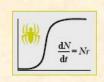


#### MODULARIZACE VÝUKY EVOLUČNÍ A EKOLOGICKÉ BIOLOGIE CZ.1.07/2.2.00/15.0204





# Enemy-Victim Models

"Populační ekologie živočichů"

Stano Pekár











## Predator-prey system

Acarus



Cheyletus





## Predator-prey model

- ▶ continuous model of Lotka & Volterra (1925-1928) used to explain decrease in prey fish and increase in predatory fish after World War I
- assumptions
- continuous predation (high population density)
- populations are well mixed
- closed populations (no immigration or emigration)
- no stochastic events
- predators are specialised on one prey species
- populations are unstructured
- reproduction immediately follows feeding

H.. density of preyr.. intrinsic rate of prey population

a.. predation rate

P... density of predators

m.. predator mortality rate

b.. reproduction rate of predators

in the absence of predator, prey grows exponentially 
$$\rightarrow \frac{dH}{dt} = rH$$

in the absence of prey, predator dies exponentially 
$$\rightarrow \frac{dP}{dt} = -mP$$

- ▶ predation rate is linear function of the number of prey .. *aHP*
- ▶ each prey contributes identically to the growth of predator .. *bHP*

$$\frac{dH}{dt} = rH - aHP$$

$$\frac{dP}{dt} = bHP - mP$$

#### Analysis of the model

#### Zero isoclines:

for prey population:

$$\frac{\mathrm{d}H}{\mathrm{d}t} = 0 \qquad 0 = rH - aHP$$

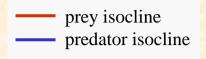
$$P = \frac{r}{a}$$

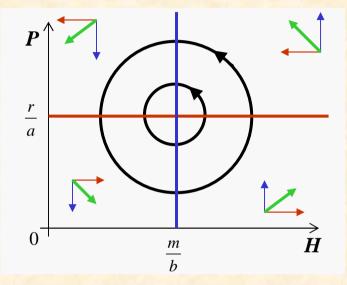
for predator population:

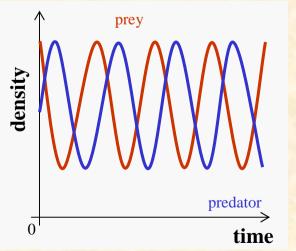
$$\frac{\mathrm{d}P}{\mathrm{d}t} = 0 \qquad 0 = bHP - mP$$

$$H = \frac{m}{b}$$

- → do not converge, has no asymptotic stability (trajectories are closed lines)
- → neutral stability
- ▶ unstable system, amplitude of the cycles is determined by initial numbers







#### Addition of density-dependence

in the absence of the predator prey population reaches

carrying capacity K

$$\frac{dH}{dt} = rH\left(1 - \frac{H}{K}\right) - aHP$$

$$\frac{dP}{dt} = bHP - mP$$

• for given parameter values: r = 3, m = 2, a = 0.1, b = 0.3, K = 10

$$\frac{\mathrm{d}H}{\mathrm{d}t} = 3H\left(1 - \frac{H}{10}\right) - 0.1HP \qquad \qquad \frac{\mathrm{d}P}{\mathrm{d}t} = 0.3HP - 2P$$

#### Zero isoclines:

• for prey population:

$$\frac{\mathrm{d}H}{\mathrm{d}t} = 0$$

$$\frac{\mathrm{d}H}{\mathrm{d}t} = 0 \qquad 0 = 3H \left(1 - \frac{H}{10}\right) - 0.1HP$$

if 
$$H = 0$$
 (trivial solution) or if  $0 = 3\left(1 - \frac{H}{10}\right) - 0.1P$ 

P = 30 - 3H

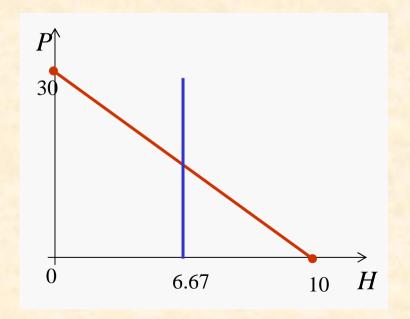
• for <u>predator</u> population:  $\frac{dP}{dt} = 0$  0.3HP - 2P = 0

