

A Couple of Systems Biological Stories told by Formal Methods

David Šafránek



Masaryk University
Czech Republic

- 1 Introduction and Motivation
- 2 Methodology
 - Biological Networks
 - Modelling Problems
- 3 Story I: Signalling Pathways of Fibroblast Growth Factors
- 4 Story II: Synthetic Biology: Trichloropropane Degradation

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Biology

- since ancient times
- **empirically** studies **life** and **living organisms**
- studied aspects: structure, **function**, growth, development and evolution
- used concepts:
 - the **cell** – the unit of life
 - the **gene** – the unit of inherited **information**
 - the **evolution** – the mechanism of species creation

Biophysics and Theoretical Biology

Domain Roots

Biophysics

- since the mid of 19th century
- living organism = open (thermodynamic) **system**
- the goal: **why** and **how** the living matter works?
- uses mathematical apparatus
- a fascinating phenomenon: homeostasis
 - maintain a **stable condition** in a **changing environment**
 - **robust** (up-to certain limits)

Motivation: Rigorously Answer Biological Questions

- biology is goal-oriented
- biological problems typically address complex processes

Examples of biological problems

How the bacteria cell **utilises** particular nutritions?

Which nutritions imply fastest **growth** under given conditions?

Motivation: Rigorously Answer Biological Questions

- biology is goal-oriented
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Examples of biological problems

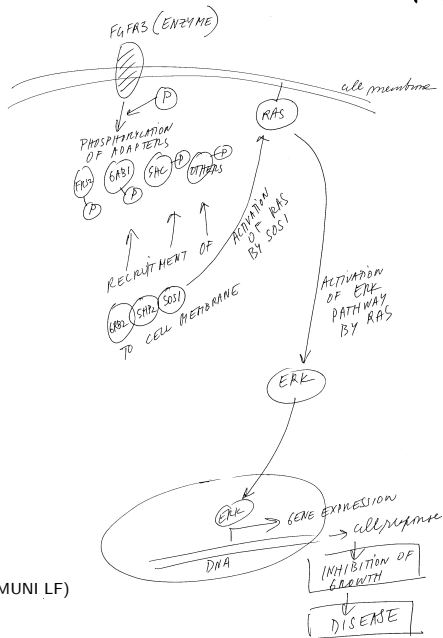
How the bacteria cell **utilises** particular nutritions?

Which nutritions imply fastest **growth** under given conditions?

The answer should fulfil specific requirements

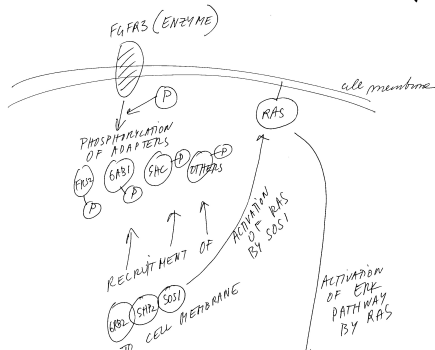
- to formulate and analyse a biological problem **holistically**
- to give mechanistic explanation based on known facts –
mechanistic means in the context of laws of physics/chemistry
- to project the mechanistic details onto the genetic information

From Biologist's Table



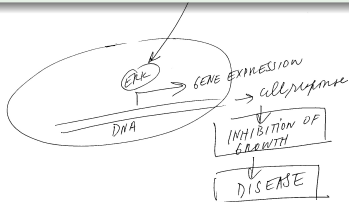
slide credits: Pavel Krejčí (MUNI LF)

From Biologist's Table



Biological Problem

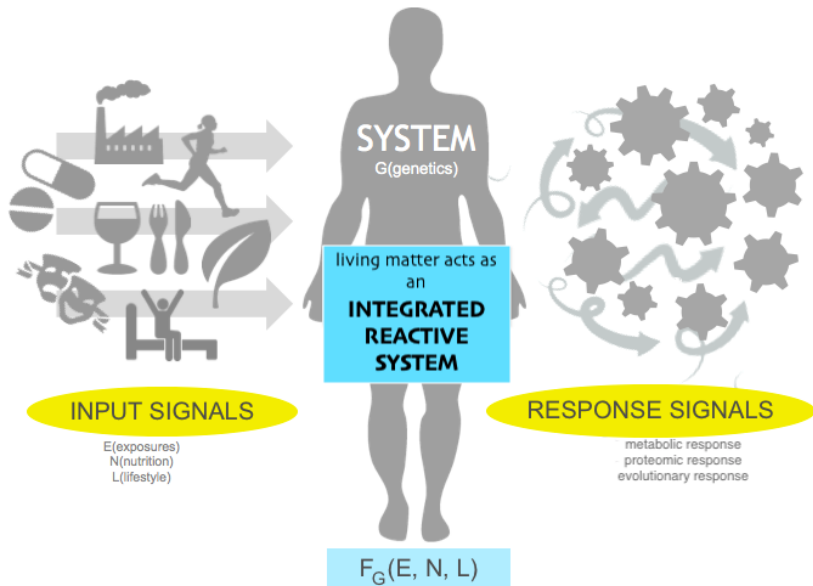
Why a human fibroblast cell misinterprets a certain growth factor?



slide credits: Pavel Krejčí (MUNI LF)

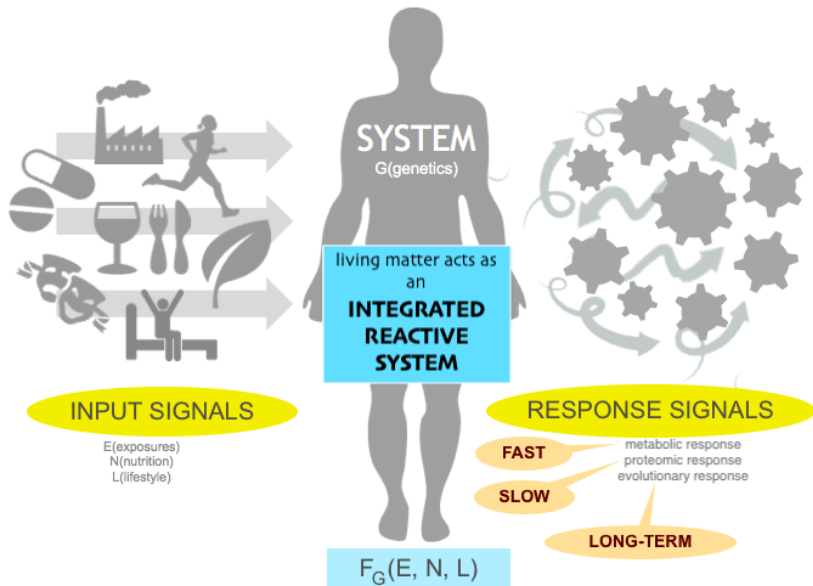
Systems Approach: The Grand Challenge

Complex Organism as a System



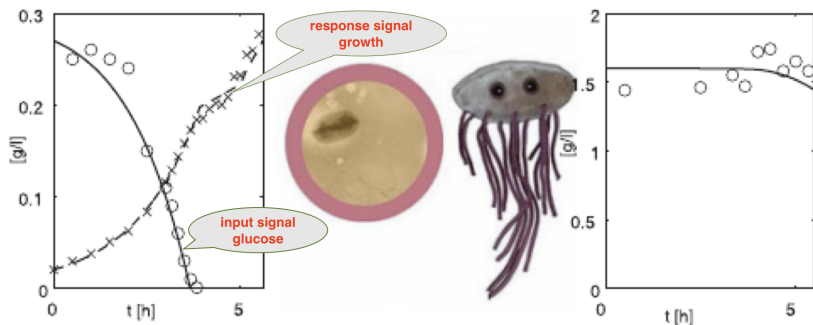
Systems Approach: The Grand Challenge

Complex Organism as a System



Systems Approach: A Moderate Challenge

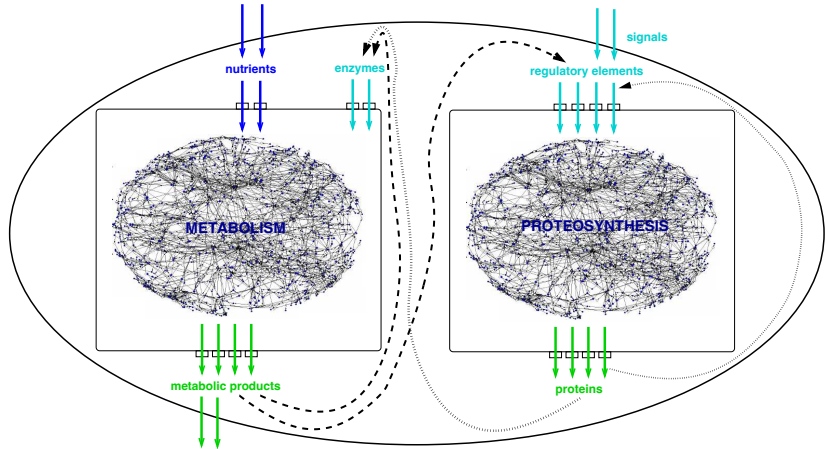
Population of Bacteria as a System



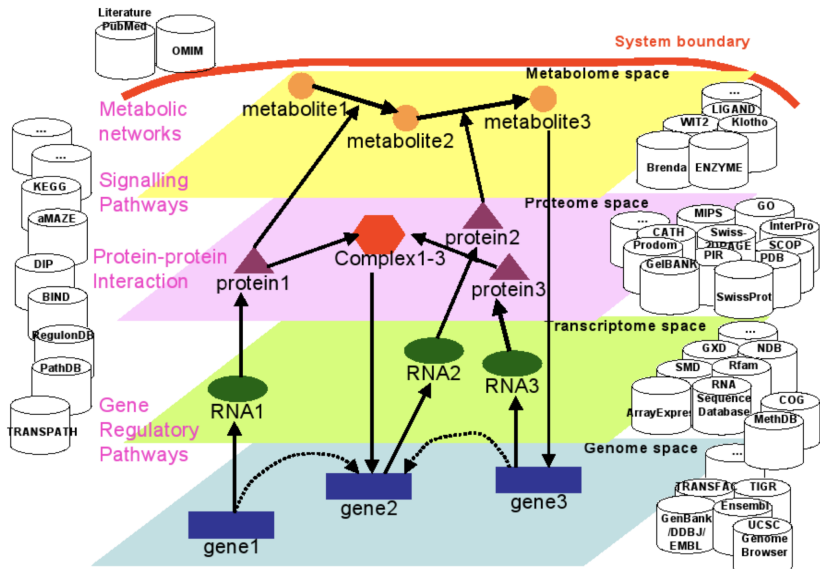
for a particular set of genes G

F_G : (environment exposure, nutrition) \rightarrow growth profile

Systems View of Processes Driving the Cell



The Cell as a Complex Interaction Network



slide credits: David Gilbert (Brunel Univ.)

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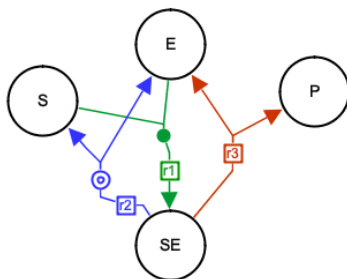
Assumptions

- The biological reality (a biophysical process) is understood as a **biological system**.
- A biological system is given as a **network** \mathcal{N} of biochemical **components** connected by chemical/physical **interactions**.
- The components include relevant genes and gene products.

Biological Networks

CRNs

- basic form: **chemical reaction networks (CRNs)**
 - elementary chemical reactions
 - represent the flow of the mass
- example:

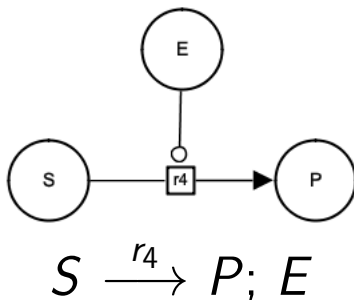


SBGN standard notation, see <https://www.sbgn.org>

Biological Networks

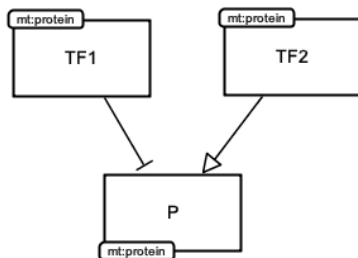
Reaction-Influence Networks

- simplified form: **reaction-influence networks (RINs)**
 - chemical reactions influenced by other molecules
 - represent the modulated flow of the mass
- example:



SBGN standard notation, see <https://www.sbgm.org>

- abstract form: **influence networks (INs)**
 - represent positive/negative influences among molecules
 - well fit incomplete knowledge
 - typically gene regulatory networks, signalling pathways
- example:



The Goal of Computational Systems Biology

The General Goal

For a biological system given by a network \mathcal{N} **reconstruct** the system's **dynamics**:

*Define a function that encodes the information (signal) processing occurring in **all** components of the system in time.*

$$F_{\mathcal{N}} : (\text{input stimuli, environment signals}) \rightarrow \text{response signals}$$

Modelling Frameworks

state-transition systems

states: discrete molecule numbers or qualities (on/off)

qualitative model

abstraction

abstraction

abstracted
time
modeled

stochastic model

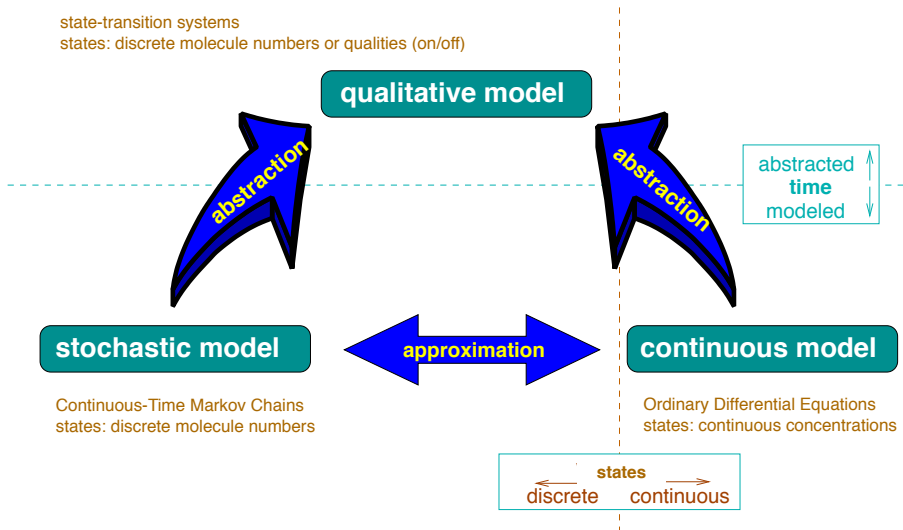
Continuous-Time Markov Chains
states: discrete molecule numbers

approximation

continuous model

Ordinary Differential Equations
states: continuous concentrations

states
discrete ← → continuous



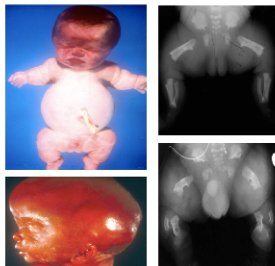
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Why to model?

Achondroplasia



Thanatophoric Dysplasia



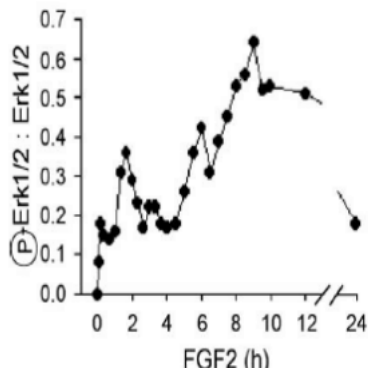
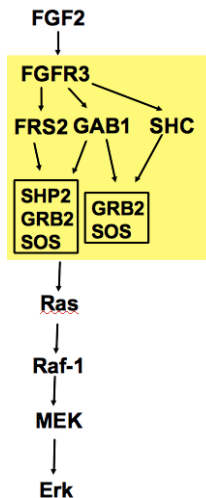
- short long bones
- brachydactyly
- macrocephaly
- low nasal bridge
- spinal stenosis
- temporal lobe malformations

Nat Genet 1995, 9:321-8.

e.g., FGFR3-related skeletal dysplasia

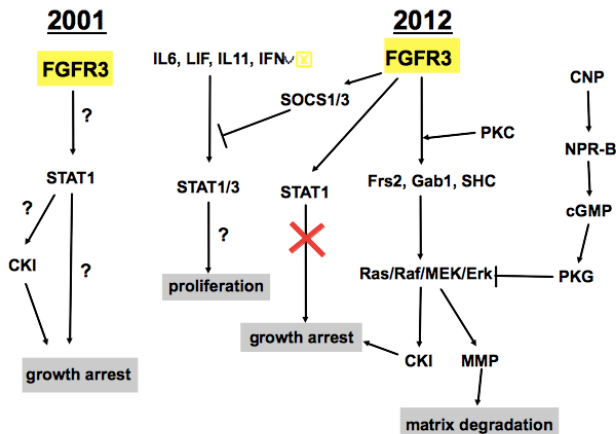
Why to model?

Need to explain...



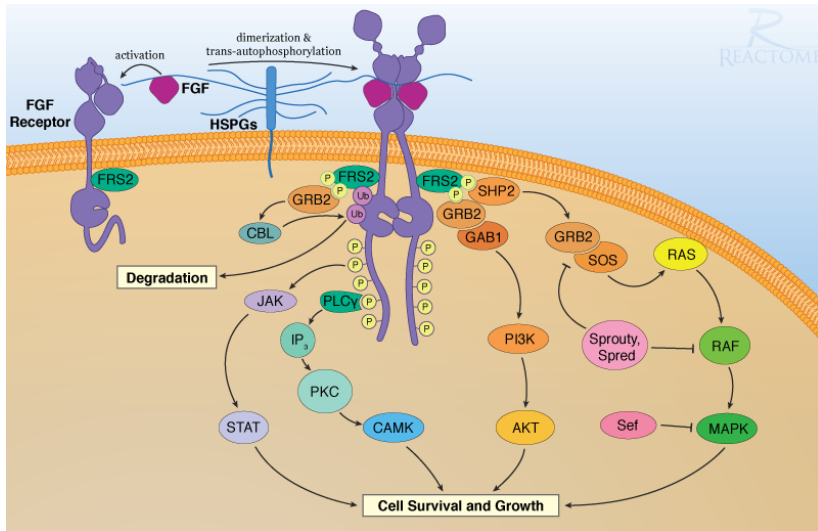
Why to model?

Try to fill in the unknown information...



Current State of Knowledge

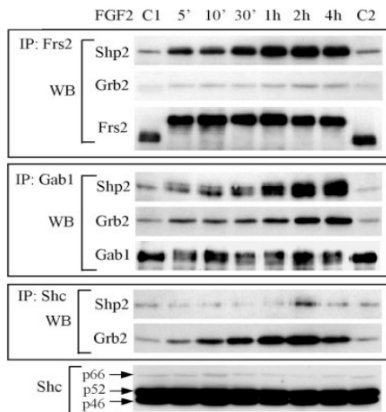
Reactome Database



also available in SBGN on Reactome.org

Wet-lab Measurements

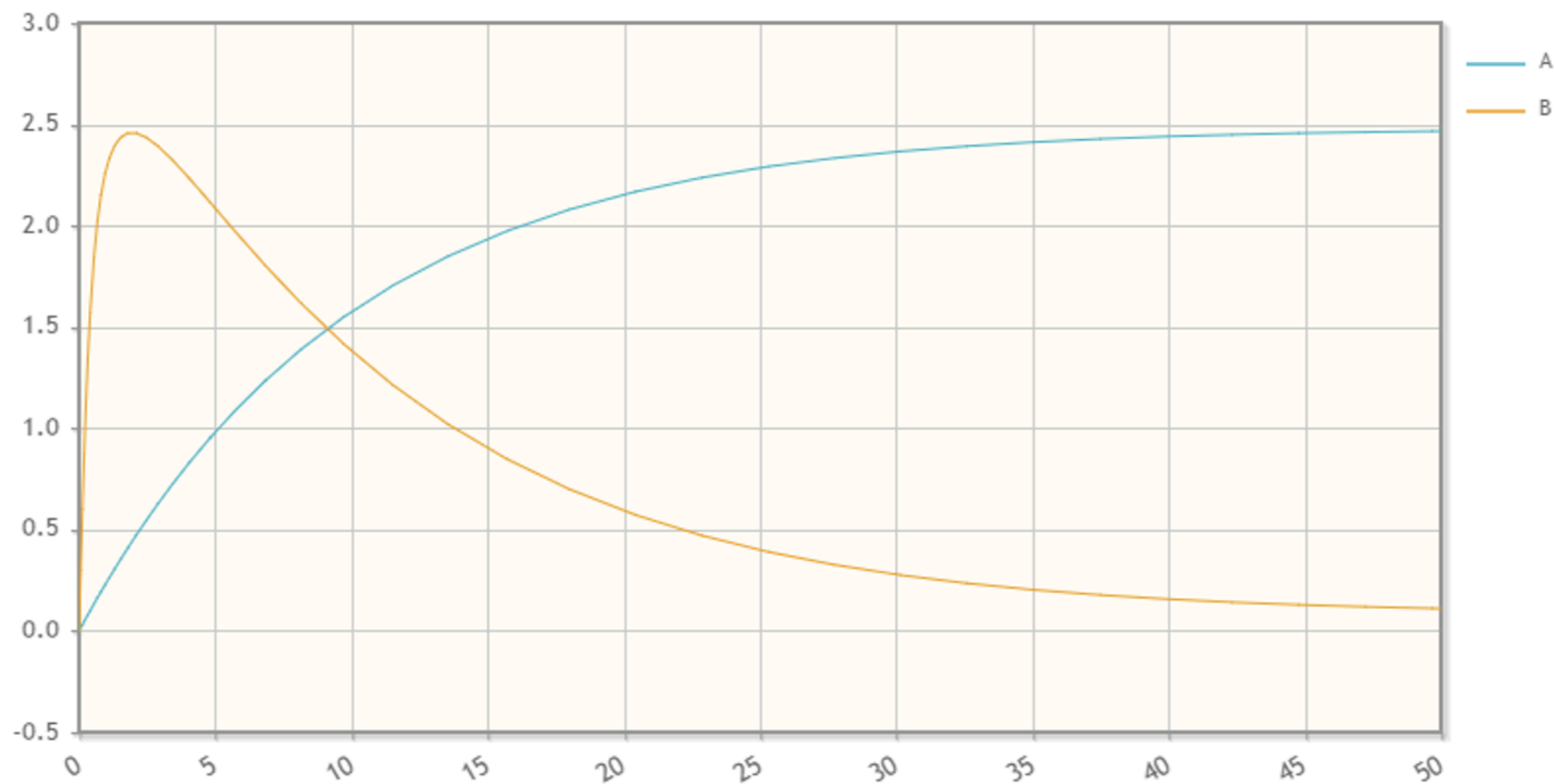
- western blots
- measurements of protein binding (presence of certain proteins)



