

# Měření úhlové distribuce listů v listnatých porostech za použití UAV

**Jan Pisek**



TARTU OBSERVATORY  
space research centre

**Brenden McNeil**



**Harald Lepisk**



## Vzdělání

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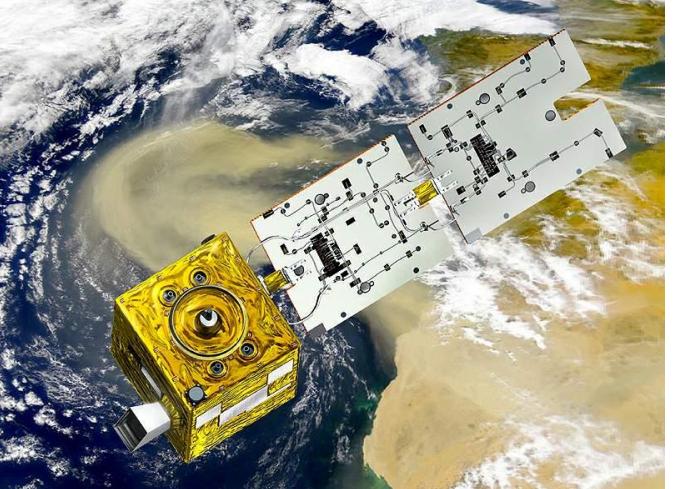
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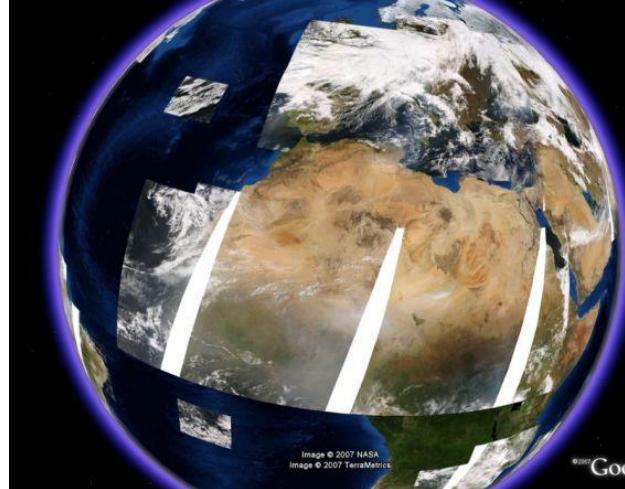
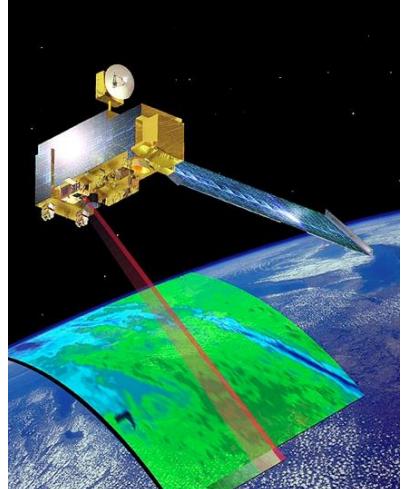
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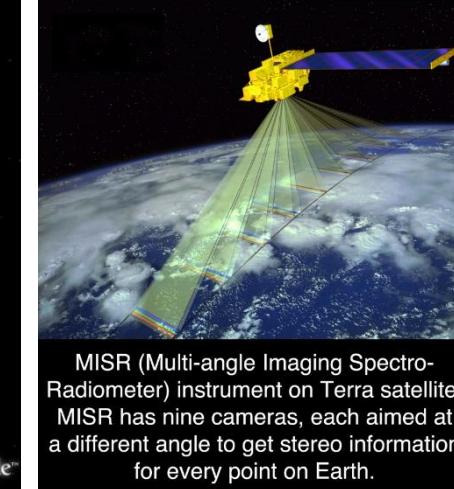
POLDER 1-3 (~6 km)



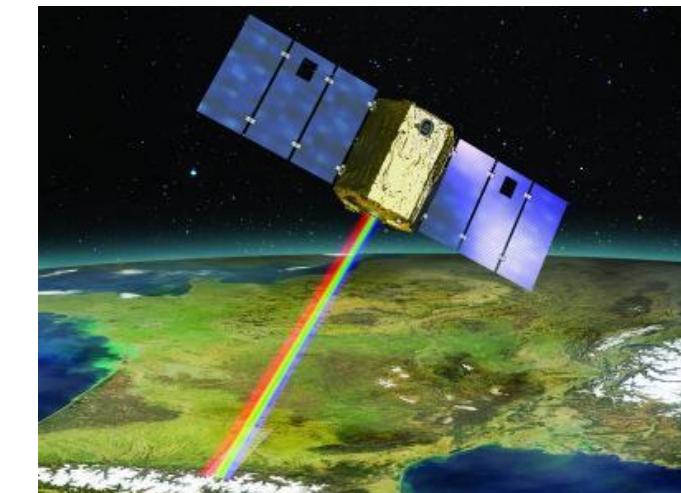
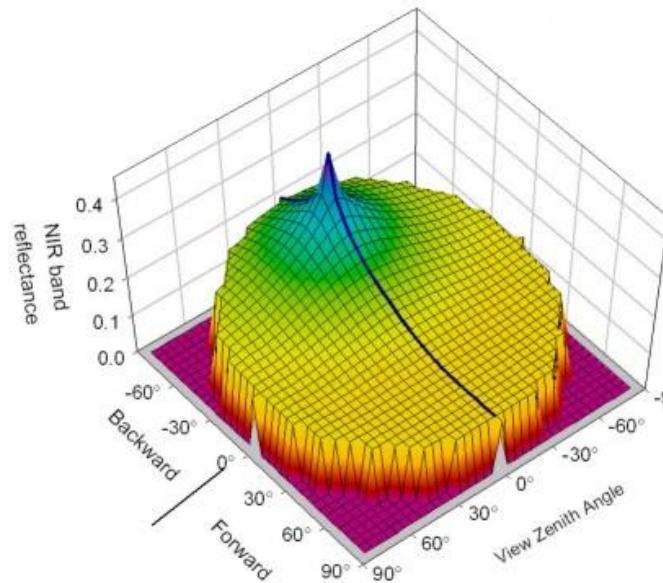
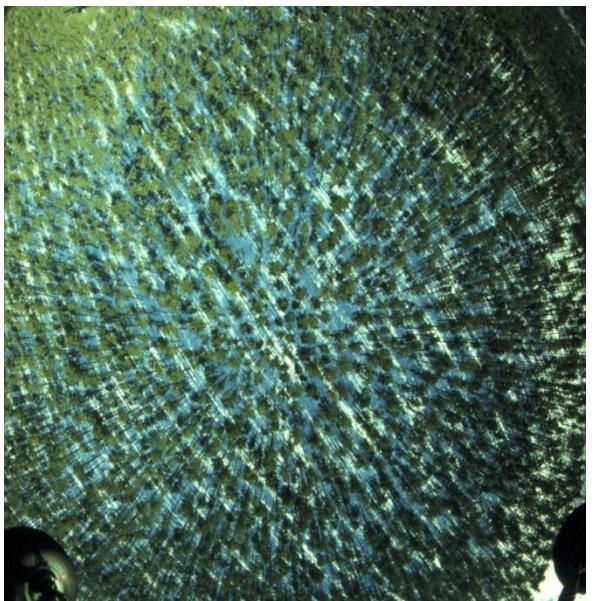
MODIS (500 m)



MISR (275 m)



MISR (Multi-angle Imaging Spectro-Radiometer) instrument on Terra satellite.  
MISR has nine cameras, each aimed at a different angle to get stereo information for every point on Earth.



Venus microsatellite, 12 spectral bands, 5-10 m every 2 days



# Järvselja RAMI testovací plochy

A-Z Index | Acknowledgements | Contact Us | Search | Legal notes | English (en) ▾

European Commission | JRC | IES | CRM | CRM-LESS/MORE | RAMI

26-Oct-2013 Path: RAMI-IV : EXPERIMENTS : ACTUAL CANOPIES : JARVSELJA SUMMER PINESTAND

**rami**

**RAMI-IV** **RAMI3** **RAMI2** **RAMI1** **DEFINITIONS** **FAQs** **FORMATS** **ORGANISATION**

**LINKS**

**iPILPS**

**Czech RAMI CM repository**

## RAdiation transfer Model Intercomparison (RAMI)

### Järvselja Pine Stand (Summer): HET07\_JPS\_SUM

This page provides descriptions of the architectural, spectral and illumination related properties of a 124 year old *Pinus sylvestris* stand located at 58° 18' 47.13" N 27° 17' 48.23" E. The stand was inventoried in the summer 2007 by Andres Kuusk, Joel Kuusk, Mait Lang, Tõnu Lükk, Matti Möttus, Tiiu Nilson, Milna Rautalainen, and Alo Benmäe of the Tartu Observatory, in Tõravere, Estonia as well as the Estonian University of Life Sciences, Tartu, Estonia. Potential RAMI participants thus are to treat the information presented on this page as actual 'inventory data', that is, they should identify/extract those parameters and characteristics that are required as input to their canopy reflectance models. In some cases this may mean that simplifications have to be made to the available information, or, that parts of the available information cannot be - or have to be modified before being - exploited with a given radiative transfer model. Whatever the case may be, all potential RAMI participants should mimic the standard practices that they use when matching actual field measurements to the required set(s) of input parameters for their model(s). If this means that you need more information than provided, please do not hesitate in contacting [us](#). Last but not least, for those 3D models capable of maintaining architectural fidelity down to the individual shoot and branch level a series of ASCII (text) files containing the Cartesian coordinates of various geometric primitives (triangles, spheres and cylinders) and their transformations will be given.



