


Corollary 1.21 Let $\varphi: H \rightarrow G$ be a continuous group homomorphism between two Lie groups H and G . Then φ is smooth.

Proof

First we show the statement for $H = (\mathbb{R}, +)$ (i.e. φ is a continuous 1-parameter subgroup).

Claim If $\varphi = \alpha: (\mathbb{R}, +) \rightarrow G$ is a contin. 1-parameter subgroup, then α is smooth.

By Thm. 1.19, $\exists r > 0$ s.t. $\exp: B_{2r}^{\subseteq \mathfrak{g}}(0) \rightarrow \exp(B_{2r}(0))$
with radius $2r$ open ball around $0 \in \mathfrak{g}$

is a diffeom. onto an open neighbld. of $e \in G$.

Since α is continuous (and $\alpha(0) = e$), $\exists \varepsilon > 0$
s.t. $\alpha([- \varepsilon, \varepsilon]) \subseteq \exp(B_r(0)) =: B_r(e)$.

Define

$$\beta: [- \varepsilon, \varepsilon] \longrightarrow B_r(0)$$

$$\beta = \underbrace{\exp^{-1}}_{B_r(0)} \circ \alpha$$

For $|t| < \frac{\varepsilon}{2}$ we have:

$$\underline{\exp(\beta(2t))} = \alpha(2t) = \underbrace{\exp(\beta(t))}_{\alpha(t)} \cdot \alpha(t) = \underline{\exp(2\beta(t))}$$

$$\Rightarrow \beta(2t) = 2\beta(t) \Rightarrow \beta\left(\frac{s}{2}\right) = \frac{1}{2}\beta(s) \quad \forall s \in [\varepsilon, \varepsilon].$$

By induction, one gets :
$$\underline{\beta\left(\frac{s}{2^k}\right) = \frac{1}{2^k}\beta(s)} \quad \forall s \in [\varepsilon, \varepsilon] \\ \forall k \in \mathbb{N}.$$

\Rightarrow For $\underline{k, n \in \mathbb{N}}$ one has :

$$\alpha\left(\frac{n\varepsilon}{2^k}\right) = \alpha\left(\frac{\varepsilon}{2^k}\right)^n = \exp\left(\beta\left(\frac{\varepsilon}{2^k}\right)\right)^n = \exp\left(\frac{n}{2^k}\beta(\varepsilon)\right)$$

$$\Rightarrow \boxed{\alpha(t) = \exp\left(t \frac{1}{\varepsilon} \beta(\varepsilon)\right)} \quad \forall t \in \underbrace{\left\{\frac{n\varepsilon}{2^k} : k \in \mathbb{N}, n \in \mathbb{Z}\right\}}_{=:\mathbb{D}}$$

since $\alpha(t)^{-1} = \alpha(-t)$ and $\exp(-x) = \exp(x)^{-1}$

Since $D \subseteq \mathbb{R}$ is dense and both sides of $\boxed{\dots = \dots}$ are continuous, we deduce that $\alpha(t) = \exp\left(t \frac{1}{\varepsilon} \beta(\varepsilon)\right) \forall t \in \mathbb{R}$.

So α is smooth, since the right-hand side is.

Now consider the general case: $\psi: \mathfrak{h} \rightarrow \mathfrak{g}$.

Take a basis X_1, \dots, X_n of \mathfrak{h} . Then

$$u^{-1}(t_1, \dots, t_n) = \exp(t_1 X_1) \dots \exp(t_n X_n)$$

defines a diffeomorphism from a neighborhood of $0 \in \mathbb{R}^n$ to a neighborhood of $e \in \mathfrak{h}$ and its inverse u is a chart.

Then

$$\begin{aligned}(\varphi \circ \psi^{-1})(t_1, \dots, t_n) &= \varphi(\exp(t_1 X_1) \dots \exp(t_n X_n)) \\ &= \varphi(\exp(t_1 X_1)) \dots \varphi(\exp(t_n X_n))\end{aligned}$$



continuous 1-parameter subgroups,
hence smooth by what we have
shown.

\Rightarrow $\varphi \circ \psi^{-1}$ is smooth and hence φ is smooth locally
around $e \in H$.

\Rightarrow $\lambda_{\varphi(h)} \circ \varphi = \varphi \circ \lambda_{h^{-1}}$ implies that φ is smooth
locally around every $h \in H$.

□

Prop. 1.22 For a Lie group G we denote by $G_0 \subseteq G$ the connected component of G containing $e \in G$, which is called **the connected component of the identity of G** .

- ① G_0 is an open and closed subset of G . In particular, G_0 is a submfd. of G of the same dimension as G .
- ② G_0 is a normal subgroup of G .

Hence, G_0 is a Lie subgroup of G and G/G_0 is a discrete topological group, called **the component group of G** .