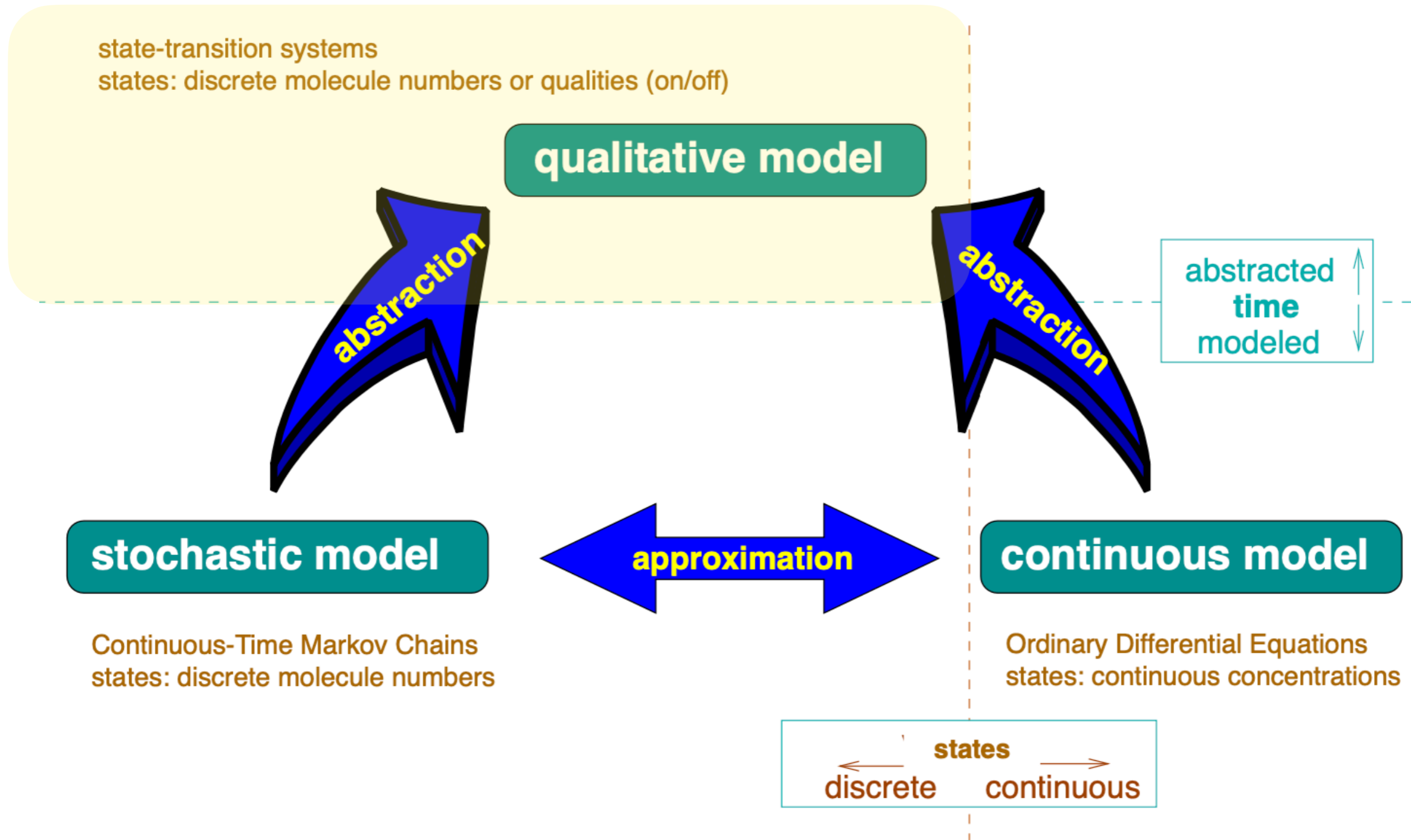
Signal Response Modes

Transient vs. Sustained Effector Activation

- In both cases we assume constantly active growth factor (FGF)
- Pathological cells display sustained response (A)
- Healthy cells display non-monotonous response (B)

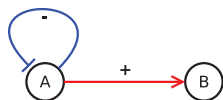


Modelling Frameworks



Model Construction

Qualitative View of Influence Nets – Discrete Regulatory Networks



$$A \in \{0, 1, 2\}, B \in \{0, 1\}$$

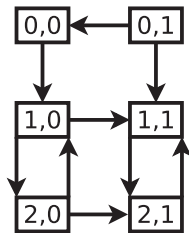
$$t_{AA} = 2, t_{AB} = 1$$

$$K_{A, \emptyset} = 2$$

$$K_{A, \{A\}} = 0$$

$$K_{B, \emptyset} = 0$$

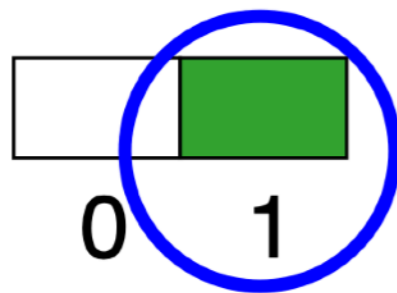
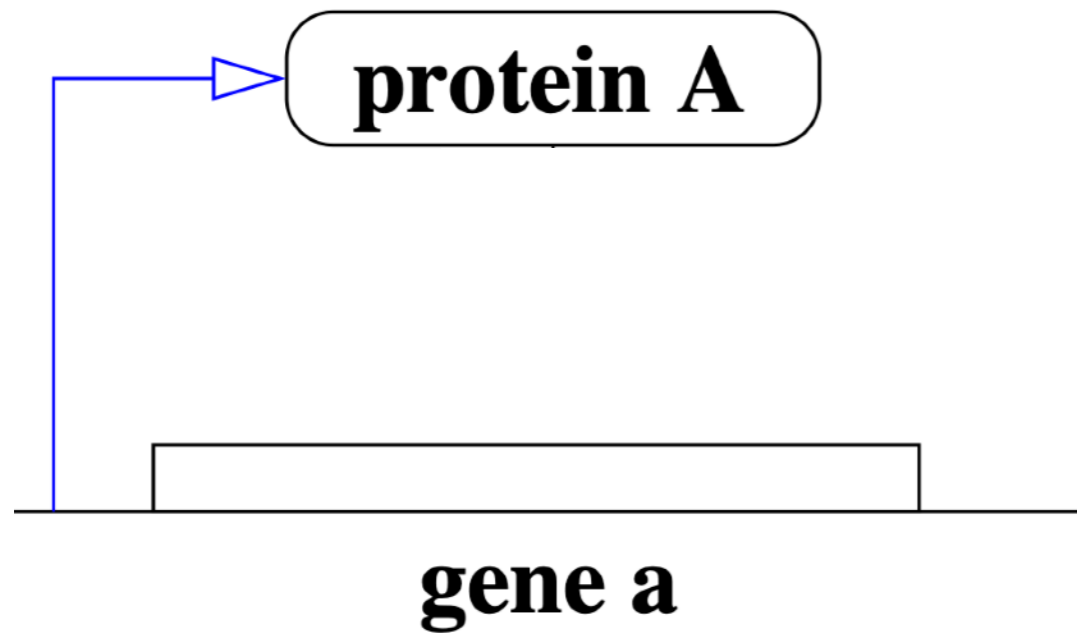
$$K_{B, \{A\}} = 1$$



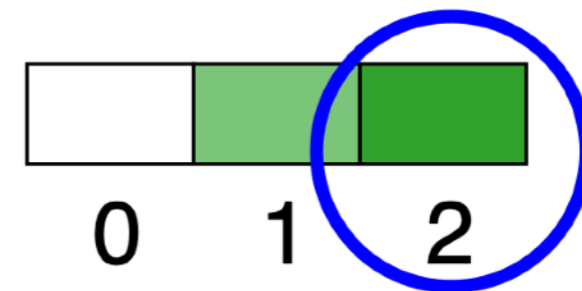
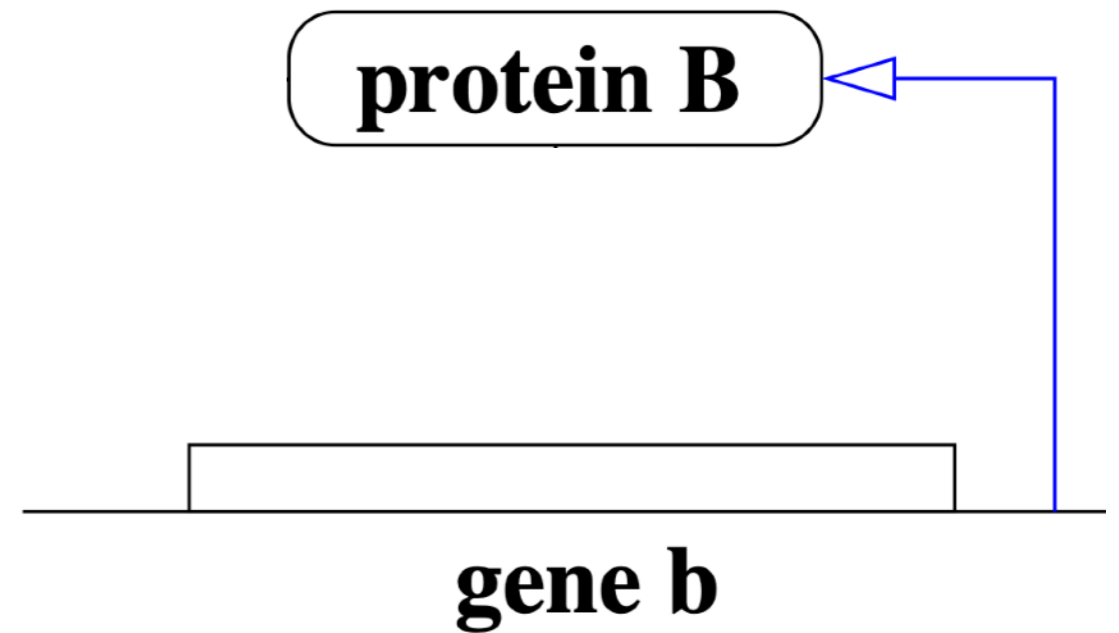
- introduced by René Thomas [1973]
- refined by Chaouiya et al. [2003]
- simplistic case: binary domain \implies Boolean Networks

Model Construction

Discrete Models of Influence (Regulatory) Networks



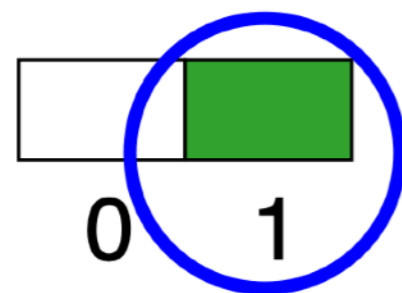
$$K_{A,\emptyset} = 1$$



$$K_{B,\emptyset} = 2$$

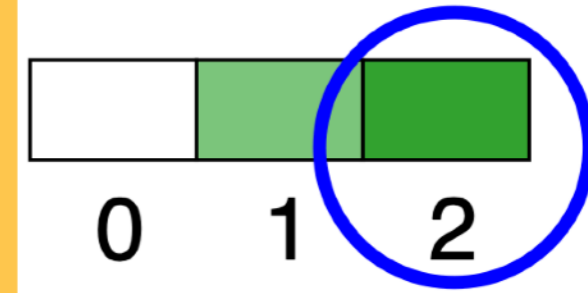
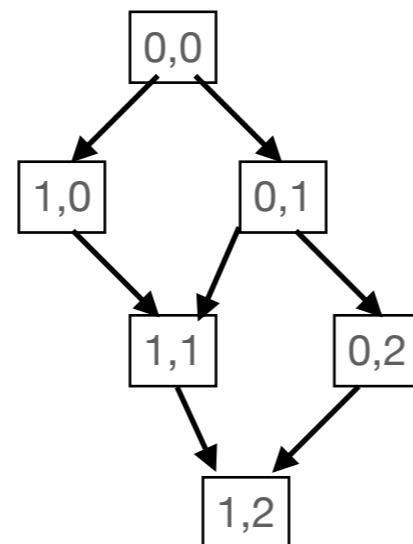
Model Construction

Discrete Models of Influence (Regulatory) Networks



$$K_{A,\emptyset} = 1$$

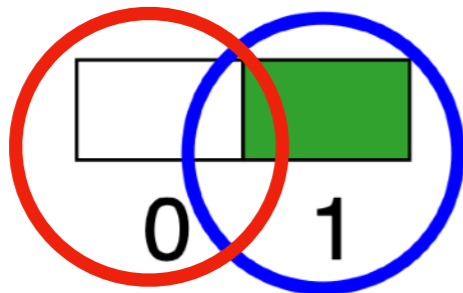
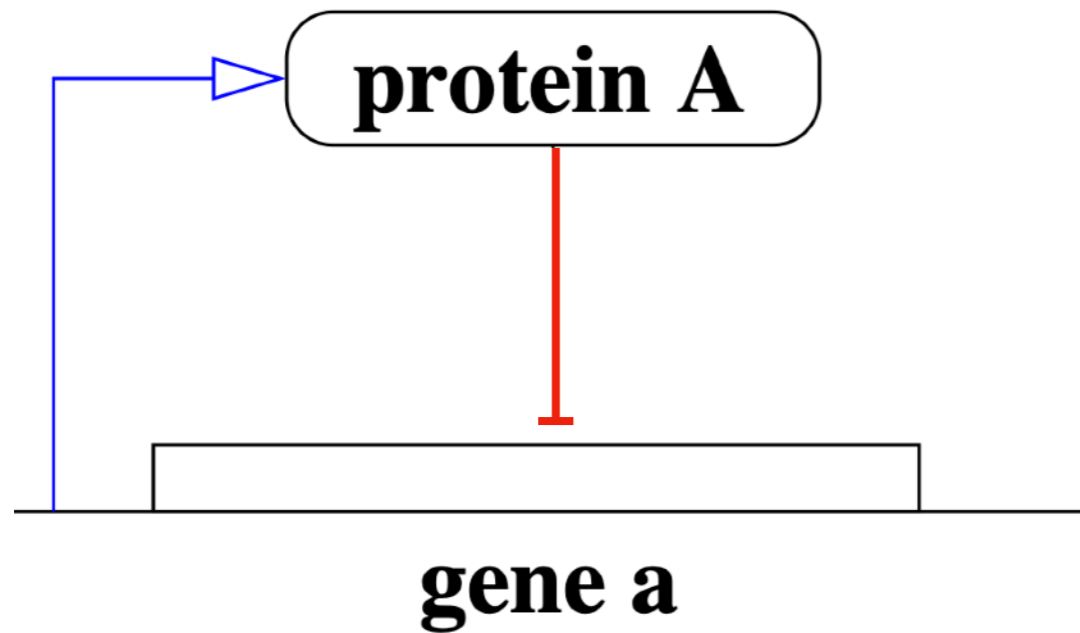
Asynchronous Update State Transition Graph (STG)



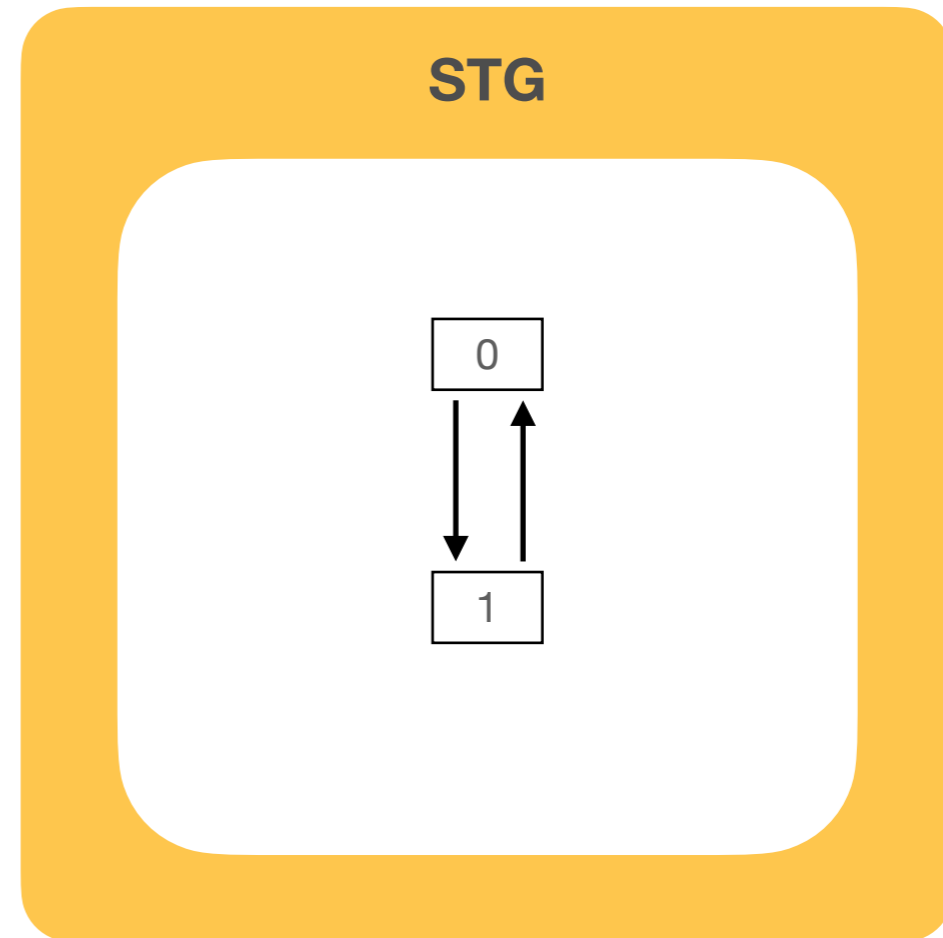
$$K_{B,\emptyset} = 2$$

Model Construction

Negative Influence (Inhibition)

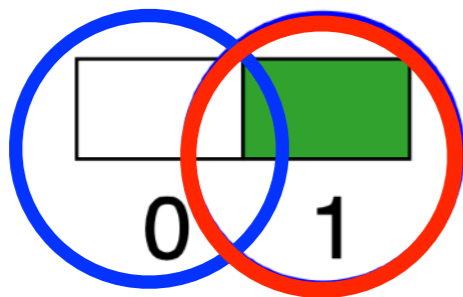
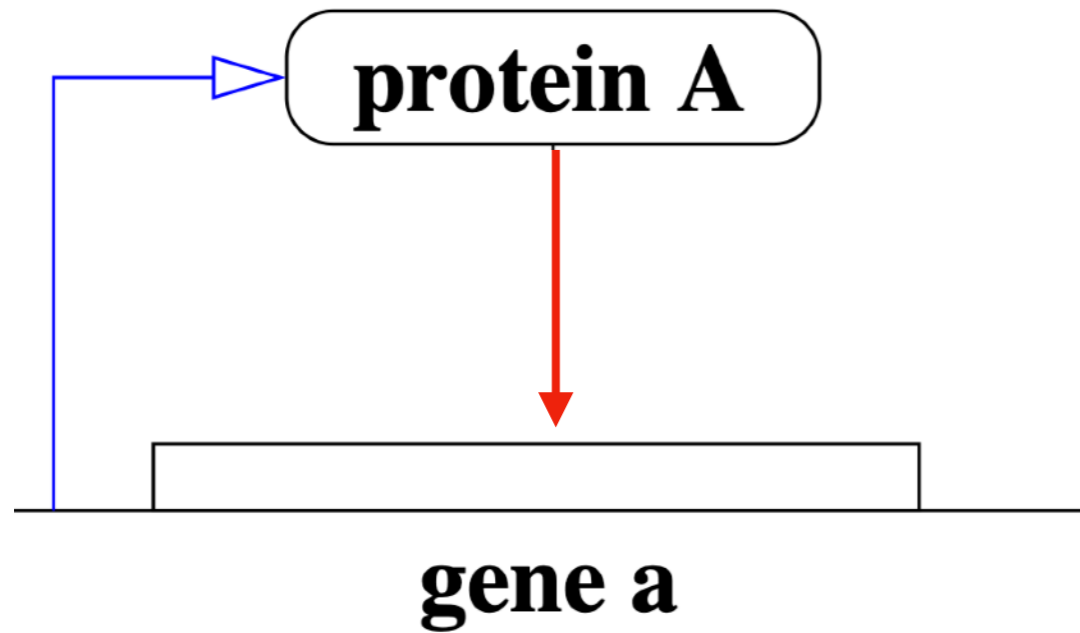


$$K_{A,\emptyset} = 1$$
$$K_{A,\{A\}} = 0$$

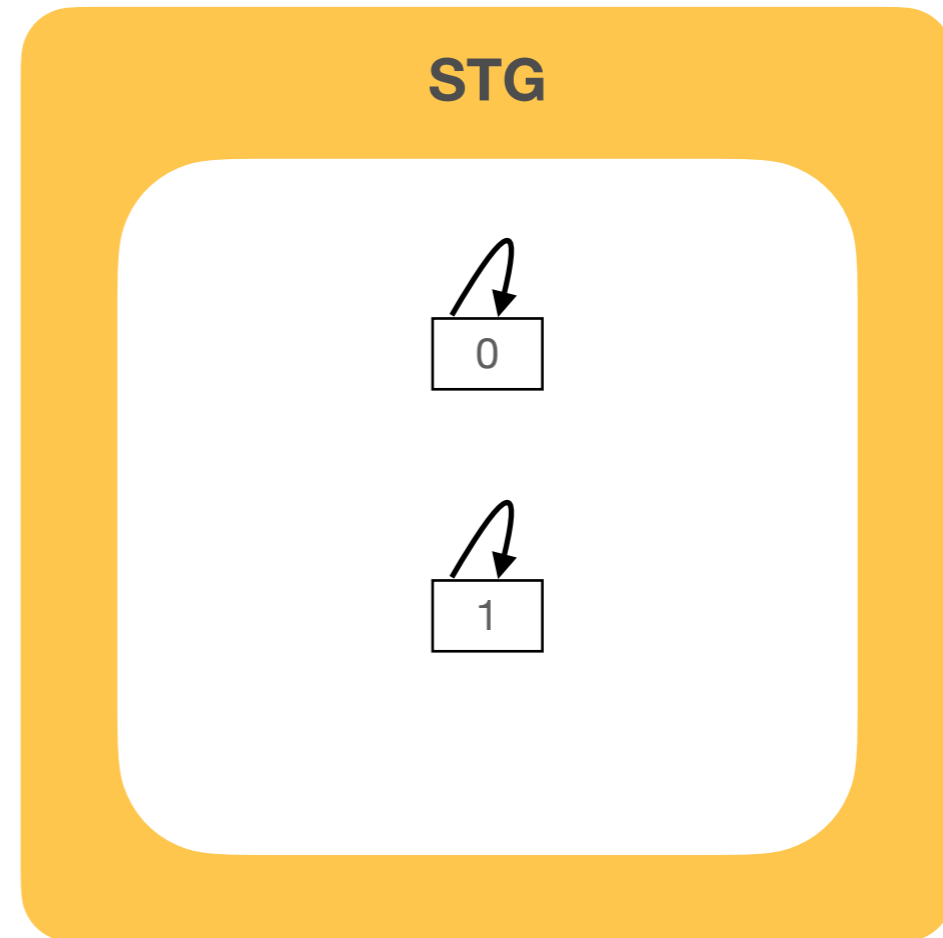


Model Construction

Negative Influence (Inhibition)