In order to facilitate the generation of the Järvselja Scots Pine (Summer) forest the information on this page has been subdivided into four different categories. For each one of these categories the relevant descriptions will be contained within a uniquely coloured text frame and can be accessed by clicking on one of the four links below:

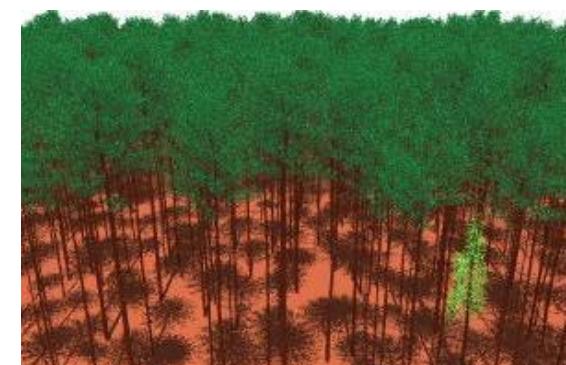
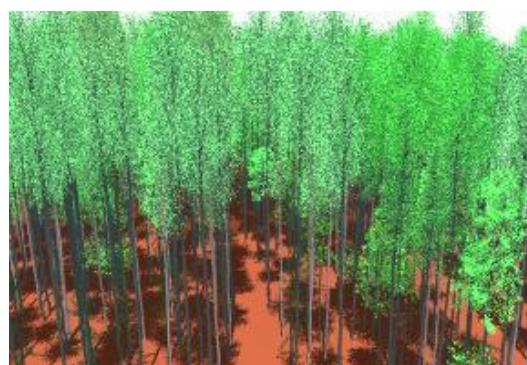
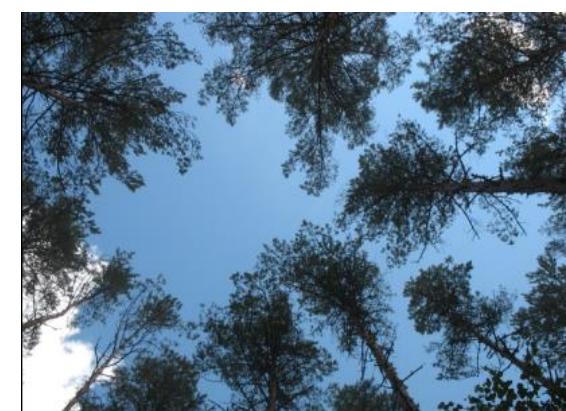
[architectural characteristics](#) [spectral characteristics](#) [illumination characteristics](#) [measurements characteristics](#)

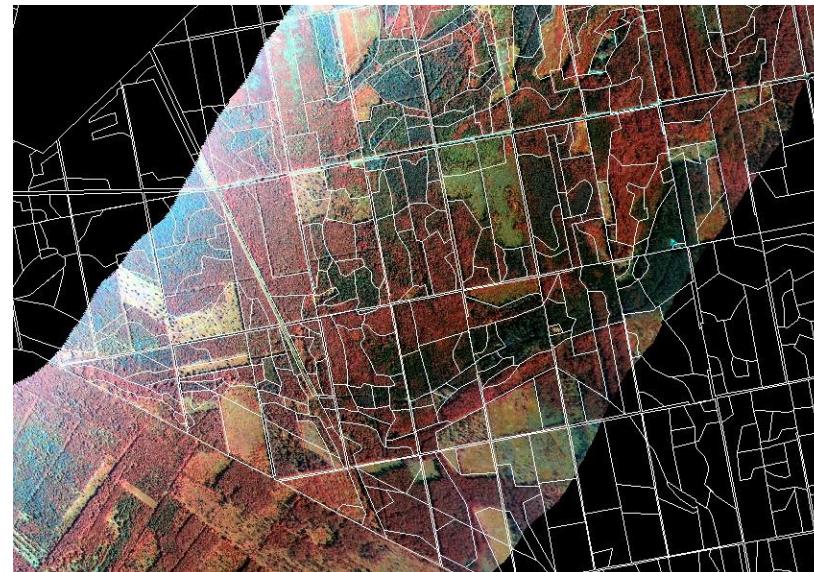
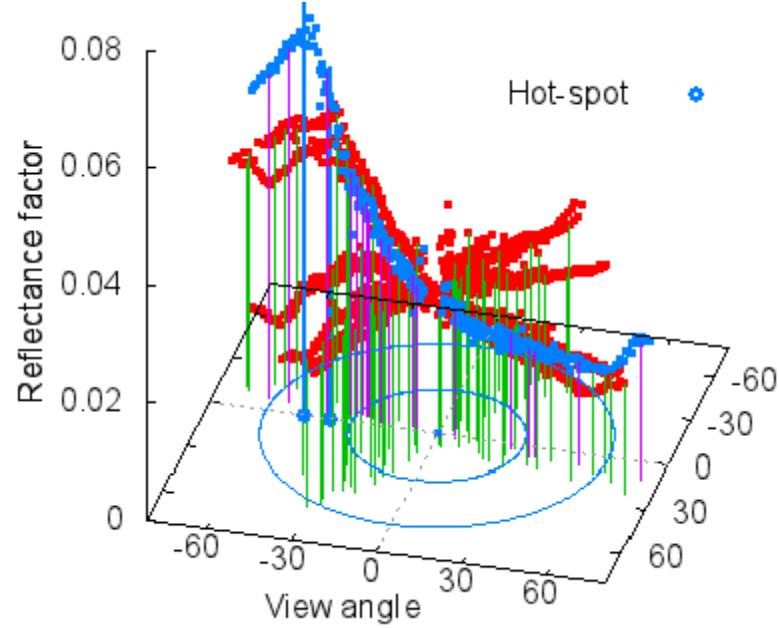
In case of difficulties or missing data on this page please do not hesitate in contacting [us](#) so that the problems may be resolved as fast as possible.

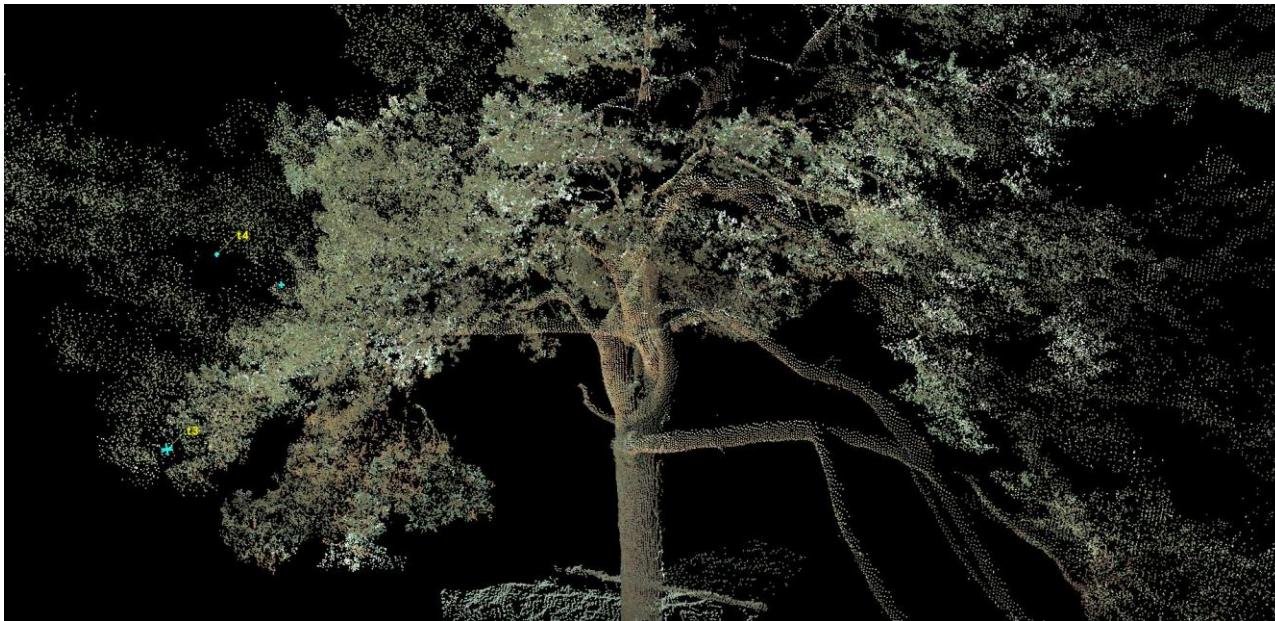
## Bříza



## Borovice







# Lightweight unmanned aerial vehicles will revolutionize spatial ecology

Karen Anderson\* and Kevin J Gaston

**E**cologists require spatially explicit data to relate structure to function. To date, heavy reliance has been placed on obtaining such data from remote-sensing instruments mounted on spacecraft or manned aircraft, although the spatial and temporal resolutions of the data are often not suited to local-scale ecological investigations. Recent technological innovations have led to an upsurge in the availability of unmanned aerial vehicles (UAVs) – aircraft remotely operated from the ground – and there are now many lightweight UAVs on offer at reasonable costs. Flying low and slow, UAVs offer ecologists new opportunities for scale-appropriate measurements of ecological phenomena. Equipped with capable sensors, UAVs can deliver fine spatial resolution data at temporal resolutions defined by the end user. Recent innovations in UAV platform design have been accompanied by improvements in navigation and the miniaturization of measurement technologies, allowing the study of individual organisms and their spatiotemporal dynamics at close range.

