Integral and Discrete Transforms in Image Processing Z-transform

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October 24, 2022

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Z-Transform

Definition

(bilateral) Z-Transform

$$F(z) = \sum_{n=-\infty}^{\infty} f(n)z^{-n}$$

(unilateral) Z-Transform

$$F(z) = \sum_{n=0}^{\infty} f(n)z^{-n}$$

Notice: Here $z \in \mathbb{C}$, i.e. for $z = e^{i\omega}$ we get a special case of Z-transform, which is DFT.

Outline

- **Properties**
- 3 Applications

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Z-Transform

Definition

Forward transform

converts discrete series into continuous signal (Z-plane)

$$F(z) = \sum_{n=-\infty}^{\infty} f(n)z^{-n}$$

Inverse transform

• If F(z) is a polynomial, i.e. $F(z) = \sum_{k=-\infty}^{\infty} c_k z^{-k}$, then

$$f(n) = \mathcal{Z}^{-1}(F(z)) = \sum_{k=-\infty}^{\infty} c_k \delta(n-k)$$

Notice: Forward transform applied to discrete signals or linear filters always creates a polynomial with one variable z.

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Z-Transform

Some examples

• Z-transform of a constant signal/averaging filter (left aligned):

$$f(n) = [\underline{1}, 1, 1, 1, 1]$$

 $F(z) = 1 + z^{-1} + z^{-2} + z^{-3} + z^{-4}$

• Z-transform of a constant signal/averaging filter (centered):

$$f(n) = [1, 1, \underline{1}, 1, 1]$$

 $F(z) = z^{+2} + z^{+1} + 1 + z^{-1} + z^{-2}$

Z-transform of Sobel filter:

$$f(n) = [-1, \underline{0}, 1]$$

 $F(z) = -z^{+1} + z^{-1}$

Z-transform of any random filter:

$$f(n) = [1, \underline{3}, 1, 4, 2]$$

 $F(z) = z^{+1} + 3 + z^{-1} + 4z^{-2} + 2z^{-3}$

Notice: With Z-transform, we always pay attention to origin!

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Z-Transform

Relationship to other transforms

Important notes:

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- green circle ($z=e^{i\varphi} \Rightarrow |z|=1$) reduces Z-transform simply to discrete Fourier transform
- DC (direct current) term is DC term from DFT

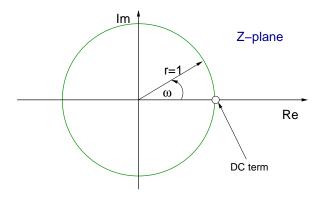


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Z-Transform

An inverse transfom

Inverse transform for linear filters is an easy step:

Signal of length 5:

$$F(z) = 3z^3 + z - 3z^{-1}$$

 $f(n) = Z^{-1}(F(z)) = [3, 0, 1, \underline{0}, -3]$

• Gaussian filter in Z-domain:

$$F(z) = \frac{1}{4}z + \frac{1}{2} + \frac{1}{4}z^{-1}$$

$$f(n) = \mathcal{Z}^{-1}(F(z)) = \frac{1}{4}[1, \underline{2}, 1]$$

Step function in Z-domain

$$F(z) = z^{-1} + z^{-2} + z^{-3} + z^{-4}$$

$$f(n) = \mathcal{Z}^{-1}(F(z)) = [0, 0, 0, 0, 0, 1, 1, 1, 1, 1]$$

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Z-Transform – Properties

Delay/Shift

$$\mathcal{Z}\{f(n-k)\}=F(z)z^{-k}$$

An example:

$$f(n) = [\underline{1}, 2, 3, 4]$$

 $g(n) = [1, \underline{2}, 3, 4]$
 $h(n) = [1, 2, \underline{3}, 4]$

$$F(z) = 1 + 2z^{-1} + 3z^{-2} + 4z^{-3}$$

$$G(z) = z^{1} + 2 + 3z^{-1} + 4z^{-2}$$

$$H(z) = z^{2} + 2z + 3 + 4z^{-1}$$

$$F(z) = G(z)z^{-1}$$

$$F(z) = H(z)z^{-2}$$

$$G(z) = H(z)z^{-1}$$

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Z-Transform – Properties

Convolution theorem

$$\mathcal{Z}\{f(n)*g(n)\}=F(z)\cdot G(z)$$

Corollary: Convolution in time domain becomes a polynomial multiplication in Z-domain:

$$\mathcal{Z}([\underline{3},5]*[\underline{-1},1]) = (3+5z^{-1})\cdot(-1+z^{-1})$$

An example:

$$\begin{array}{rcl}
[\underline{3},5] * [\underline{-1},1] & = & [\underline{-3},-2,5] & /\mathcal{Z}(\cdot) \\
\mathcal{Z}([3,5] * [\underline{-1},1]) & = & \mathcal{Z}([\underline{-3},-2,5]) \\
\mathcal{Z}([3,5]) \cdot \mathcal{Z}([\underline{-1},1]) & = & \mathcal{Z}([\underline{-3},-2,5]) \\
(3+5z^{-1}) \cdot (-1+z^{-1}) & = & -3-2z^{-1}+5z^{-2} \\
-3-2z^{-1}+5z^{-2} & = & -3-2z^{-1}+5z^{-2}
\end{array}$$