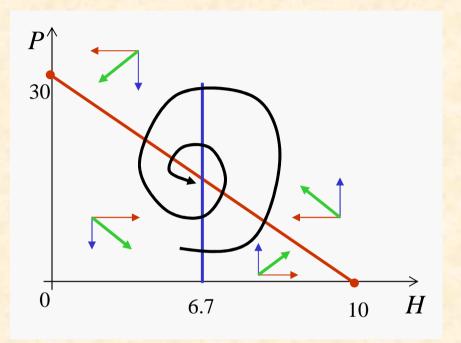
$$\frac{dP}{dt} = 0 \qquad 0.3HP -$$

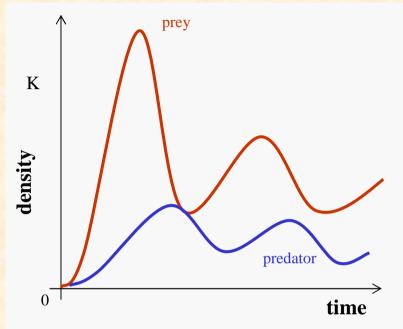
if P = 0 (trivial solution) or if 0.3H - 2 = 0

$$H = 6.667$$

gradient of prey isocline is negative







- ▶ has single positive asymptotically stable equilibrium defined by crossing of isoclines
- converges to the stable equilibrium

#### Addition of functional response of Type II

▶ functional response Type II:

$$H_a = \frac{aHT}{1 + aHT_h}$$

rate of consumption by all predators:  $\frac{H_a P}{T} = \frac{aHP}{1 + aHT_h}$ 

$$\frac{H_a P}{T} = \frac{aHP}{1 + aHT_h}$$

$$\frac{\mathrm{d}H}{\mathrm{d}t} = r_H H \left( 1 - \frac{H}{K} \right) - \frac{aHP}{1 + aHT_h} \qquad \frac{dP}{\mathrm{d}t} = bHP - mP$$

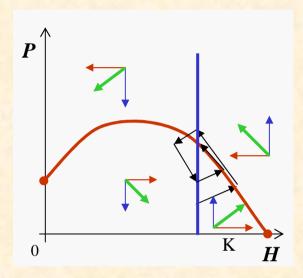
• for parameters:  $r_H = 3$ , a = 0.1,  $T_h = 2$ , K = 10

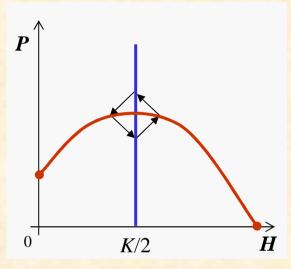
$$\frac{dH}{dt} = 0$$
  $0 = 3H\left(1 - \frac{H}{10}\right) - \frac{0.1HP}{1 + 0.1H2}$ 

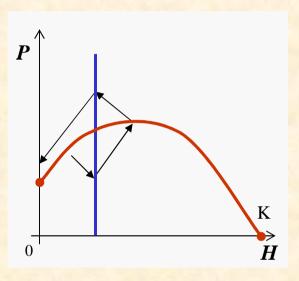
prey isocline: 
$$P = 30 + 6H - 0.6H^2$$
 predator isocline:  $H = constant$ 

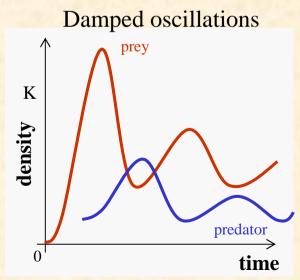
- predator exploits prey close to K
- isocline: H = 9

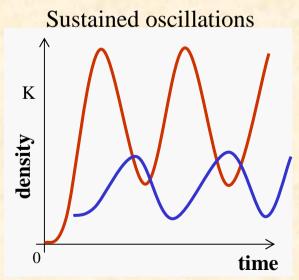
- predator exploits prey close to K/2
- isocline: H = 5
- predator exploits prey at low density - isocline: H = 2