*Front Ecol Environ* 2013; 11(3): 138–146, doi:10.1890/120150 (published online 18 Mar 2013)

**R**emote-sensing techniques have transformed ecological research by providing both spatial and temporal perspectives on ecological phenomena that would otherwise be difficult to study (eg Kerr and Ostrovsky 2003; Running *et al.* 2004; Vierling *et al.* 2008). In particular, a strong focus has been placed on the use of data obtained from space-borne remote-sensing instruments because these provide regional- to global-scale observations and repeat time-series sampling of ecological indicators (eg Gould 2000). The main limitation of most of the research-focused satellite missions is the mismatch between the pixel resolution of many regional-extent sensors (eg Landsat [spatial resolution of ~30 m] to the Moderate Resolution Imaging Spectro-

range of new (largely commercially operated) satellite sensors have become operational over the past decade, offering data at finer than 10-m spatial resolution with more responsive capabilities (eg Quickbird, IKONOS, GeoEye-1, OrbView-3, WorldView-2). Such data are useful for ecological studies (Fretwell *et al.* 2012), but there remain three operational constraints: (1) a high cost per scene; (2) suitable repeat times are often only possible if oblique view angles are used, distorting geometric and radiometric pixel properties; and (3) cloud contamination, which can obscure features of interest (Loarie *et al.* 2007). Imaging sensors on board civilian aircraft platforms may also be used; these can provide more scale-appropriate data for

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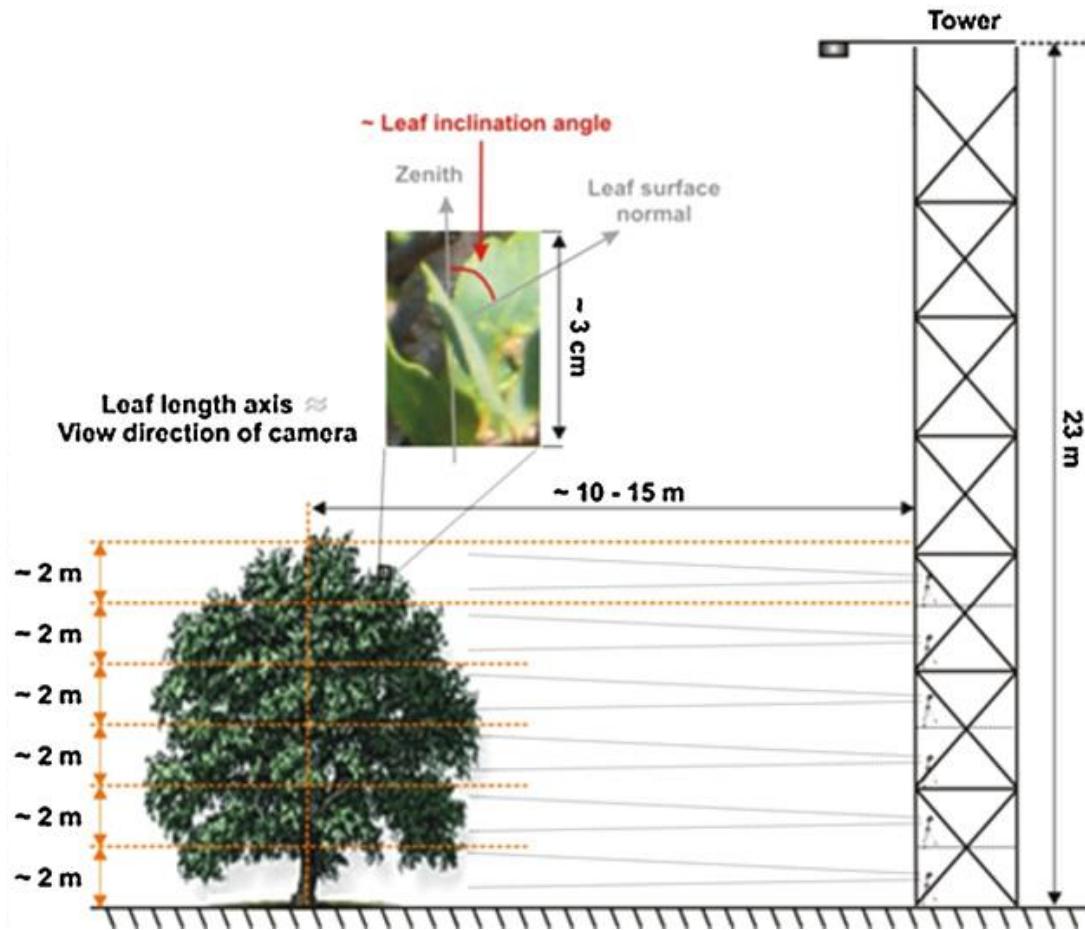


# Listy

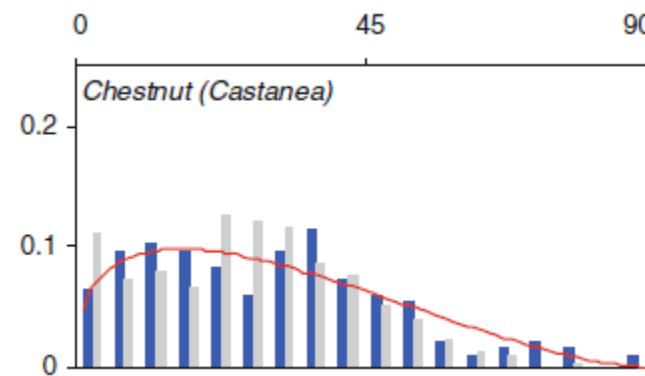
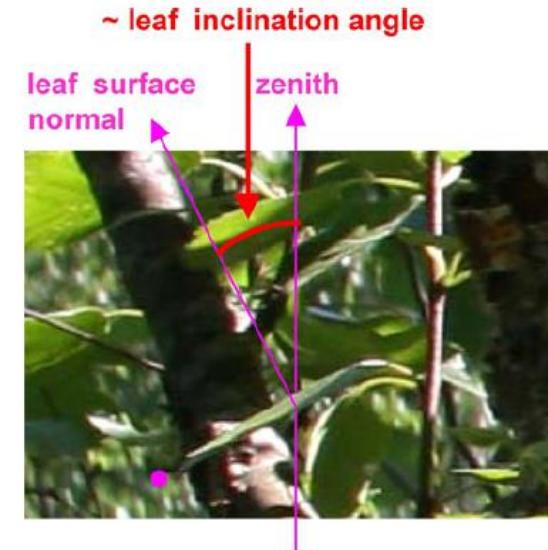
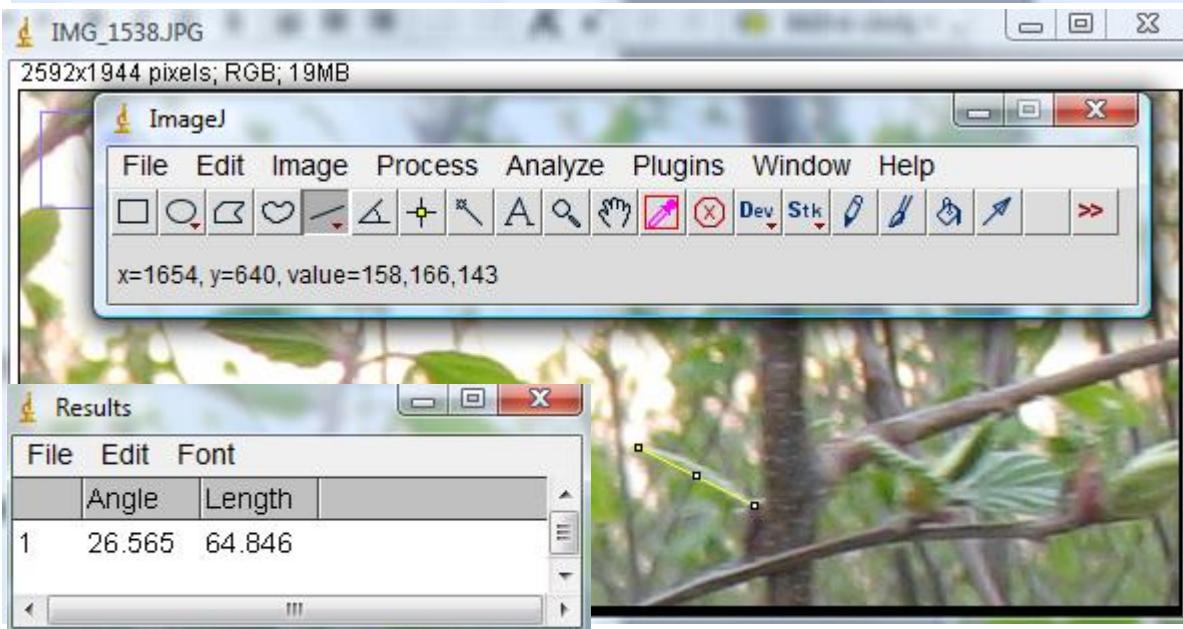
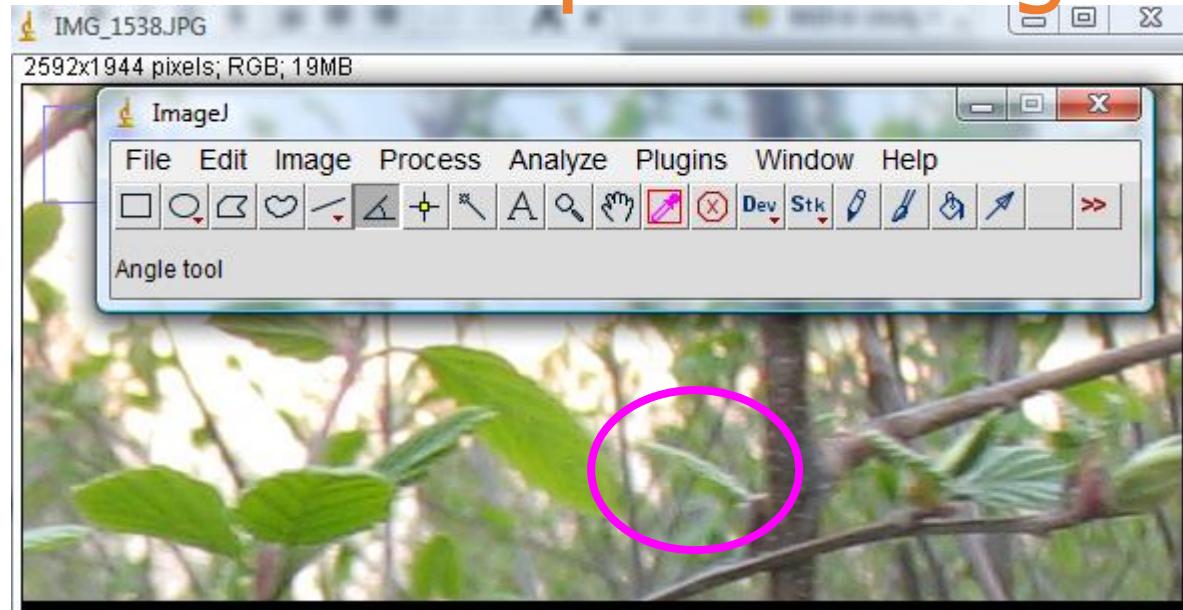
- rozdělení úhlů listoví (the leaf angle distribution - LAD) je jedním z hlavních parametrů ovlivňujících spektrální odrazivost a charakter šíření světla/záření skrz vegetaci
- navzdory svému významu ale zůstává jedním z nejméně prostudovaných parametrů/vstupů v modelech spektrální odrazivosti díky relativní obtížnosti měření úhlů listoví v terénu – obzvláště pak stromů



