IA169 System Verification and Assurance

CTL Model Checking

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Linear vs. Branching Time

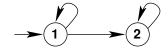
Pnueli, 1977

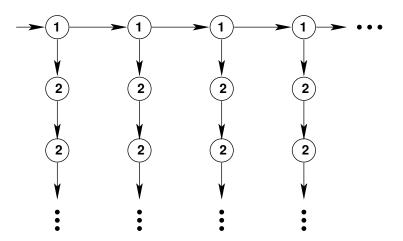
- System is viewed as a set of state sequences Runs.
- System properties are given as properties of runs,
- ... and can be described with a linear-time logic.

Clarke & Emerson, 1980

- System is viewed as a branching structure of possible executions from individual system states Computation Tree.
- System properties are given as properties of the tree,
- ... and can be described with a branching-time logic.

System and Computation Tree





Computation Tree Logic (CTL)

CTL Informally

Possible Future Computations

- For a given node of a computation tree, the sub-tree rooted in the given node describes all possible runs the system can still take.
- Every such a run is possible future computation.

CTL Formulae Allow For

- Specification of state qualities with atomic propositions.
- Quantify over possible future computations.
- Restrict the set of possible future computations with (quantified) LTL operators.

Example

- $\varphi \equiv EF(a)$
- It is possible to take a future computation such that *a* will hold true in the computation eventually.

Let AP by a set of atomic propositions.

- If $p \in AP$, then p is a CTL formula.
- If φ is a CTL formula, then $\neg \varphi$ is a CTL formula.
- If φ and ψ are CTL formulae, then $\varphi \lor \psi$ is a CTL formula.
- If φ is a CTL formula, then $EX \varphi$ is a CTL formula.
- If φ and ψ are CTL formulae, then $E[\varphi \, U \, \psi]$ is a CTL formula.
- If φ and ψ are CTL formulae, then ${\it A}[\varphi\, U\,\psi]$ is a CTL formula.

Alternatively (Backus-Naur Form)

$$\varphi ::= p \mid \neg \varphi \mid \varphi \lor \varphi \mid EX \varphi \mid E[\varphi \ U \varphi] \mid A[\varphi \ U \varphi]$$

Syntactic Shortcuts

Already Known

- The standard shortcuts from the propositional logic.
- Syntactic shortcuts from LTL
 - *F* φ ≡ *true U* φ
 G φ ≡ ¬*F* ¬φ

Deduced CTL Operators

- $EF \varphi \equiv E[true U \varphi]$
- $AF \varphi \equiv A[true U \varphi]$
- $EG \varphi \equiv \neg AF \neg \varphi$
- $AG \varphi \equiv \neg EF \neg \varphi$
- $AX \varphi \equiv \neg EX \neg \varphi$

Models of CTL formulae

Model of a CTL formula

- Let AP be a set of atomic propositions.
- Model of a CTL formula is a state $s \in S$ of Kripke structure $M = (S, T, I, s_0)$.

Reminder

- Run of a Kripke structure is maximal path starting at the initial state of the structure.
- Finite maximal paths are viewed as infinite runs due to infinite repetition of the last state on the path.

Notation

- Let $s \in S$ be a state of Kripke structure $M = (S, T, I, s_0)$.
- $P_M(s) = \{\pi \mid \pi \text{ is a run initiated at state } s\}$

Semantics of CTL

Assumptions

- Let AP be a set of atomic propositions.
- Let $p \in AP$ be an atomic proposition.
- Let $s \in S$ be a state of Kripke structure $M = (S, T, I, s_0)$.
- Let $\varphi,\,\psi$ denote syntactically correct CTL formulae.