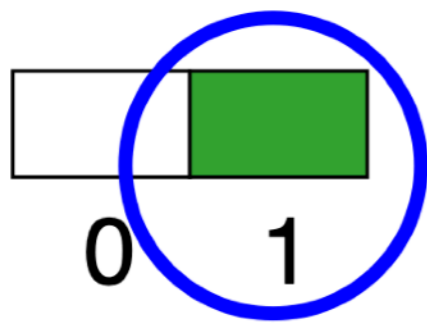
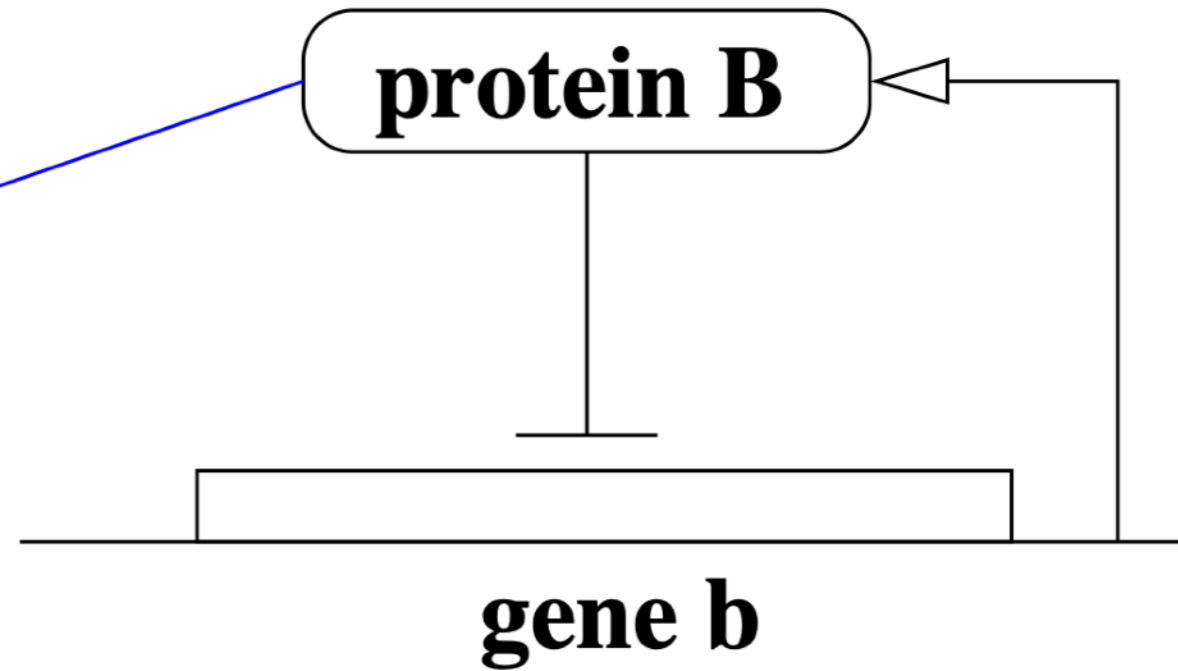
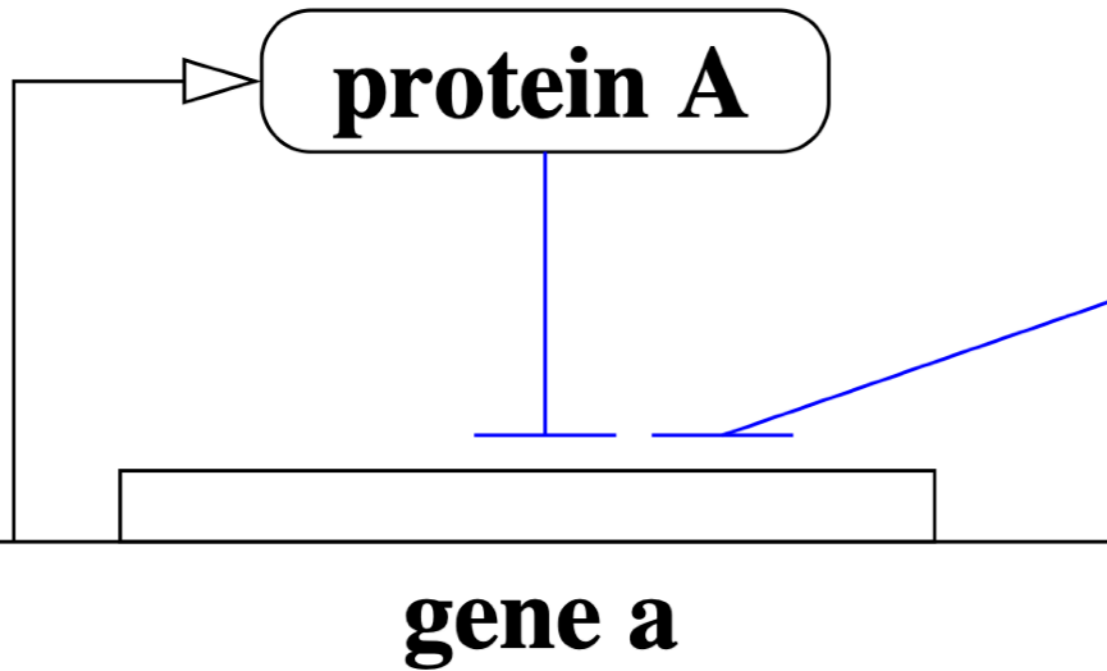


$$K_{A,\emptyset} = 0$$
$$K_{A,\{A\}} = 1$$



Model Construction

Discrete Models of Influence (Regulatory) Networks



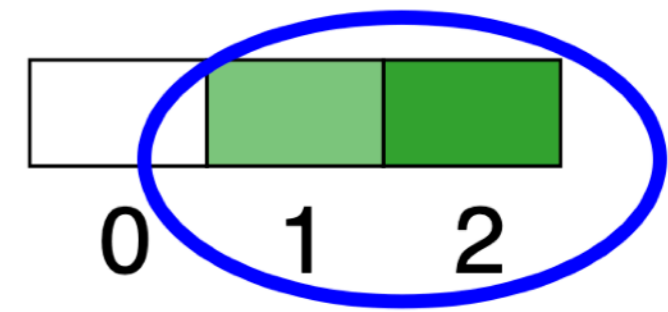
$$t_{AA} = 1$$

$$K_{A,\{A,B\}} = ?$$

$$K_{A,\{A\}} = ?$$

$$K_{A,\{B\}} = ?$$

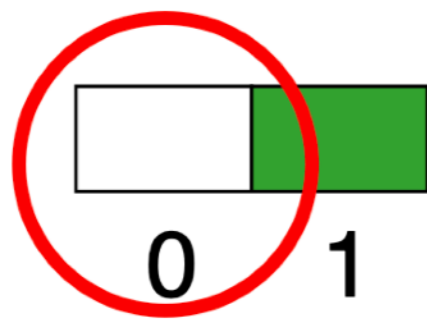
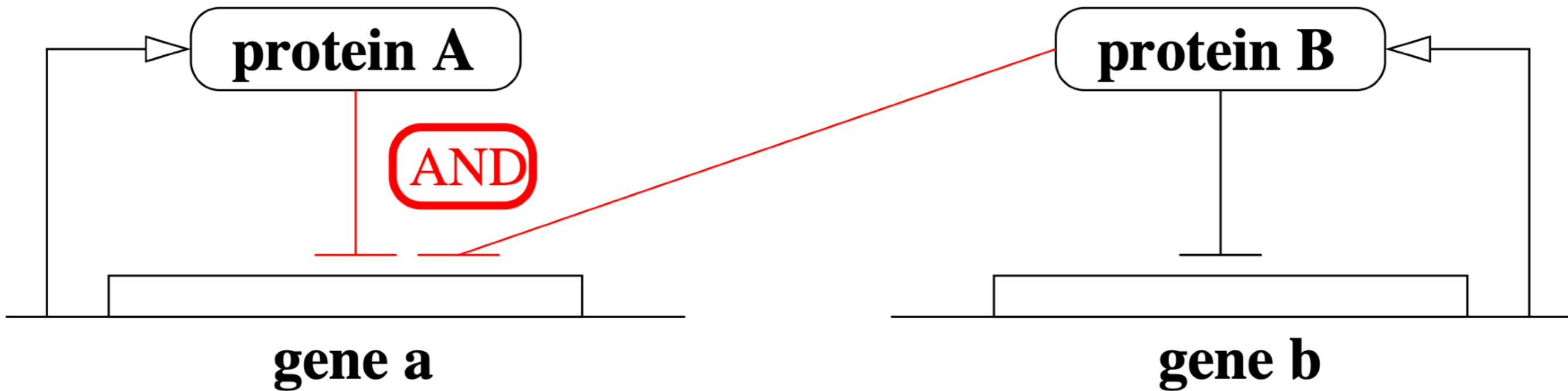
$$K_{A,\emptyset} = 1$$



$$t_{BA} = 1$$

Model Construction

Discrete Models of Influence (Regulatory) Networks



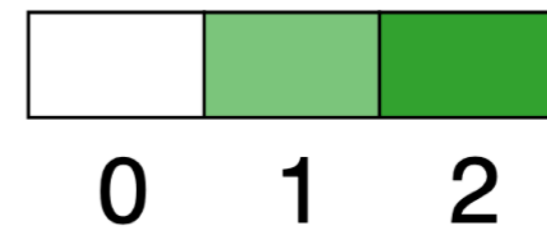
$$t_{AA} = 1$$

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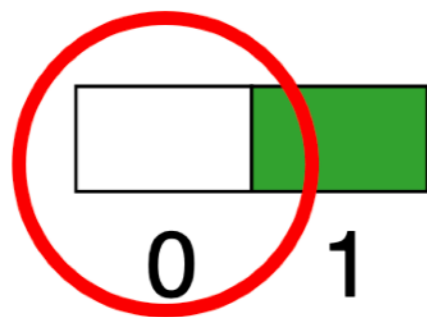
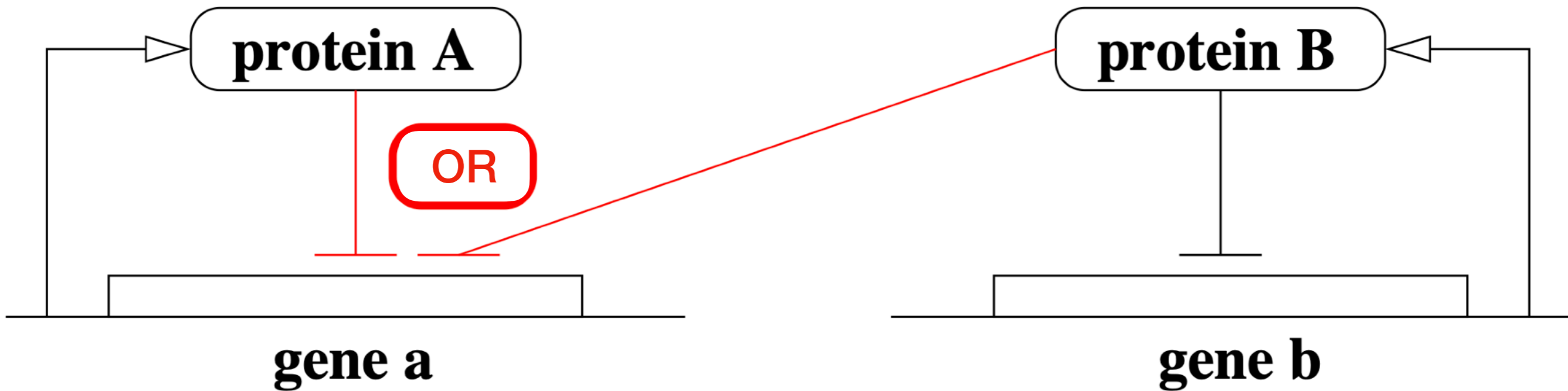
$$K_{A,\emptyset} = 1$$



$$t_{BA} = 1$$

Model Construction

Discrete Models of Influence (Regulatory) Networks



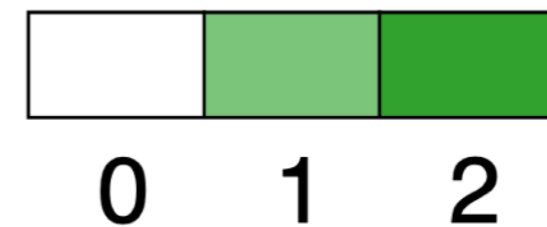
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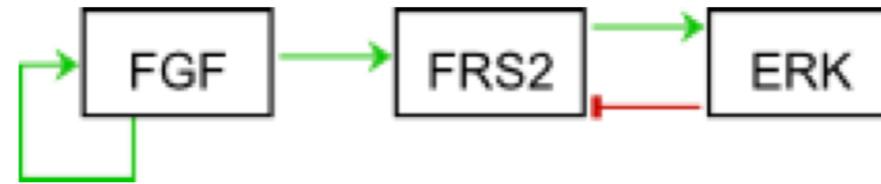
$$K_{A,\emptyset} = 1$$



$$t_{BA} = 1$$

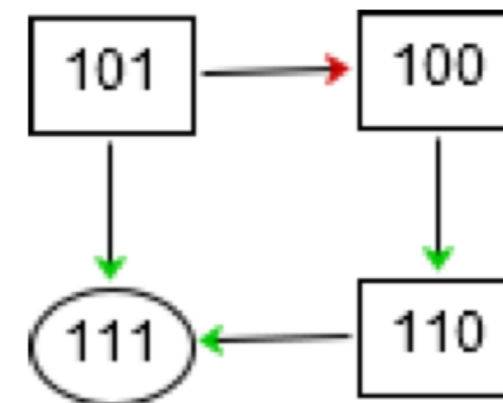
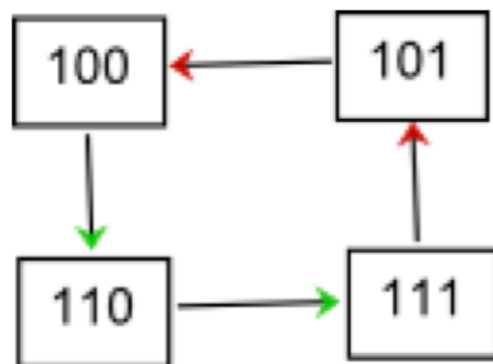
Revealing the Story Behind

Boolean Network Approach

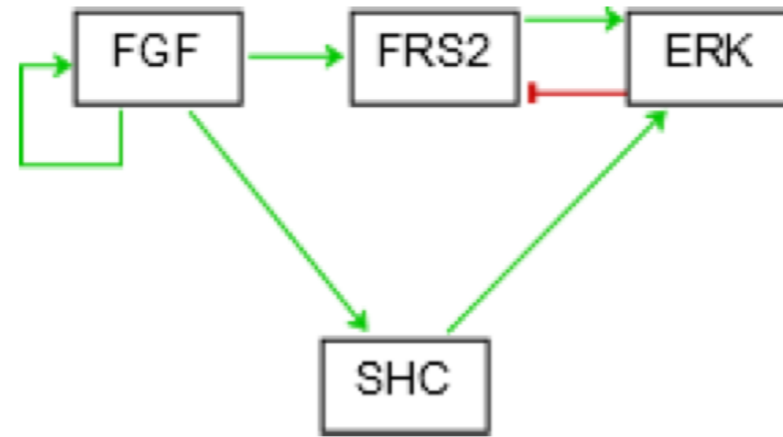


$$\begin{aligned}K_{FGF, \emptyset} &= 0 \\K_{FGF, \{FGF\}} &= 1 \\K_{FRS2, \emptyset} &= 0 \\K_{FRS2, \{FGF\}} &= 1 \\K_{FRS2, \{ERK\}} &= 0 \\K_{FRS2, \{FGF, ERK\}} &= 0 \\K_{ERK, \emptyset} &= 0 \\K_{ERK, \{FRS2\}} &= 1\end{aligned}$$

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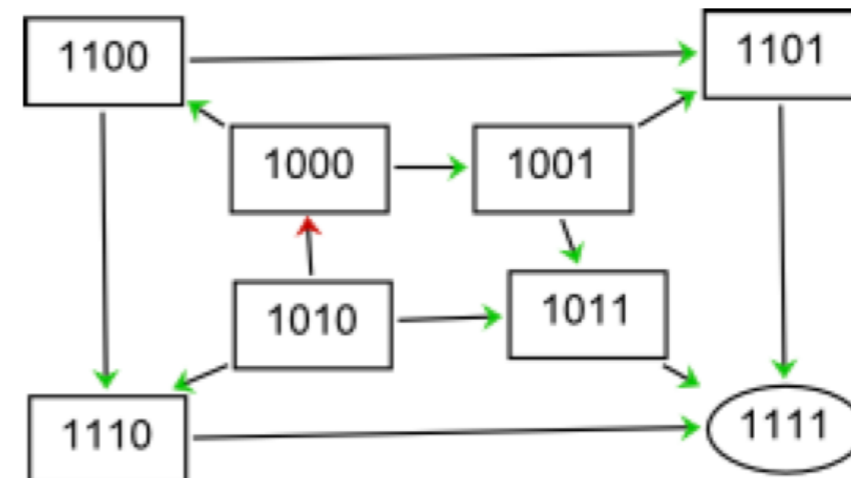
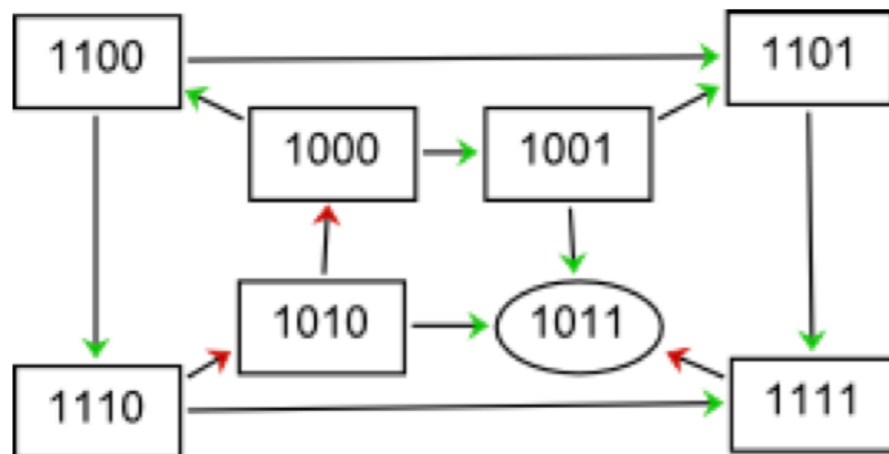