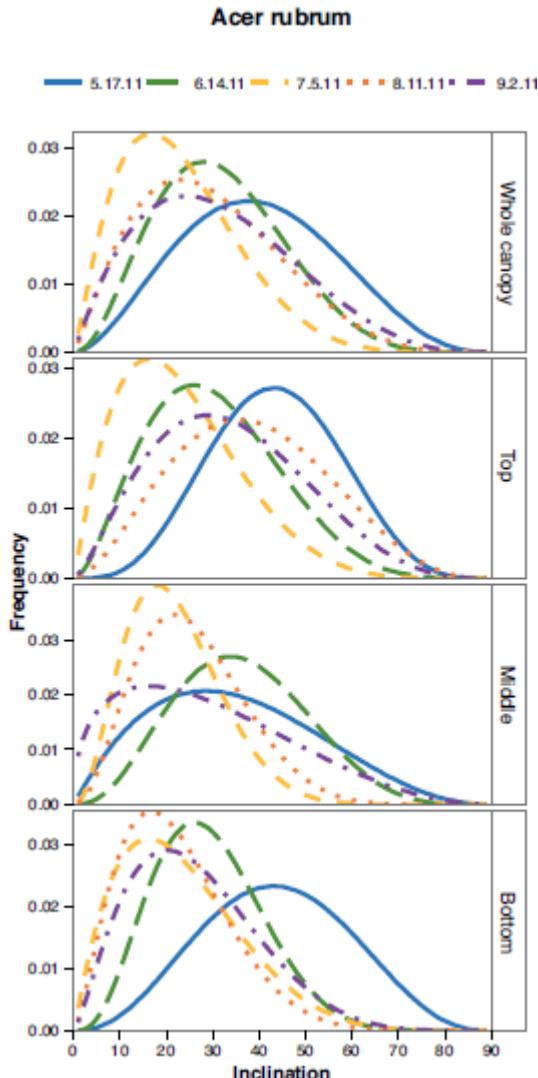
# Měření pomocí dig. fotoaparátu (leveled digital camera approach)



# Měření pomocí dig. fotoaparátu



# Je možné měřit úhly listoví kdykoliv/kdekoliv?



# Je možné měřit úhly listoví kdykoliv/kdekoliv?



DJI Phantom 3 Professional  
4K camera with 3-axis gimbal  
94 deg. recti-linear lens

# Je možné měřit úhly listoví kdykoliv/kdekoliv?



30. června, 2015, Toravere,  
Estonsko

Betula pendula, Alnus incana,  
Aesculus hippocastanum



**Původní RAW**

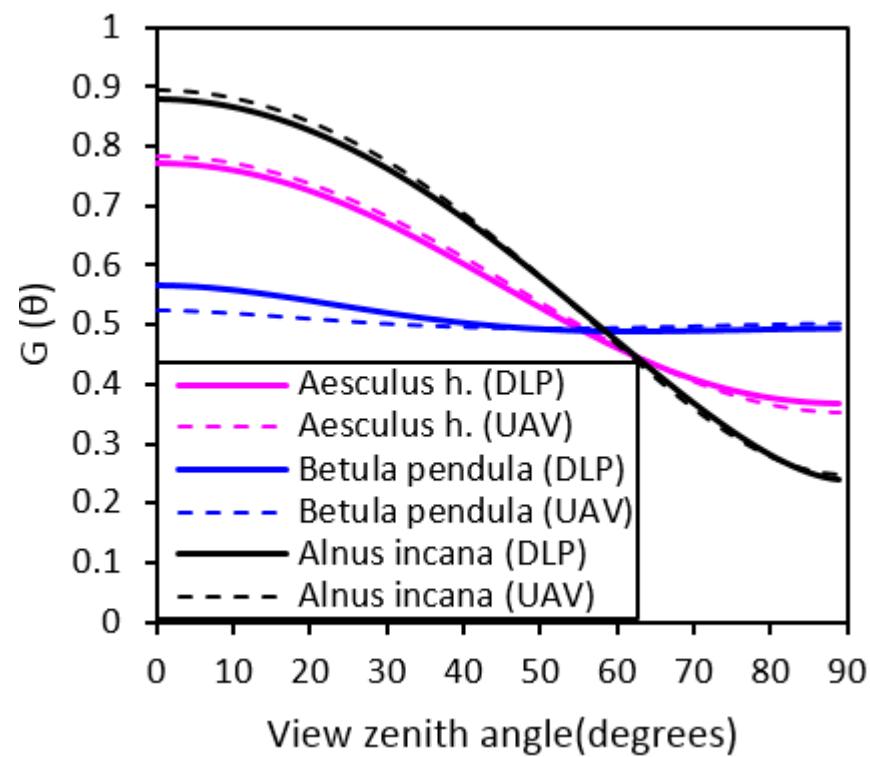
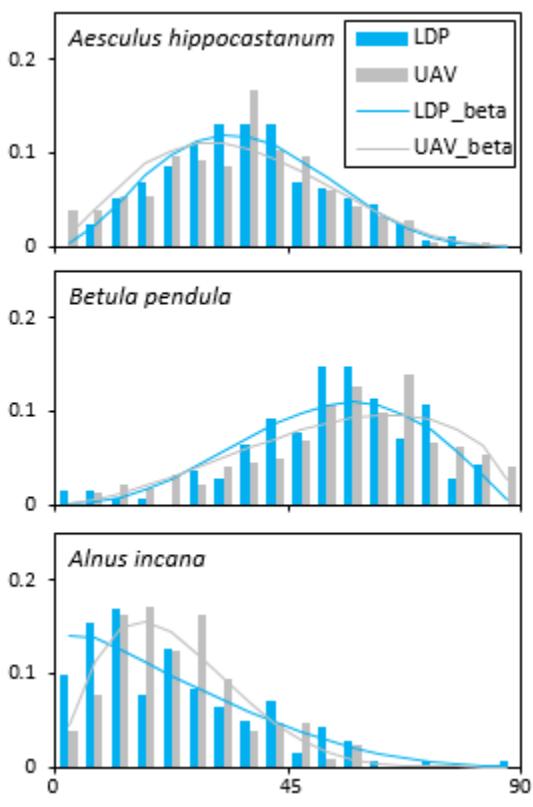


