Probability

PA154 Jazykové modelování (1.2)

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Source: Introduction to Natural Language Processing (600.465) Jan Hajič, CS Dept., Johns Hopkins Univ. www.cs.jhu.edu/~hajic

Events

- Event (jev) A is a set of basic outcomes
- Usually A $\subset \Omega$, and all A $\in 2^{\Omega}$ (the event space, jevové pole)
 - Ω is the certain event (jistý jev), \emptyset is the impossible event (nemožný jev)
- Example:
 - experiment: three times coin toss
 - $\Omega = \{HHH, HHT, HTH, HTT, THH, THT, TTH, TTT\}$
 - ▶ count cases with exactly two tails: then
 - ► A = {HTT, THT, TTH}
 - ► all heads:
 - ► A = {HHH}

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Estimating Probability

- Remember: ... close to an unknown constant.
- We can only estimate it:
 - ▶ from a single series (typical case, as mostly the outcome of a series is given to us we cannot repeat the experiment):

$$p(A) = \frac{c_1}{T_1}$$

- ightharpoonup otherwise, take the weighted average of all $\frac{c_i}{T_i}$ (or, if the data allows, simply look at the set of series as if it is a single long series).
- This is the **best** estimate.

Experiments & Sample Spaces

- Experiment, process, test, . . .
- Set of possible basic outcomes: sample space Ω (základní prostor obsahující možné výsledky)
 - coin toss ($\Omega = \{\text{head, tail}\}\)$, die ($\Omega = \{1..6\}$)
 - yes/no opinion poll, quality test (bad/good) ($\Omega = \{0,1\}$)
 - ▶ lottery ($|\Omega| \cong 10^7..10^{12}$)
 - # of traffic accidents somewhere per year ($\Omega = N$)
 - lacktriangle spelling errors $(\Omega=Z^*)$, where Z is an aplhabet, and Z^* is set of possible strings over such alphabet
 - ▶ missing word ($|\Omega|$ \cong vocabulary size)

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Probability

- Repeat experiment many times, record how many times a given event A occured ("count" c_1).
- Do this whole series many times; remember all c_i s.
- Observation: if repeated really many times, the ratios of $\frac{c_i}{T_i}$ (where T_i is the number of experiments run in the *i-th* series) are close to some (unknown but) constant value.
- Call this constant a **probability of A**. Notation: **p(A)**

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Example

- Recall our example:
 - experiment: three times coin toss
 - $\Omega = \{HHH, HHT, HTH, HTT, THH, THT, TTH, TTT\}$
 - ► count cases with exactly two tails: *A* = {*HTT*, *THT*, *TTH*}
- Run an experiment 1000 times (i.e. 3000 tosses)
- Counted: 386 cases with two tails (HTT, THT or TTH)
- \blacksquare estimate: p(A) = 386/1000 = .386
- Run again: 373, 399, 382, 355, 372, 406, 359
 - ▶ p(A) = .379 (weighted average) or simply 3032/8000
- *Uniform* distribution assumption: p(A) = 3/8 = .375

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Basic Properties

■ Basic properties:

- $\begin{array}{ll} \blacktriangleright & p \colon \, 2^\Omega \to [0,1] \\ \blacktriangleright & p(\Omega) = 1 \end{array}$
- ▶ Disjoint events: $p(\cup A_i) = \sum_i p(A_i)$
- NB: <u>axiomatic definiton</u> of probability: take the above three conditions as axioms
- Immediate consequences:
 - ► P(∅) = 0
 - $ightharpoonup p(\overline{A}) = 1 p(A)$
 - ► $A \subseteq B \Rightarrow p(A) \le P(B)$ ► $\sum_{a \in \Omega} p(a) = 1$

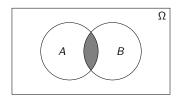
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Bayes Rule

- p(A,B) = p(B,A) since $p(A \cap B) = p(B \cap A)$
 - ▶ therefore p(A|B)p(B) = p(B|A)p(A), and therefore:

Bayes Rule

$$p(A|B) = \frac{p(B|A) \times p(A)}{p(B)}$$



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Chain Rule

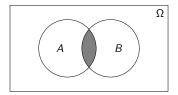
$$p(A_1, A_2, A_3, A_4, \dots, A_n) = p(A_1|A_2, A_3, A_4, \dots, A_n) \times p(A_2|A_3, A_4, \dots, A_n) \times p(A_3|A_4, \dots, A_n) \times \dots \times p(A_{n-1}|A_n) \times p(A_n)$$

■ this is a direct consequence of the Bayes rule.

