


Recall : Frobenius Thm.

- $E \subseteq TM$ smooth distribution that is involutive.

$\Rightarrow E$ is integrable.

- E involutive distr. $\hookrightarrow \mathcal{F}_E$ foliation.

Some applications of Thm. 3.38 (Frobenius Thm.) to the study of PDEs:

Ex Consider system of PDEs for a fct. $f: \mathbb{R}^3 \rightarrow \mathbb{R}$

(x, y, z)
coordinates
on \mathbb{R}^3)

$$(*) \begin{cases} -2z^2 \frac{\partial f}{\partial x} + 2x \frac{\partial f}{\partial z} = 0 \\ -3z^3 \frac{\partial f}{\partial y} + 2y \frac{\partial f}{\partial z} = 0 \end{cases} \quad \begin{matrix} \text{linear system of first} \\ \text{order PDEs} \end{matrix}$$

Does $(*)$ has only non-constant solutions f ?

→ see Tutorial.

Ex. Consider system of PDEs for a fct. $f : \mathbb{R}^2 \rightarrow \mathbb{R}$

$$\frac{\partial f}{\partial x}(x,y) = \alpha(x,y, f(x,y)) \quad (**)$$

$$\frac{\partial f}{\partial y}(x,y) = \beta(x,y, f(x,y))$$

α, β smooth fcts defined on an open subset $V \subseteq \mathbb{R}^3$.

Q When does $(**)$ has a solution? Conditions on α, β ?

→ see tutorial.

On the opposite ending of integrable distributions (among all dist.) are the so-called bracket-generating dist.:

Def. 3.41. A smooth distribution $E \subseteq TM$ on a mfld. M is called **bracket-generating**, if any local frame $\{\xi_1, \dots, \xi_n\}$ of E together with its iterated Lie brackets $[\xi_i, \xi_j], [\xi_i, [\xi_j, \xi_k]], \dots$ form a local frame of TM .

Remark If a local frame is bracket-generating around some point, then so is another frame around that point.

Ex. Standard contact distribution on \mathbb{R}^3

$$E = \left\langle \frac{\partial}{\partial y}, \frac{\partial}{\partial x} + y \frac{\partial}{\partial z} \right\rangle \text{ smooth rank 2 distribution,}$$

$$\left[\frac{\partial}{\partial y}, \frac{\partial}{\partial x} + y \frac{\partial}{\partial z} \right] = \frac{\partial}{\partial z} \quad \cancel{\text{not a section}} \\ \text{of } E.$$

$T\mathbb{R}^3$ spanned by $\frac{\partial}{\partial y}, \frac{\partial}{\partial x} + y \frac{\partial}{\partial z}, \frac{\partial}{\partial z}$.

Ex. Contact manifolds

M odd dim. w/ of dim. $2n+1$. A distribution

$E \subseteq TM$ ~~real~~ is a contact distribution, if E has rank $2n$

s.t. $\overset{\rightarrow}{\mathcal{L}}_x : E_x \times E_x \rightarrow T_x M / E_x \cong \mathbb{R}$ 1) non-degenerate
 Levi-bracket $(s, n) \mapsto q_x([\tilde{s}, \tilde{n}](x))$ $\forall x \in M.$

\tilde{s}, \tilde{n} are extension of s, n to local lf. around x

and $q_x : T_x M \rightarrow T_x M / E_x$ is the standard projection.

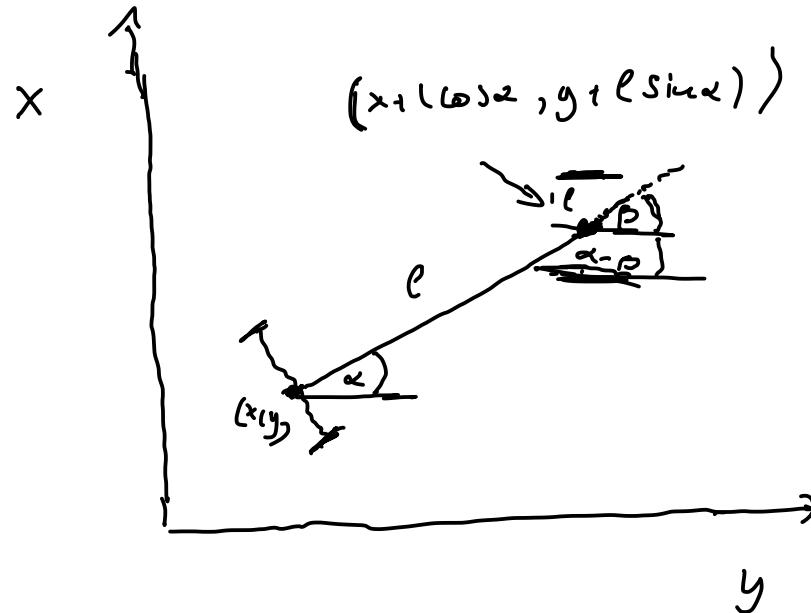
DEFINITION A odd dim. mfld. equipped with a contact distribution is called a contact manifold.