Semantics

$$\begin{split} s &\models p \quad \text{iff} \quad p \in I(s) \\ s &\models \neg \varphi \quad \text{iff} \quad \neg (s \models \varphi) \\ s &\models \varphi \lor \psi \quad \text{iff} \quad s \models \varphi \text{ or } s \models \psi \\ s &\models EX \varphi \quad \text{iff} \quad \exists \pi \in P_M(s).\pi(1) \models \varphi \\ s &\models E[\varphi \cup \psi] \quad \text{iff} \quad \exists \pi \in P_M(s).(\exists k \ge 0.(\pi(k) \models \psi \text{ and} \\ \forall 0 \le i < k.\pi(i) \models \varphi)) \\ s &\models A[\varphi \cup \psi] \quad \text{iff} \quad \forall \pi \in P_M(s).(\exists k \ge 0.(\pi(k) \models \psi \text{ and} \\ \forall 0 \le i < k.\pi(i) \models \varphi)) \end{split}$$



Atomic Propositions

• AP={*a*, *b*, *Req*, *Ack*, *Restart*}

Express with CTL Formulae

- A state where *a* is true, but *b* is not, is reachable.
- Whenever system receives a request *Req*, it generates acknowledgement *Ack* eventually.
- In every run there are infinitely many b's.
- There is always an option to reset the system (reach state *Restart*).

Model Checking CTL

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Problem Statements

Model Checking CTL

- Let $M = (S, T, I, s_0)$ be a Kripke structure.
- Let φ be a CTL formula.
- Does initial state of M satisfies φ ?

Alternatively

- Let $M = (S, T, I, s_0)$ be a Kripke structure.
- Let φ be a CTL formula.
- Compute a set of states of M satisfying φ .

Above mentioned approaches are also referred to as to

- Local model checking problem $M, s_0 \models \varphi$.
- Global model checking problem $\{s \mid M, s \models \varphi\}$.

Observation

If the validity of formulae φ and ψ is known for all states, it is easy to deduce validity of formulae ¬φ, φ ∨ ψ, EX φ,

CTL Model Checking – Sketch

- Let M = (S, T, I) be a Kripke structure and φ a CTL Formula.
- A labelling function *label* : $S \rightarrow 2^{2^{\varphi}}$ is computed such that it gives validity of all sub-formulae of φ for all states of Kripke structure M.
- Obviously, $s_0 \models \varphi \iff \varphi \in label(s_0)$.
- Function *label* is computed gradually for individual sub-formulae of φ , starting with the simplest sub-formula and proceeding towards more complex sub-formulae, ending with φ itself.

Sub-formulae of a CTL Formula

Sub-formulae of formula φ

- Let φ be a CTL formula.
- The set of all sub-formulae of formula φ is denoted by 2^{φ} .
- 2^{φ} is defined inductively according to the structure of φ .

Inductive Definition of 2^{φ}

1)
$$\varphi \in 2^{\varphi} (\varphi \text{ is a sub-formula of } \varphi)$$

2) If $\eta \in 2^{\varphi}$ and
• $\eta \equiv \neg \psi$, then $\psi \in 2^{\varphi}$
• $\eta \equiv \psi_1 \lor \psi_2$, then $\psi_1, \psi_2 \in 2^{\varphi}$
• $\eta \equiv EX \psi$, then $\psi \in 2^{\varphi}$
• $\eta \equiv E[\psi_1 \cup \psi_2]$, then $\psi_1, \psi_2 \in 2^{\varphi}$
• $\eta \equiv A[\psi_1 \cup \psi_2]$, then $\psi_1, \psi_2 \in 2^{\varphi}$

3) Nothing else.

Equivalent Existential Form of CTL

Observation

- It is easier to prove validity of existential quantified modal operators than validity of universally quantified ones.
- For the purpose of verification of CTL-specified properties, it is possible to express the CTL formula in an equivalently expressive existential form of CTL.

Equivalent CTL Syntax

• $\varphi ::= p \mid \neg \varphi \mid \varphi \lor \varphi \mid EX \varphi \mid E[\varphi \ U \varphi] \mid EG \varphi$

