Crystal Defects

The crystal lattices = an idealized, simplified system of geometrical points used to understand important principles governing the behavior of solids

Real crystals - contain large numbers of defects, e.g., variable amounts of impurities, missing or misplaced atoms or ions

These defects occur for three main reasons:

1) It is impossible to obtain any substance in 100% pure for, some impurities are always present

2) Even if a substance were 100% pure, forming a perfect crystal would require cooling the liquid phase infinitely slowly to allow all atoms, ions, or molecules to find their proper positions. Cooling at more realistic rates usually results in one or more components being trapped in the "wrong" place in a lattice or in areas where two lattices that grew separately intersect

3) Applying an external stress to a crystal can cause microscopic regions of the lattice to move with respect to the rest, thus resulting in imperfect alignment

Crystal Defects

Perfect crystals - every atom of the same type in the correct equilibrium position in the cell (does not exist at T > 0 K)

Real crystals - all crystals have some imperfections - defects most atoms are in ideal locations, a small number are out of place

Intrinsic – present for thermodynamic reasons

• Extrinsic – not required by thermodynamics, can be controlled by purification or synthetic conditions

- Chemical foreign atom, mixed crystals, nonstoichiometry
- Geometrical vacancy, interstitials, dislocations, boundaries, surface

Defects dominate the material properties:

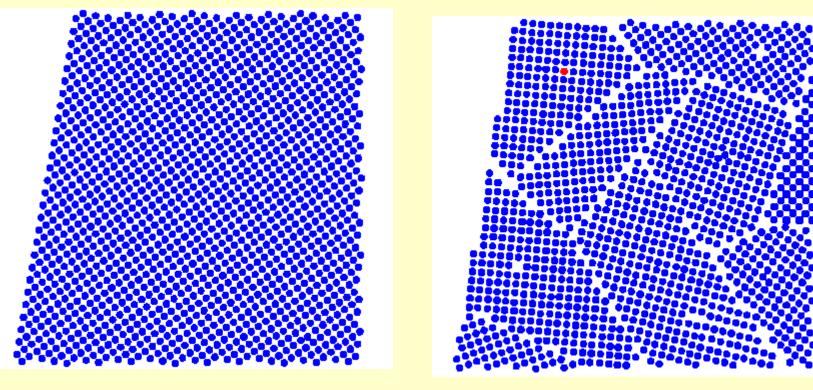
Mechanical, Chemical, Electrical, Diffusion

Defects can be added intentionally

Crystal Defects

Perfect crystal

Real crystal



Does not exist at T > 0 K

Classes of Crystal Defects

Point defects (0D)

places where an atom is missing or irregularly placed in the lattice structure – lattice vacancies, self-interstitial atoms, substitution impurity atoms, interstitial impurity atoms

Linear defects (1D)

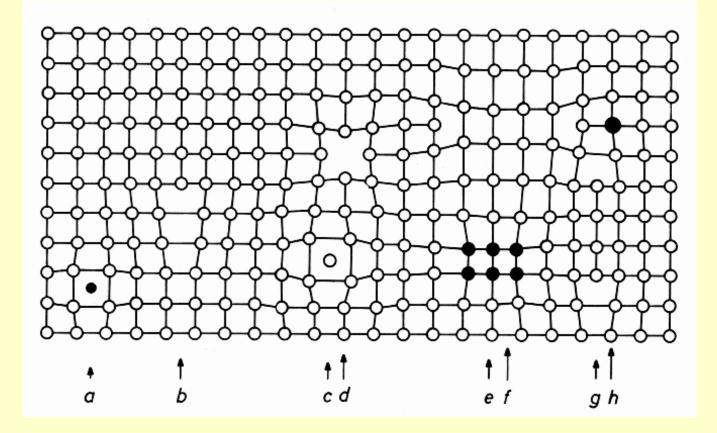
groups of atoms in irregular positions – dislocations

Planar defects (2D)

interfaces between homogeneous regions of the material - grain boundaries, stacking faults, shear planes, external surfaces