**Opravený JPEG (opravené prostorové zkreslení)**



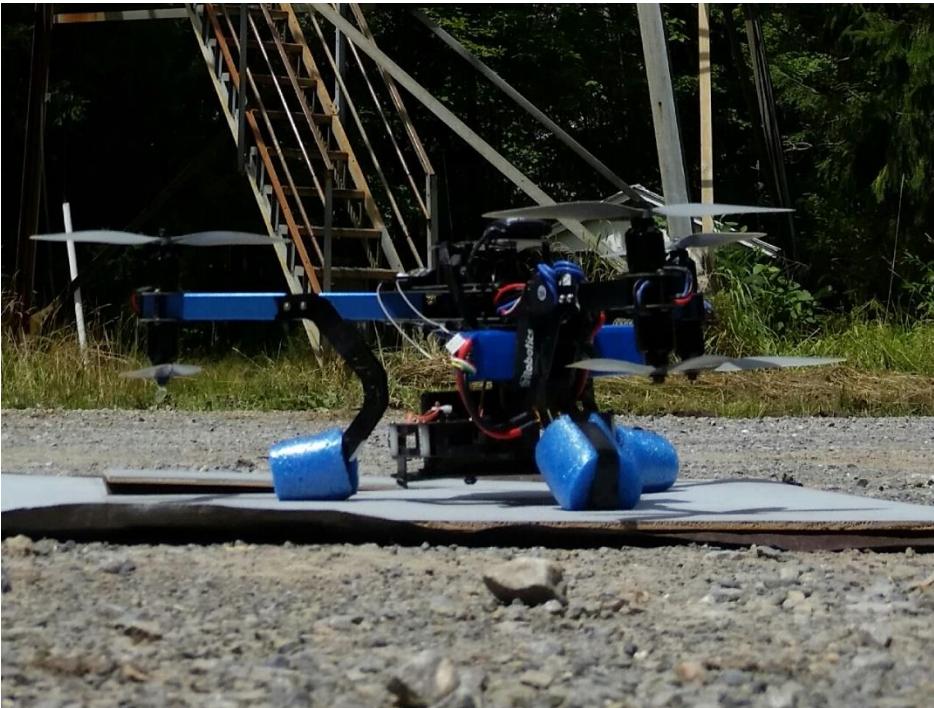
# Výsledky

| species                       | control |       |         |             | UAV |       |         |             |
|-------------------------------|---------|-------|---------|-------------|-----|-------|---------|-------------|
|                               | n       | mean  | standev | deWit       | n   | mean  | standev |             |
| <i>Aesculus hippocastanum</i> | 175     | 36.91 | 15.22   | plagiophile | 186 | 35.28 | 16.34   | plagiophile |
| <i>Betula pendula</i>         | 141     | 53.81 | 16.47   | spherical   | 244 | 56.26 | 18.63   | spherical   |
| <i>Alnus incana</i>           | 142     | 22.98 | 17.04   | planophile  | 128 | 23.48 | 12.67   | planophile  |



# 13. srpna, 2015, Monongahela National Forest, Central Appalachian Mountains, West Virginia, USA

## Acer rubrum, Quercus rubra

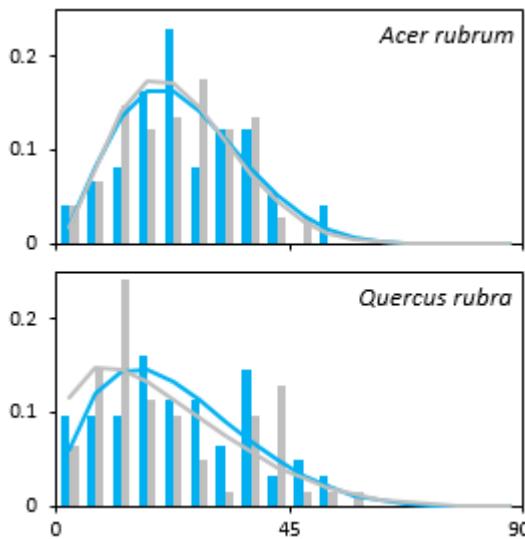


3DRobotics Y6 hexacopter outfitted with a gimbal-mounted Canon Powershot S110 compact camera



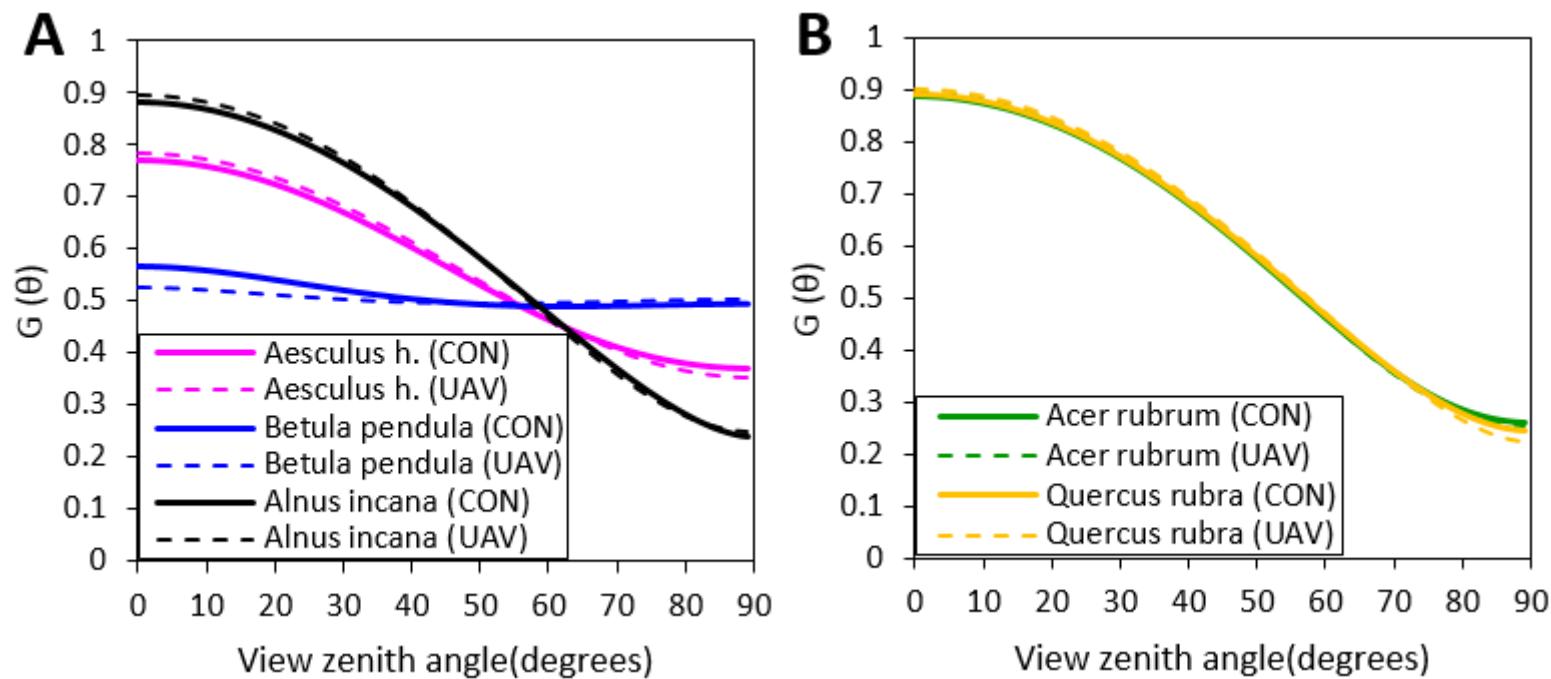
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| <i>Acer rubrum</i>            | 74      | 24.81 | 11.76   | planophile  | 74  | 24.15 | 11.06   | planophile  |
| <i>Quercus rubra</i>          | 62      | 23.56 | 13.66   | planophile  | 62  | 21.87 | 14.45   | planophile  |



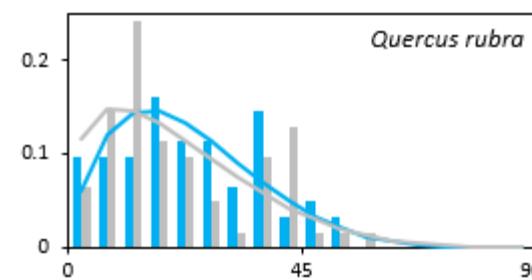
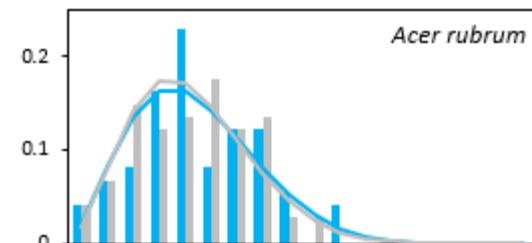
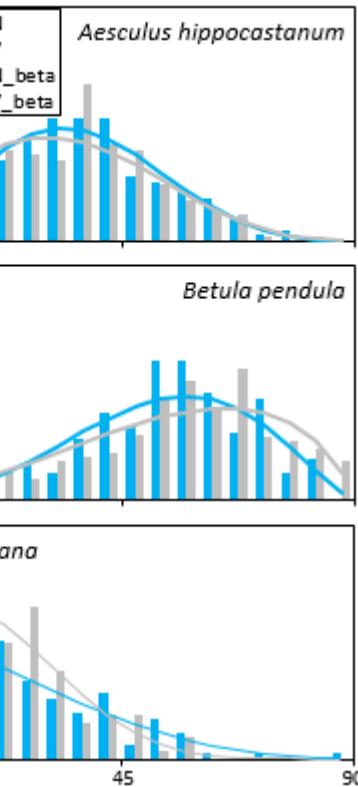
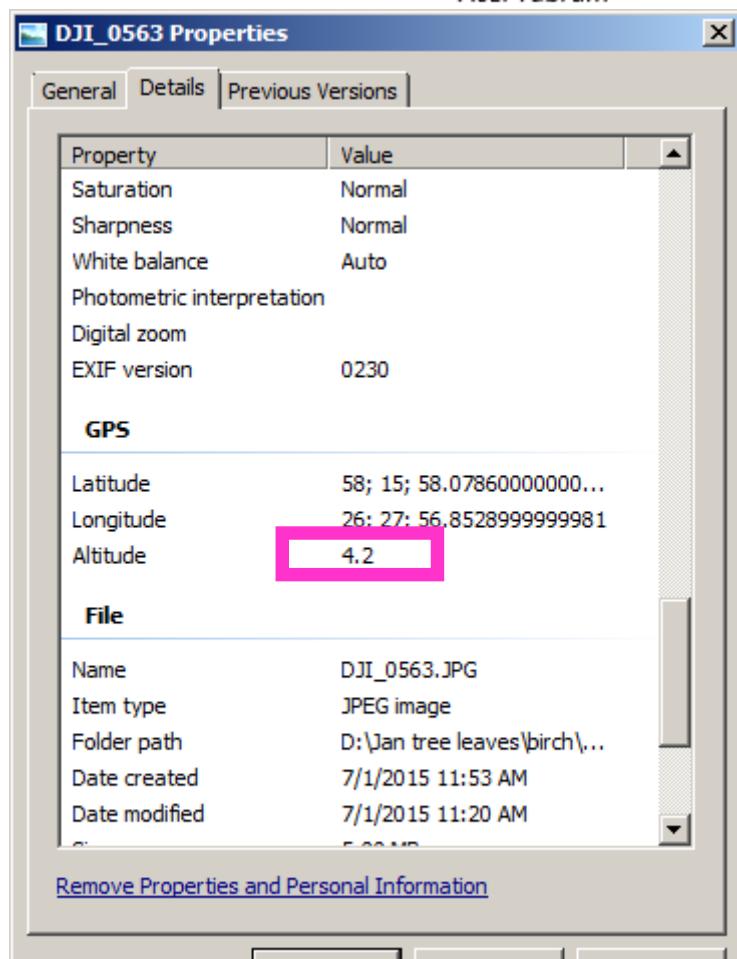
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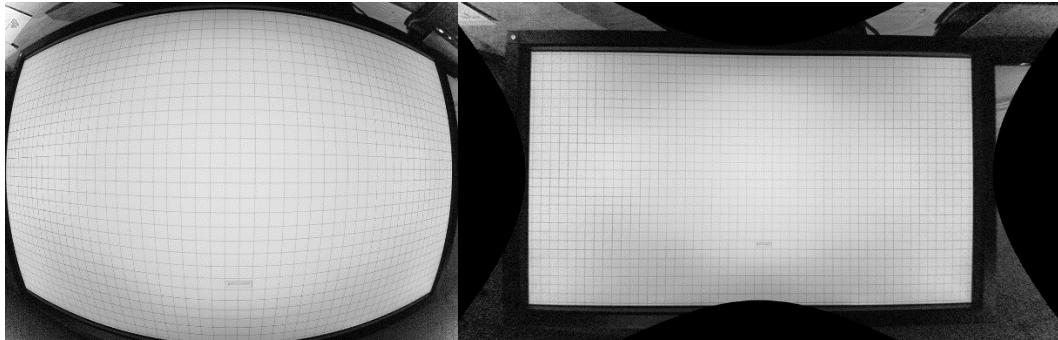