Task

- Express formula $EG \varphi$ in the original syntax of CTL.
- Give accordingly modified definition of the set of sub-formulae of φ for the above mentioned equivalent syntax.

```
INPUT: Kripke structure M = (S, T, I, s_0), CTL formula \varphi.
OUTPUT: True, if s_0 \models \varphi; False otherwise.
```

```
proc CTLMC(\varphi, M)
   label := l
   Solved := AP \cap 2^{\varphi}
   while \varphi \notin Solved do
            foreach (\eta \in \{\neg \psi_1, \psi_1 \lor \psi_2, EX \psi_1, E[\psi_1 U \psi_2], EG \psi_1 \mid \psi_1, \psi_2 \in Solved\})do
                if (\eta \in 2^{\varphi} \text{ and } \eta \notin \text{Solved})
                   then label := updateLabel(\eta, label, M)
                          Solved := Solved \cup \{\eta\}
                fi
            od
   od
   return (\varphi \in label(s_0))
end
```

```
proc updateLabel(\eta, label, M)
   if (\eta \equiv E[\psi_1 \ U \ \psi_2])
      then return checkEU(\psi_1, \psi_2, label, M)
   fi
   if (\eta \equiv EG\psi)
      then return checkEG(\psi, label, M)
   fi
   foreach ( s \in S)do
       if (\eta \equiv \neg \psi \text{ and } \psi \notin label(s)) or
          (\eta \equiv \psi_1 \lor \psi_2 \text{ and } (\psi_1 \in label(s) \lor \psi_2 \in label(s))) \text{ or }
          (\eta \equiv EX \psi \text{ and } (\exists t \in \{t \mid (s, t) \in T\} \text{ such that } \psi \in label(t)))
          then label(s) := label(s) \cup \{\eta\}
       fi
   od
   return label
end
```

updateLabel()

Algorithm for CTL Model-Checking

```
INPUT:
                 Kripke structure M = (S, T, I),
                 Labelling function label : S \rightarrow 2^{\varphi}, correct w.r.t validity of \psi_1 and \psi_2
OUTPUT: Labelling function label : S \rightarrow 2^{\varphi}, correct w.r.t E[\psi_1 U \psi_2]
proc checkEU(\psi_1, \psi_2, label, M)
   \mathsf{Q} := \{\mathsf{s} \mid \psi_2 \in label(\mathsf{s})\}
   foreach ( s \in Q)do
      label(s) := label(s) \cup \{E[\psi_1 \cup \psi_2]\}
   od
   while (\mathbf{Q} \neq \emptyset) do
           choose s \in Q
           Q := Q \setminus \{s\}
           foreach (t \in \{t \mid T(t, s)\}) do /* all immediate predecessors */
              if (E[\psi_1 \cup \psi_2] \notin label(t) \land \psi_1 \in label(t))
                 then label(t) := label(t) \cup \{E[\psi_1 U \psi_2]\}
                        \mathsf{Q} := \mathsf{Q} \cup \{t\}
              fi
           od
   od
   return label
end
```

 $E[\psi_1 U \psi_2]$

Strongly Connected Components

Sub-graph

- Let G = (V, E) be a graph, ie. $E \subseteq V \times V$.
- Graph G' = (V', E') is called sub-graph of G if it holds that $V' \subseteq V$ and $E' = E \cap V' \times V'$.

Sub-graph C = (V', E') of G = (V, E) is called

- Strongly Connected Component, if $\forall u, v \in V'$ it holds that $(u, v) \in E'^*$ and $(v, u) \in E'^*$.
- Maximal Strongly Connected Component (SCC), if C is strongly connected component and for every v ∈ (V \ V') it is the case that (V' ∪ {v}, E ∩ (V' ∪ {v} × V' ∪ {v})) is not.
- Non-trivial SCC, if C is Strongly Connected Component and $E' \neq \emptyset$.

Algorithm for CTL Model-Checking

```
INPUT: Kripke structure M = (S, T, I, s_0),
                Labelling function label : S 
ightarrow 2^{arphi}, correct w.r.t. \psi
OUTPUT: Labelling function label : S \rightarrow 2^{\varphi}, correct w.r.t. EG \psi
proc checkEG(\psi, label, M)
  S' := \{s \mid \psi \in label(s)\}
   SCC := {C | C is non-trivial SCC G' = (S', T \cap S' \times S')}
   \mathsf{Q} := \bigcup_{C \in SCC} \{ s \mid s \in C \}
   foreach ( s \in Q)do
      label(s) := label(s) \cup \{ EG \psi \}
   od
   while Q \neq \emptyset do
          choose s \in Q
          Q := Q \setminus \{s\}
          foreach (t \in (S' \cap \{t \mid T(t, s)\}))do /* all immediate predecessors in S' */
             if EG \psi \notin label(t)
                then label(t) := label(t) \cup \{EG\psi\}
                       \mathsf{Q} := \mathsf{Q} \cup \{t\}
             fi
          od
   od
end
```