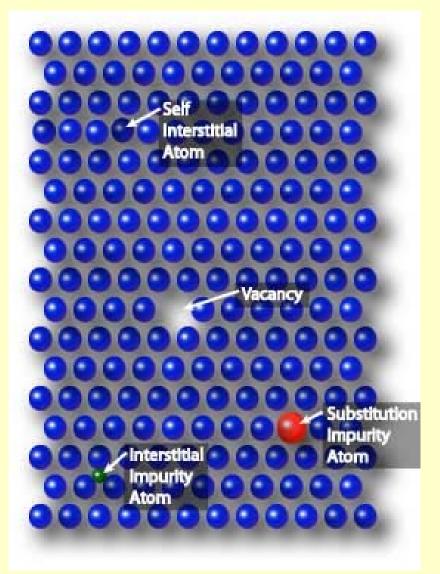
Volume defects (3D) spaces of foreign matter – pores, inclusions, mosaic, domains

Classes of Crystal Defects



a - interstitial impurity atoms, b, g - dislocations, c - self-interstitial atom, d - vacancy, e,f - inclusions, h - substitution impurity atom

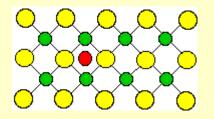
Point Defects



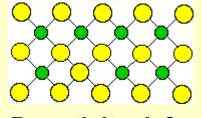
Point defects an atom is missing or is in an irregular position in the lattice

- self interstitial atoms
- interstitial impurity atoms
- substitutional impurity atoms
- vacancies

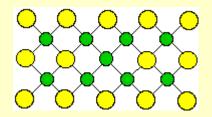
Point Defects – Ionic Compounds



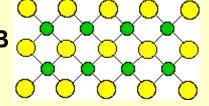
interstitial imputity



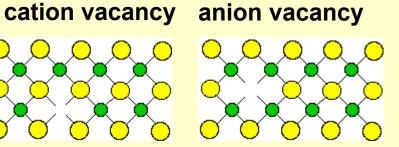
B_A antisite defect

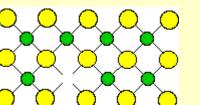


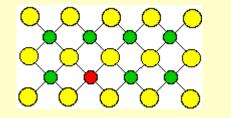
A_B antisite defect 7

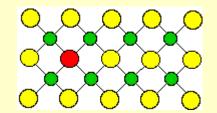


perfect crystal lattice AB





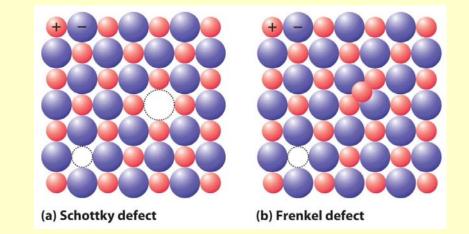




substitution of a cation substitution of an anion

Point Defects – Ionic Compounds

- Vacancy
- Interstitial
- Substitutional
- Frenkel
- Schottky



Schottky: a pair of vacancies, missing cation/anion moved to the surface, **equal numbers of vacancies at both A and B sites** preserving charge balance, found in highly ionic compounds where cation and anion have comparable size and high coordination numbers (NaCl), metal ions are able to assume multiple oxidation states

Frenkel: ions moved to interstitial positions, vacancies, found in open structures (wurtzite, sphalerite, AgX, etc.) with low coordination numbers, open structure provides room for interstital sites to be occupied, cations much smaller than anions, more covalent bonding

Vacancies

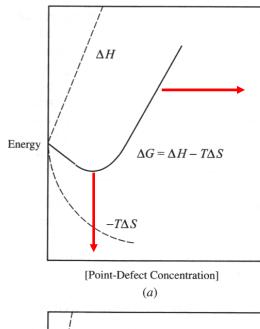
There are naturally occurring vacancies in all crystals **Equilibrium defects** – thermal oscillations of atoms at T > 0 K The number of vacancies grows as the temperature increases The number of vacancies:

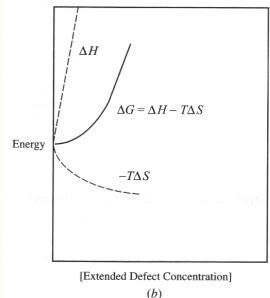
$$N_V = N \exp\left(-\frac{\Delta H^a}{RT}\right)$$

- N = the total number of sites in a crystal
- N_v = the number of vacancies
- ΔH^a = the activation energy for the formation of a vacancy
- R = the gas constant

 N_v goes up exponentially with temperature T

$\Delta G = \Delta H - T \Delta S$





Crystal Energies

Point defects = equilibrium concentration Enthalpy ΔH is positive but configurational entropy ΔS is positive – defects = disorder Minimum on free energy ΔG = equilibrium concentration of defects The concentration of vacancies grows as the temperature increases

Extended defects = no equilibrium concentration Enthalpy is HIGHLY positive, configurational entropy cannot outweight No minimum on free energy ΔG

Metastable defects – dislocations, grain boundaries, surface

Heating = minimize free energy: polycrystalline \rightarrow single crystal grain growth Grains with high dislocation density consumed Atoms move across grain boundary

Typical Point Defects in Crystals

Alkali halides
Alkaline earth oxides
Silver halides
Alkaline earth fluorides

Schottky (cations and anions) Schottky (cations and anions) Frenkel (cations) Frenkel (anions)

Typical activation energies for ion diffusion

Na⁺ in NaCl	~ 0,7 eV
Cl ⁻ in NaCl	~ 1 eV
Schottky pair	~ 2,3 eV

(1 eV/molecule = 96.49 kJ/mol)

Extrinsic Defects

The addition of the dopant (an impurity) into a perfect crystal = point defects in the crystal

NaCl heated in Na vaporsNa is taken into the crystal and changes itscompositionNaCl \rightarrow Na_{1+x}Cl

Na atoms occupy cation sites, an equivalent number of unoccupied anion sites, Na atoms ionize, Na⁺ ions occupy the cation sites, the electrons occupy the anion vacancies – F centers – color (Farbe)

Such solid is now a non-stoichiometric compound as the ratio of atoms is no longer the simple integer

Violet color of Fluorite (CaF₂) = missing F⁻ anions replaced by e^-



Solid Solutions

Substitution (mixing, solution) of ions on specific sites

Forsterite: Mg₂SiO₄

Can substitute Fe for Mg

Fayalite: Fe₂SiO₄

Olivine - the substitution is very readily accomplished and any intermediate composition is possible

Olivine: (Mg, Fe)₂SiO₄

Olivine is a solid-solution series in which any ratio of Mg/Fe is possible as long as they sum to two ions per formula unit required for electric neutrality

Non-stoichiometry can be caused by

- introducing an impurity (doping)
- the ability of an element to show multiple valencies

Vanadium oxide varies from $VO_{0.79}$ to $VO_{1.29}$

What oxidation states?

other examples: TiO_x , Ni_xO , UO_x , WO_x , and Li_xWO_3

Covalent compounds - held to together by very strong covalent bonds which are difficult to break, do not show a wide range of compositions

Ionic compounds - do not show a wide range because a large amount of energy is required to remove / add ions

Non-stoichiometric ionic crystals

a multi-valent element - changes in the number of ions can be compensated for by changes in the charge on the ions, therefore maintaining charge balance but changing the stoichiometry

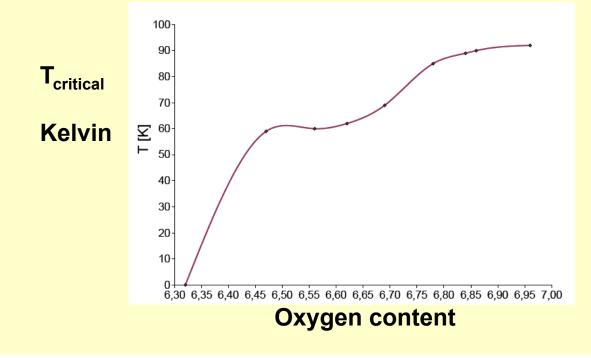
Non-stoichiometric compounds have formulae with non-integer ratios and can exhibit a range of compositions