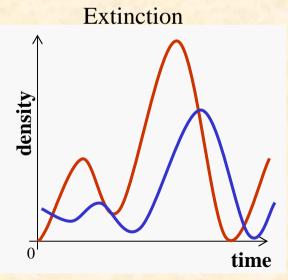












Rosenzweig & MacArthur (1963)

#### Addition of predator's carrying capacity

- ▶ logistic model with carrying capacity proportional to *H*
- ▶ k .. carrying capacity of the predator
- $r_P = bH m$

$$\frac{\mathrm{d}P}{\mathrm{d}t} = bHP - mP$$

$$\frac{\mathrm{d}P}{\mathrm{d}t} = r_P P \left( 1 - \frac{P}{kH} \right) \qquad \frac{\mathrm{d}H}{\mathrm{d}t} = r_H H \left( 1 - \frac{H}{K} \right) - \frac{aHP}{1 + aHT_h}$$

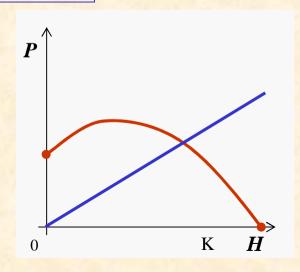
• for parameters:  $r_P = 2$ , k = 0.2

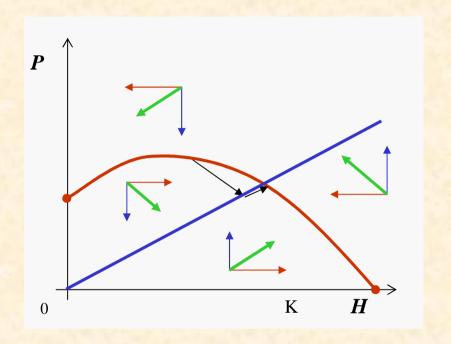
$$\frac{\mathrm{d}P}{\mathrm{d}t} = 0 \qquad 0 = 2P \left(1 - \frac{P}{0.2H}\right)$$

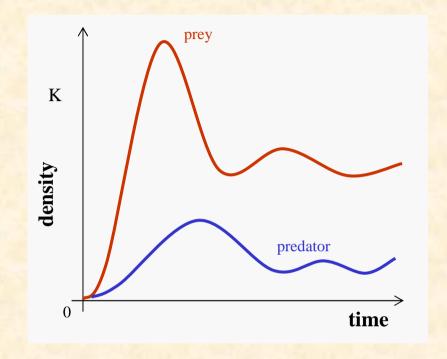
predator isocline:

$$H = 5P$$

prey isocline: 
$$P = 30 + 6H - 0.6H^{2}$$







• quick approach to stable equilibrium

### Host-parasitoid system

Zatypota



**Theridion** 





## Host-parasitoid model

- ▶ discrete model of Nicholson & Bailey (1935)
- discrete generations
- 1, ..., several, or less than 1 host
- random host search and functional response Type III
- lay eggs in aggregation

 $H_t$  = number of hosts in time t

 $H_a$  = number of attacked hosts

 $\lambda$  = finite rate of increase of the host

 $P_t$  = number of parasitoids c = conversion rate, no. of parasitoids for 1 host

$$H_{t+1} = \lambda (H_t - H_a)$$

$$P_{t+1} = cH_a = H_a$$

$$P_{t+1} = cH_a = H_a$$

#### **Incorporation of random search**

- parasitoid searches randomly
- encounters (x) are random (Poisson distribution)

$$p_x = \frac{\mu^x e^{-\mu}}{x!}$$
  $x = 0, 1, 2, ...$   $p_0 = e^{-\mu}$ 

 $p_0$  = proportion of not encountered,  $\mu$  .. mean number of encounters

 $E_t$  = total number of encounters a = searching efficiency (proportion of hosts encountered)

$$E_t = a H_t P_t \longrightarrow \mu = \frac{E_t}{H_t} = a P_t \longrightarrow p_0 = e^{-a P_t}$$

