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Recall :  $G$  is a Lie group

- representation of  $G$  :  $\rho : G \rightarrow GL(V)$  Lie group homomorphism.
- Adjoint representation of  $G$  :  $Ad : G \rightarrow GL(\mathfrak{g})$ .

$$Ad(g) := T_e \text{conj}_g$$

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Def. 1.25 Suppose  $\mathfrak{g}$  is a Lie algebra over  $\mathbb{K} = \mathbb{R}, \mathbb{C}$ .

A representation of  $\mathfrak{g}$  on a  $\mathbb{K}$ -vector space  $V$  is a Lie algebra homomorphism  $\psi : \mathfrak{g} \rightarrow \mathfrak{gl}(V) = \{ \text{linear maps } V \rightarrow V \}$ .

$$\begin{aligned} (\text{i.e. } \psi \text{ is linear and } \psi([X, Y]) &= [\psi(X), \psi(Y)] \\ &= \psi(X) \circ \psi(Y) - \psi(Y) \circ \psi(X) \end{aligned}$$

$$\forall X, Y \in \mathfrak{g} ) ,$$

Equivalently, a bilinear map  $\psi : \mathfrak{g} \times V \rightarrow V$  s.t.

$$\psi([X, Y], v) = \psi(X, \psi(Y, v)) - \psi(Y, \psi(X, v))$$

$$\forall X, Y \in \mathfrak{g} \text{ and } \forall v \in V .$$

By Prop. 1.12, any representation  $\rho : G \rightarrow GL(V)$  of a Lie group  $G$  induces a representation  $\rho' = T_e \rho : \mathfrak{g} \rightarrow \mathfrak{gl}(V)$

of its Lie algebra  $\mathfrak{g}$ .

For  $G = GL(n, \mathbb{R})$ , the standard representation  $\rho$  of  $GL(n, \mathbb{R})$  gives the standard representation of  $\mathfrak{gl}(n, \mathbb{R})$  on  $\mathbb{R}^n$ :

$$\begin{aligned}\psi' : \mathfrak{gl}(n, \mathbb{R}) \times \mathbb{R}^n &\longrightarrow \mathbb{R}^n \\ (X, v) &\longmapsto Xv\end{aligned}$$

Similarly, for any matrix group and its standard representation.

For the adjoint repres. of a Lie group  $G$ ,  $\text{Ad} : G \rightarrow GL(\mathfrak{g})$ , the induced representation of  $\mathfrak{g}$ , the so called

adjoint representation of  $\mathfrak{g}$ , is given by

$$\text{ad} : \mathfrak{g} \rightarrow \text{gl}(\mathfrak{g}) .$$

$$\begin{aligned} \text{Ad}^1 &= \text{ad}(X)(Y) = [X, Y] \quad \forall X, Y \in \mathfrak{g} . \\ &= T_e \text{Ad} \end{aligned}$$

as the following proposition shows :

Prop. 1.26  $G$  Lie group with Lie algebra  $(\mathfrak{g}, [\cdot, \cdot])$ .

① For  $X \in \mathfrak{g}$  and  $g \in G$  :  $L_X(g) = R_{\text{Ad}(g)X}(g)$  .

② For  $X, Y \in \mathfrak{g}$  ,  $\text{ad}(X)(Y) = [X, Y] \quad \forall X, Y \in \mathfrak{g}$  .