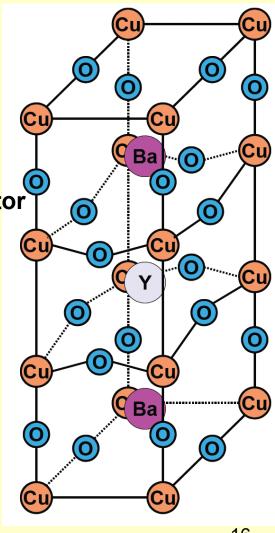
The electronic, optical, magnetic and mechanical properties of non-stoichiometric compounds can be controlled by varying their composition

Non-stoichiometric superconductor YBCO

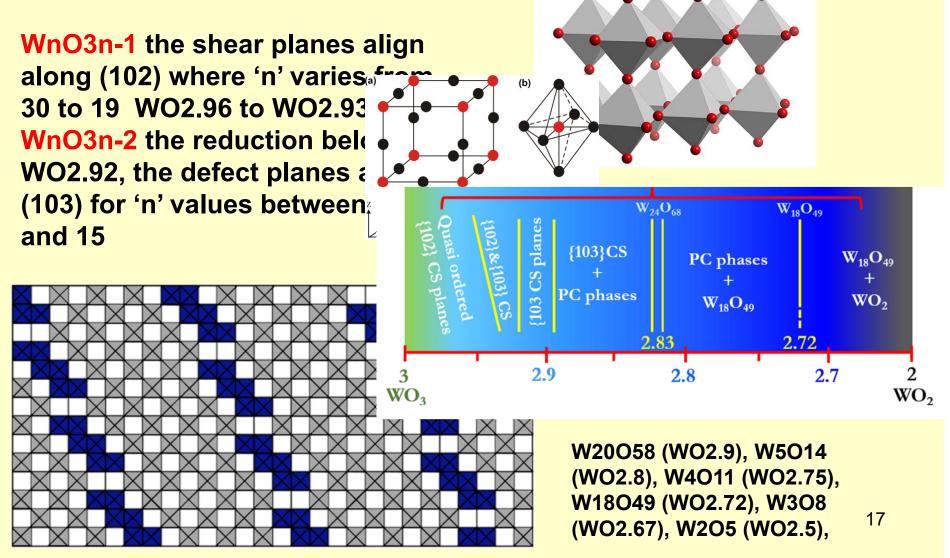
 $YBa_2Cu_3O_{6.5}$ a multi-valent element = Cu

YBa₂Cu₃O_{6.8-7.0} 90 K superconductor YBa₂Cu₃O_{6.45-6.7} 60 K superconductor YBa₂Cu₃O_{6.0-6.45} antiferromagnetic semiconductor





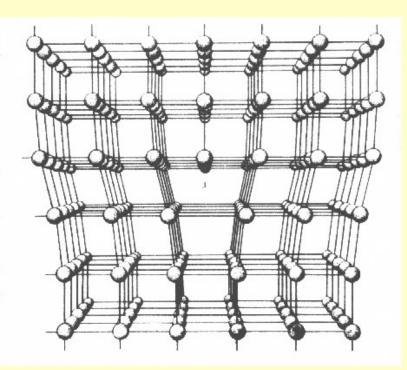
Magnéli phase WO_{2.9} (W₂₀O₅₈)