Revealing the Story Behind Boolean Network Approach



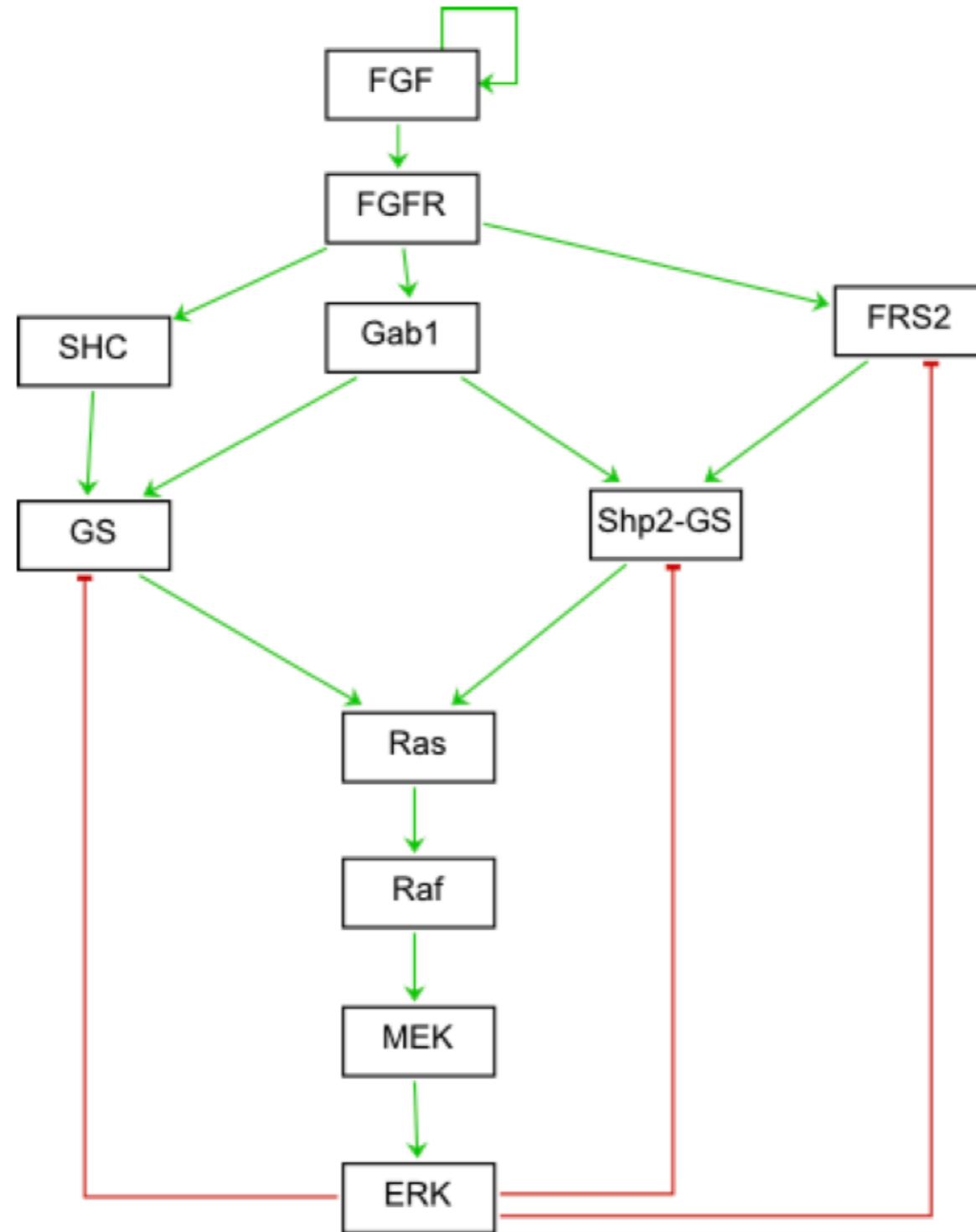
$$\begin{aligned}
 K_{FRS2, \{FGF, ERK\}} &= 0 \\
 K_{ERK, \emptyset} &= 0 \\
 K_{ERK, \{FRS2\}} &= 1 \\
 K_{ERK, \{SHC\}} &= 1 \\
 K_{ERK, \{FRS2, SHC\}} &= 1 \\
 K_{Shc, \emptyset} &= 0 \\
 K_{Shc, \{FGF\}} &= 1
 \end{aligned}$$

$$\begin{aligned}
 K_{FRS2, \{FGF, ERK\}} &= 1 \\
 K_{ERK, \emptyset} &= 0 \\
 K_{ERK, \{FRS2\}} &= 1 \\
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 K_{Shc, \emptyset} &= 0 \\
 K_{Shc, \{FGF\}} &= 1
 \end{aligned}$$

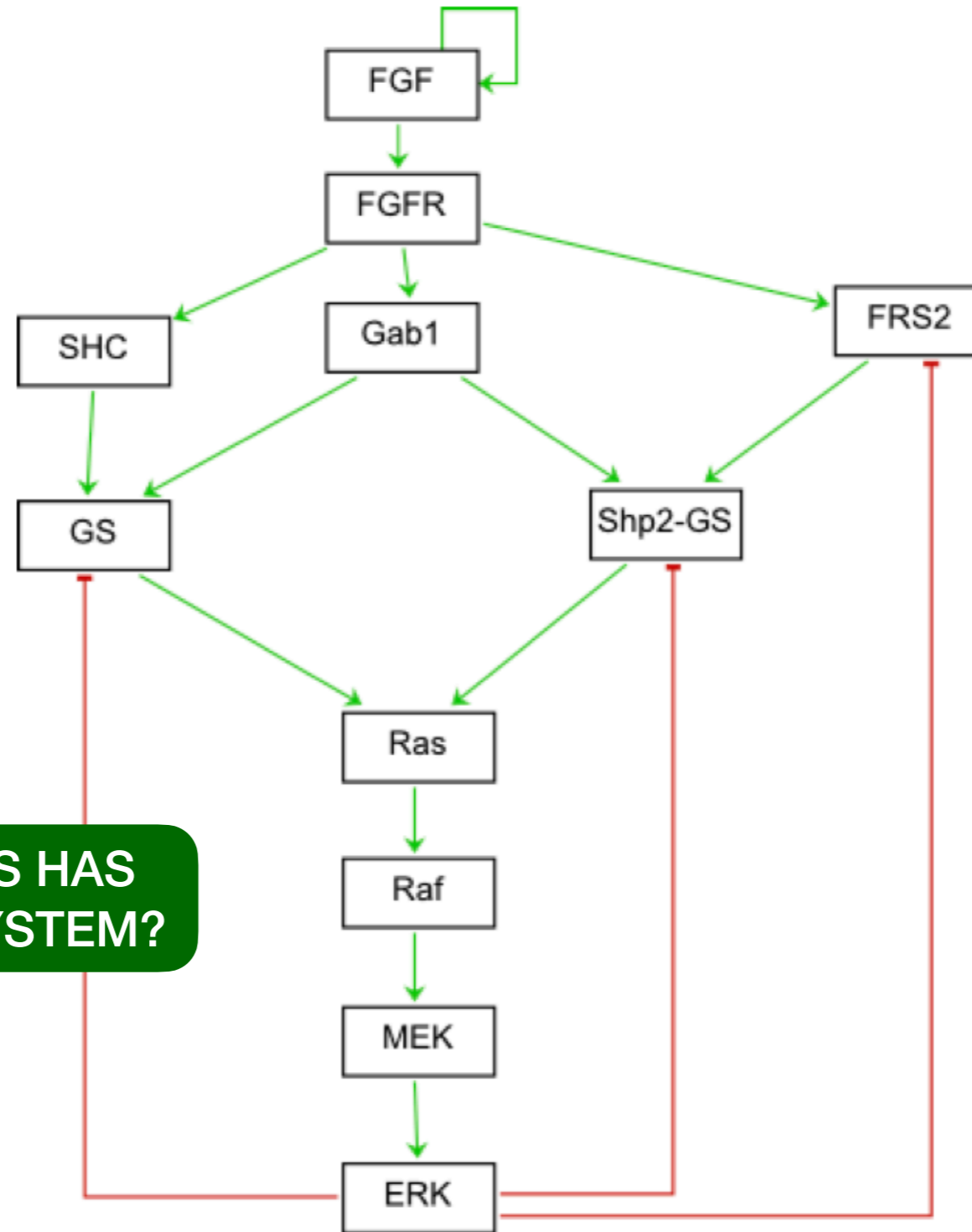


Revealing the Story Behind

Boolean Network Approach



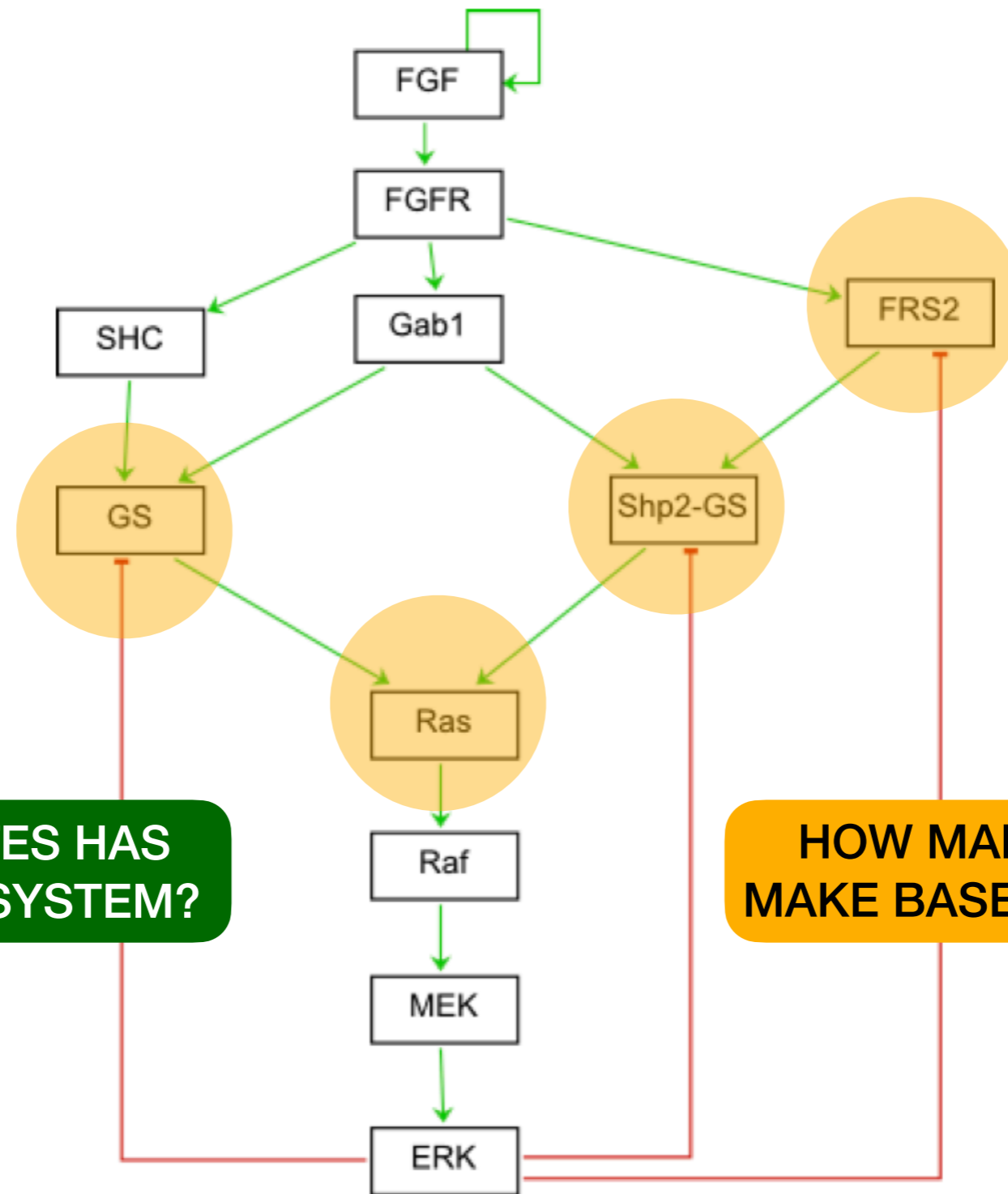
Revealing the Story Behind Boolean Network Approach



**HOW MANY STATES HAS
THE TRANSITION SYSTEM?**

Revealing the Story Behind

Boolean Network Approach

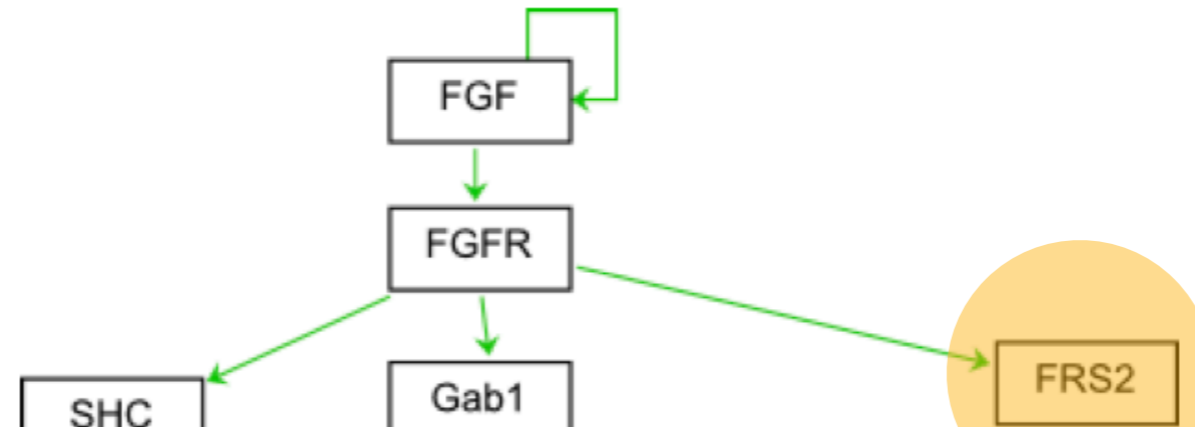


HOW MANY STATES HAS THE TRANSITION SYSTEM?

HOW MANY MODELS WE CAN MAKE BASED ON THIS NETWORK?

Revealing the Story Behind

Boolean Network Approach



**USE MODEL CHECKING
WITH TEMPORAL LOGICS**

**HOW MANY STATES HAS
THE TRANSITION SYSTEM?**

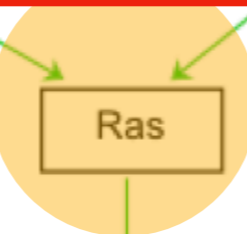
**HOW MANY MODELS WE CAN
MAKE BASED ON THIS NETWORK?**

Ras

Raf

MEK

ERK



Definition

Let AP be the set of *atomic propositions* (logical expressions over model variables, typical inequalities). *Kripke structure* is the quadruple $K = \langle S, S_0, T, L \rangle$ where:

- S is the finite set of states
- $S_0 \subseteq S$ is the set of initial states
- $T \subseteq S \times S$ such that $\forall s \in S, \exists s' \in S : \langle s, s' \rangle \in T$
- L is the labeling $L : S \rightarrow 2^{AP}$

Kripke structure – properties

- for a state $s \in S$, $L(s)$ represents the set of all atomic propositions satisfied in s
- unfolding of the Kripke structure from any initial state is always an infinite-depth tree
 - maximal paths in the unfolding represent individual (infinite) executions of the Kripke structure

Linear-time Temporal Logic – syntax

Let AP be the set of atomic propositions. Formula φ is *linear temporal logic (LTL) formula* iff the following holds:

- $\varphi = p$ for any $p \in AP$
- If φ_1 and φ_2 LTL formulae then:
 - $\neg\varphi_1$, $\varphi_1 \wedge \varphi_2$ and $\varphi_1 \vee \varphi_2$ are LTL formulae
 - $\mathbf{X}\varphi_1$, $\mathbf{F}\varphi_1$ a $\mathbf{G}\varphi_1$ are LTL formulae
 - $\varphi_1\mathbf{U}\varphi_2$ a $\varphi_1\mathbf{R}\varphi_2$ are LTL formulae

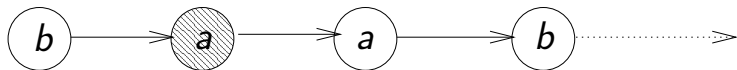
Linear Temporal Logic – semantics

Let $\pi = s_0, s_1, \dots, s_i, \dots$ be an infinite sequence of states (a path) in a Kripke structure K . For $j > 0$ we denote π^j the suffix $s_j, s_{j+1}, \dots, s_i, \dots$. Satisfiability relation \models is defined by induction:

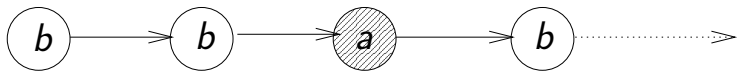
- $\pi \models p$ iff $p \in L(s_0)$
- $\pi \models \neg\varphi$ iff $\pi \not\models \varphi$
- $\pi \models \varphi_1 \wedge \varphi_2$ iff $\pi \models \varphi_1$ and $\pi \models \varphi_2$
- $\pi \models \varphi_1 \vee \varphi_2$ iff $\pi \models \varphi_1$ or $\pi \models \varphi_2$
- $\pi \models \mathbf{X}\varphi$ iff $\pi^1 \models \varphi$
- $\pi \models \mathbf{F}\varphi$ iff $\exists i \geq 0. \pi^i \models \varphi$
- $\pi \models \mathbf{G}\varphi$ iff $\forall i \geq 0. \pi^i \models \varphi$
- $\pi \models \varphi_1 \mathbf{U} \varphi_2$ iff $\exists j \geq 0. \pi^j \models \varphi_2$ and $\forall i < j. \pi^i \models \varphi_1$
- $\pi \models \varphi_1 \mathbf{R} \varphi_2$ iff $\forall j \geq 0, \forall 0 \leq i < j. \pi^i \not\models \varphi_1 \Rightarrow \pi^j \models \varphi_2$.

Linear Temporal Logic – semantics

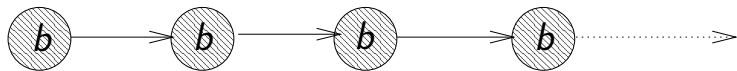
Xa



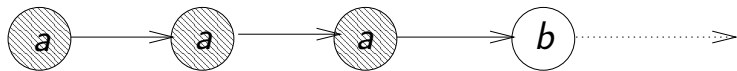
Fa



Gb



aUb



Kripke structure as a model for a formula

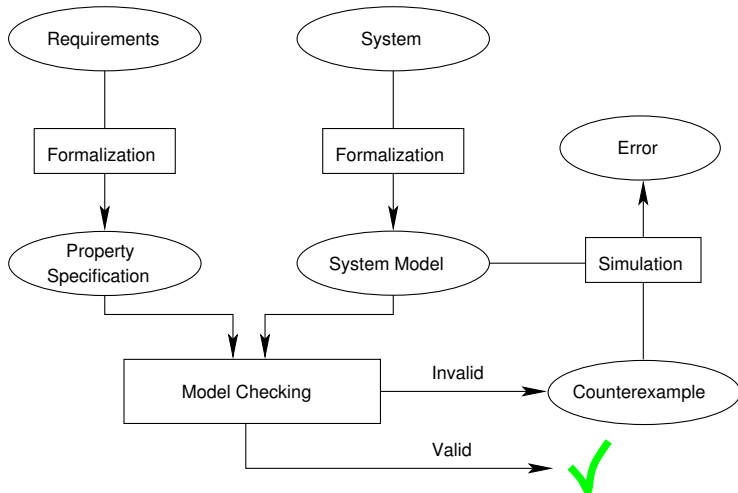
Let K be a Kripke structure. A formula φ is satisfied by K , $K \models \varphi$ iff for each execution $\pi = s_0, \dots$ such that $s_0 \in S_0$ it holds $\pi \models \varphi$.

Model Checking Problem

Model checking problem is to decide for a given Kripke structure K and a temporal property Φ the problem $K \models \Phi$.

If the result is negative, a path π such that $\pi \not\models \Phi$ is returned (a so-called *counterexample*).

Model-Checking Overview



Temporal Properties

Transient vs. Sustained Dynamics

Sustained Dynamics

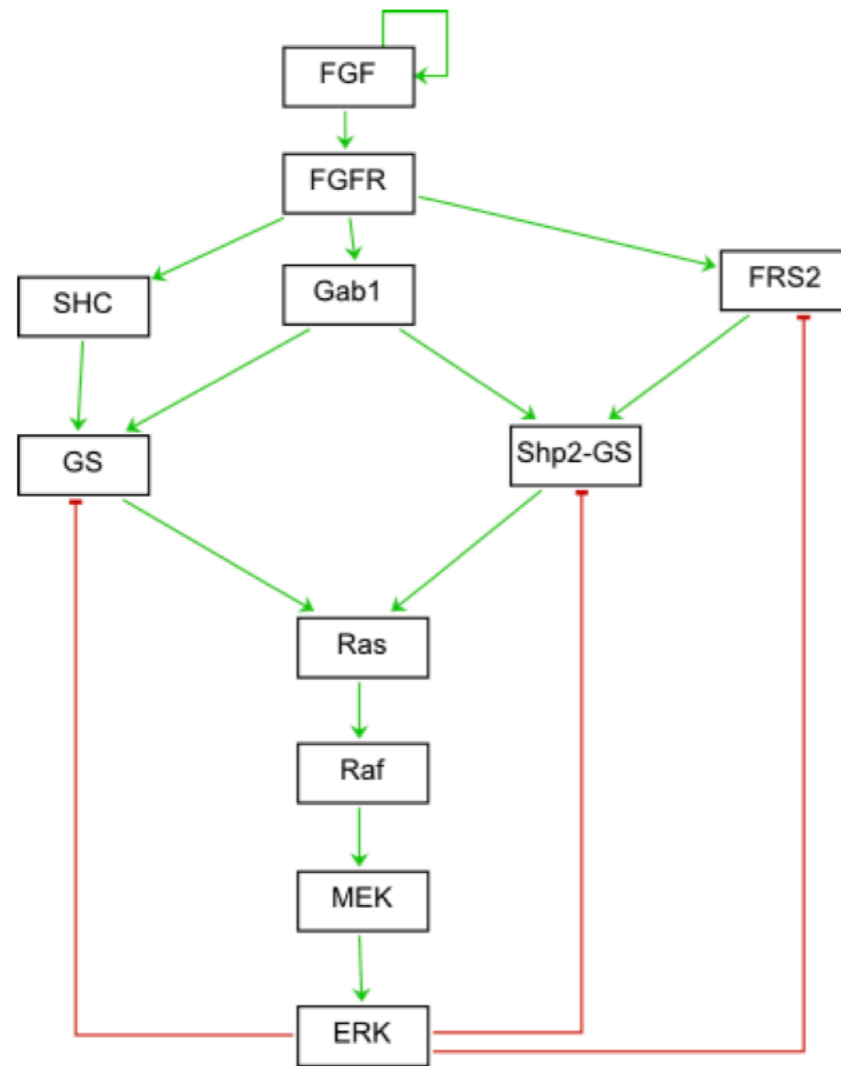
- $\mathbf{FG}(ERK > 0)$
- $\mathbf{FG}(FRS2 > 0)$
- $\mathbf{FG}(ERK > 0) \wedge \mathbf{FG}(FRS2 > 0)$

Transient Dynamics

- $\mathbf{F}(ERK > 0) \wedge \mathbf{GF}(ERK < 1)$
- $\mathbf{F}(ERK > 0) \wedge \mathbf{GF}(ERK < 1)$