in contact geometry / topology -

Ex. Driving a car.

Configuration space / phase space of a car : $M = \mathbb{R}^2 \times S^1 \times S^1$

$$(x, y, \alpha, \beta)$$



(x, y) position of
mid point of rear axle

α angle of the chassis
to x-axis

β steering angle of
the front wheels.

Moving the car traverses a curve $c(t) = (x(t), y(t), \alpha(t), \beta(t))$
in M .

$\frac{d}{dt} \begin{pmatrix} x(t) \\ y(t) \end{pmatrix}$ is parallel to $\begin{pmatrix} \cos \alpha \\ \sin \alpha \end{pmatrix}$

$\frac{d}{dt} \begin{pmatrix} x(t) + l \cos(\alpha(t)) \\ y(t) + l \sin(\alpha(t)) \end{pmatrix}$ is parallel to $\begin{pmatrix} \cos(\alpha - \beta) \\ \sin(\alpha - \beta) \end{pmatrix}$

↑

$$x'(t) \sin \alpha(t) - y'(t) \cos \alpha(t) = 0$$

$$(x'(t) - l \sin(\alpha(t)) \alpha'(t)) \sin(\alpha(t) - \beta(t)) - (y'(t) + l \cos(\alpha(t)) \alpha'(t)) \cos(\alpha(t) - \beta(t)) = 0$$

~) Solutions

$$\begin{pmatrix} x'(t) \\ y(t) \\ \alpha'(t) \\ \beta'(t) \end{pmatrix} = \lambda(t) \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix} + \mu(t) \begin{pmatrix} l \cos \alpha(t) \cos \beta(t) \\ l \sin \alpha(t) \cos \beta(t) \\ -\sin \beta(t) \\ 0 \end{pmatrix}$$

steer vf : $X := \frac{\partial}{\partial \beta}$

drive vf : $Y := l \cos \beta \cdot \left(\cos \alpha \frac{\partial}{\partial x} + \sin \alpha \frac{\partial}{\partial y} \right) - \sin \beta \frac{\partial}{\partial x}$.

The two, control' vector fields X and Y span a rank 2 bracket generating distribution on M . ($X, Y, [X, Y]$
 $[Y, [X, Y]]$)

$(TM \text{ is spanned by } x, y, [x, y], [y, [x, y]])$ -

Given $E \subseteq TM$ a smooth involutive distribution, we know that through each point $x \in M$ we have an integral submfld. by FB-Theorem.

Q What about maximal integral submfld. through a point?

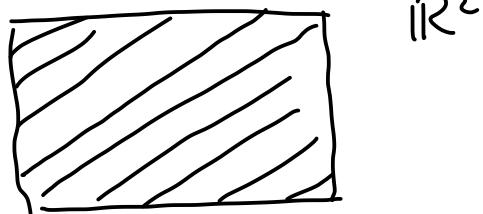
These are in general not submfld. but so called initial submfld.

$$\begin{array}{ccc} \mathbb{R}^2 & (x,y) & (x,y) \\ & \downarrow \pi & \downarrow \\ T^2 & & (e^{ix}, e^{iy}) \\ (= \mathbb{R}^2 / \mathbb{Z}^2) & & \end{array}$$

vector field on \mathbb{R}^2 ,

$$\zeta := \frac{\partial}{\partial x} + \omega \frac{\partial}{\partial y} \quad \omega \in \mathbb{R}$$

integral curves $\text{last} + \left(\begin{smallmatrix} 1 \\ \omega \end{smallmatrix} \right)$



ζ (i) π -related to a vf.

on T^2 \rightsquigarrow integral curves of ζ be the range of the integral curves of ζ via π .

$$\pi((+ \begin{pmatrix} 1, \omega \end{pmatrix})) = (e^{it}, e^{i\omega t}) \subset T^2$$

\equiv



If α rational, that's a submfld.