③ For  $X \in \mathfrak{g}$ ,  $g \in G$  we have

$$\exp(\text{Ad}(g)(X)) = g \exp_r(X) g^{-1}$$

④ For  $X, Y \in \mathfrak{g}$  we have :

$$\begin{aligned} \text{Ad}(\exp(X))(Y) &= e^{\text{ad}(X)}(Y) = \sum_{k=0}^{\infty} \frac{1}{k!} \underbrace{\text{ad}(X)^k Y}_{[\underbrace{X, [X, [X, \dots, [X, Y] \dots]}_k]} \\ &= Y + [X, Y] + \frac{1}{2} [X, [X, Y]] + \frac{1}{3!} [X, [X, [X, Y]]] + \dots \end{aligned}$$

Proof.

$$\textcircled{1} \quad L_x(\mathfrak{g}) = R_{\text{Ad}(\mathfrak{g})}(x)$$

$$\underline{\lambda_{\mathfrak{g}} = \rho^{\mathfrak{g}} \circ \text{conj}_{\mathfrak{g}}}$$

$$\Rightarrow \underbrace{T_e \lambda_{\mathfrak{g}} X}_{L_x(\mathfrak{g})} = \underbrace{T_e \rho^{\mathfrak{g}}}_{=} \cdot \underbrace{T_e \text{conj}_{\mathfrak{g}} X}_{\text{Ad}(\mathfrak{g})X} = R_{\text{Ad}(\mathfrak{g})}(x)$$

$\textcircled{2}$  Choose a basis  $X_1, \dots, X_n$  of the vector space  $\mathfrak{g}$ .

Then  $\text{Ad}(\mathfrak{g}) : \mathfrak{g} \rightarrow \mathfrak{g}$  corresponds to a  $n \times n$  matrix  $(a_{ij}(\mathfrak{g}))$ , for every  $\mathfrak{g} \in G$ .

Note that  $a_{ij} : G \rightarrow \mathbb{R}$  are smooth, since  $\text{Ad}$  is smooth.

Matrix presentation of  $\text{ad}(x) : \mathfrak{g} \rightarrow \mathfrak{g}$  equals

$$\underline{(X \cdot a_{ij})} = \underline{T_e a_{ij} X} = \underline{(L_x \cdot a_{ij})(e)}.$$

Any  $Y \in \mathfrak{g}$  can be written as  $Y = \sum_{i=1}^n y_i X_i$  and

$$\underline{L_Y(g)} = \underline{R(g)} \underbrace{\underline{\text{Ad}(g)(Y)}}_{\sum_{i,j} a_{ij}(g) X_i y_j} = \underline{\sum_{i,j} y_i a_{ij}(g) R_{X_i}(g)}$$



$$\begin{aligned} \implies [L_x, L_y] &= \sum_{i,j} y_j \underbrace{[L_x, a_{ij} R_{x_i}]} = \\ &= a_{ij} \underbrace{[L_x, R_{x_i}]}_{=0} + \underbrace{(L_x a_{ij}) R_{x_i}} \\ &\quad \text{by Prop. 1.14} \end{aligned}$$

$$= \sum_{i,j} y_j (L_x a_{ij}) R_{x_i} .$$

Evaluate at  $e \in G$  : 
$$\begin{aligned} \underline{[X, Y]} &= [L_x, L_y](e) \\ &= \sum_{i,j} y_j (x \cdot a_{ij}) X_i \\ &= \underline{\text{ad}(X)(Y)} . \end{aligned}$$

③ Since  $\text{Ad}(g) = T_e \text{conj}_g$ , the result follows directly from ① of Thm. 1.23. ( $\psi: G \rightarrow H$ )

$$\text{conj}_g(\exp(tx)) = \exp(\text{Ad}(g)(tx)) = \exp(t \text{Ad}(g)x)$$

$$\psi \circ \exp^G = \exp^H \circ \psi'$$

④ Apply ① of Thm. 1.23 to  $\text{Ad}: G \rightarrow \text{GL}(\mathfrak{g})$ .

$$\text{Ad}(\exp(x))(Y) = \exp(\text{ad}(x))(Y) = e^{\text{ad}(x)}(Y)$$

$$= \sum_{k=0}^{\infty} \frac{1}{k!} \text{ad}(x)^k(Y).$$

□.

Prop. 1.27 Suppose  $G$  is a Lie group with Lie algebra  $(\mathfrak{g}, \tau, \mathcal{J})$ .