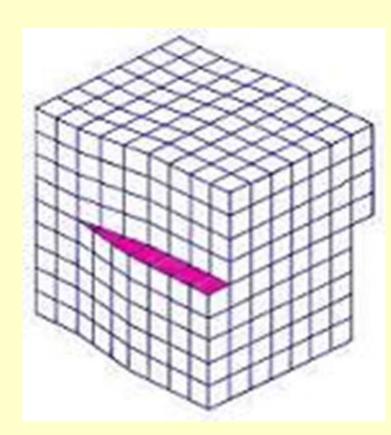


Dislocations

Line imperfections in a 3D lattice

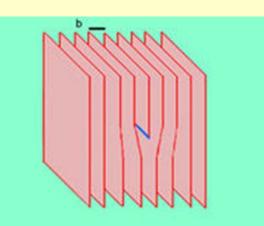
- Edge
- Screw
- Mixed



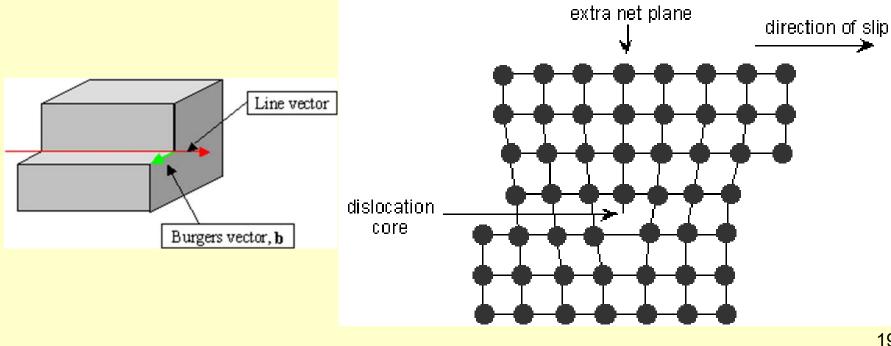


Edge Dislocation

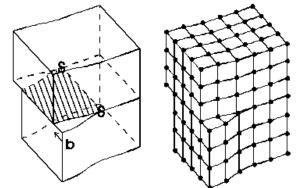
- Extra plane of atoms ٠
- **Burgers vector** ٠
 - Deformation direction



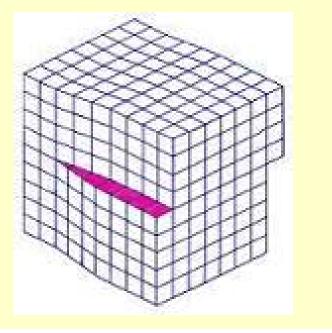
 For edge dislocations it is perpendicular to the dislocation line

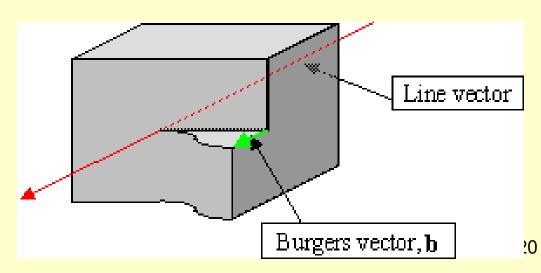


Screw Dislocation



- A ramped step
- Burgers vector
 - Direction of the displacement of the atoms
 - For a screw dislocation it is parallel to the line of the dislocation





Deformation

When a shear force is applied to a material, the dislocations move

Plastic deformation = the movement of dislocations (linear defects)

The strength of the material depends on the force required to make the dislocation move, not the bonding energy

Deformation

Millions of dislocations in a material - result of plastic forming operations (rolling, extruding,...)

Any defect in the regular lattice structure (point, planar defects, other dislocations) disrupts the motion of dislocation - makes slip or plastic deformation more difficult

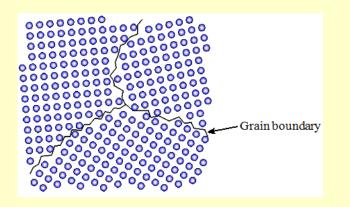
Dislocation movement produces additional dislocations