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EGψ

Observation

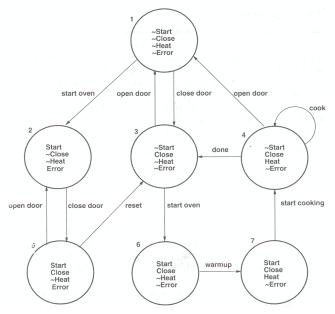
- Every CTL formula φ is made of at most $\mid \varphi \mid$ sub-formulae.
- Decomposition of every sub-graph of G = (S, T) into SCCs can be done in time $\mathcal{O}(|S| + |T|)$.
- Every call to *updateLabel* terminates in time $\mathcal{O}(|S| + |T|)$.

Overall complexity

 Algorithm CTLMC exhibits O(| φ || S |) space and O(| φ | (| S | + | T |)) time complexity.

Example: Microwave oven

$AG(Start \implies AF(Heat))$



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Example: Microwave oven

Transformation of formula $\varphi \equiv AG(Start \implies AF(Heat))$

 $AG(Start \implies AF(Heat))$

- $AG(Start \implies AF(Heat))$
- AG(¬(Start ∧ ¬AF(Heat)))
- AG(¬(Start ∧ EG(¬Heat)))
- ¬EF(Start ∧ EG(¬Heat))
- $\neg E[true U(Start \land EG(\neg Heat))]$

Validity of sub-formulae $[S(\varphi) = \{s \mid s \models \varphi\}]$

- *S*(*Start*) = {2, 5, 6, 7}
- $S(Heat) = \{4,7\}$
- $S(\neg Heat) = \{1, 2, 3, 5, 6\}$
- *S*(*EG*(¬*Heat*)) = {1, 2, 3, 5}
- $S(Start \land EG(\neg Heat)) = \{2, 5\}$
- *S*(*E*[*true U*(*Start* ∧ *EG*(¬*Heat*))]) = {1, 2, 3, 4, 5, 6, 7}
- S(¬E[true U (Start ∧ EG(¬Heat))]) = ∅

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CTL^*

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CTL* as Extension of CTL

Observation

• Every use of temporal operator in a formula of CTL must be immediately preceded with a quantifier, i.e. use of a modal operator without quantification is not possible.

Logic CTL*

- Branching time logic.
- Similar to CTL.
- Unlike CTL, allows for standalone use of modal operators.

Example

• $A[p \land X(\neg p)]$ is CTL^{*}, but is not CTL formula.

Types of CTL* formulae

- Quantifiers *E* and *A* are standalone operators in syntax construction rules. As a result there are two types of formulae in *CTL*: path and state formulae.
- Application of *E* and *A* operators on a path formula (formula of which model is a run of Kripke structure) results in a state formula (formula of which model is a state of Kripke structure)

Syntax of CTL*

 $\begin{array}{ll} \text{state formula} & \varphi ::= p \mid \neg \varphi \mid \varphi \lor \varphi \mid E \ \psi \\ \text{path formula} & \psi ::= \varphi \mid \neg \psi \mid \psi \lor \psi \mid X \ \psi \mid \psi \ U \ \psi \end{array}$

Semantics of CTL*

Assumption

- Let AP be a set of atomic propositions, and $p \in AP$.
- Let M = (S, T, I) be a Kripke structure.
- Let φ_i denote CTL* state formulae, and ψ_i denote CTL* state formulae.