Revealing the Story Behind Growth Factor Signalling

Boolean Network Approach

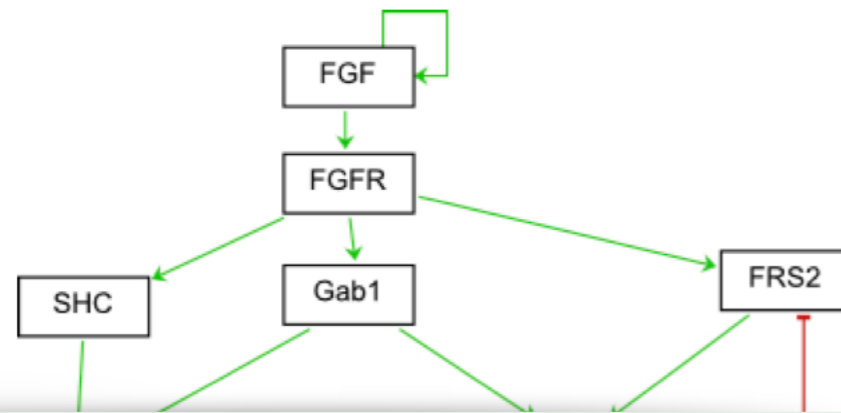


$$\begin{aligned}
 K_{Shp2-GS, \{FRS2\}} &= 1 \\
 K_{Shp2-GS, \{Gab1\}} &= 1 \\
 K_{Shp2-GS, \{FRS2, Gab1\}} &= 1 \\
 K_{Shp2-GS, \{ERK, FRS2\}} &= 1 \\
 K_{Shp2-GS, \{ERK, Gab1\}} &= 1 \\
 K_{Shp2-GS, \{ERK, FRS2, Gab1\}} &= 1 \\
 K_{Shp2-GS, \{ERK\}} &= 0
 \end{aligned}$$

$$\begin{aligned}
 K_{g_i, \emptyset} &= 0 \\
 K_{FGFR, \{FGF\}} &= 1 \\
 K_{SHC, \{FGFR\}} &= 1 \\
 K_{Gab1, \{FGFR\}} &= 1 \\
 K_{FRS2, \{FGFR\}} &= 1 \\
 K_{FRS2, \{FGFR, ERK\}} &= 1 \\
 K_{FRS2, \{ERK\}} &= 0 \\
 K_{Ras, \{GS\}} &= 1 \\
 K_{Ras, \{Shp2 - GS\}} &= 1 \\
 K_{Ras, \{GS, Shp2 - GS\}} &= 1 \\
 K_{Raf, \{Ras\}} &= 1 \\
 K_{MEK, \{Raf\}} &= 1 \\
 K_{ERK, \{MEK\}} &= 1 \\
 K_{GS, \{SHC\}} &= 1 \\
 K_{GS, \{Gab1\}} &= 1 \\
 K_{GS, \{SHC, Gab1\}} &= 1 \\
 K_{GS, \{ERK, Gab1\}} &= 0 \\
 K_{GS, \{ERK, SHC\}} &= 0 \\
 K_{GS, \{ERK, SHC, Gab1\}} &= 0 \\
 K_{GS, \{ERK\}} &= 0
 \end{aligned}$$

Revealing the Story Behind Growth Factor Signalling

Boolean Network Approach



$$K_{g_i, \emptyset} = 0$$

$$K_{FGFR, \{FGF\}} = 1$$

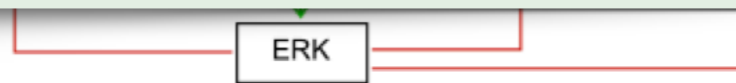
$$K_{SHC, \{FGFR\}} = 1$$

$$K_{Gab1, \{FGFR\}} = 1$$

$$K_{FRS2, \{FGFR\}} = 1$$

Satisfied Properties

- $(\mathbf{FG}(ERK > 0)) \vee (\mathbf{F}(ERK > 0) \wedge \mathbf{GF}(ERK < 1)) = \text{TRUE}$
- $\mathbf{FG}(FRS2 > 0) = \text{TRUE}$



$$K_{Shp2-GS, \{FRS2\}} = 1$$

$$K_{Shp2-GS, \{Gab1\}} = 1$$

$$K_{Shp2-GS, \{FRS2, Gab1\}} = 1$$

$$K_{Shp2-GS, \{ERK, FRS2\}} = 1$$

$$K_{Shp2-GS, \{ERK, Gab1\}} = 1$$

$$K_{Shp2-GS, \{ERK, FRS2, Gab1\}} = 1$$

$$K_{Shp2-GS, \{ERK\}} = 0$$

$$K_{GS, \{SHC\}} = 1$$

$$K_{GS, \{Gab1\}} = 1$$

$$K_{GS, \{SHC, Gab1\}} = 1$$

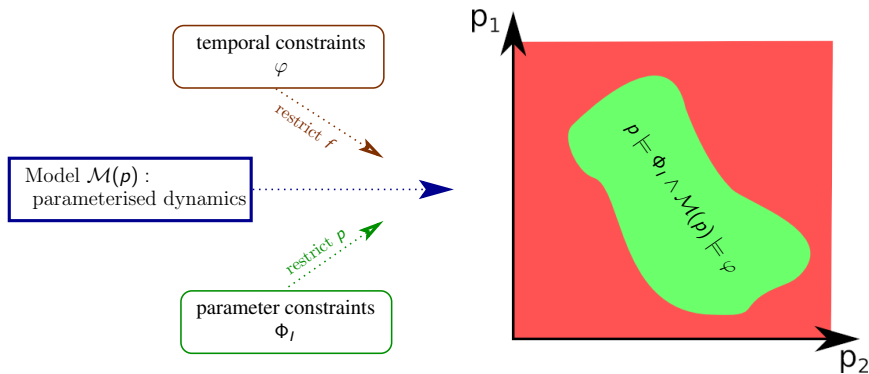
$$K_{GS, \{ERK, Gab1\}} = 0$$

$$K_{GS, \{ERK, SHC\}} = 0$$

$$K_{GS, \{ERK, SHC, Gab1\}} = 0$$

$$K_{GS, \{ERK\}} = 0$$

From Model Checking to Parameter Synthesis

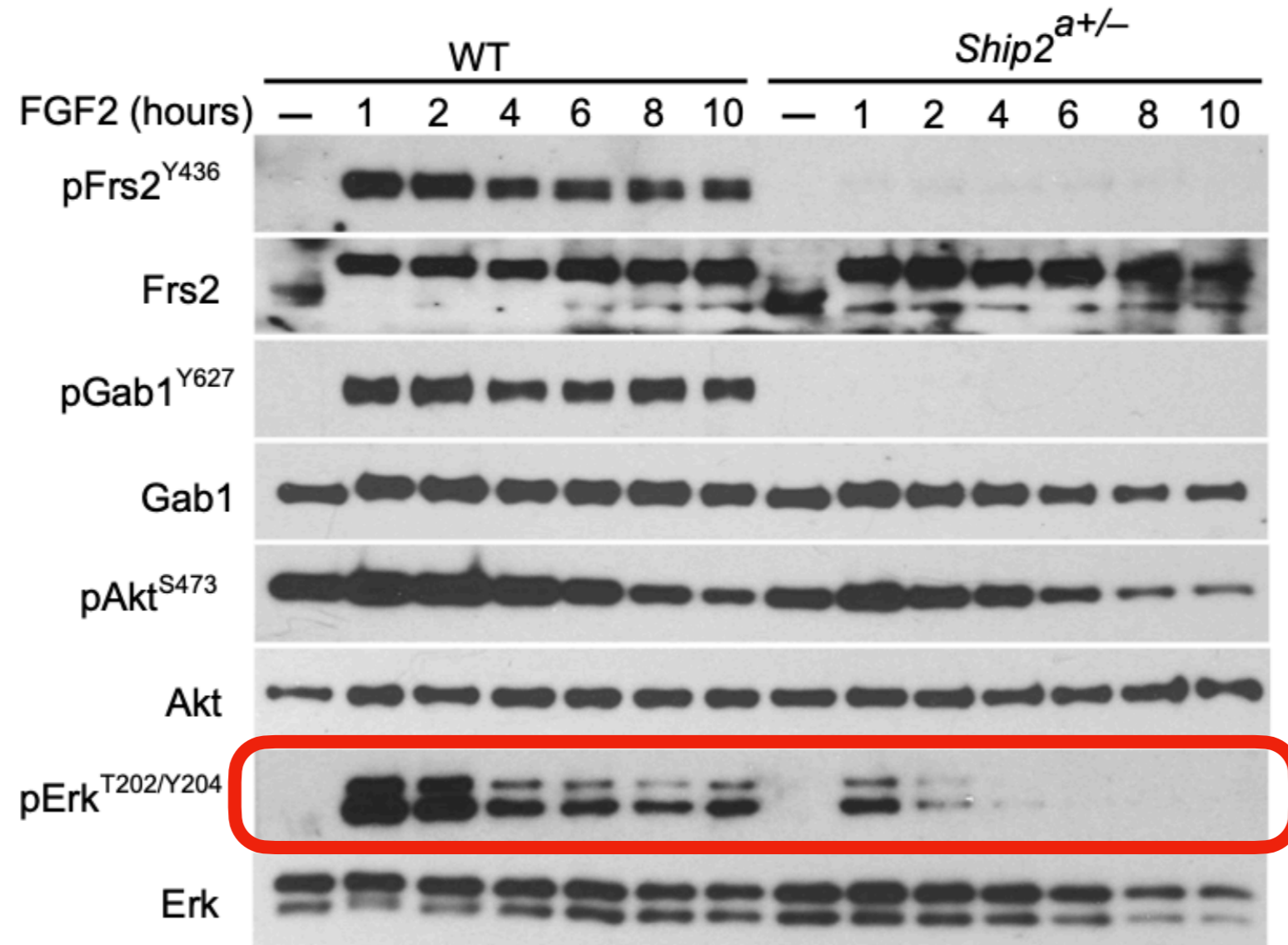


Parameter Synthesis Problem

Assume \mathcal{P} is the admissible **parameter space**. Given a *behaviour constraint* φ , *parameter constraint* Φ_I , and a *parameterised model* \mathcal{M} , **find the maximal set** $P \subseteq \mathcal{P}$ **of parameterisations** such that $p \models \Phi_I$ and $\mathcal{M}(p) \models \varphi$ for all $p \in P$.

- GINsim, <http://ginsim.org>
non-parameterised, edit, generate STG, graph-based analysis
- CellCollective, <https://cellcollective.org>
non-parameterised, simulation, annotation, repository
- TREMPPI, <http://tremppi.fi.muni.cz>
parameterised, LTL parameter synthesis, model ranking
- AEON,
https://sybila.fi.muni.cz/tools_html/aeon.html
parameterised, attractor analysis, knowledge inference
- many others...

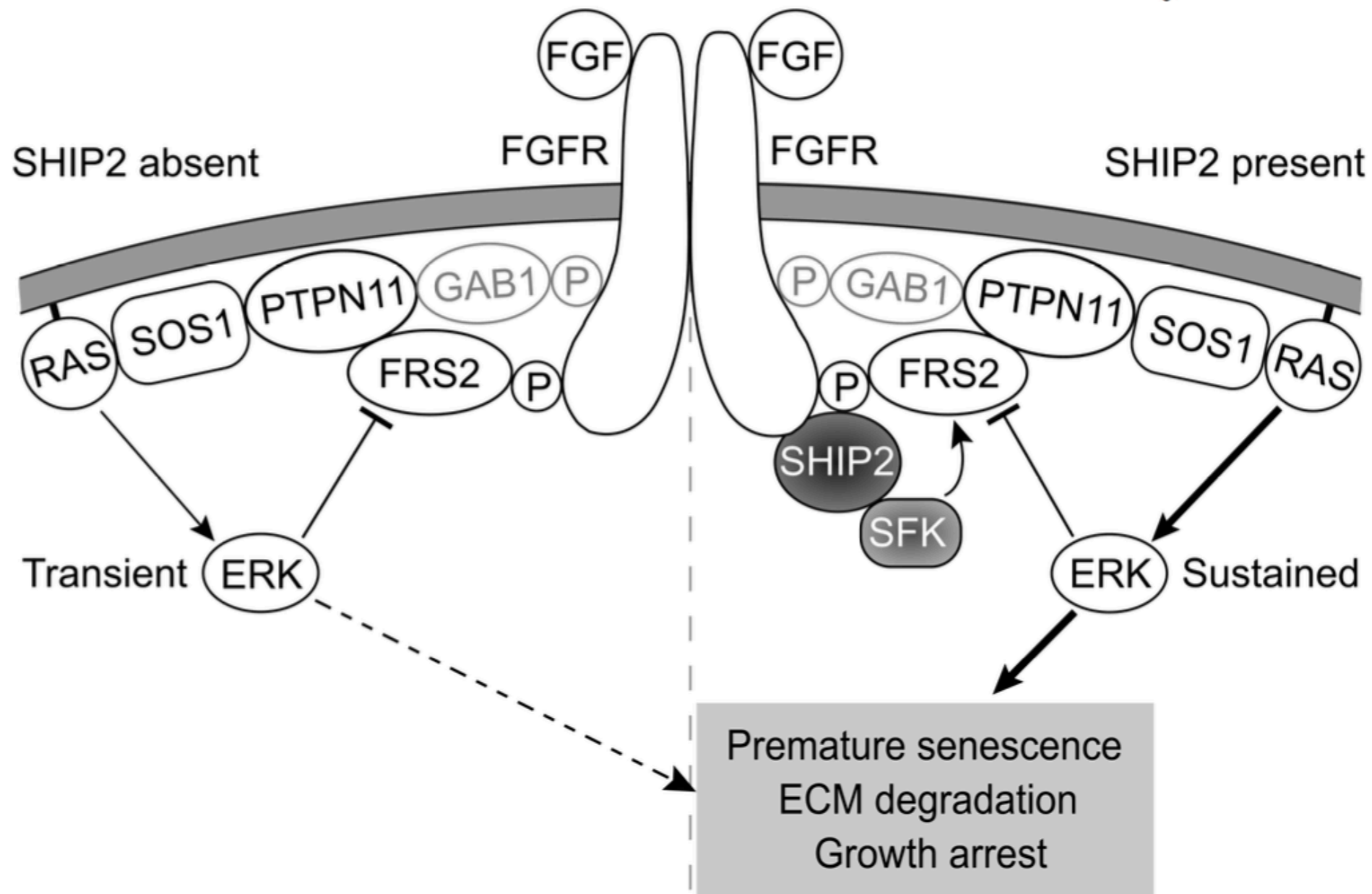
New Observations — The Role of SHIP2 Protein



Signaling Dynamics with and without SHIP2

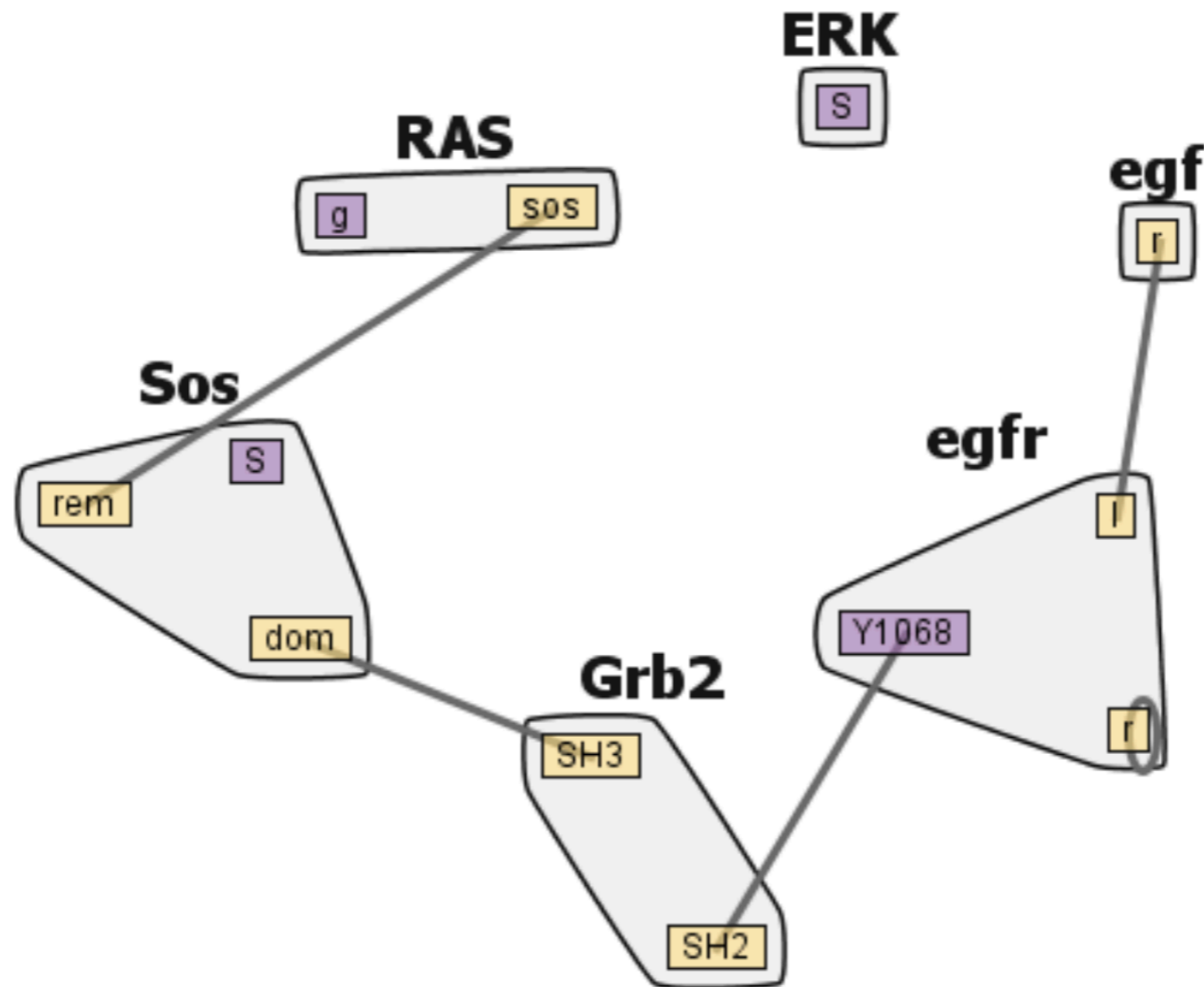
- wildtype includes the inositol phosphatase SHIP2
- when SHIP2 is removed, transient dynamics of pERK is obtained

Role of SHIP2 Protein — The Hypothesis



Revealing the Story Behind Growth Factor Signalling

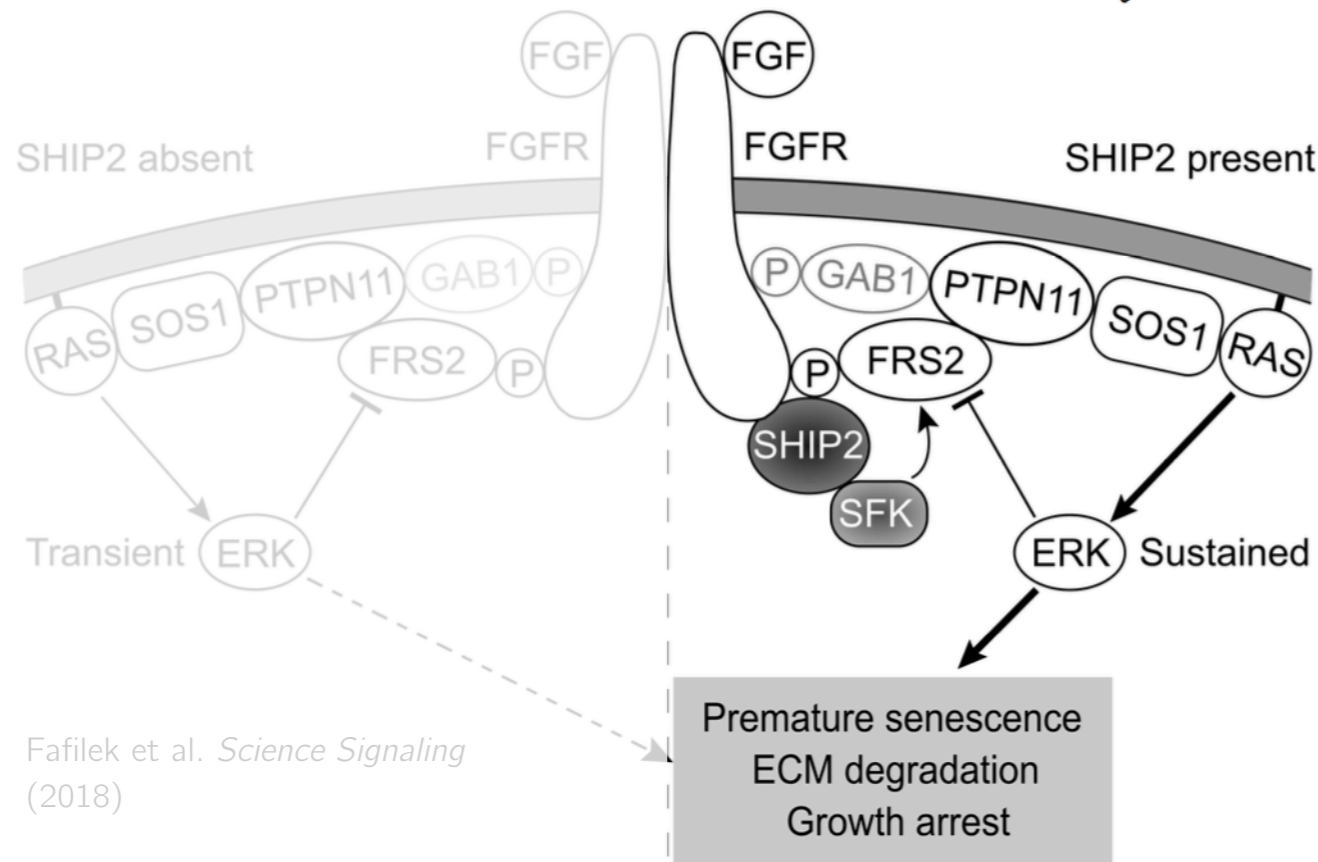
Rule-Based Approach



- modelling the exact binding and modifications of the proteins
- BNGL rule-based language (BioNetGen and RuleBender tools)

Revealing the Story Behind Growth Factor Signalling

Rule-Based Approach



Fafilek et al. *Science Signaling* (2018)

begin molecule types

FGF (R)

FGFR (L, R, Y1~u~p, Y2~u~p)

FRS2 (pR, Y1~u~p, Th1~u~p, S)

GS (SH2, REM)

SHIP (Y~u~p)

SFK (Y~u~p)

RAS (sos, g~GDP~GTP)

RasGAP (ras)

RAF (S~A~I~P)

MEK (T292~U~P, S~U~P~PP)

ERK (S~U~P~PP)

end molecule types

begin reaction rules

Ligand-receptor binding (ligand-monomer)