Let  $\varphi : G \rightarrow GL(V)$  be a Lie group representation of  $G$  with

induced representation  $\varphi' : \mathfrak{g} \rightarrow \mathfrak{gl}(V)$  of  $\mathfrak{g}$ .

$$\textcircled{1} \quad \underline{\varphi(\exp(tx))}(v) = \underline{\exp(t\varphi'(x))}(v)$$

$$= \sum_{k=0}^{\infty} \frac{t^k}{k!} \varphi'(x)^k v = v + t \varphi'(x) v$$

$\forall X \in \mathfrak{g}, v \in V, t \in \mathbb{R}$ .

$$+ \frac{t^2}{2!} \varphi'(x) \varphi'(x) v \\ + \dots$$

$$\textcircled{2} \quad X \cdot v := \varphi'(x)v = \left. \frac{d}{dt} \right|_{t=0} \varphi(\exp(tx))v = \left. \frac{d}{dt} \right|_{t=0} \exp(tx) \cdot v$$

Proof.

① follows from ① of Thm. 1.23 and ② follows immediately from ①.

We will later develop the basic representation theory of Lie groups and Lie algebras.

## 1.3 Lie subgroup and virtual Lie subgroups

We already defined what a Lie subgroup of a Lie group is.

Prop. 1.28 Suppose  $H$  is a Lie subgroup of a Lie group  $G$ .  
Then  $H$  is closed as a subset of the topological space  $G$ .

Proof.

Any submtd.  $N$  of a mtd.  $M$  is locally closed, i.e.  $N$  is open in its closure  $\overline{N}$  ( $\Leftrightarrow$  every  $x \in N$  has neighbd  $U$  in  $M$  s.t.  $U \cap N$  is closed in  $U$ ).

$\longrightarrow$

For any subgroup  $H$  of a topological group  $G$ ,  $\overline{H}$  is also

a subgroup of  $G$   $\left( \begin{array}{l} h_n \rightarrow h \in \overline{H} \\ \in H \quad n \rightarrow \infty \end{array} \quad g_n \rightarrow g \in \overline{H} \implies h_n g_n \rightarrow h \cdot g \in \overline{H} \right)$   
 $\in H \quad n \rightarrow \infty$

If  $H$  is a Lie subgroup of a Lie group  $G$ ,  $H$  is open and dense  $\overline{H}$ .

Hence, for  $g \in \overline{H}$ ,  $\lambda_g(H) \subseteq \overline{H}$  is open in  $\overline{H}$  ( $\lambda_g: \overline{H} \rightarrow \overline{H}$  homeomorphism)

Since  $H$  is dense in  $\overline{H}$ ,  $\lambda_g(H) \cap H \neq \emptyset$ , which implies  $g \in H$ .  $\left( \exists h, h' \in H \text{ s.t. } g \cdot h' = h \implies g \in H \right)$ .  $\square$

Conversely, one has:

Thm. 1.29 Suppose  $H$  is a subgroup of a Lie group  $G$  that is closed as a subset of the topolog. space  $G$ .

Then  $H$  is a Lie group.

Proof. We write  $\mathfrak{g}$  for the Lie alg. of  $G$  and

$$\mathfrak{h} := \left\{ c'(0) : c : \mathbb{R} \rightarrow G \text{ is smooth, } c(0) = e \text{ and } c \text{ has values in } H \right\}.$$

$$\subseteq \mathfrak{g}.$$

Claim 1.  $\mathfrak{h}$  is a linear subspace.

If  $c_1, c_2 : \mathbb{R} \rightarrow H \subseteq G$  <sup>are</sup>  $C^\infty$ -curves and  $c_1(0) = c_2(0) = e$ ,

then  $c(t) := c_1(t)c_2(\alpha t)$  is a  $C^\infty$ -curve with values in  $H$  and  $c(0) = e$ . ( $\alpha \in \mathbb{R}$ ).

