

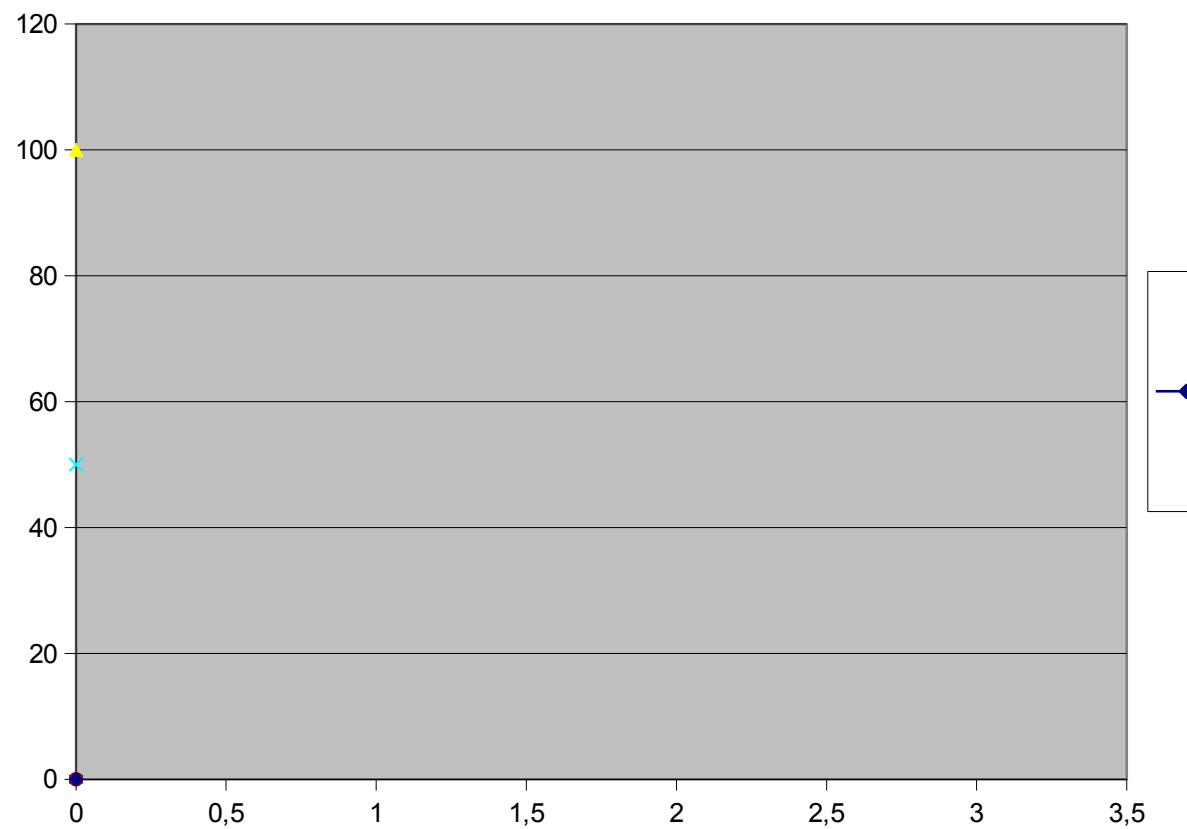
|                                                                                                                                      |         |     |        |    |   |    |          |
|--------------------------------------------------------------------------------------------------------------------------------------|---------|-----|--------|----|---|----|----------|
| 2A                                                                                                                                   | +       | B   | -----> | 3C | + | 4D |          |
| výchozí                                                                                                                              | -2      |     | -1     |    | 3 |    | 4        |
|                                                                                                                                      | 100     |     | 50     |    | 0 |    | 0 mM     |
|                                                                                                                                      |         |     |        |    |   |    |          |
| v=(dz)/dt=(dx)/(V dt)=1/n_I d(n_I-n_I0)/(V dt)=1/n_I dI/( dt)=1/n_A dB/( dt)=1/n_C dC/( dt)=1/n_D dD/( dt)=[ k A ]^(n_A) [ B ]^(n_B) |         |     |        |    |   |    |          |
| t                                                                                                                                    | $\zeta$ | A   | B      | C  | D |    | kontrola |
| 0                                                                                                                                    | 0       | 100 | 50     | 0  | 0 |    | 100      |
| 1                                                                                                                                    |         |     |        |    |   |    |          |
| 2                                                                                                                                    |         |     |        |    |   |    |          |
| 3                                                                                                                                    |         |     |        |    |   |    |          |

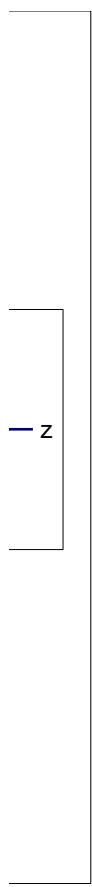


kn = 0,001 sec-1  
dt0= 1 sec-1 expanze t 1

dA/( dt)=1/n\_B  
rad vuci A 1  
rad vuci B 1  
B )

dopočty  
 $I = I_0 + v_i * \zeta$  kontrola:  $I/n_- (I@) = \text{konst}$





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