Joint and Conditional Probability

- $p(A,B) = p(A \cap B)$
- $p(A|B) = \frac{p(A,B)}{p(B)}$
 - ► Estimating form counts:

$$p(A|B) = \frac{p(A,B)}{p(B)} = \frac{\frac{c(A \cap B)}{T}}{\frac{c(B)}{T}} = \frac{c(A \cap B)}{c(B)}$$



Independence

- Can we compute p(A,B) from p(A) and p(B)?
- Recall from previous foil:

$$p(A|B) = \frac{p(B|A) \times p(A)}{p(B)}$$

$$p(A|B) \times p(B) = p(B|A) \times p(A)$$

$$p(A, B) = p(B|A) \times p(A)$$

- ... we're almost there: how p(B|A) relates to p(B)?
 - p(B|A) = p(B) iff A and B are **independent**
- Example: two coin tosses, weather today and weather on March 4th
- Any two events for which p(B|A) = P(B)!

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The Golden Rule of Classic Statistical NLP

- Interested in an event A given B (where it is not easy or practical or desirable) to estimate p(A|B):
- take Bayes rule, max over all Bs:
- $= \underset{\underline{}}{\operatorname{argmax}_{A}} p(A|B) = \underset{\underline{}}{\operatorname{argmax}_{A}} \frac{p(B|A) \times p(A)}{p(B)} =$

 $argmax_A(p(B|A) \times p(A))$

■ ...as p(B) is constant when changing As

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Random Variables

■ is a function $X : \Omega \rightarrow Q$

▶ in general $Q = R^n$, typically R

• easier to handle real numbers than real-world events

 \blacksquare random variable is *discrete* if Q is <u>countable</u> (i.e. also if <u>finite</u>)

■ Example: die: natural "numbering" [1,6], coin: {0,1}

■ Probability distribution:

• $p_X(x) = p(X = x) =_{df} p(A_x)$ where $A_x = \{a \in \Omega : X(a) = x\}$

• often just p(x) if it is clear from context what X is

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Standard Distributions

- Binomial (discrete)
 - ▶ outcome: 0 or 1 (thus binomial)
 - ► make *n* trials
 - ightharpoonup interested in the (probability of) numbers of successes r
- Must be careful: it's not uniform!
- $p_b(r|n) = \frac{\binom{n}{r}}{2^n}$ (for equally likely outcome)
- $lackbox{ } \binom{n}{r}$ counts how many possibilities there are for choosing r objects out of n;

Expectation

Joint and Conditional Distributions

■ is a mean of a random variable (weighted average)

$$\blacktriangleright E(X) = \sum_{x \in X(\Omega)} x.p_X(x)$$

- Example: one six-sided die: 3.5, two dice (sum): 7
- Joint and Conditional distribution rules:
 - ► analogous to probability of events
- Bayes: $p_{X|Y}(x,y) =_{notation} p_{XY}(x|y) =_{even simpler notation}$

$$p(x|y) = \frac{p(y|x).p(x)}{p(y)}$$

■ Chain rule: p(w,x,y,z) = p(z).p(y|z).p(x|y,z).p(w|x,y,z)

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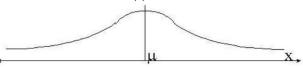
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Continuous Distributions

■ The normal distribution ("Gaussian")

$$p_{norm}(x|\mu,\sigma) = exp \begin{bmatrix} \frac{-(x-\mu)^2}{2\sigma^2} \\ \frac{\sigma\sqrt{2\pi}}{\sigma} \end{bmatrix}$$

- where:
 - lacksquare μ is the mean (x-coordinate of the peak) (0)
 - lacktriangledown σ is the standard deviation (1)



■ other: hyperbolic, t

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