# Liability for a conduct of Artificial Intelligence

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Artificial
Intelligence /
Autonomous
Machines

**TERMINOLOGY** 

BASIC INFORMATION ON FUNCTION OF AI

**EXAMPLES** 

# Characteristics of an Al driven machine



Perception of the environment



Differentiation of objects, events and situations



Assesment of relations among them



Creation of internal models of the environment



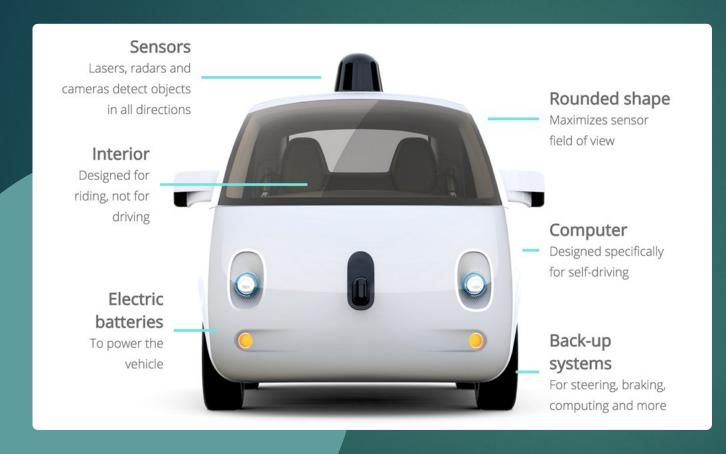
Adoption of decisions



Perception of consequences of those decisions

### Autonomous Agent

- ► Autonomous behaviour Al is further capable of gathering information through its own sensors or by data exchange and of making independent decisions based on that information, all without further human input
- Autonomous agent a software entity (goal-oriented) capable of executing actions in its environment: virtual, physical
- Examples of autonomous agents: autonomous intelligent cars (AIC), drones/unmanned aircraft vehicles (UAV), satellites
- Sources of information: sensors, cameras, data connection, lasers



# Autonomous / Driverless Vehicles

# General Classification of Autonomous Agents I.

- Is the classification used for AIC applicable for other autonomous agents?
- Different level of:
  - connectivity (interaction, user input)
  - mobility (virtual x physical, means of movement)
  - ▶ intelligence (programming, machine learning)
- Variability in data input
  - sensors
  - data exchange
  - products

#### **Five Levels of Vehicle Autonomy**



#### Level 0

#### No automation:

the driver is in complete control of the vehicle at all times.





Level 1











#### Driver assistance:

the vehicle can assist the driver or take control of either the vehicle's speed, through cruise control, or its lane position, through lane guidance.

#### Level 2

#### Occasional self-driving:

the vehicle can take control of both the vehicle's speed and lane position in some situations, for example on limited-access freeways.

#### Level 3

#### Limited self-driving:

the vehicle is in full control in some situations, monitors the road and traffic, and will inform the driver when he or she must take control.

#### Level 4

#### Full self-driving under certain conditions:

the vehicle is in full control for the entire trip in these conditions, such as urban ride-sharing.

#### Level 5

#### Full self-driving under all conditions:

the vehicle can operate without a human driver or occupants.

Level of Automation/Autonomy in Autonomous Intelligent Cars

Source: SAE & NHTSA

# General Classification of Autonomous Agents II.

- ► Failure of AIC on one level of autonomy will not be the same as the failure of another AIC on the same level
- Level of autonomy as a useful concept for classification but not for liability distribution
- ► UAVs, planes, ships similar autonomy level concepts (applicable), yet different purpose, users
- Possible to compare liability concepts according to certain features used in autonomous agents

Overview of Legal Materials & Preparation Works

EUROPEAN UNION
COUNCIL OF EUROPE
CZECH REPUBLIC

#### European Union

10. 5. 2017 – Single Digital Market – development of Al 21. 7. 2017 – Report with Recommendations to the Commission on Civil Law Rules on Robotics – law, ethics

10. 4. 2018 – Declaration of Cooperation on Artificial Intelligence 25. 4. 2018 – Artificial Intelligence for Europe – common european approach

7. 12. 2018 –
Coordinated plan for artificial intelligence – part Ethics by design and the regulatory framework

8. 4. 2019 – Draft of the Ethics Guidelines for Trustworthy Al

Al H-LEG (High-Level Expert Group)

## Council of Europe

Specific issues in the protection of human rights and democracy

Governing the Game Changer – Conclusions from the conference – 27 February 2019 The European
Commission for the
Efficiency of Justice
(ECFEJ) – monitoring
body bringing together
the national experts

