E7441: Scientific computing in biology and biomedicine

Introduction to parallel computing

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Outline

3 [Principles of parallel computing](#page-16-0)

- [Introduction](#page-16-0)
- o [Programming models](#page-26-0)
- o [Implementations](#page-33-0)
- "I think there is a world market for maybe five computers." (Thomas Watson, chairman of IBM, 1943)
- "There is no reason for any individual to have a computer in their home." (Ken Olson, founder Digital Equipment Corporation, 1977)
- "640K of memory ought to be enough for anybody." Bill Gates, chairman of Microsoft, 1981
- ∼ 2500 BC: Babylon - the first abacus
- ∼ 100 BC: Antikythera device believed to be the first mechanical computer
- first half of the 19th century: Charles Babbage's differential machine (to tabulate polynomials) and analytical machine (only design)
- 1941: Z3 computer by Konrad Zuse: first programmable, fully automatic computing machine

source: Wikipedia

∼ 1840 Charles Babbage produces the differential machine, a mechanical computer.

source: Wikipedia

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1941: Z3 computer: electro-mechanical computer, ∼ 2000 relays, 22-bit words, operating at 5-10 Hz.

source: Wikipedia

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1946: ENIAC - Electronic Numerical Integrator And Computer used initially by US Army to compute tables for artilery. Uses vacuum tubes as switches.

source: Wikipedia

1976: Cray-1 - the first successful supercomputer

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...fast forward: Tianhe-2 (top supercomputer as Nov. 2013): 33.86 PFlop/s, 3,120,000 cores; 1,024,000 GB, CPU: Intel Xeon

Moore's law

Gordon E. Moore (co-founder Intel): "Cramming More Components onto Integrated Circuits", Electronics Magazine, 1965

source: Wikipedia

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Software and hardware

Software crises:

- '60s-'70s: assembly language difficult to use for large complex problems \rightarrow Fortran, C: provide abstraction and portability for uniprocessors
- \bullet '80s-'90s: problems in maintaining complex systems \rightarrow object-oriented programming (C++, Java)
- ∼ 2000s: sequential performance lags behind Moore's law → programmers are oblivious to hardware better compilers, higher level languages, virtual machines
- parallel computing: using multiple execution units concurrently to solve a problem
- examples:
	- ▶ multi-core processors: several processors (cores) in a chip
	- \triangleright shared memory processors (SMP): several processors interconnected through a shared memory
	- ▶ cluster computer: several computers interconnected through high-speed network

Issues with the traditional model: power density

(Ross: Why CPU Frequency Stalled, IEEE Spectrum Magazine, 2008)

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Issues cont'd: gains from implicit parallelism tapped out

Example: instruction-level parallelism. Machine instruction: decomposed into 4-stages: fetch, decode, execute and write-back

Issues cont'd

Other issues:

- increase in production costs (decrease in "chip yield")
- increase in amount of data to be processed
- Solution: explicit parallelism
	- multi-core
	- multi-processor
	- multi-machine

Principles

- identifying parallelism
- granularity: more smaller or fewer larger tasks?
- locality: data and instruction location
- load balance: aim: no lost CPU cycles
- **•** synchronization
- overhead

Identifying parallelism

Amdahl's law:

$$
S_n = \frac{T_1}{T_n} \le \frac{1}{\alpha + (1 - \alpha)/n} \le \frac{1}{\alpha}
$$

where α is the fraction of the program that is strictly sequential, T_i is the
execution time on i processors and S, is the speed-up obtained by using execution time on *i* processors and S_i is the speed-up obtained by using *i* processors instead of 1.

Identifying parallelism

- implicit parallelism
	- ▶ hardware level: superscalar processors, multi-core, cluster computing
	- ▶ compiler level: parallelizing compilers
- explicit parallelism
	- ▶ programming language level
	- \blacktriangleright library level

Processing architectures

Flynn's taxonomy ("old way"): Single/Multiple Instruction \times Single/Multiple Data

Source: Wikipedia

Examples: SISD: mainframes; SIMD: GPUs; MISD: fault tolerant systems; MIMD: most computers nowadays

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Locality: a box in a box in a box...

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Computing topologies

Figure 2.15 Linear arrays: (a) with no wraparound links: (b) with wraparound link.

Figure 2.16 Two and three dimensional meshes: (a) 2-D mesh with no wraparound; (b) 2-D mesh with wraparound link (2-D torus); and (c) a 3-D mesh with no wraparound.

Source: Grama - Introduction to Parallel Computing

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Shared memory: multicore or multi-CPU machines

Distributed memory: clusters with single CPUs nodes

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Hybrid systems

- a limited number of CPUs have access to a pooled memory
- using more CPUs implies communication over network through message-passing

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Hybrid systems with multicore CPUs

- extension of the hybrid model
- communication becomes increasingly complex
- many levels in the memory hierachy: cache(s), local main memory, \bullet other node's memory, etc
- you can add accelerators: e.g, GPUs
- **•** requires a new programming model, and different communication protocols

Load balancing

- aim: distribute evenly the *load* (work) on all available resources...
- \bullet and thus minimize the time a resource is idle
- causes of imbalanced load:
	- \blacktriangleright insufficient paralelism
	- ▶ unequal task size (poor design?)

Types of parallelism

- data parallelism: each processor performs the same task on different data (h/w: SIMD, MIMD)
- **•** task parallelism: each processor performs a different task on the same data (h/w: MISD, MIMD)
- usually, both types of parallelism are present

Example: re-annotation of a microarray chip

(embarrassingly parallel problem)

Problem: map (BLAST) each probe from a microarray against the latest version of the human genome (RefSeq).