Proof

① ✓

② $g, h \in G_0 \implies \exists$ continuous curves $c_g, c_h: [0, 1] \rightarrow G$
s.t. $c_g(0) = c_h(0) = e \in G$
and $c_g(1) = g$, $c_h(1) = h$.

$\implies t \mapsto \mu(c_g(t), c_h(t)) = c_g(t) \cdot c_h(t)$
is a continuous curve connecting $e \in G$
with gh .

$\implies gh \in G_0$ -

Since, $t \mapsto \nu(c_g(t))$ is continuous, also $g^{-1} \in G_0$ for
any $g \in G_0$.

It is a normal subgroup : for $g \in G_0$, $k \in G$,

$t \rightarrow k c_g(t) k^{-1}$ is continuous curve
connecting $e \in G$ with kgk^{-1}
 $\Rightarrow \underline{kgk^{-1}} \in G_0$.

① and ②

$\Rightarrow G_0 \subseteq G$ is a Lie subgroup and G/G_0 is
group, which is a discrete topolog. group.

($\pi: G \rightarrow G/G_0$, quotient topolog. on G/G_0 .

$U \subseteq G/G_0$ is open $\Leftrightarrow \pi^{-1}(U)$ is open in G .

$$g \cdot G_0 \in G/G_0 \quad \pi^{-1}(g \cdot G_0) = \{g \cdot h : h \in G_0\}$$

$$= \lambda_g(\underline{G_0}) \subseteq G.$$

Theorem 1.23 G and H are Lie groups with Lie algebras \mathfrak{g} and \mathfrak{h} . Then one has: \square .

① If $\psi : G \rightarrow H$ is a Lie group homomorphism, then

$$\psi \circ \exp^G = \exp^H \circ \psi' \longleftarrow$$

where $\psi' := T_e \psi : \mathfrak{g} \rightarrow \mathfrak{h}$.

② G_0 coincides with the subgroup generated by $\exp(\mathfrak{g}) \subseteq G$.

③ If $\varphi, \psi: G \rightarrow H$ are Lie group homomorphisms s.t.

$$\varphi' = \psi' \quad \text{then} \quad \varphi|_{G_0} = \psi|_{G_0}.$$

In particular, if G is connected, then $\varphi = \psi$.

Proof.

① Recall that $T_g \varphi L_x(g) = L_{\varphi'(x)}(\varphi(g))$

(see proof of ① of Prop. 1.12: L_x and $L_{\varphi'(x)}$ are φ -related),

which implies $\varphi \circ \underline{F_t^{L_x}} = \underline{F_t^{L_{\varphi'(x)}}} \circ \varphi$.

Hence,

$$\begin{aligned} \underline{\varphi(\exp(x))} &= \varphi(\text{FL}_1^{L_x}(e)) = \text{FL}_1^{L_{\varphi'(x)}}(\varphi(e)) \\ &= \underline{\exp(\varphi'(x))} \end{aligned}$$

$\forall x \in \mathfrak{g}$.

(2) If \tilde{G} is the subgroup generated by $\exp(\mathfrak{g}) \subseteq G$,
then $\tilde{G} \subseteq G_0$, since $t \mapsto \exp(tx)$ is a C^∞ -curve

connecting e to $\exp(x)$.
To see that $G_0 \subseteq \tilde{G}$, note that, since \exp restricts to a
diffeom. ~~from~~ ^{on} a neighborhood of $0 \in \mathfrak{g}$,

$\exp(\mathfrak{g})$ (and thus also \tilde{G}) contains an open neighborhood.

$U \subseteq G$ of $e \in G$.

Then for $g \in \tilde{G}$, $\lambda_g(U)$ is an open neighborhood of g contained in \tilde{G} , since \tilde{G} is a subgroup.

Thus, \tilde{G} is an open subset of G .

But $\tilde{G} \subseteq G$ is also closed, equivalently $G \setminus \tilde{G}$ is open, since for $g \in G \setminus \tilde{G}$, $\lambda_g(U) = \{g \cdot h^{-1} \mid h \in U\}$ is an open neighborhood of g contained in $G \setminus \tilde{G}$.

Thus, \tilde{G} is also closed. $\implies \tilde{G} = \bar{G}$.

$$\begin{aligned} g \cdot h^{-1} &\in \tilde{G} \\ \implies g \cdot h^{-1} &\in \tilde{G} \\ &g'' \end{aligned}$$

③ By ①, ψ and φ coincide on $\exp(\mathfrak{g})$.

Since they are group homomorphisms, $\varphi|_{\mathfrak{g}} = \psi|_{\mathfrak{g}}$ and so the claim follows from ②.

□.