• proportion of encounters (1 or more times):  $p = (1 - p_0)$ 

$$p = (1 - e^{-aP_t})$$

$$p = (1 - e^{-aP_t})$$

$$H_a = H_t \left(1 - e^{-aP_t}\right)$$

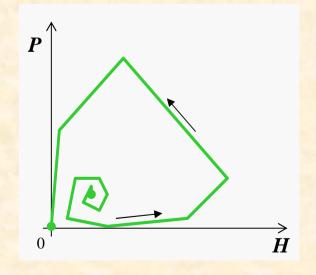
$$H_{t+1} = \lambda (H_t - H_a)$$

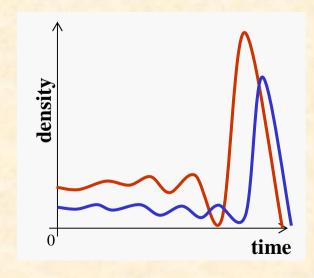
$$P_{t+1} = H_a$$

$$H_{t+1} = \lambda H_t e^{-aP_t}$$

$$P_{t+1} = H_t (1 - e^{-aP_t})$$

- ▶ highly unstable model for all parameter values:
- equilibrium is possible but the slightest disturbance leads to divergent oscillations (extinction of parasitoid)





#### Addition of density-dependence

exponential growth of hosts is replaced by logistic equation

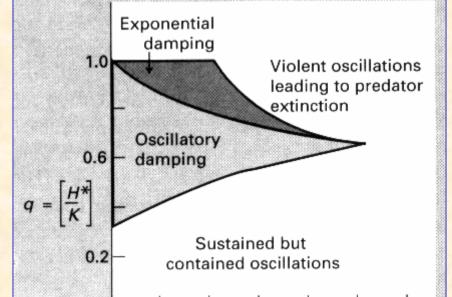
$$H_{t+1} = \lambda H_t e^{\left(1 - \frac{H_t}{K}\right) - aP_t}$$

$$P_{t+1} = H_t \left(1 - e^{-aP_t}\right)$$

$$q = \frac{H^*}{K}$$

H\*.. new host carrying capacity

- depends on parasitoids' efficiency
- when a is low then  $q \rightarrow 1$
- when a is high then  $q \rightarrow 0$
- ▶ density-dependence havestabilising effect for moderate r and q



 $r(=\log_e R)$ 

Stability boundaries

#### Addition of the refuge

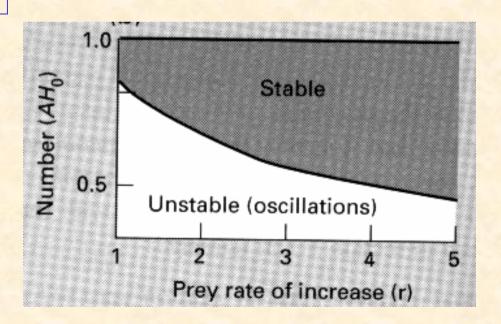
if hosts are distributed non-randomly in the space

Fixed number in refuge:  $H_0$  hosts are always protected

$$H_{t+1} = \lambda H_0 + \lambda (H_t - H_0) e^{-aP_t}$$

$$P_{t+1} = (H_t - H_0) (1 - e^{-aP_t})$$

have strong stabilising effect even for large *r* 



#### Addition of aggregated distribution

binomial distribution) distribution) distribution of encounters is not random but aggregated (negative binomial distribution)

- proportion of hosts not encountered  $(p_0)$ :  $p_0 = \left(1 + \frac{aP_t}{k}\right)^{-k}$ 

where k =degree of aggregation

$$H_{t+1} = \lambda H_t e^{\left(1 - \frac{H_t}{K}\right)\left(1 + \frac{aP_t}{k}\right)^{-k}}$$

$$P_{t+1} = H_t \left(1 - \left(1 + \frac{aP_t}{k}\right)^{-k}\right)$$

• very stable model system if  $k \le 1$ 

Stability boundaries:

a) 
$$k=\infty$$
, b)  $k=2$ , c)  $k=1$ , d)  $k=0$ 