Semantics

$$\begin{split} M, s &\models p \quad \text{iff} \quad p \in I(s) \\ M, s &\models \neg \varphi_1 \quad \text{iff} \quad \neg (M, s \models \varphi_1) \\ M, s &\models \varphi_1 \lor \varphi_2 \quad \text{iff} \quad M, s \models \varphi_1 \text{ or } M, s \models \varphi_2 \\ M, s &\models E \psi_1 \quad \text{iff} \quad \exists \pi \in P_M(s).\pi \models \psi_1 \\ M, \pi \models \varphi_1 \quad \text{iff} \quad M, \pi(0) \models \varphi_1 \\ M, \pi \models \neg \psi_1 \quad \text{iff} \quad \neg (M, \pi \models \psi_1) \\ M, \pi \models \psi_1 \lor \psi_2 \quad \text{iff} \quad M, \pi \models \psi_1 \text{ or } M, \pi \models \psi_2 \\ M, \pi \models X \psi_1 \quad \text{iff} \quad M, \pi^1 \models \psi_1 \\ M, \pi \models \psi_1 U \psi_2 \quad \text{iff} \quad \exists k \ge 0.(M, \pi^k \models \psi_2 \text{ and} \\ \forall 0 \le i < k.M, \pi^i \models \psi_1) \end{split}$$

Comparison of Expressive Power of LTL, CTL and CTL*

Model Unification

Observation

- Every LTL formula is a CTL* path formula.
- Every CTL formula is a CTL* state formula.
- Model of a path formula is a run of Kripke structure.
- Model of a state formula is a state of Kripke structure.
- Not very suitable for comparison.

Model Unification

- For the purpose of comparison we define how a CTL* path formula is evaluated in a state of Kripke structure.
- Let ψ be CTL^* path formula, then

$$M, s \models \psi$$
 iff $M, s \models A \psi$

Motivation

Goals

- We intend to find out whether there are properties (formulae) that can be expressed in one of the logic, but cannot be expressed in another one.
- We intend to find out in which logic more properties can be expressed.
- We intend to identify concrete properties, that cannot be expressed in some other logic, i.e. to find out a formula of logic \mathcal{L}_1 , for which an equivalent formula of logic \mathcal{L}_2 does not exist.

Formula Equivalence

• Formulae φ and ψ are equivalent if and only if for any possible Kripke structure $M = (S, T, I, s_0)$ and any state $s \in S$ it is true that

$$M, s \models \varphi$$
 iff $M, s \models \psi$.

Equivalently Expressive

 Temporal logic L₁ and L₂ have the same expressive power, if for all Kripke structures M = (S, T, I, s₀) and states s ∈ S it holds that

$$\forall \varphi \in \mathcal{L}_1.(\exists \psi \in \mathcal{L}_2.(M, s \models \varphi \iff M, s \models \psi))$$
(1)

$$\wedge \forall \psi \in \mathcal{L}_2.(\exists \varphi \in \mathcal{L}_1.(M, s \models \varphi \iff M, s \models \psi)).$$
(2)

Less Expressiveness

• If only statement (1) is valid, then logic \mathcal{L}_1 is less expressive than logic \mathcal{L}_2 , and vice versa.

Theorem

- LTL and CTL are incomparable in expressive power.
 - 1) AG(EF(q)) is a CTL formula that cannot be expressed in LTL.
 - 2) FG(q) is an LTL formula that cannot be expressed in CTL.

Example – Proof Sketch for 1)

• Find two different Kripke structures and identify two states that can be differentiated with CTL formula AG(EF(q)), but cannot be differentiated with any LTL formula (they generate the same set of runs).

Example – Intuition behind 2) [proof is too complex]

• Show that CTL formula AF(AG(q)) is not equivalent to LTL formula FG(q).

Comparison of LTL, CTL, and CTL*

Consequence

- CTL* is strictly more expressive than LTL.
 - Every LTL formula is a CTL* formula.
 - CTL* formula AG(EFq) is not expressible in LTL.

Consequence 2

- CTL* is strictly more expressive than CTL.
 - Every CTL formula is a CTL* formula.
 - CTL* formula FG(q) is not expressible in CTL.

Observation

- There are properties expressible on both LTL and CTL.
 - CTL formula A[p U q] is equivalent to LTL formula p U q.

Challenge

• Solve The wolf, goat and cabbage problem with NuSMV

Reading

• Moshe Vardi: Branching vs. Linear Time: Final Showdown