted file system access
- not a complete virtual computer
- turbocharged processes

Bundling vs Sharing

- bundling makes deployment easier
- the bundled components have known behaviour
- but updates are much trickier
- this also prevents resource sharing

The End

Actually...

- a 2-part, written final exam
- test: 9/10 required
 - pool of 44 questions (in the slides)
- free-form text
 - one of the 11 lecture topics
 - 1 page A4: be concise but comprehensive