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Z-Transform – Properties

Linearity

$$\mathcal{Z}\{af(n) + bg(n)\} = aF(z) + bG(z)$$

An example:

$$f'(n) = f(n) * [1, -1, \underline{2}]$$

$$f'(n) = 2f(n) - f(n+1) + f(n+2) / \underline{\mathcal{Z}}(\cdot)$$

$$\mathcal{Z}(f'(z)) = \mathcal{Z}(2f(n)) - \mathcal{Z}(f(n+1)) + \mathcal{Z}(f(n+2))$$

$$F'(z) = 2F(z) - F(z)z^{1} + F(z)z^{2}$$

$$F'(z) = F(z)[2 - z^{1} + z^{2}]$$

Notice: Keep in mind that: $\mathcal{Z}([1, -1, 2]) = z^2 - z^1 + 2$

Z-Transform – Properties

Convolution theorem - cont'd

time domain	Z-domain
separation of convolved signals	polynomial factorization

An example (Gaussian decomposition):

$$[1, \underline{2}, 1] = \mathcal{Z}^{-1} [z + 2 + z^{-1}]$$

$$= \mathcal{Z}^{-1} [(1 + z^{-1}) \cdot (z + 1)]$$

$$= \mathcal{Z}^{-1} [1 + z^{-1}] * \mathcal{Z}^{-1} [z + 1]$$

$$= [\underline{1}, 1] * [1, \underline{1}]$$

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Z-Transform - Properties

Symmetry

$$\mathcal{Z}\{f(-n)\} = F\left(\frac{1}{z}\right)$$

See the relationship betwenn time-revesed signals:

$$f(n) = [\underline{1}, 2, 3, 4, 5, 6]$$

$$F(z) = 1 + 2z^{-1} + 3z^{-2} + 4z^{-3} + 5z^{-4} + 6z^{-5}$$

$$\downarrow \downarrow$$

$$f(-n) = [6, 5, 4, 3, 2, \underline{1}]$$

$$F(z^{-1}) = 1 + 2z^{1} + 3z^{2} + 4z^{3} + 5z^{4} + 6z^{5}$$

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Z-Transform – Properties

Signal upsampling

Let L be a positive integer and

$$h(n) = \begin{cases} f(n/L) & n/L \text{ is an integer} \\ 0 & \text{otherwise} \end{cases}$$

Then

$$H(z) = F(z^L)$$

Derivation:

$$H(z) = \sum_{n=...,-L,0,L,...} f(n/L)z^{-n}$$

$$= \sum_{m=...,-1,0,1,...} f(m)z^{-mL}$$

$$= \sum_{m=...,-1,0,1,...} f(m) (z^{L})^{-m}$$

$$= F(z^{L})$$

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Z-Transform – Properties

Signal decomposition without downsampling

$$F(z) = \frac{1}{2} [F(z) + F(-z)] + \frac{1}{2} [F(z) - F(-z)]$$

where

$$F_{even}(z^2) = \frac{1}{2} [F(z) + F(-z)]$$
 ... even component
 $F_{odd}(z^2) = \frac{1}{2} [F(z) - F(-z)]$... odd component

An example:

$$f = [\underline{a}, b, c, d, e, f] / \mathcal{Z}(\cdot)$$

$$F(z) = a + bz^{-1} + cz^{-2} + dz^{-3} + ez^{-4} + fz^{-5}$$

$$EVEN = \frac{1}{2} [F(z) + F(-z)] = a + cz^{-2} + ez^{-4}$$

$$= \mathcal{Z}^{-1} [\underline{a}, 0, c, 0, e, 0]$$

$$ODD = \frac{1}{2} [F(z) - F(-z)] = bz^{-1} + dz^{-3} + fz^{-5}$$

$$= \mathcal{Z}^{-1} [\underline{0}, b, 0, d, 0, f]$$

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Z-Transform – Properties

Signal decomposition with downsampling

$$F(z) = F_{even}(z^2) + z^{-1}F_{odd}(z^2)$$

An example:

$$f(n) = [\underline{a}, b, c, d, e, f]$$
 $F(z) = a + bz^{-1} + cz^{-2} + dz^{-3} + ez^{-4} + fz^{-5}$
 $f_{even}(n) = [\underline{a}, c, e]$ $F_{even}(z) = a + cz^{-1} + ez^{-2}$
 $f_{odd}(n) = [\underline{b}, d, f]$ $F_{odd}(z) = b + dz^{-1} + fz^{-2}$

$$F_{even}(z^{2}) = a + cz^{-2} + ez^{-4}$$

$$F_{odd}(z^{2}) = b + dz^{-2} + fz^{-4}$$

$$F_{even}(z^{2}) + z^{-1}F_{odd}(z^{2}) = a + bz^{-1} + cz^{-2} + dz^{-3} + ez^{-4} + fz^{-5}$$

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Z-Transform

Transfer function

Definition

Let f and h be input and output signals, respectively, and let g be a linear filter such that h = f * g, then $\mathcal{Z}(g)$ is called a *transfer function*.

An example:

$$h = f * [1, 2, 1] / Z(\cdot)$$

$$H(z) = F(z) \cdot (z + 2 + z^{-1})$$

$$\frac{H(z)}{F(z)} = z + 2 + z^{-1}$$

$$G(z) = \frac{H(z)}{F(z)} = z + 2 + z^{-1}$$

Notice: Transfer function expresses the frequency response of selected linear filter. In optics, G(z), when assigning $z = e^{i\varphi}$, is called a *optical transfer function* (OTF) and its time-domain counter part is a point spread function (PSF).

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Z-Transform

Applications

The areas that rely on Z-transform

- Linear recursive filters
- Optimization of wavelet transform
- Understanding and frequency analysis of linear filters

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You should know the answers ...

- Describe the relationship between Fourier transform and Z-transform.

- How is the time delay expressed with Z-transform?
- How is the signal upsampling expressed with Z-transform?
- What is a transfer function?
- What does the polynomial $z \frac{1}{z}$ mean?

Bibliography

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- What is the Z-transform of signal [1, 2, 4, 3, 20, -5, 23]?
- What is the Z-transform of Gaussian filter?
- Is it possible to perform inverse Z-transform for a linear filter?

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