Naive implementation on 2 CPUs:

Better ways of distributing the data exists for this problem! Ex: distribute also the RefSeq...

Problem decomposition

- split the computations into concurrent tasks
- build the task-dependency graph
- there is no one-size-fits-all technique
- some methods: recursive decomposition, data-decomposition, \bullet exploratory decomposition and speculative decomposition

Recursive decomposition: example

Problem: find the minimum of a vector

```
proc serial min (A, n)
  min = A[1]for i = 2 to n do
    if A[i] < min
    then min = A[i]end for
  return min
end serial_min
                                                          proc rec min (A, i, j)
                                                            \text{if } i == ithen min = A[i]else
                                                              lmin = rec_{min}(A, i, j/2)rmin = rec_min (A, j/2+1, j)if Imin \, \epsilon rmin
                                                               then min = 1min
                                                               else min = rmin
                                                              end i f
                                                            end i f
                                                            return min
                                                          end rec_min
```
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Data decomposition: example

Matrix multiplication: $\mathbf{A} \cdot \mathbf{B} = \mathbf{C}$. Write it as

$$
\begin{bmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{bmatrix} \cdot \begin{bmatrix} B_{11} & B_{12} \\ B_{21} & B_{22} \end{bmatrix} = \begin{bmatrix} C_{11} & C_{12} \\ C_{21} & C_{22} \end{bmatrix}
$$

and distribute the four tasks:

Task 1:
$$
C_{11} = A_{11}B_{11} + A_{12}B_{21}
$$

Task 2: $C_{12} = A_{11}B_{12} + A_{12}B_{22}$
Task 3: $C_{21} = A_{21}B_{11} + A_{22}B_{21}$
Task 4: $C_{22} = A_{21}B_{12} + A_{22}B_{22}$

Other decompositions

- exploratory decomposition: decompose the search space for the solution and search for a solution in each subspace; then choose among the solutions
- speculative decomposition: launch alternative computation branches in parallel while waiting for input for deciding which branch to use
- hybrid decompositions

Mapping techniques

- problem decomposition \rightarrow tasks
- the tasks need to be allocated (mapped) to processors/processes
- objective: minimize the execution time
- overheads: time spent for everything else but actually solving the problem:
	- \triangleright inter-process interaction synchronization and control
	- \cdot time spent being idle poor load balancing
- reduce the process inter-dependencies and communication: e.g. maximize data locality
- improve load balancing
- reduce blocking operations

Implementations on multihtread/multicore machines

• POSIX threads (*pthreads*): OS-level paralelism.

- \triangleright threads: lightweight processes
- \rightarrow the same program runs on single- or multi-core machines
- \triangleright OS has the responsibility of mapping the threads
- ▶ needs low-level programming, dedicated library
- OpenMP: built on top of pthreads for SIMD-kind of parallelism
	- \rightarrow implemented through compiler directives
	- \rightarrow easier to use than pthreads
	- ▶ performance depends on compiler's 'intelligence'

OpenMP: how does it look like? $(\sum_i a_i b_i)$

```
double a[N];
  double sum = 0.0;
  int i, n, tid :
#pragma omp parallel shared (a) private (i)
    tid = comp get thread num ();
     /
Only one of the th read s do t h i s
*
/
*
#pragma omp s i n g l e
     {
       n = omp_get_num_threads ( ) ; p r i n t f ( "Number<sub>-of-threads -=</sub>\mathscr{A}d \nmid n " , n ) ;
     /* Initialize a */
*
#pragma omp fo r
    for (i = 0; i < N; i++) {
       a[i] = 1.0:
     }
     /
P a r a l l e l f o r loop computing the sum of a [ i ]
*
/
*
#pragma omp fo r reduction ( + :sum)
    for (i=0; i < N; i++) {
       sum = sum + (a[i]):
   \} /\star End of parallel region \star/
```
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Implementations on distributed-memory systems

• MPI: Message Passing Interface

- \rightarrow de facto standard for distributed memory programming (clusters)
- \rightarrow data must be manually decomposed
- \triangleright use special libraries
- ▶ based on sending and receiving messages: data and synchronization
- PVM: Parallel Virtual Machine
	- \rightarrow previous library for cluster programming
	- ▶ based on message-passing principle
	- ▶ supplanted by MPI

MPI: how does it look like?

```
#include <mpi . h>
int main(int argc, char *argv[])
  int numprocs, mvid:
  MPI_Init (& argc ,& argv ) ;
  MPI_Comm_size (MPI_COMM_WORLD,&numprocs ) ;
  MPI_Comm_rank(MPI_COMM_WORLD, & myid) ;
   /* print out my rank and this run's PE size */
   * print out my rank and this run s rL size */<br>printf("Hello_from_%d_of_%d\n", myid, numprocs);
  MPI_Finalize ( ) ;
}
```
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Implementations in R

- **•** parallelism came as an after thought
- target: massive data applications
- tries to bring to R some of the libraries existing to other languages
- snow: for traditional clusters, supports PVM, MPI,...; is portable (UNIX, Windows)
- *multicore*: targets multi-core/-CPU machines; simple; does not run on Windows; does not handle parallel RNGs
- parallel: snow+multicore in new R $(>=2.14)$; strange interactions with OS
- R+Hadoop: based on Hadoop cluster
- RHIPE: based on Hadoop, targets map-reduce operations
- Segue: APPLY-like calculations on Hadoop clusters, using Amazon's Elastic MapReduce

Questions?

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