If α is irrational, it's not, because it winds densely
or and the torus. In appropriate chart around a point
 $(e^{it}, e^{i\alpha t})$ consists of countably many line segments

Def. 3.4.1 M mfd. of dim. n .

- ① For v subset $A \subset M$ and $x_0 \in A$ let $C_{x_0}(A) := \{x \in A : \exists$
- (smooth curve
 $c: [0, 1] \rightarrow M$
with values in A
and $c(0) = x_0$
and $c(1)$)

② $N \subseteq M$ is called an initial subfd. of M of dim. k ,
 if for any $x \in N$ \exists a chart (U, u) for M with $x \in U$
 and $u(x) = 0$ and $u(C_x(U \cap N)) = u(U) \cap (\mathbb{R}^k \times \{0\})$.

If $N \subseteq M$ is an initial subfd. Then $\exists!$ C[∞]-mfld.
 structure on N s.t. $i: N \xrightarrow{\text{the inclusion}} M$ is an injective immersion
 with the property that for any mfd. P and a map $f: P \rightarrow N$
 we have f is smooth \Leftrightarrow $i \circ f$ is smooth. $(*)$.

The connected comp. one and countable but uncountably many
of them. (so N might be not and countable).

One uses ~~as~~^{as} on other $\mathcal{B} = \left\{ \left(C_x(\cup N), \iota_x \right) \right\}_{x \in N}$ for
charts as in (2).

- Equipp N ^{with} the topology generated by $\underline{C_x(\cup N)}$ - sets
 - ~> this topology is in general finer than the subspace topology on N induced from M .

In particular, it is still Hausdorff.

- Transitions maps of \mathcal{D} are smooth, since restrictions of smooth maps.
- Uniqueness follows from (*) (cf. subf.)

$\left\{ \begin{array}{l} C_x(U \cap N) \text{ not open } \Rightarrow \text{subspace topology.}; \text{ If } i: D \\ \text{a homeom. onto its range than it is and } C_x(U \cap N) \\ = V \cap N \\ \text{for } V \subseteq M \text{ open and } (V \cap U, \nu|_{V \cap U}) \text{ is a submfld. chart} \end{array} \right\}$

Conversely, one may show that the image of an injective immersion $i: N \hookrightarrow M$ with property (*) is an immersed submanifold.

Coming back to integrate div. / foliations:

$E \subseteq TM$ ^{integrable} with corresp. foliation \mathcal{F}_E .

For any $x \in M$ let $\mathcal{F}_x^E := \{y \in M : \exists C\text{-curve } c: [0,1] \rightarrow M$
s.t. $c(0) = x$ and $c(1) = y$
and $c'(t) \in E_{c(t)} \forall t \in (0,1)\}$
It is called the leaf through x of \mathcal{F}_E .

Note that if a plaque intersects \mathcal{F}_x^E it must be contained
in that leaf. Hence, the plagues contained in \mathcal{F}_x^E and
restrictions of chart maps can be used to give \mathcal{F}_x^E the
structure of a k-dim. mf.

- i : $\tilde{F}_x^E \hookrightarrow M$ is initial submfld. (Haefl. + AZ).
- It is an integral submfld. ($T_y \tilde{F}_x^E = E_y \xrightarrow{T_y i} T_y M \quad \forall y$).
- Any connected integral (mfld) submfld intersects \tilde{F}_x^E
↳ contained in \tilde{F}_x^E (\tilde{F}_x^E = "maximal integrable submfld.
terrang x ".)

Foliation \tilde{F}^E divides M into k -dim. intdle submflds.

Rework We can equip H with a different top. str.

M_E where at los give by $\text{pr}_1 \circ u_\alpha : u_\alpha^{-1}(W_\alpha \times \mathbb{R}^n) \rightarrow W_\alpha \subseteq \mathbb{R}^n$ for $(U_\alpha, u_\alpha) \in \tilde{\mathcal{F}}^E$.

Topology on M_E finer than on H but $\text{id} : M_E \rightarrow H$ is bijective hence.

Non holonomic constraints : constraints on position and velocity
that can not be integrated to constraints on position only :