FGFR(L,R) + FGF(R) <-> FGFR(L!1,R).FGF(R!1) kp1, km1

Receptor-dimerisation

FGFR(L!+,R) + FGFR(L!+,R) <-> FGFR(L!+,R!3).FGFR(L!+,R!3) kp2, km2

FRS2 phosphorylation by FGFR

FGFR(R!+,Y1~p!1).FRS2(pR!1,Y1~u,Th1~u) -> FGFR(R!+,Y1~p!1).FRS2(pR!1,Y1~p,Th1~u) kp14

FRS2(pR!+,Y1~p) -> FRS2(pR!+,Y1~u) km14

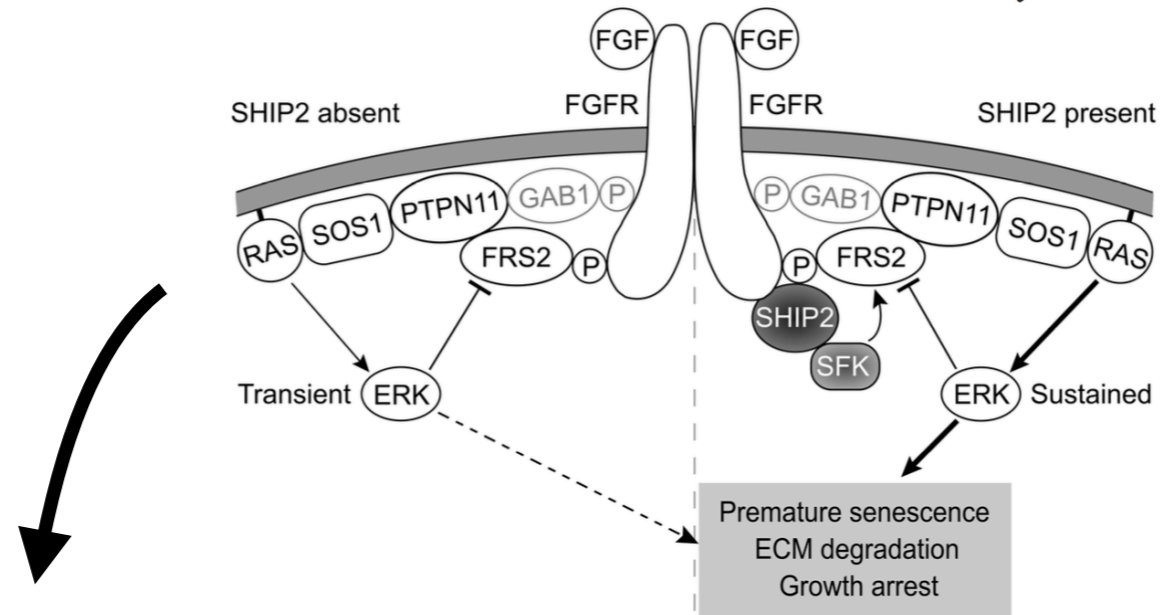
#SFK-mediated FRS2 phosphorylation (hypothetised)

FRS2(Y1~u) + SFK(Y~p) -> FRS2(Y1~p) + SFK(Y~p) 1000*kp14

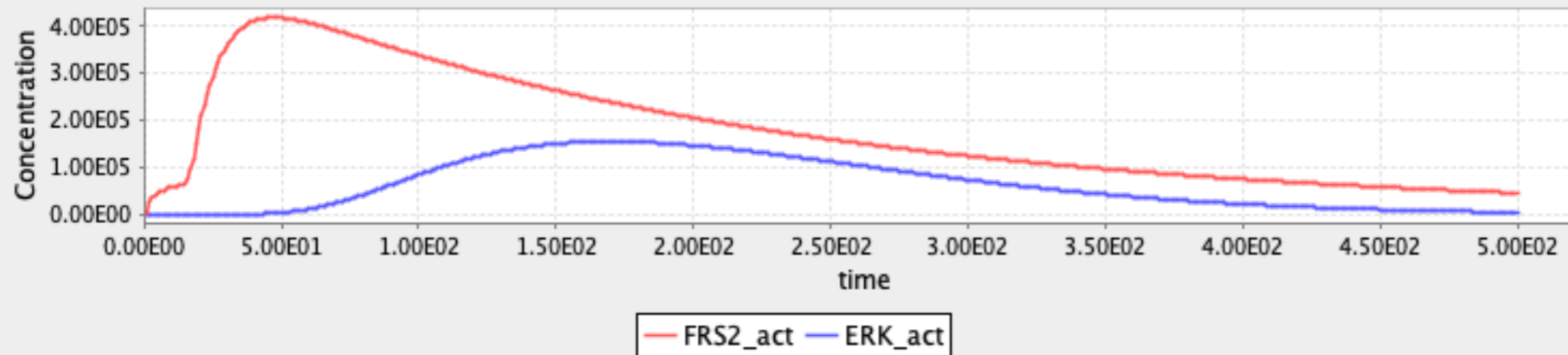
...

Revealing the Story Behind Growth Factor Signalling

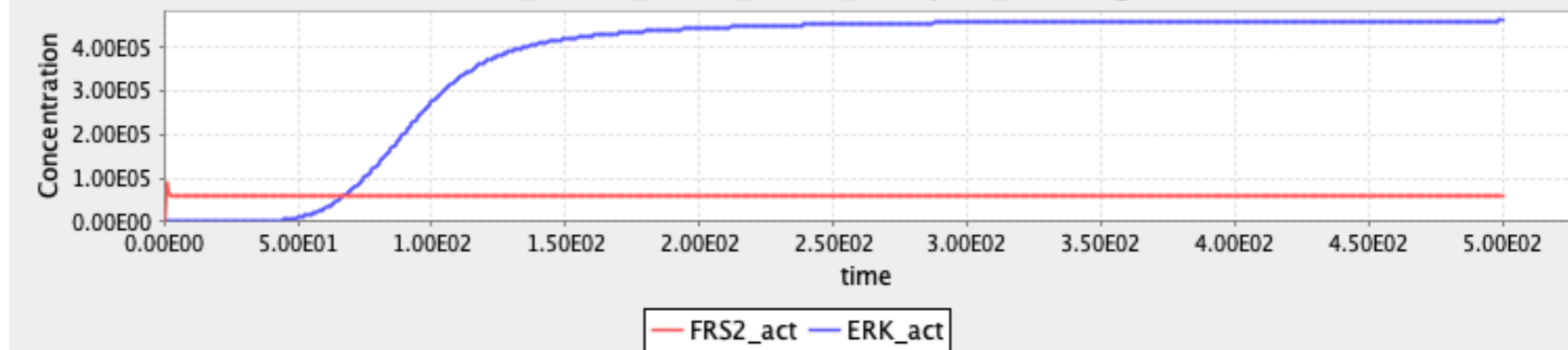
Rule-Based Approach



model_FRS2_fdbk_Sim1.gdat

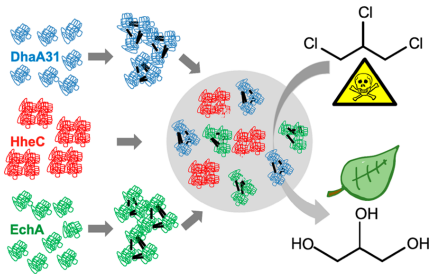
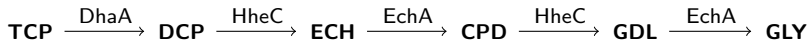


model_FRS2_fdbk_SHIP_simple_Sim1.gdat



- 1 Introduction and Motivation
- 2 Methodology
 - Biological Networks
 - Modelling Problems
- 3 Story I: Signalling Pathways of Fibroblast Growth Factors
- 4 Story II: Synthetic Biology: Trichloropropane Degradation

Biodegradation of Trichloropropane in *E. coli*



$$\frac{d[\text{TCP}]}{dt} = -\frac{k_1 \cdot \text{DhaA} \cdot [\text{TCP}]}{K_{m,1} + [\text{TCP}]}$$

$$\frac{d[\text{DCP}]}{dt} = \frac{k_1 \cdot \text{DhaA} \cdot [\text{TCP}]}{K_{m,1} + [\text{TCP}]} - \frac{k_2 \cdot \text{HheC} \cdot [\text{DCP}]}{K_{m,2} + [\text{DCP}]}$$

$$\frac{d[\text{ECH}]}{dt} = \frac{k_2 \cdot \text{HheC} \cdot [\text{DCP}]}{K_{m,2} + [\text{DCP}]} - \frac{k_3 \cdot \text{EchA} \cdot [\text{ECH}]}{K_{m,3} + [\text{ECH}]}$$

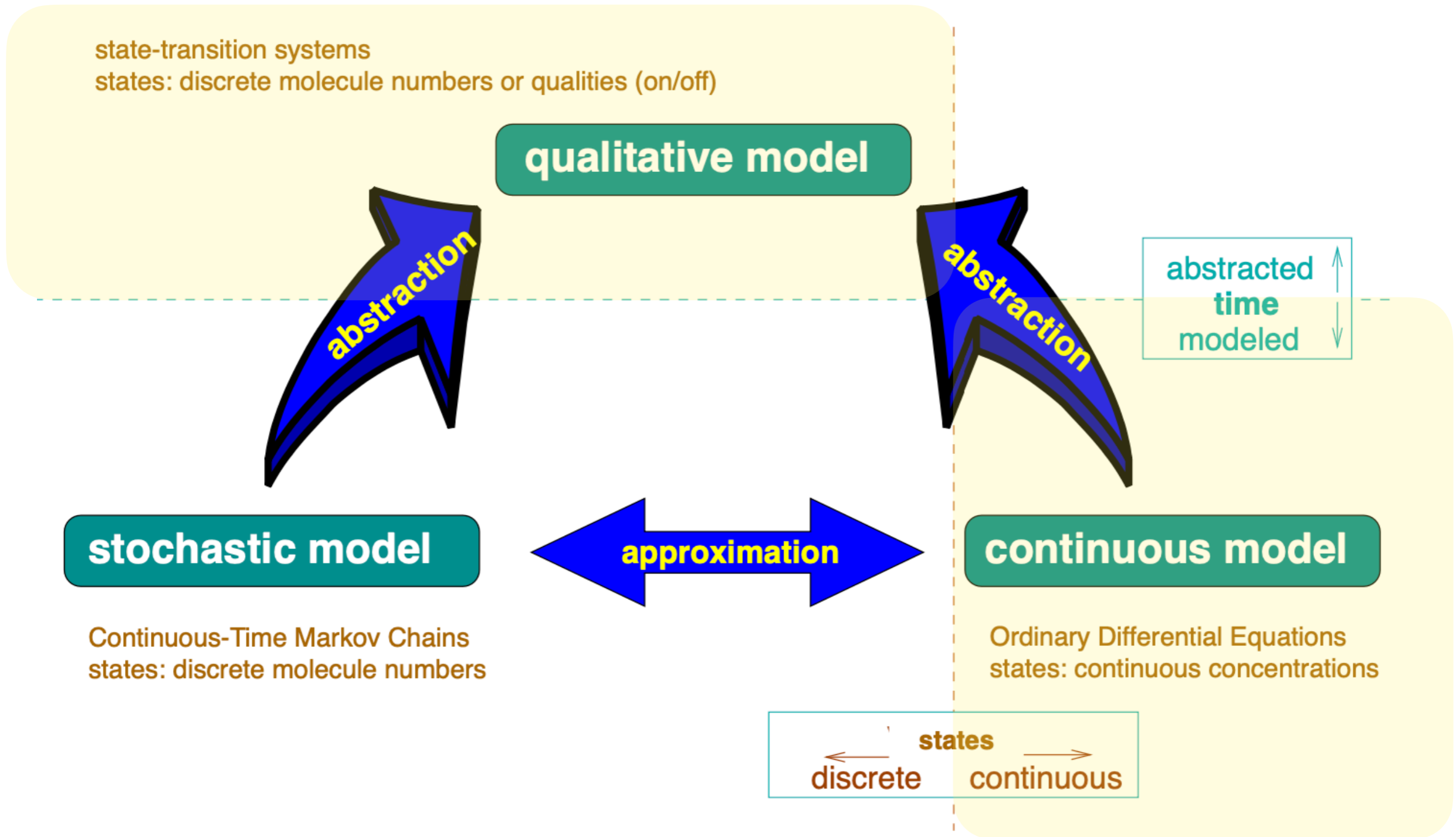
$$\frac{d[\text{CPD}]}{dt} = \frac{k_3 \cdot \text{EchA} \cdot [\text{ECH}]}{K_{m,3} + [\text{ECH}]} - \frac{k_4 \cdot \text{HheC} \cdot [\text{CPD}]}{K_{m,4} + [\text{CPD}]}$$

$$\frac{d[\text{GDL}]}{dt} = \frac{k_4 \cdot \text{HheC} \cdot [\text{CPD}]}{K_{m,4} + [\text{CPD}]} - \frac{k_5 \cdot \text{HheC} \cdot [\text{GDL}]}{K_{m,5} + [\text{GDL}]}$$

$$\frac{d[\text{GLY}]}{dt} = \frac{k_5 \cdot \text{HheC} \cdot [\text{GDL}]}{K_{m,5} + [\text{GDL}]}$$

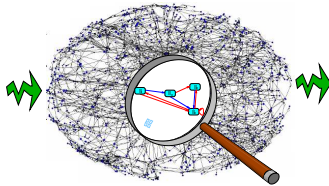
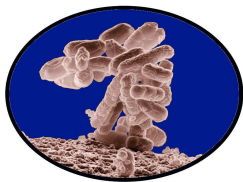
- biodegradation of toxic substrate and intermediates
- synthetic pathway utilising enzymes from two other bacteria
Rhodococcus rhodochrous NCIMB 13064; *Agrobacterium radiobacter* AD1
- find optimal enzymes concentration balancing *metabolic burden* and *toxicity*

Modelling Frameworks

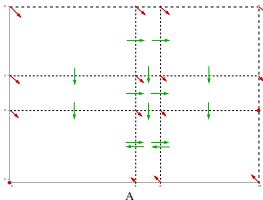
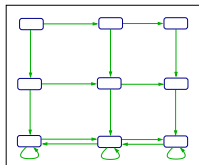
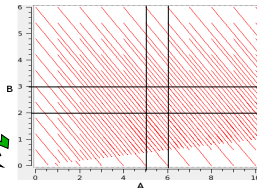


The Approach: Rectangular Abstraction of ODE

From a Continuous System to a Discrete Finite Quotient



system of ODEs
$\frac{dA}{dt} = -k_1 \cdot A + k_2 \cdot B$
$\frac{dB}{dt} = k_1 \cdot A - k_2 \cdot B$



P. Collins, L. Habets, J.H. van Schuppen, I. Černá, J. Fabriková, and D. Šafránek. Abstraction of Biochemical Reaction Systems on Polytopes. In Proceedings of 18th IFAC World Congress, 2011.

Parameter Synthesis over Rectangular Abstraction

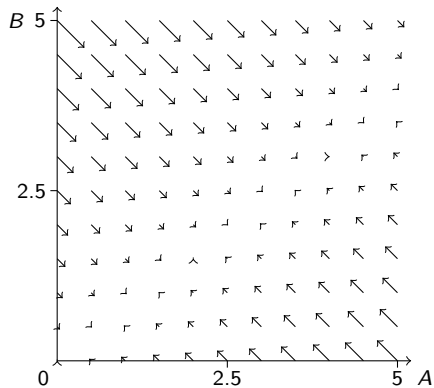
Phase Space Discretisation Leads to Parameter Space Discretisation

$$\frac{dA}{dt} = -k_1 \cdot A + k_2 \cdot B$$

$$\frac{dB}{dt} = k_1 \cdot A - k_2 \cdot B$$

$$k_2 = 0.8$$

$$k_1 = 0.6$$



Parameter Synthesis over Rectangular Abstraction

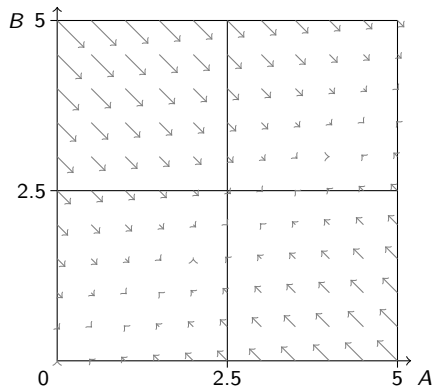
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Parameter Synthesis over Rectangular Abstraction

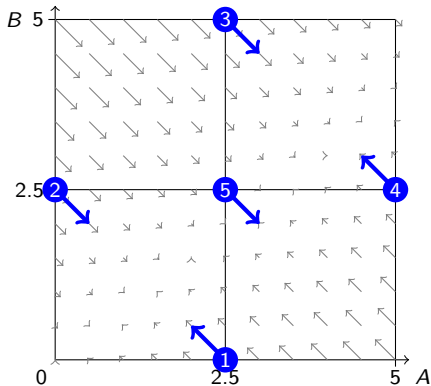
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Parameter Synthesis over Rectangular Abstraction

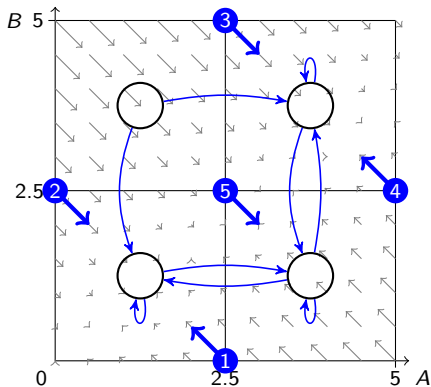
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Parameter Synthesis over Rectangular Abstraction

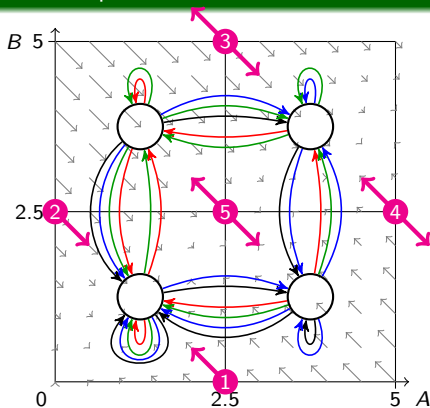
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$$\frac{dB}{dt} = k_1 \cdot A - k_2 \cdot B$$

$$k_2 = 0.8$$

$$k_1 = ?$$



	(0,0.4)	(0.4,0.8)	(0.8,1.6)	(1.6,max)
1	↗	↖	↖	↖
2	↘	↘	↘	↘
3	↘	↘	↘	↖
4	↘	↗	↖	↖
5	↘	↘	↖	↖

Parameter Synthesis over Rectangular Abstraction

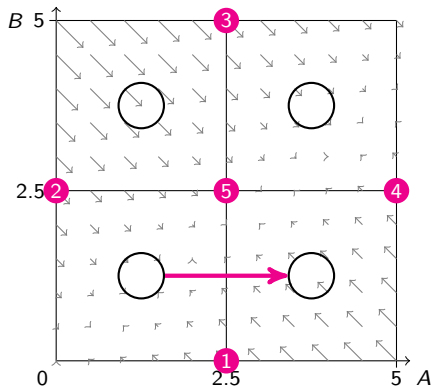
Phase Space Discretisation Leads to Parameter Space Discretisation

$$\frac{dA}{dt} = -k_1 \cdot A + k_2 \cdot B$$

$$\frac{dB}{dt} = k_1 \cdot A - k_2 \cdot B$$

$$k_2 = 0.8$$

$$k_1 = ?$$



	(0,0.4)	(0.4,0.8)	(0.8,1.6)	(1.6,max)	
1	↗	↖	↗	↖	$-2.5 \cdot k_1 > 0$
2	↘	↘	↘	↘	
3	↘	↘	↘	↗	
4	↘	↗	↗	↗	
5	↘	↘	↗	↗	$-2.5 \cdot k_1 + 2.5 \cdot k_2 > 0$

Parameter Synthesis over Rectangular Abstraction

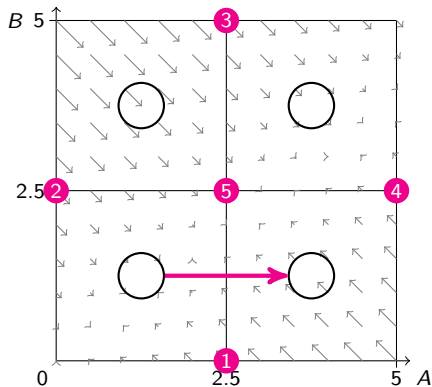
Phase Space Discretisation Leads to Parameter Space Discretisation

$$\frac{dA}{dt} = -k_1 \cdot A + k_2 \cdot B$$

$$\frac{dB}{dt} = k_1 \cdot A - k_2 \cdot B$$

$$k_2 = 0.8$$

$$k_1 = ?$$



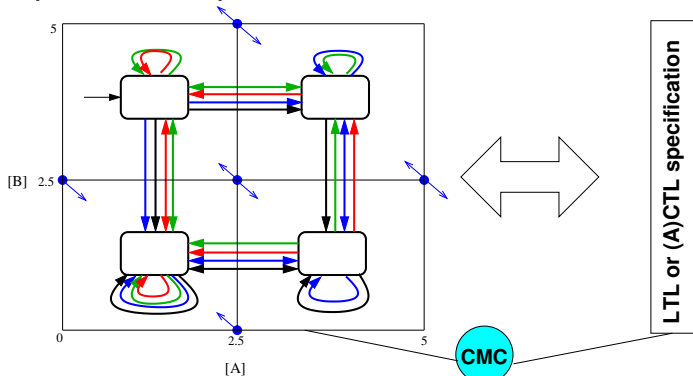
$$\Phi_{\text{state00} \rightarrow \text{state10}} := -2.5 \cdot k_1 > 0 \vee -2.5 \cdot k_1 + 2.5 \cdot k_2 > 0$$

The transition exists if and only if the formula is **satisfiable**.

Local parameter constraints are **predicates over reals**.