Then,  $c'(0) \in \mathfrak{g}$

$$\begin{aligned} \left. \frac{d}{dt} \right|_{t=0} \mu(c_1(t), c_2(\alpha t)) &= T_M(c_1'(0), \alpha c_2'(0)) \\ &= \underbrace{c_1'(0)}_{\text{Lemma 1.5}} + \alpha \underbrace{c_2'(0)} \end{aligned}$$

Claim 2: Suppose  $(X_n)_{n \in \mathbb{N}}$  is a sequence in  $\mathfrak{g}$  with  $\lim_{n \rightarrow \infty} X_n = X \in \mathfrak{g}$  and let  $(t_n)_{n \in \mathbb{N}}$  is a sequence in  $\mathbb{R}_{>0}$  s.t.



$$\lim_{n \rightarrow \infty} t_n = 0.$$

Then if  $\exp(t_n X_n) \in H \forall n \in \mathbb{N}$ , then  $\exp(tX) \in H \forall t \in \mathbb{R}$ .

Fix  $t \in \mathbb{R}$ . For  $n \in \mathbb{N}$  let  $a_n$  be the largest integer  $\leq \frac{t}{t_n}$ .

Then,  $a_n t_n \leq t$  and  $t - a_n t_n < t_n$ , so

$$\lim_{n \rightarrow \infty} a_n t_n = t$$

$H \subseteq G$   
is closed

$$\implies \lim_{n \rightarrow \infty} \underbrace{\left( \exp(t_n X_n) \right)^{a_n}}_H = \lim_{n \rightarrow \infty} \exp(\underbrace{a_n t_n}_{= \exp(tX)} X_n) \in H$$

by continuity of  $\exp$  in  $G$

by assumption +  $H$  closed

~~since~~

Claim 3  $\mathfrak{g} = \{X \in \mathfrak{g} : \exp(tX) \in H \quad \forall t \in \mathbb{R}\}$ .

RHS  $\subseteq \mathfrak{g}$ . by definition of  $\mathfrak{g}$ .

To show  $\mathfrak{g} \subseteq \text{RHS}$ , let  $c: \mathbb{R} \rightarrow H \subseteq G$  be a  $C^\infty$ -curve with  $c(0) = e$  ( $c'(0) \in \mathfrak{g}$ ).

Then  $\exists \varepsilon > 0$  and a  $C^\infty$ -curve  $v: (-\varepsilon, \varepsilon) \rightarrow \mathfrak{g}$  s.t.  $c(t) = \exp(v(t)) \quad \forall t \in (-\varepsilon, \varepsilon)$ . ( $v(0) = 0 \in \mathfrak{g}$ ).

$\implies$

$$c'(0) = \left. \frac{d}{dt} \right|_{t=0} \exp(v(t)) = \underbrace{T_0 \exp}_{= \text{Id}_{\mathfrak{g}}} v'(0) = v'(0) = \lim_{h \rightarrow 0} \frac{v(1/h)}{1/h}$$

$v'(0) = \lim_{t \rightarrow 0} \frac{v(t)}{t}$

Set  $t_n := \frac{1}{n}$  and  $X_n := n v(\frac{1}{n})$ , then

$$\exp(t_n X_n) = \exp\left(v\left(\frac{1}{n}\right)\right) = c\left(\frac{1}{n}\right) \in H$$

$\uparrow$   
for big  $n$

By Claim 2,  $\exp(t c'(0)) \in H \quad \forall t \in \mathbb{R}$ .

Claim 4. Write  $\mathfrak{g} = \mathfrak{h} \oplus \mathfrak{k}$  as a vector space ( $\mathfrak{k}$  is linear complement of  $\mathfrak{h}$  in  $\mathfrak{g}$ .)

Then  $\exists$  an open neighborhood  $W$  of  $0 \in \mathfrak{k}$  in  $\mathfrak{k}$  s.t.

$$\exp(W) \cap H = \{e\}.$$

TO BE CONTINUED...