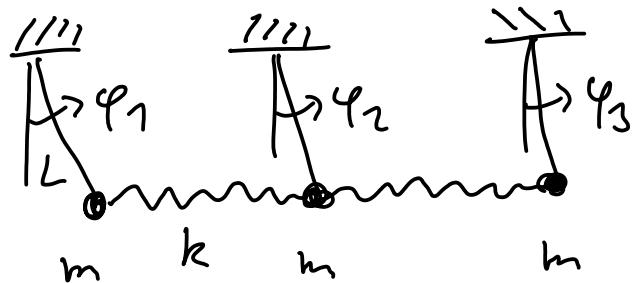
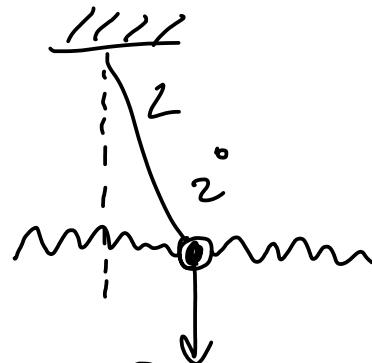


Cvičení'



pohybové rovnice pro malé výchylky

$$J \ddot{\varphi} = M$$



$$mL^2 \ddot{\varphi}_i = -mgL\varphi_i + L \left[ kL(\varphi_{i+1} - \varphi_i) - kL(\varphi_i - \varphi_{i-1}) \right] - mg$$

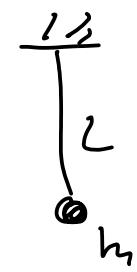
$$\ddot{\varphi}_i = -\frac{g}{L}\varphi_i + \frac{k}{m}(\varphi_{i-1} - 2\varphi_i + \varphi_{i+1}) \quad \text{pohyb. rovnice pro } i\text{-tí kyvadlo}$$

$$\varphi_i = \phi_i \cos \omega t \quad \rightarrow \quad \omega^2 \phi_i = \underbrace{\left( \frac{g}{L} \right)}_{\omega_k^2} \phi_i + \underbrace{\left( \frac{2k}{m} \right)}_{\omega_p^2} \left( \phi_i - \frac{1}{2} \phi_{i-1} - \frac{1}{2} \phi_{i+1} \right)$$

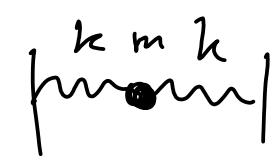
$$\begin{pmatrix} \ddots & & & & \\ & -\frac{1}{2}\omega_p^2 & & & \\ & & \omega_k^2 + \omega_p^2 & & \\ & & & -\frac{1}{2}\omega_p^2 & \\ & & & & \ddots \end{pmatrix} \begin{pmatrix} \vdots \\ \phi_{i-1} \\ \phi_i \\ \phi_{i+1} \\ \vdots \end{pmatrix} = \omega^2 \begin{pmatrix} \vdots \\ \phi_{i-1} \\ \phi_i \\ \phi_{i+1} \\ \vdots \end{pmatrix}$$

$$\begin{pmatrix}
 \omega_k^2 + \omega_p^2 & & 0 \\
 -\frac{\omega_p^2}{2} & \omega_k^2 + \omega_p^2 & -\frac{\omega_p^2}{2} \\
 0 & -\frac{\omega_p^2}{2} & \omega_k^2 + \omega_p^2
 \end{pmatrix}$$

k diagonalizacja



$$\omega_k = \sqrt{\frac{g}{L}}$$



$$\omega_p = \sqrt{\frac{2k}{m}}$$

# Vzteklina

$$c \Delta x^2 > \Delta t$$

S, I, R

S... susceptible

I... infected

R... rabid

$$\frac{dS}{dt} = (a-b)S \left(1 - \frac{N}{K}\right) - \beta RS$$

a... natalita

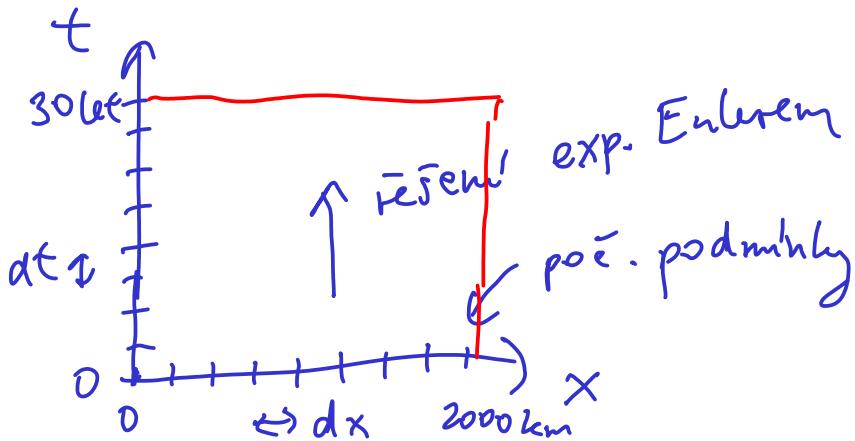
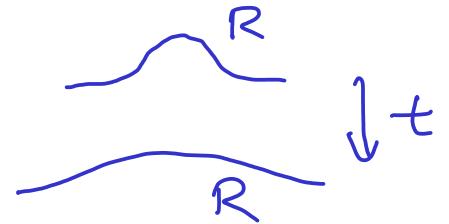
b... mortalita