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# Na co dávat pozor?



Kamera z GoPro Hero 2 UAV (zde nepoužita!)



Canon PowerShot A610 (použitý foták pro ověření výsledků)



Short communication

## Measuring leaf angle distribution in broadleaf canopies using UAVs



Brenden E. McNeil <sup>a,\*</sup>, Jan Pisek <sup>b,1</sup>, Harald Lepisk <sup>c</sup>, Evelin A. Flamenco <sup>a</sup>

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Unmanned aerial vehicle

### ABSTRACT

Leaf angle distribution (LAD) is an important parameter affecting the biophysical interaction of sunlight and forest canopies. But, difficulty in measuring LAD has limited exploration of its species-specific phenology and variation across environmental gradients. To evaluate whether digital photographs from unpiloted aerial vehicles (UAVs) could be used to measure LAD, we directly compared UAV-based measurements of leaf angle against those made from conventional leveled digital photographs taken from towers, ladders, buildings, or poles. We used two different UAV and camera systems, and found that both systems provided statistically similar results to the conventional measurements of LAD on five common broadleaf tree species of Europe and North America. In addition to overcoming challenges of UAV airspace regulation and piloting UAVs within complex forest canopies, we recommend potential users of this method should identify, minimize, and correct for any image distortion effects created by their UAV and camera system. With these considerations in mind, our results indicate that UAVs can be used to measure LAD in virtually any broadleaf forest environment, which opens the new possibility for obtaining accurate, species-specific information on the variability of LAD through time and along broad environmental gradients.

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### 1. Introduction

The leaf angle distribution (LAD) is a key parameter in models useful for understanding the forest canopy processes of photosynthesis, evapotranspiration, radiation transmission, and spectral reflectance (Warren Wilson, 1959; Lemeur and Blad, 1974; Myneni et al., 1989; Asner, 1998). Yet, despite the strong sensitivity of many of these models to variability in LAD, the difficulty in measuring LAD often causes it to be one of the most poorly constrained model parameters (see e.g. Ollinger, 2011). Improving methodologies for measuring LAD is thus essential for advancing ecological understanding of its role within the biophysical interaction of sunlight and the forest canopy.

Recently, Ryu et al. (2010) introduced a robust and affordable method that allows reproducible measurements of leaf inclination angles based on digital photography. The method has shown potential to overcome many of the shortcomings of other LAD measurement techniques (Pisek et al., 2011; Zou et al., 2014). However, since only a small fraction of the ecological variability in forests can

be measured from towers, poles, ladders, and other conventional platforms, the remaining challenge is how to collect these photographic leaf angle measurements for the remaining tall, or remote forest canopies.

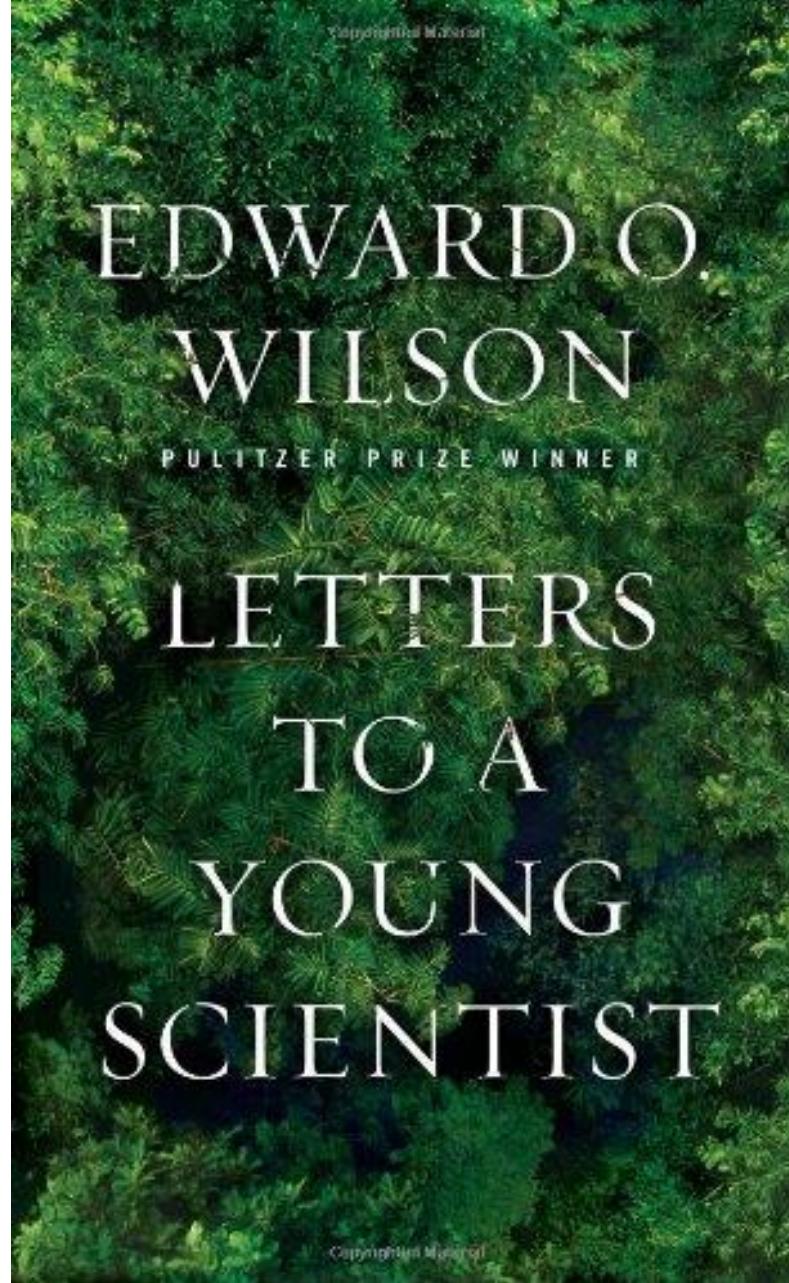
Recent technological innovations have led to an upsurge in the availability of unpiloted aerial vehicles (UAVs) – aircraft remotely operated from the ground – and there are now many lightweight UAVs available at reasonable costs. Specifically for small, multi-rotor UAVs, recent innovations in power systems, self-leveling gimbal designs, stabilized flight, and lightweight cameras now allow for the study of individual organisms and their spatiotemporal dynamics at close range (Anderson and Gaston, 2013). Crucially for forest canopy research, these small multi-rotor UAVs could serve as portable canopy research towers: they are potentially small and nimble enough to pilot throughout a complex three-dimensional forest canopy environment, all while taking high-resolution, and level photographs of individual tree crowns.

In this short communication, we seek to test the potential of small multi-rotor UAVs to serve as a platform for measuring leaf angles using the leveled digital photography method. Specifically, we use two different UAV and camera systems to measure leaf angles, as well as estimate the LAD and G-functions of five broadleaf tree species common to Europe and North America. After discussing some important considerations for minimizing errors caused by

# Jak dál?



-automatizace identifikace listů a měření úhlů  
-jehličnany?