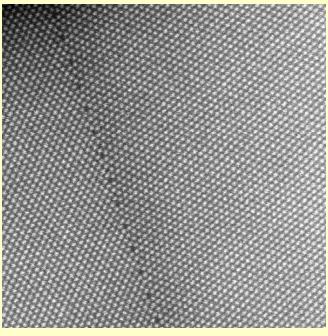
Dislocations collide – entangle – impede movement of other dislocations - the force needed to move the dislocation increases the material is strengthened

Applying a force to the material increases the number of dislocations Called "strain hardening" or "cold work"

Surface and Grain Boundaries

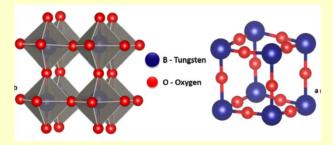
- The atoms at the boundary of a grain or on the surface are not surrounded by other atoms – lower coordination number (CN), weaker bonding
- Grains line up imperfectly where the grain boundaries meet
- Dislocations can not cross grain boundaries
- Tilt and Twist boundaries
- Low and High angle boundaries

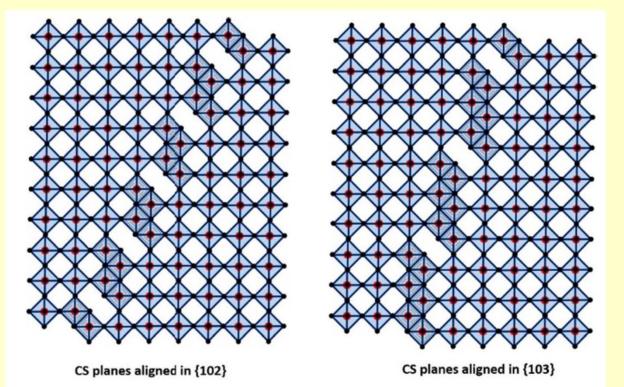




High resolution STEM image from a grain boundary in Au23at the atomic level, imaged on an FEI Titan STEM 80-300

Crystal Shear Planes



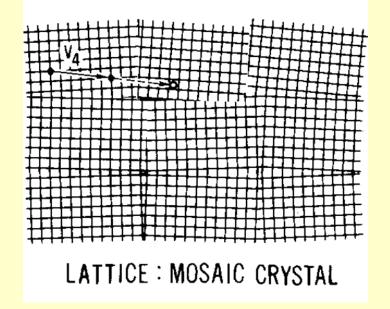


Mosaic Crystals

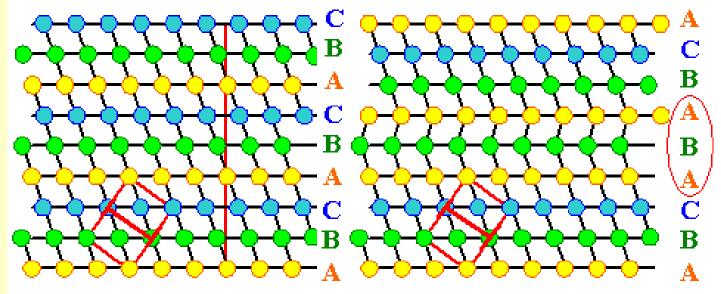
Boundary of slightly mis-oriented volumes within a single crystal

Lattices are close enough to provide continuity (so not separate crystals)

Has short-range order, but not long-range order



Stacking Faults



Perfect Crystal

Stacking Fault

ABCABCABCABABCABC

ΑΑΑΑΑΑΒΑΑΑΑΑΑΑ

ABABABABABCABABAB

Effect of Grain Size on Strength

- Material with a small grain = a dislocation moves to the • boundary and stops – slip stops
- Material with a large grain = the dislocation can travel farther ۲
- Small grain size = more strength •
- **Hall-Petch Equation** ۲