Artificial Intelligence at the Service of the Judiciary – September 2018 European ethical charter on the use of artificial intelligence in judicial systems and their environment – December 2018

## Czech Republic



The Czech Republic is one of the signatories of the Declaration on Cooperation on Artificial Intelligence



December 2018 - Analysis of the Development Potential of Artificial Intelligence in the Czech Republic – 3rd part on legal and ethical aspects



National Strategy of Artificial Intelligence which builds on the recommendations in the study and the EU-wide Coordinated Plan for Artificial Intelligence



Platforms – academical, industrial, focus on autonomous vehicles

# LIABILITY AS THE KEY ISSUE

WHY IS LIABILITY AN ISSUE IN AI

WHAT ARE THE POSSIBLE SOLUTIONS

LIABILITY CONCEPTS

#### Liability as the Key Legal Issue in Al

- Actions are carried out by the machine independently (liability for damages)
- Software x physical components (preventive liability)
- Software service level x Driving school for humans
- Changes in the code, unpredictability

# Liability for Emerging Digital Technologies

- Commission Staff Working Document Liability for emerging digital technologies
  - Accompanying the document Communication from the Commission to the European Parliament, the European Council, the Council, the European Economic and Social Committee and the Committee of the Regions - Artificial intelligence for Europe
  - ▶ Issued on 25th of April 2018
- https://ec.europa.eu/digital-single-market/en/news/european-commission-staff-working-document-liability-emerging-digital-technologies

## Liability Principles

- Liability responsibility of one party for harm or damage caused to another party, may be a cause for compensation, financially or otherwise, by the former to the latter
- Civil law x Administrative law x Criminal law
- Contractual x Extracontractual
- Fault-based (subjective) x Strict-based (objective)



#### Principles of European Tort Law

- Non harmonized accross EU
- The European Group on Tort Law a group of scholars in the area of tort law
- Principles of European Tort Law (PETL) similar to the Principles of European Contract Law: <a href="http://civil.udg.edu/php/biblioteca/items/283/PETL.pdf">http://civil.udg.edu/php/biblioteca/items/283/PETL.pdf</a>
- ▶ Attribution to a concrete person (PETL):
  - Whose conduct have caused the damage
  - Whose abnormally dangerous activity has caused the damage
  - Whose auxiliary has caused the damage within the scopes of its functions

### Liability Principles in Civil Law

- 1) Illegal action (tort)
- 2) Damage
- 3) Causal Nexus
- 4) Fault (intent, negligence)
- In strict based liability fault is not one of the conditions causal nexus the element present in every liability principle
- Causal nexus causa / conditio sine qua non / but for principle would the negative effect appear without the conduct of the defendant?

# Causal nexus for the conduct of Al

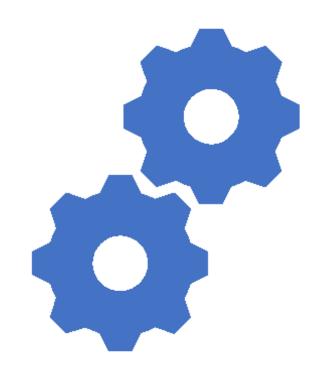
- Lower ability to control an autonomous machine

   does not follow the will of the driver, decision making is not fully predictable (even by the programmer) as the machine learns itself while in function
- Inherent level of uncertainty in software "The long-term operation of complex systems entails a fundamental uncertainty, especially in the context of complex environments, including new or unpredictable environments"



# Causal nexus for the conduct of distributed Al

In complex processing environment, it is not possible to simply impose liability on any identifiable unit – multiple units means: multiple programmers, vast number of users, unpredictable number of interactions between the machines on number or platforms, operating systems, data exchanges, telecommunications programmes



### Different Approaches to Causation

- ► Full liability x Proportional liability
- Multicausual damage:
  - Alternative causes
  - Concurrent causes
  - Cumulative causes
- ► Three types of approaches towards causation in Europe
  - Overarching
  - Bounded
  - Pragmatic

## Liability Concepts

- Options: keep, discard, amend
- No-fault/strict (product/design defect) liability
- Risk based liability
- Quick claim resolution in certain scenarios
- Legal personhood (subjectivity)



# Technical Standardisation

STANDARDISATION AS A PREVENTIVE MEASURE

STANDARDS VS. LEGAL REGULATION

**HOMOLOGATION** 

## Technical Standards & Product Safety

- Part of preventive liability concept
- Way of ensuring product safety
- Directive 2001/95/EC of the European Parliament and of the Council of 3 December 2001 on general product safety
- Specific product safety rules: dangerous goods, vulnerability of consumers, need for compatibility
- Involvement of all parties manufacturers, distributors, users, law-makers
- ► Technical standards description of a product from a technical perspective, construction, materials and other criteria
- Homologation when a product needs prior certification before it can be available on the market (motor and aerial vehicles)