# Vedoucí práce

# Hlavní je zápal/nadšení, až pak je kvalifikace/intelligence

Too many Ph.D.s are creatively stillborn, with their personal research ending more or less with their doctoral dissertations.

Very often ambition and entrepreneurial drive, in combination, beat brilliance.

# Zkoušejte stále něco nového

Disturb Nature and see if she reveals a secret.

Almost anything, no matter how unsophisticated, can yield discoveries publishable in scientific journals.

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Short communication

Measuring leaf angle distribution in broadleaf canopies using UAVs

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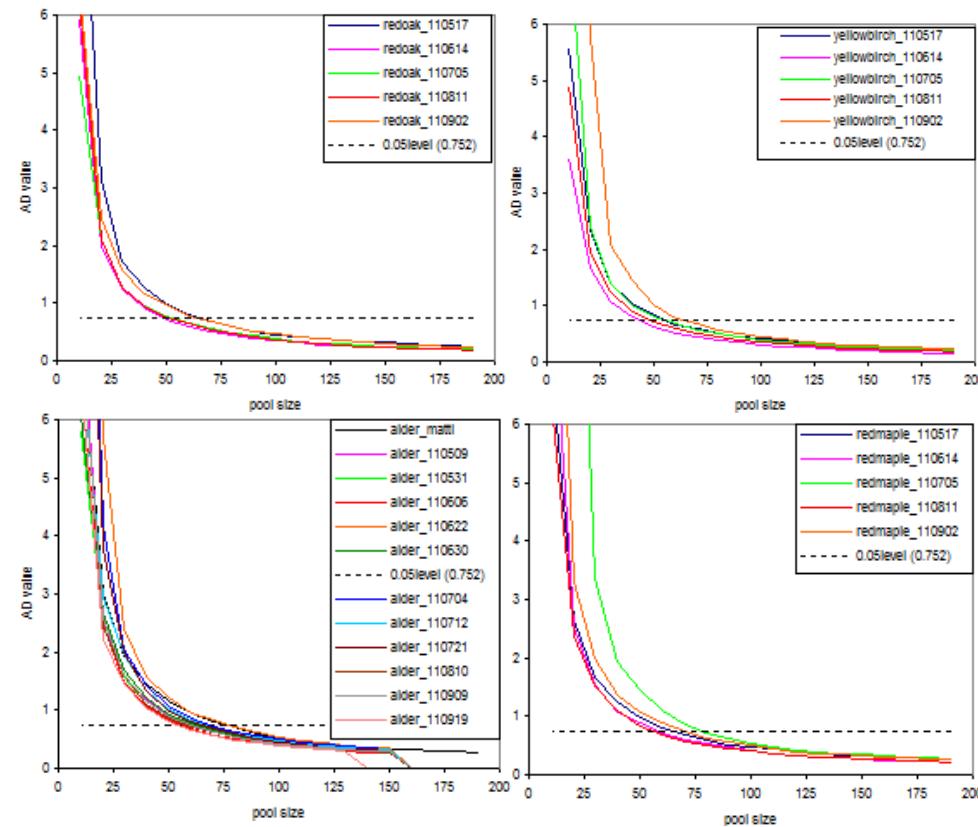
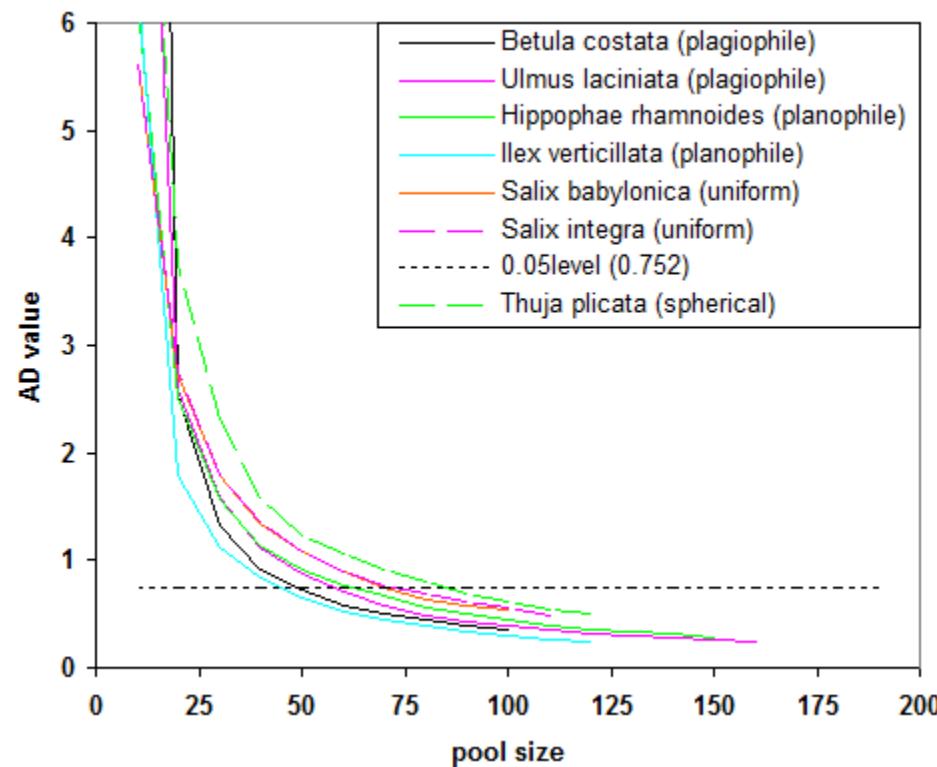
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E-mail address: bmcneil@mail.wvu.edu (B.E. McNeil).  
<sup>1</sup> Joint first authorship.

# Mějte za kamaráda/kamarádku matematika/statistika

It is far easier for scientists to acquire needed collaboration from mathematicians and statisticians than it is for mathematicians and statisticians to find scientists able to make use of their equations.

For every scientist, whether researcher, technologist, or teacher, of whatever competence in mathematics, there exists a discipline in science for which that level of mathematical competence is enough to achieve excellence.

# How many leaves are enough?



## Anderson-Darling test (Anderson and Darling, 1952)

- test statistic of the sum of squares of the differences between the distribution of sample and a given probability distribution function, with a weight function that emphasizes discrepancies in both tails

# Poznejte svůj obor/téma do poslední mrtě

Fortune favours **only** the prepared mind. Louis Pasteur, 1854

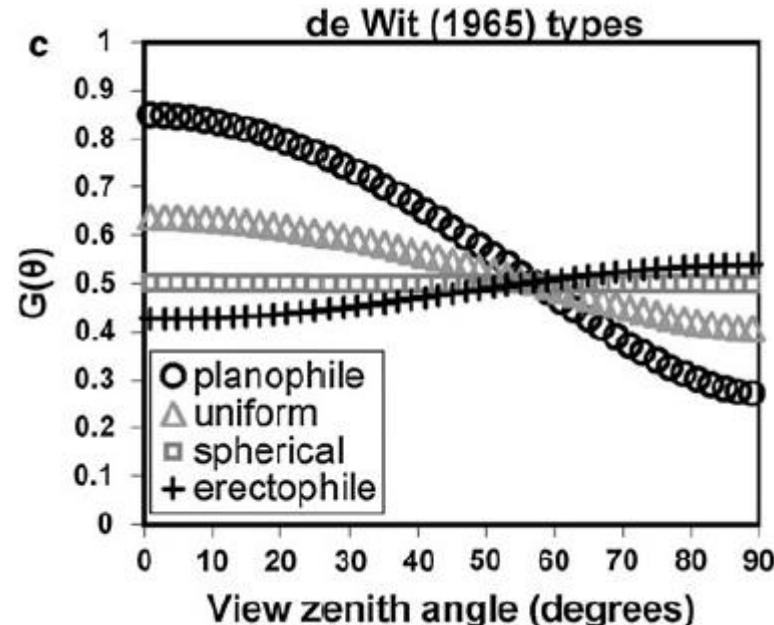
Na konci své dizertace by jste o daném tématu měli vědět více, než Váš vedoucí práce.

Využijte čas, dokud nemáte děti... ;)

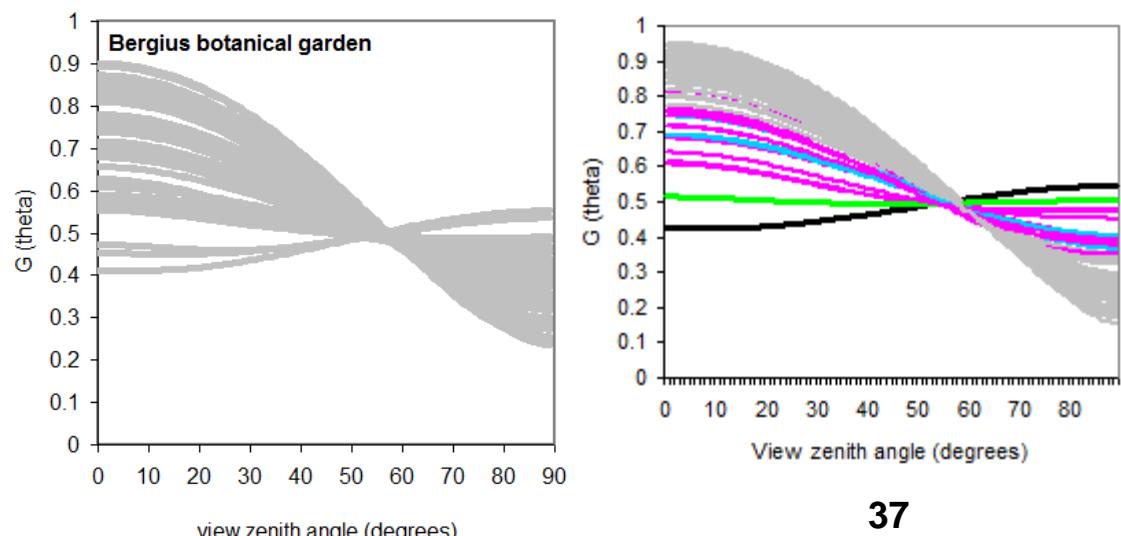
# Zajímejte se o to, co zrovna není populární

March away from the sound of the guns. Observe the fray from the distance, and while you are at it, consider making your own fray.