Parameter Synthesis over Rectangular Abstraction

parameterized Kripke structure of the model



identify states and colors for which the property does/doesn't hold

YES

NO

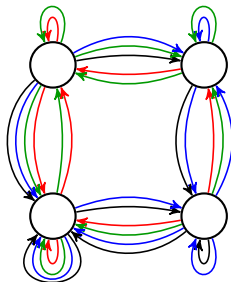
parameter intervals where
the specification is guaranteed
(some might be missing)

parameter intervals where
the specification might be violated

Parameterised Kripke Structures

State Transition Systems with Parameters

Transitions with Parameters (coloured transitions)

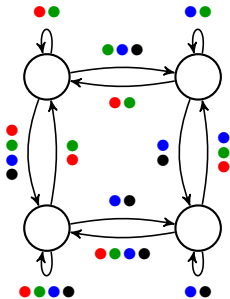


- each parameter valuation represents one Kripke structure
- shared state space, different transition space

Parameterised Kripke Structures

State Transition Systems with Parameters

Transitions with Parameters (coloured transitions)



- each parameter valuation represents one Kripke structure
- shared state space, different transition space

Pithya Tool

C:\Users\luser\skala\pithya\9\vector_field_sudt_4m - Shiny
http://127.0.0.1:5244 [Open in Browser](#) [Publish](#)

number of arrows: 100
parameter γ_{pRB} : 0.014
parameter γ_{EZF1} : 0.14
height of plots: 200
horizontal axis in plot 1: pRB
vertical axis in plot 1: EZF1
horizontal axis in plot 2: pRB
vertical axis in plot 2: EZF1

coloring threshold: 0.1
coloring direction: horizontal vertical both
choose bio file: [Upload complete](#)
choose json file: [Upload complete](#)
new [Download image](#)

Download image

<http://pithya.ics.muni.cz>

[CAV 2017]

Biodegradation of Trichloropropane in *E. coli*

Desired behaviour:

“TCP is finally completely degraded and the concentration of intermediates does not exceed given bounds”

Formally:

$$\varphi_1 = ((([TCP] > x)\mathbf{U}(\mathbf{FG} [TCP] < y))),$$

$$\varphi_2 = ((([GLY] < y)\mathbf{U}(\mathbf{FG} [GLY] > x))),$$

$$\varphi_3 = (\mathbf{G} [DCP] < v) \wedge (\mathbf{G} [GDL] < w),$$

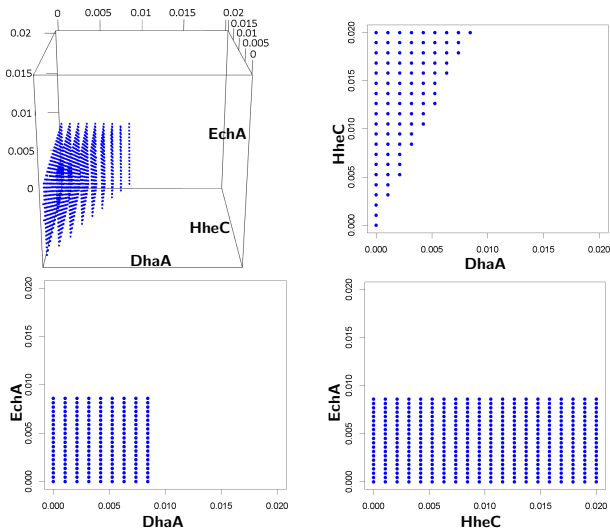
$$\varphi = (\varphi_1 \wedge \varphi_2 \wedge \varphi_3),$$

where x , y , v and w are estimated values making an instance of this property:

- $x = 1.9$ (according to authors¹ using the value 2 mM),
- $y = 0.01$ (obviously, cannot be zero),
- $v \in \{0.5, 0.3, 0.1\}$ (variations based on experimental data observation)
- $w \in \{0.5, 0.25, 0.1\}$ (variations based on experimental data observation)

¹Kurumbang et al., ACS Synthetic Biology, 2013

Biodegradation of Trichloropropane in *E. coli*

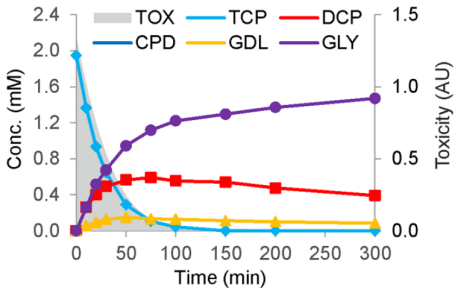
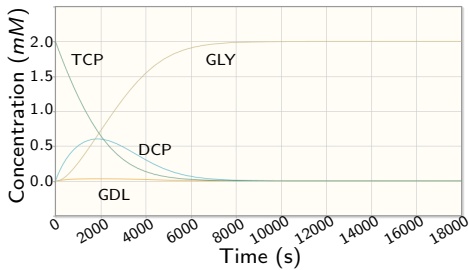
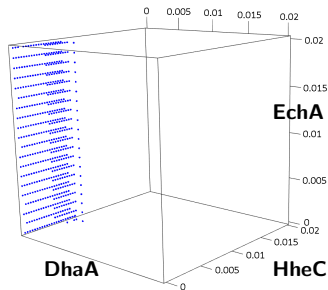


A sample of the resulting parameter space for a particular initial state:
 $TCP \in [1.9, 1.9586]$, $DCP \in [0.448898, 0.5]$, $GDL \in [0.0, 0.0669138]$, $GLY \in [0.0, 0.01]$

Dotted area corresponds to φ ($v = 0.5$, $w = 0.25$).

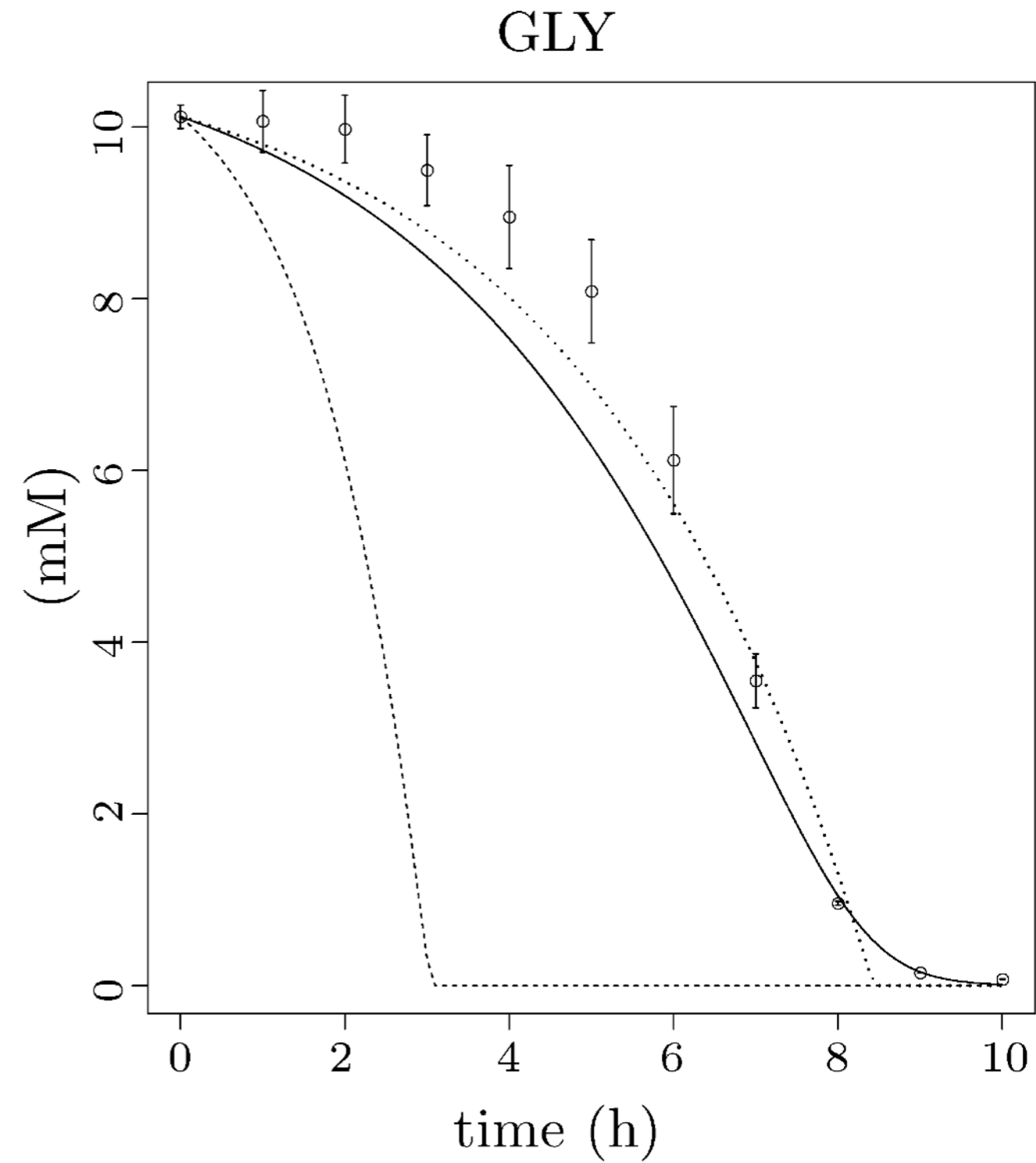
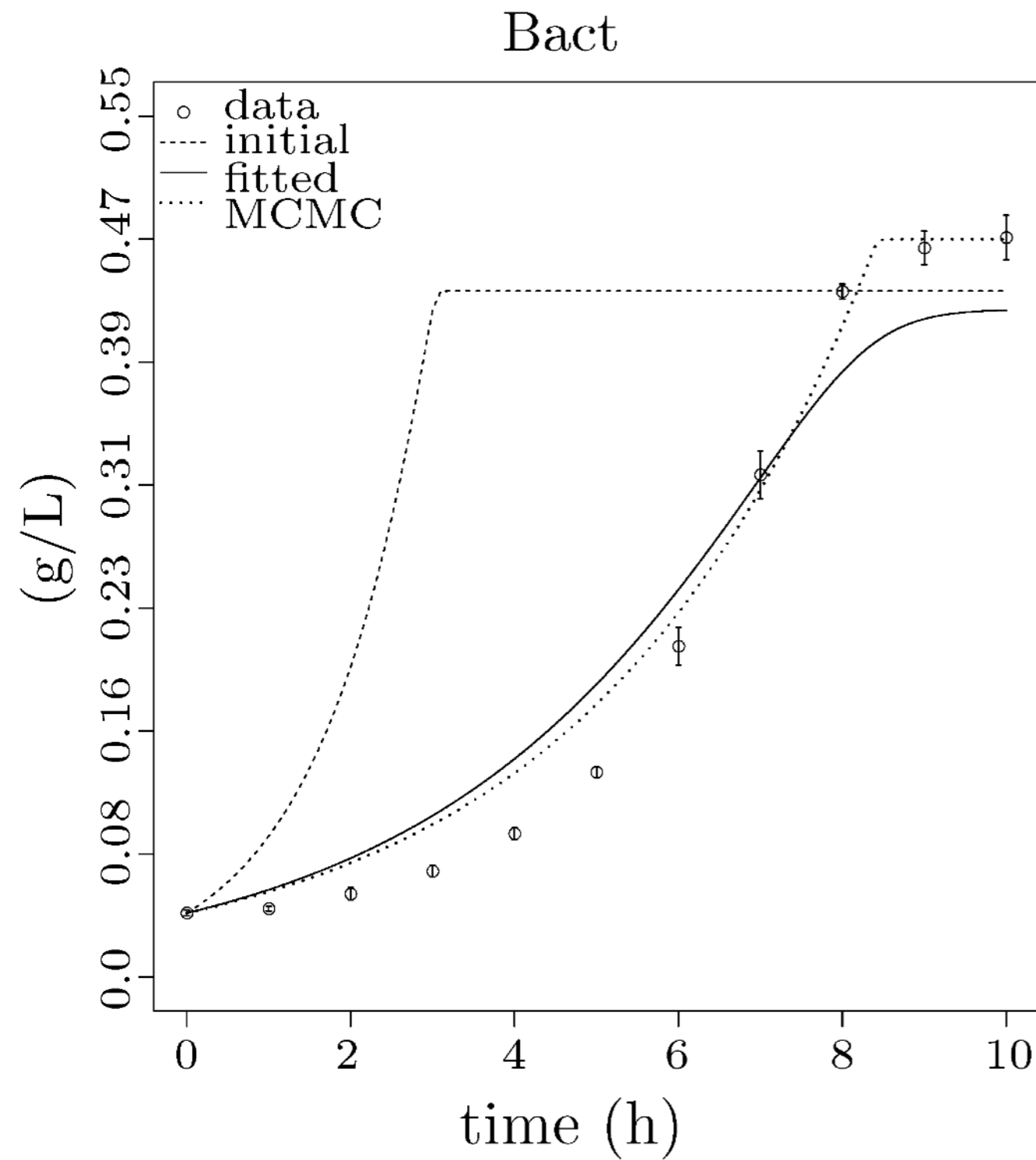
Biodegradation of Trichloropropane in *E. coli*

Preliminary Biological Validation



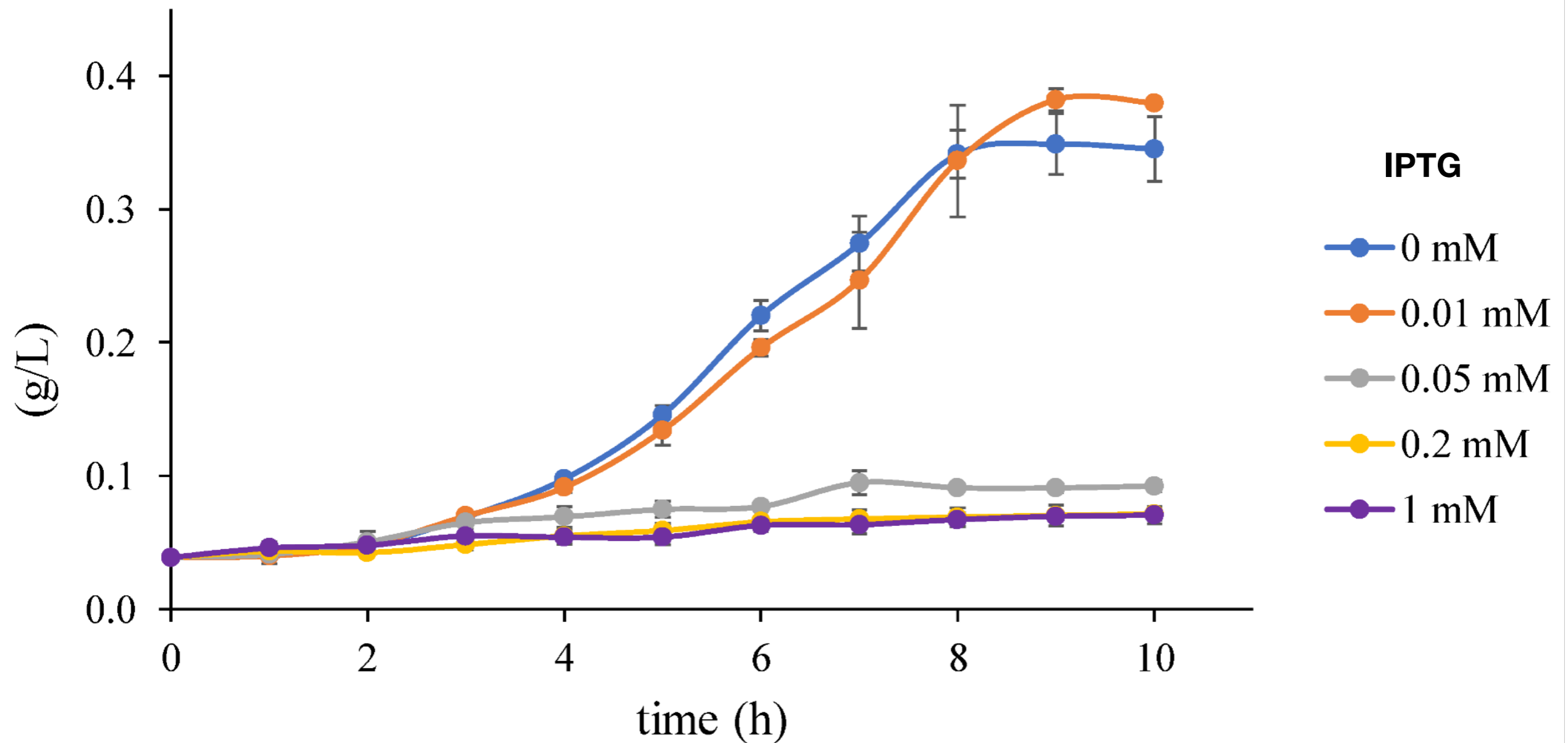
Biodegradation of Trichloropropane in *E. coli*

Extending the Model with Population Growth



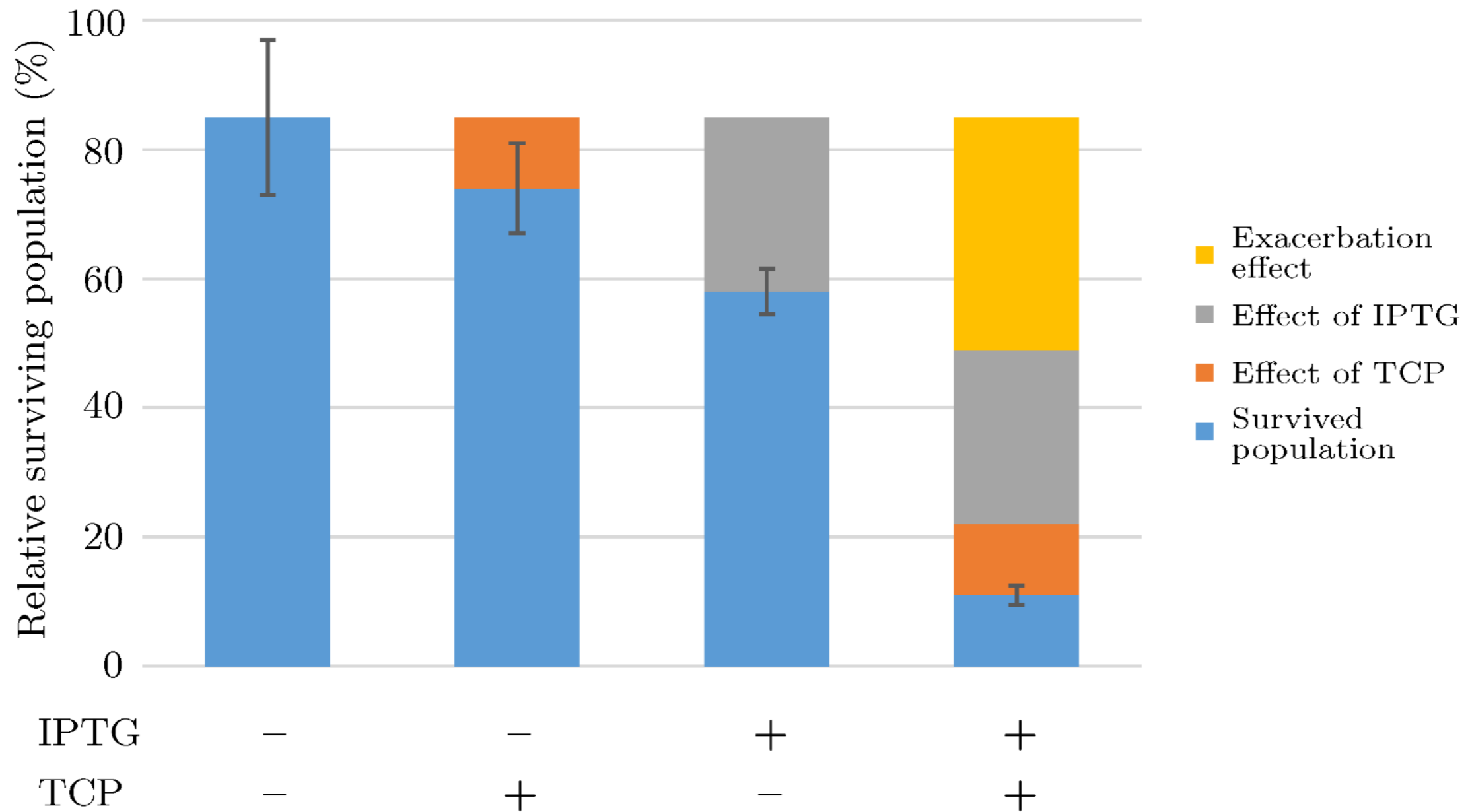
Biodegradation of Trichloropropane in *E. coli*

Extending the Model with Population Growth



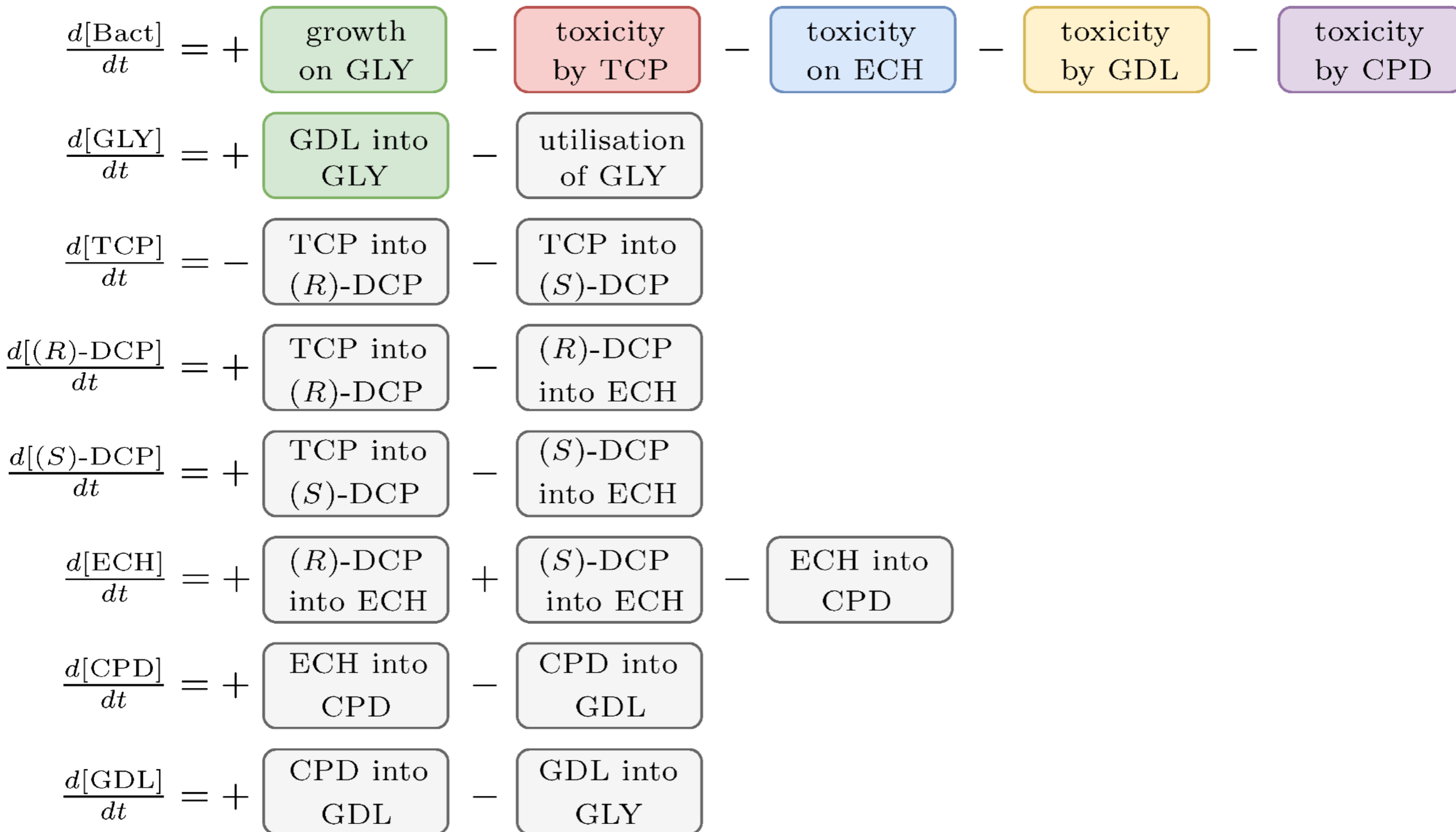
Biodegradation of Trichloropropane in *E. coli*