K... kapacita populace

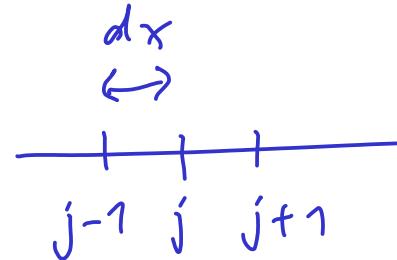
$$\frac{dI}{dt} = -bI - \frac{(a-b)N}{K}I + \beta RS - \sigma I$$

všechny lišky  $N = S + I + R$

$$\frac{dR}{dt} = -bR - \frac{(a-b)N}{K}R + \sigma I - \alpha R + D \frac{\partial^2 R}{\partial x^2}$$



Laplaceův



$$\frac{R_{j-1} - 2R_j + R_{j+1}}{dx^2} \approx \frac{\partial^2 R}{\partial x^2}$$

# Tsunami

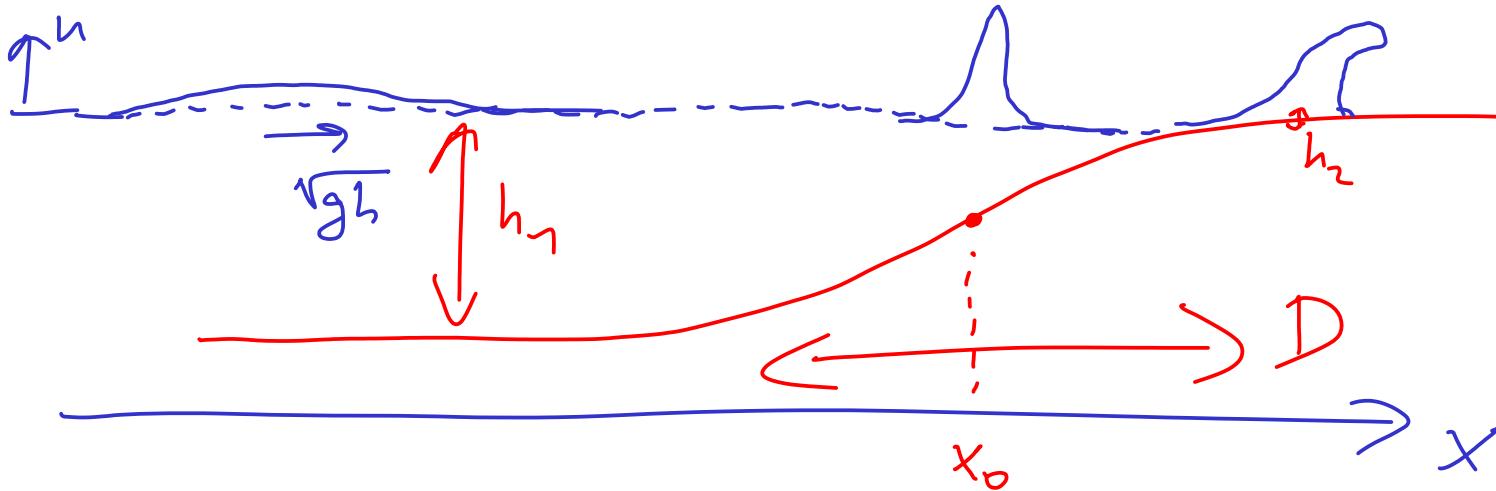
$$\frac{\partial^2 \eta}{\partial t^2} = g \frac{\partial}{\partial x} \left( h \frac{\partial \eta}{\partial x} \right)$$

$$g \approx 9.81 \text{ m s}^{-2}$$

$h$  ... hloubka vody

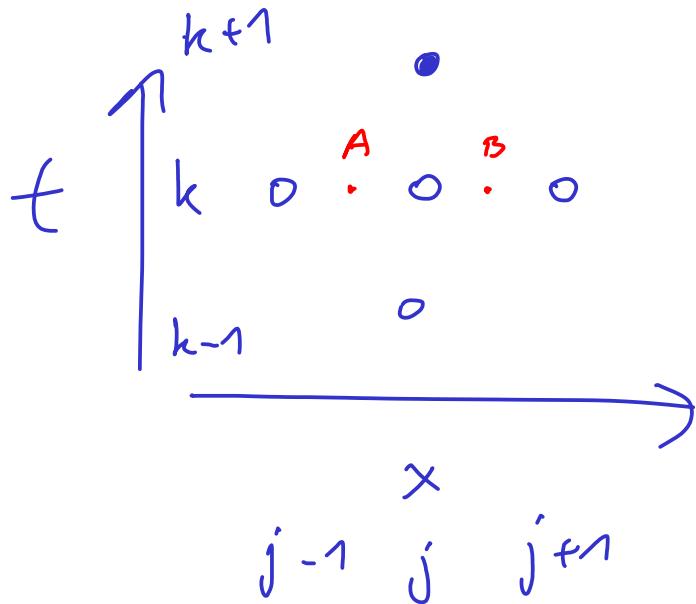
konst.  $h \rightarrow \frac{1}{\sqrt{gh}^2} \frac{\partial^2 \eta}{\partial t^2} = \frac{\partial^2 \eta}{\partial x^2}$

rychlost vln  $\sqrt{gh}$



$$h(x) = \frac{h_1 + h_2}{2} - \frac{h_1 - h_2}{2} \cdot \tanh \frac{x - x_0}{D}$$

$$\cdot \tanh \frac{x - x_0}{D}$$



$$\frac{\partial^2 u}{\partial t^2} = g \frac{\partial}{\partial x} \left( h \frac{\partial u}{\partial x} \right)$$

$$\frac{u_j^{k+1} - 2u_j^k + u_j^{k-1}}{\Delta t^2} = g$$

$$\frac{B - A}{\Delta x}$$

$$h_{j+\frac{1}{2}} \frac{u_{j+1}^k - u_j^k}{\Delta x} - h_{j-\frac{1}{2}} \frac{u_j^k - u_{j-1}^k}{\Delta x}$$

$$\Delta x$$