An application of ① of Thm. 1.23 is for example:

Example

$\det : GL(n, \mathbb{R}) \rightarrow (\mathbb{R} \setminus \{0\}, \cdot)$ is a Lie group

$\det(A \cdot B) = \det(A) \det(B)$ homomorphism.

In Global analysis we saw: $\det' := T_{\text{id}} \det = \text{trace} : \mathfrak{gl}(n, \mathbb{R}) \rightarrow \mathbb{R}$.

By ① of Thm. 1.23.

$$\det(e^x) = e^{\operatorname{tr}(x)} \quad \forall x \in \mathfrak{gl}(n, \mathbb{R})$$

1.2 Representations of Lie groups and Lie algebras

Def. 1.24 Suppose G is a Lie group.

Then a representation of G on a finite-dimensional real vector space V is a Lie group homomorphism

$$\gamma: G \rightarrow GL(V).$$

Equivalently, it is a smooth map $\varphi: G \times \underline{V} \rightarrow V$ s.t.

• $\varphi(g, -): V \rightarrow V$ is linear $\forall g \in G$.

• $\varphi(e, v) = v \quad \forall v \in V$

$\varphi(g, \varphi(h, v)) = \varphi(gh, v) \quad \forall g, h \in G, \forall v \in V.$

Remark Often one refers to V as ^a ~~the~~ representation of G when φ is understood.

Notation: $\varphi(g, v)$ $=: g \cdot v =: gv$

Examples

① $G = GL(V)$

Defining representation / standard representation of $GL(V)$:

$$\begin{aligned} \gamma : GL(V) \times V &\rightarrow V \\ (A, v) &\mapsto Av \end{aligned}$$

Via a choice of basis, we can identify $GL(V) \cong GL(n, \mathbb{R})$
and $V \cong \mathbb{R}^n$ and $\gamma : GL(n, \mathbb{R}) \times \mathbb{R}^n \rightarrow \mathbb{R}^n$

becomes multiplication of A with a vector $v \in \mathbb{R}^n$.
 $A \in GL(n, \mathbb{R})$

Similarly, any matrix group $H \subseteq GL(V)$ has a standard representation on V .

② Adjoint representation of a Lie group G

Denote by $\text{conj}_g : G \rightarrow G$ conjugation by $g \in G$.

$$\text{conj}_g(h) = ghg^{-1} \quad \forall h \in G.$$

It is a Lie group homomorphism and

$$\text{Ad} : G \rightarrow GL(\mathfrak{g}) = \{ \text{lin. isomorph. } \mathfrak{g} \rightarrow \mathfrak{g} \}$$
$$\text{Ad}(g) := T_e \text{conj}_g : \mathfrak{g} \rightarrow \mathfrak{g}.$$

is a representation of G on \mathfrak{g} , called the **adjoint representation of G** .

Let us check this is a representation:

$$\text{Conj}_g = \lambda_g \circ \rho^{g^{-1}} = \rho^{g^{-1}} \circ \lambda_g$$

$$\Rightarrow T_e \text{Conj}_g = T_{g^{-1}} \lambda_g \circ T_e \rho^{g^{-1}} = T_g \rho^{g^{-1}} \circ T_e \lambda_g. \quad (*)$$

$$\text{Conj}_{gh} = \text{Conj}_g \circ \text{Conj}_h \Rightarrow \underline{\text{Ad}(gh) = \text{Ad}(g) \circ \text{Ad}(h)}$$

$$\text{Conj}_{g^{-1}} = (\text{Conj}_g)^{-1} \Rightarrow \text{Ad}(g^{-1}) = \text{Ad}(g^{-1})$$

$\implies \text{Ad} : G \rightarrow \text{GL}(\mathfrak{g})$ is group homomorphism.

To see that Ad is smooth, it suffices to show that $(g, x) \mapsto \text{Ad}(g)(x)$ is smooth.

Set $F : G \times \mathfrak{g} \rightarrow TG \times TG \times TG$

$$F(g, x) \mapsto (0_g, X, 0_{g^{-1}}).$$

It is smooth and so is also

$$T_{\mu \circ (\text{id}_G \times T_{\mu})}(F(g, x)) = T_{g^{-1}g} \circ T_e \rho^{g^{-1}} X \\ \stackrel{(*)}{=} \text{Ad}(g)(X).$$

If $G = GL(n, \mathbb{R})$, then

$$\text{Conj}_A(B) = A B A^{-1}$$

is a linear map $\text{Conj}_A: M_n(\mathbb{R}) \rightarrow M_n(\mathbb{R})$.

$$\Rightarrow \text{Ad}(A)(X) = T_{\text{id}} \text{Conj}_A X = \text{Conj}_A X = A X A^{-1}$$

$$\begin{aligned} \forall X \in \mathfrak{gl}(n, \mathbb{R}) \\ \forall A \in GL(n, \mathbb{R}). \end{aligned}$$