Extending the Model with Population Growth

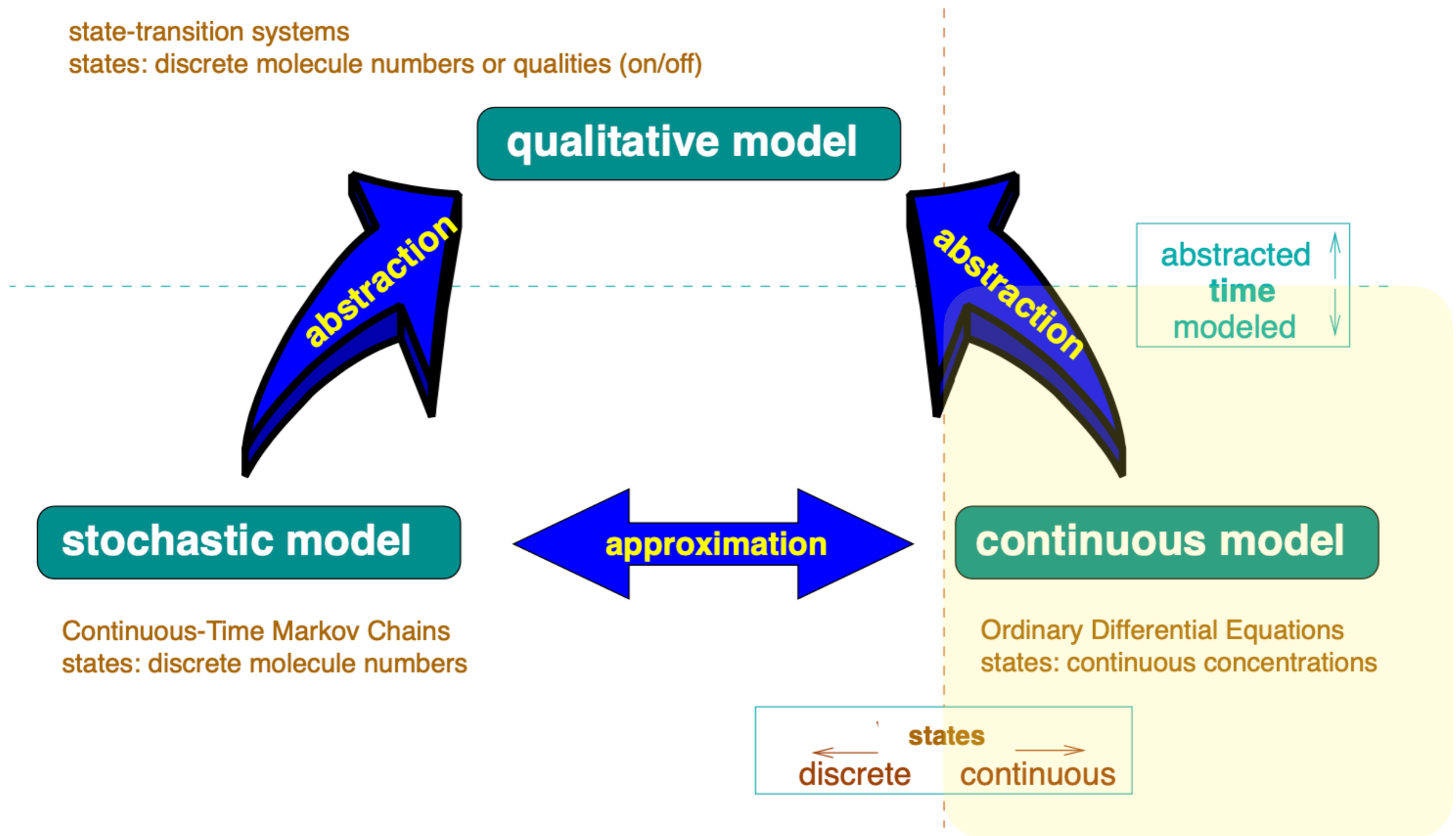


Biodegradation of Trichloropropane in *E. coli*

Extending the Model with Population Growth



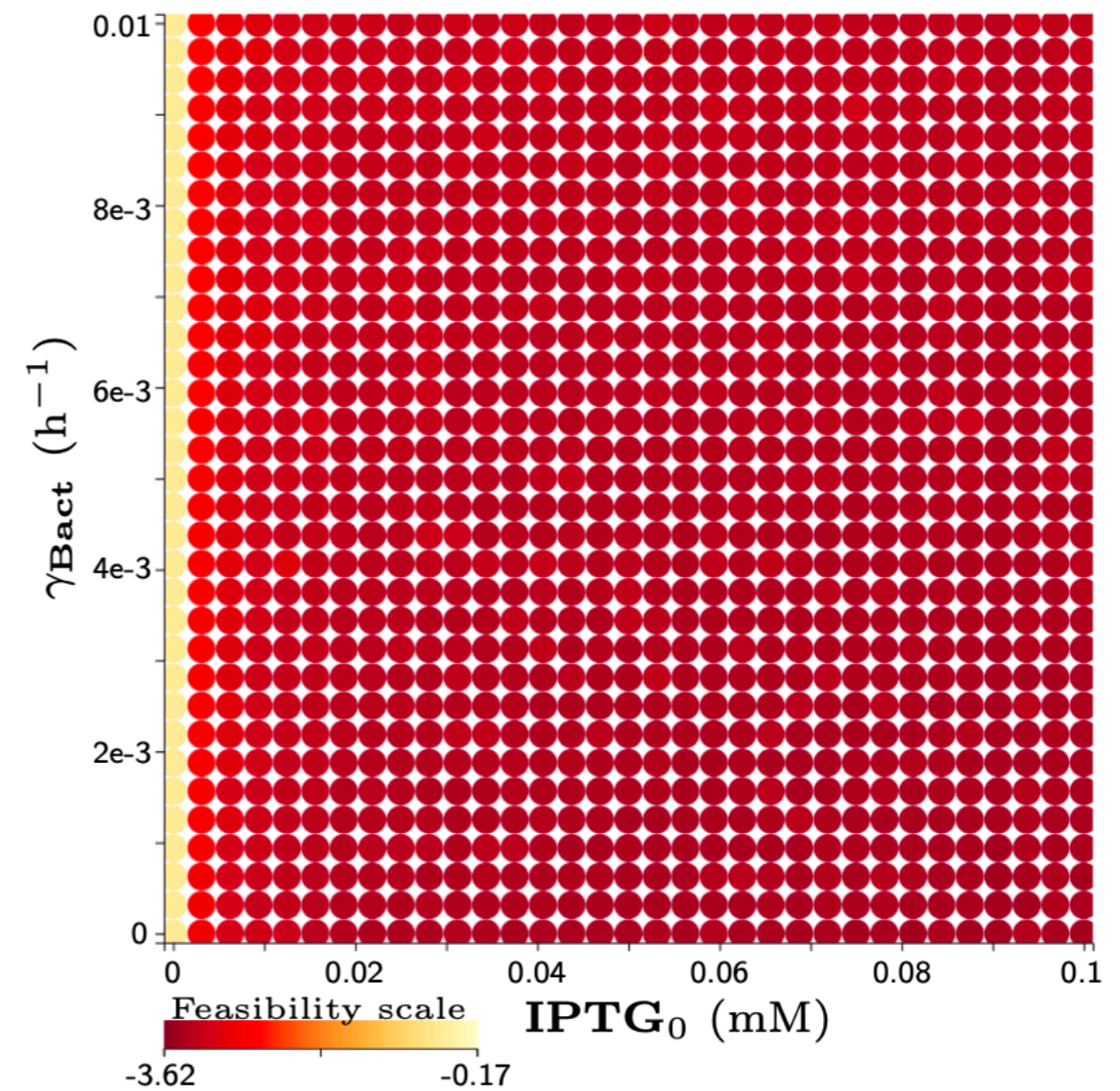
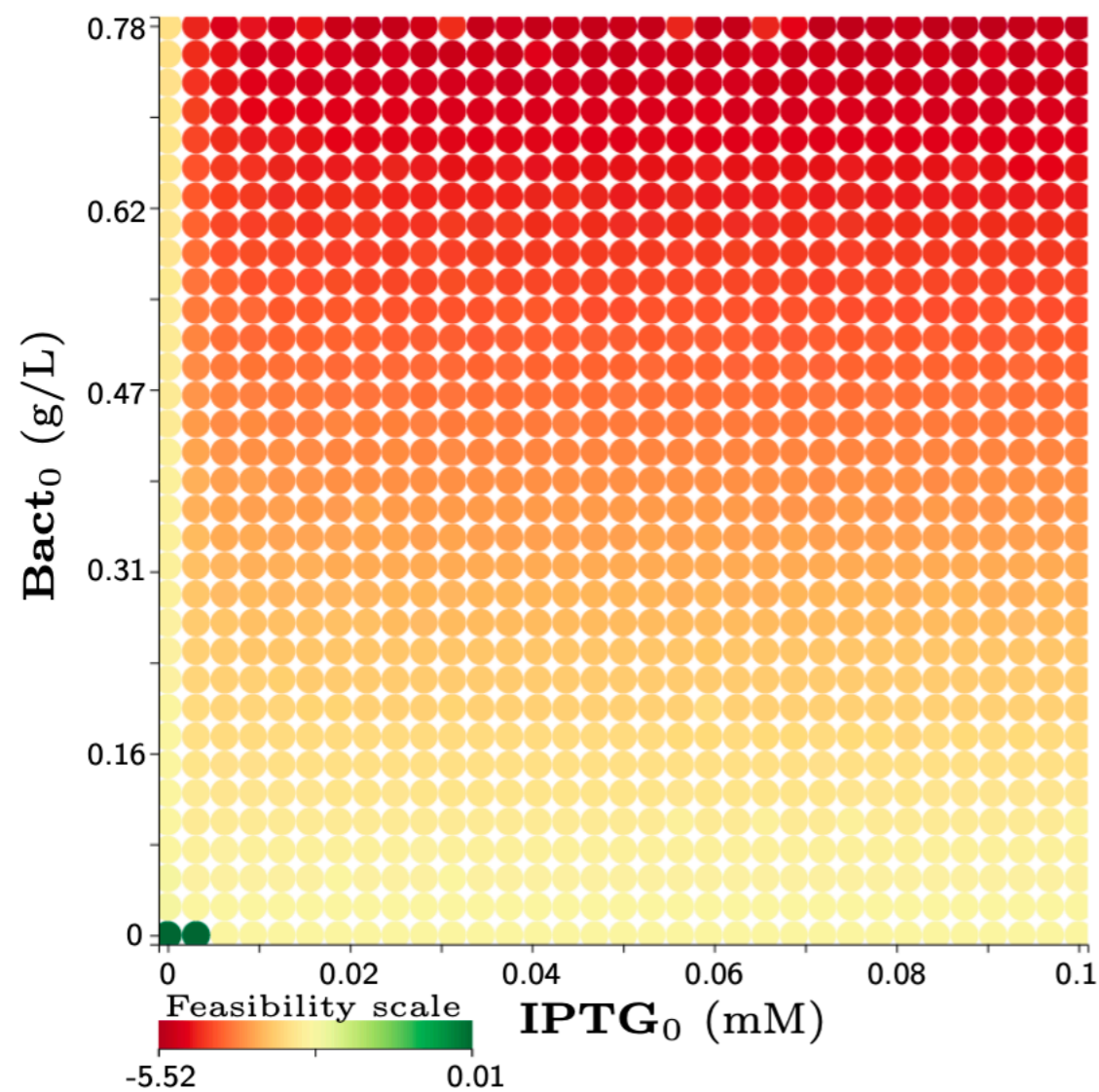
Modelling Frameworks



Biodegradation of Trichloropropane in *E. coli*

Extending the Model with Population Growth - Results

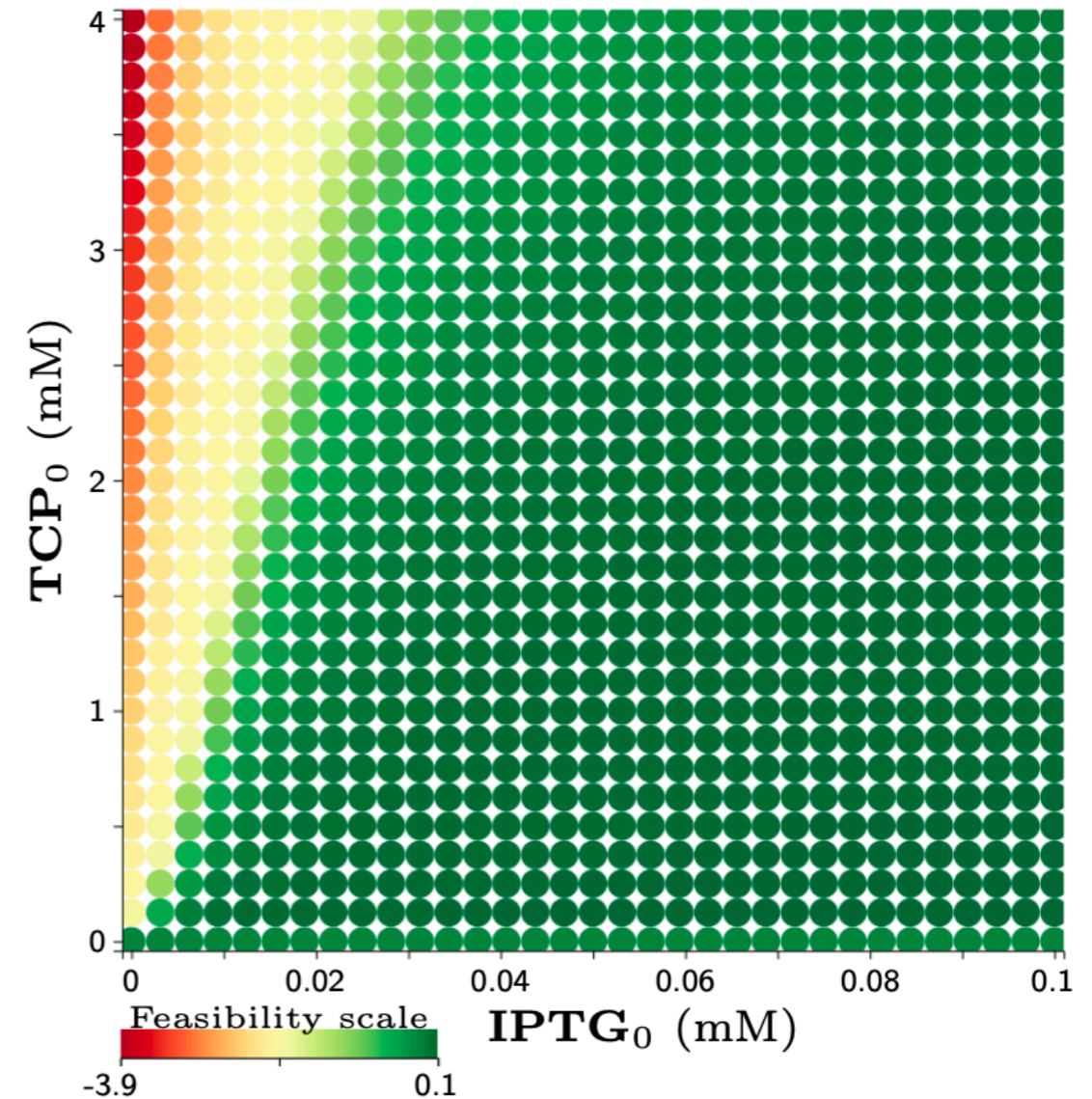
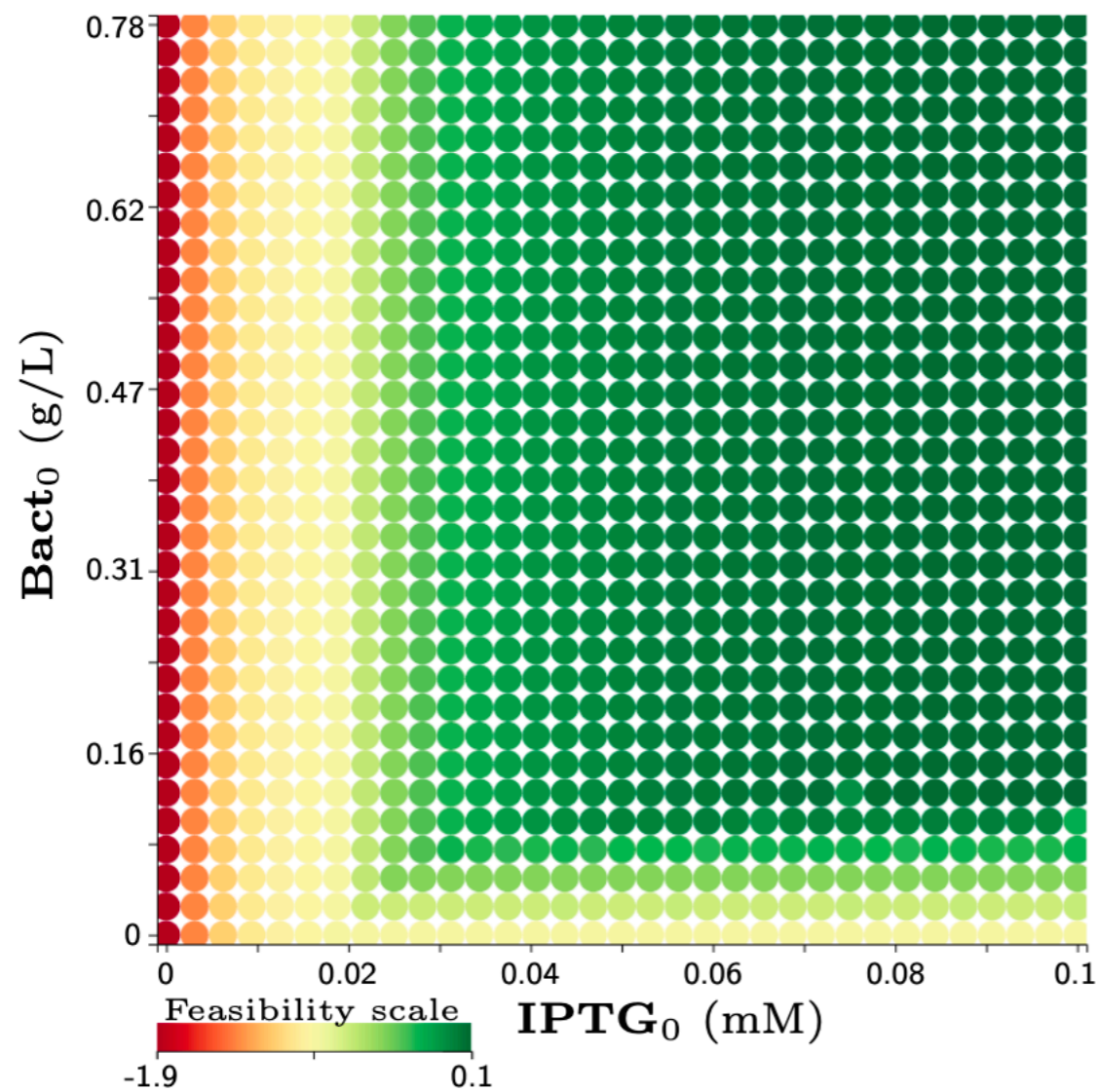
The population dies eventually (drops below 0.01 g/L) while TCP does not degrade entirely (does not drop below 0.1 mM) in the 5 h horizon.



Biodegradation of Trichloropropane in *E. coli*

Extending the Model with Population Growth - Results

The population will never drop below half of its initial value in the 5 h scope and TCP will degrade (drop below 0.01 mM) in the 2.5 h scope at the same time.



Conclusions

- using methods of computer science we can specify biological systems rigorously
- formal methods allow exhaustive exploration of models under parameter uncertainty
- use of formal methods is important for synthetic biology – we want to know what we construct!
- applications in cyber-physical systems
- problems:
 - the grand challenge not yet targeted
 - experts trained in life sciences and computer science needed
 - scalability
 - we need methods giving results up to given precision instead of insisting on exact results
- Machine Learning to learn $F_{\mathcal{N}}$?

Computer Science

Luboš Brim, Marta Kwiatkowska, Jiří Barnat, Thomas Henzinger, Loïc Paulevé, Ezio Bartocci, Luca Bortolussi, Jérôme Feret, Andrzej Mizera, Alessandro Abate, Jan Van Schuppen, Milan Češka, Nikola Beneš, Stefan Haar, Heike Siebert, Hidde de Jong, Ivana Černá

Biology

Ralf Steuer, Louis Mahadevan, Jan Červený, Dušan Lazár, Pavel Krejčí, Stefanie Hertel, Christoff Flamm

Students

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