#### Technical Standards

- Although normative, do not have legal nature
- Recommendation for manufacturers, best practice
- Can be binding, if referenced in law often published as subordinate legislation
- Adopted by specialized authorities ISO, NIST, ETSI...
- Legislation designates which products must be safe and technical standards determines how to achieve it.
- Technical standards as a necessary addendum to regulatory approach

## Missing Role Model

- ► Technical standards in the field of avionics are they usable for other technologies, f.e. autonomous vehicles?
- Software in autonomous vehicles has different challenges
  - ▶ Pedestrian crossings, objects in the road, other vehicles
  - Changing traffic conditions
  - "Piloted" by a citizen, consumer, not by a professional
  - Multitude of sensors radar, lidar, camera
- ► Technical standards for autonomous trains similar problems

## Testing / Homologation Methods



Real – life testing

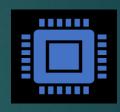
Report with recommendations to the Commission on Civil Law Rules on Robotics (2015/2103(INL))

Good for testing standard behaviour, but subjective, possibly biased (OICA)



Black – box testing

Only the desirability of the output is assessed



Hardware-in-loop

Real-time testing, capability of the controller is tested by virtual stimuli coming from a computer integrated in the simulation environment

Research on how to adapt it for Al

#### Possible Solutions

- Preventive measures testing, standardisation, homologation
- Mandatory insurance (common insurance predictability of risks)
- Explainable Al
- Reallocation of the burden from the victim towards the person with most information
- Proximal causation Harmonisation of criteria (at least doctrinally) for proving of causal nexus across EU
- Compensation fund/ liability fund

# How to Regulate Al

UNANSWERED QUESTIONS METHODOLOGY

### New Technologies & the Law

- Challenges of new technologies
  - Multidisciplinary approach is needed to comprehend how the technology works
  - Multidisciplinary approach is to be taken also in the field of law itself
  - Rapid development, unpredictability
  - ► Solutions?
  - Concentration on the content and the purpose of legal regulation
  - The use of analogy is needed
  - ▶ It is impossible to regulate the current phenomena as well as the future ones

# Artificial Intelligence as the New Legal Challenge



Is new regulation for AI needed?



When is it possible to use analogy?



Is it just another "new technology" or are there differences?



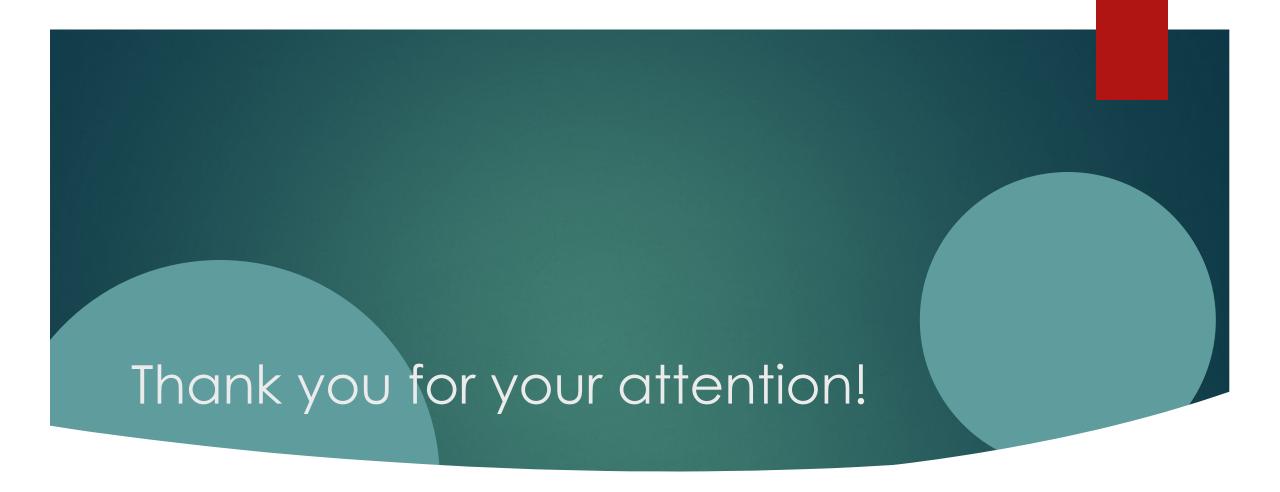
Is it possible to regulate AI as such or should sectorial approach be taken?



Which measures are more suitable for regulating AI?

## Questions?





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