In the search for scientific discoveries, every problem is an opportunity. The more difficult the problem, the greater the likely importance of its solution.



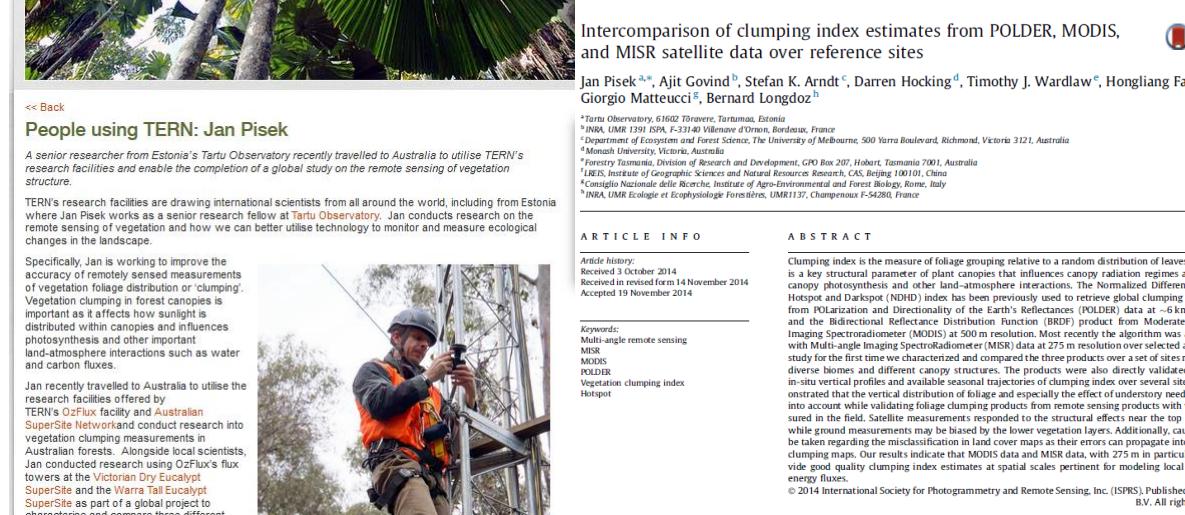
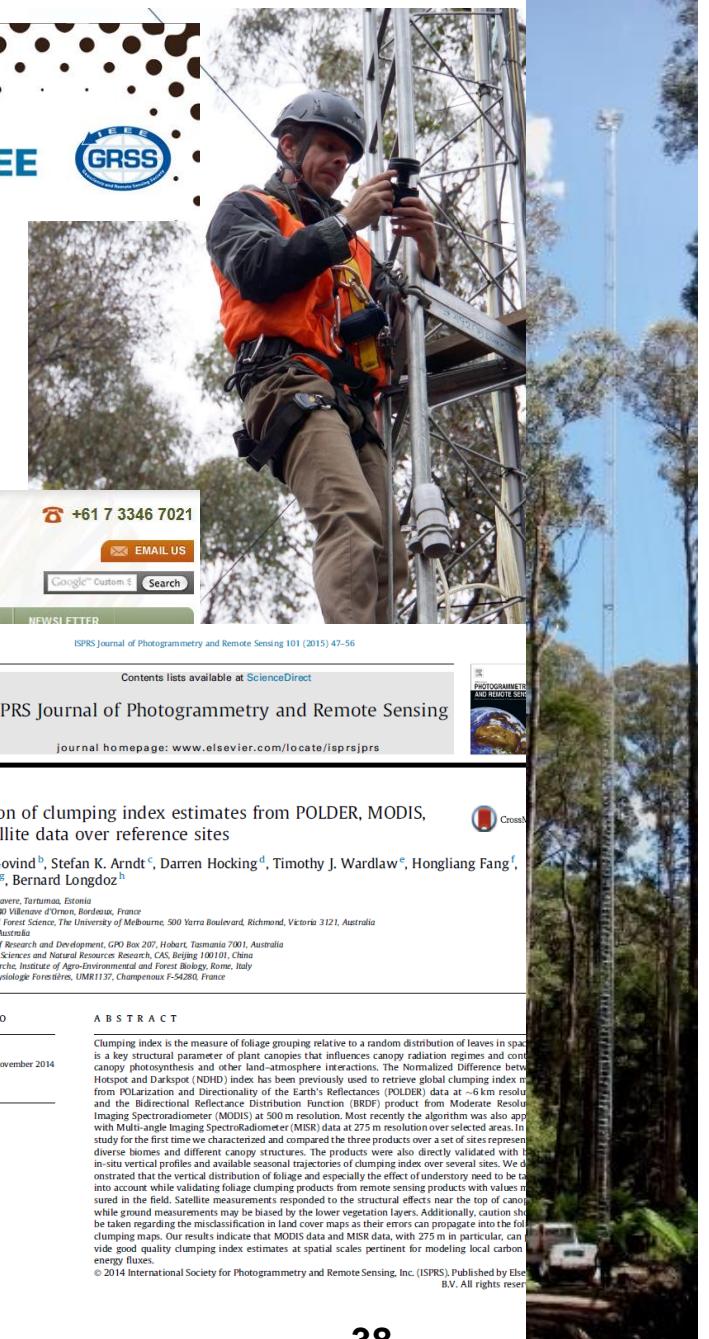
$$P(\theta) = e^{-G(\theta)L\Omega/\cos\theta}$$



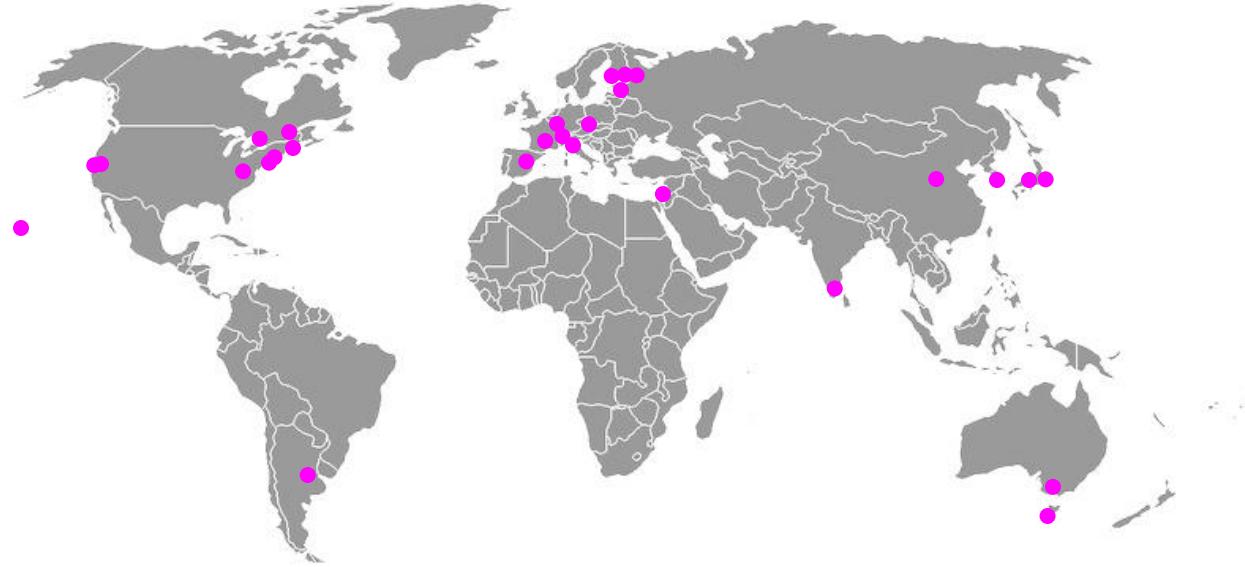
# Nikdy si neberete “dovolenou”

Real scientist takes field trips or temporary research fellowships at other institutions.

Avoid department-level administration and duties as much as possible.



# Asistujte, spolupracujte, tvořte, inovujte



University of Hawai'i, HI, USA  
San Francisco State University, CA, USA  
University of California, Berkeley, CA, USA  
Boston University, MA, USA  
Princeton University, NJ, USA  
Montclair State University, NJ, USA  
West Virginia University, WV, USA  
University of Toronto, Canada  
Université du Montréal, Canada  
Universidad de Lujan, Argentina

Joint Research Centre, Italy  
INRA, France  
University of Zurich, Switzerland  
CzechGlobe, Czech rep.  
University of Valencia, Spain  
University of Helsinki, Finland  
Aalto University, Finland  
University of Eastern Finland, Finland  
Ben-Gurion University of the Negev, Israel

Seoul National University, Korea  
JAMSTEC, Japan  
Chiba University, Japan  
Chinese Academy of Sciences, China  
University of Kerala, India  
University of Melbourne, Australia  
Forestry Tasmania, Australia

# Závist a nejistota patří mezi hlavní motory vědeckého pokroku

It won't hurt if you have a dose of them also.

# **Etika ve vědě**

Čím více budete citovat jiné, tím větší je šance, že někdo bude citovat také Vás.