 σ_v = yield strength

$$\sigma_y = \sigma_0 + K d^{-1/2}$$

(stress at which the material

permanently deforms)

d = average grain diameter

 σ_0 = yield stress for bulk

K = unpinning constant

single crystal

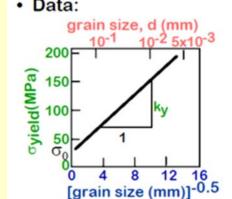
Grain Size Strengthening: Example

0.75mm

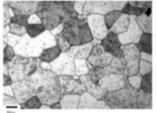
70wt%Cu-30wt%Zn brass alloy

$$\sigma_{\text{yield}} = \sigma_{o} + k_{y}d^{-1/2}$$

· Data:



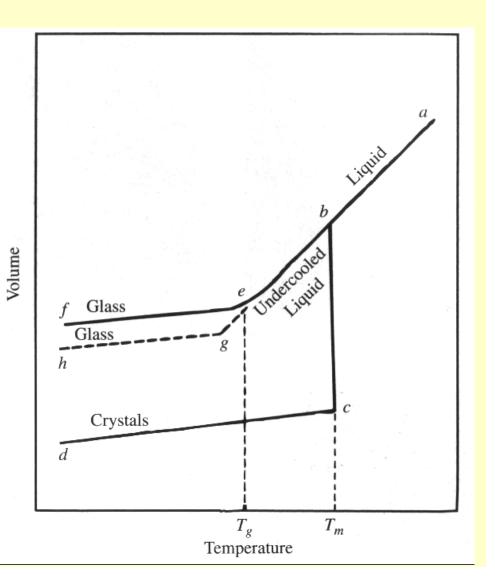




Amorphous Structures

- Cooling a material off too fast

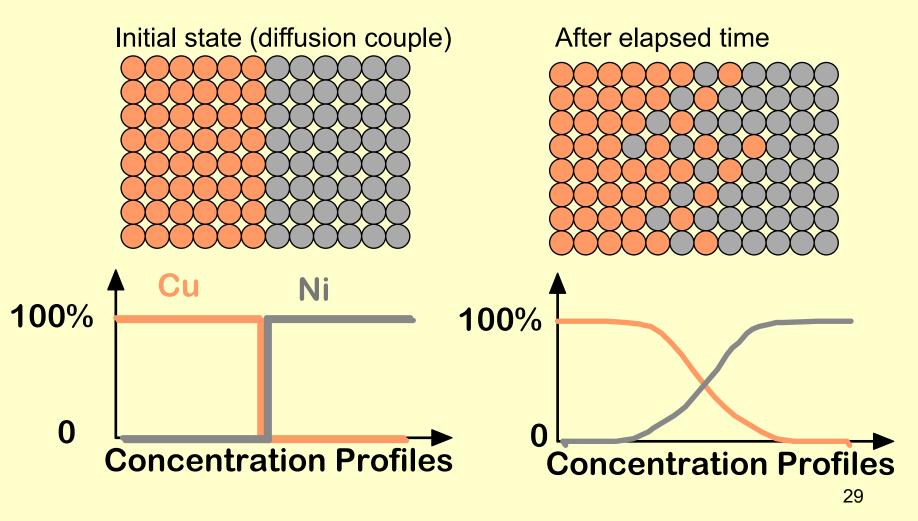
 it does not have a chance to
 crystallize
- Forms a glass
- Easy to make a ceramic glass
- Hard to make a metallic glass
- There are no slip planes, grain boundaries in a glass



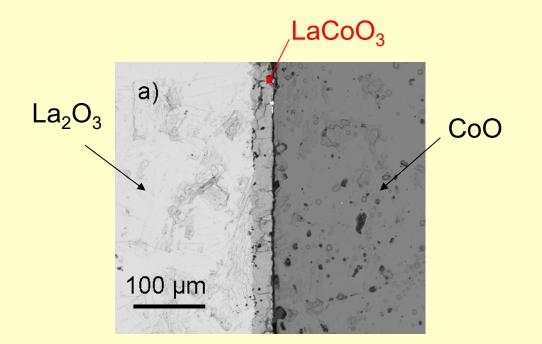
Diffusion

Interdiffusion:

atoms migrate from regions of large to lower concentration



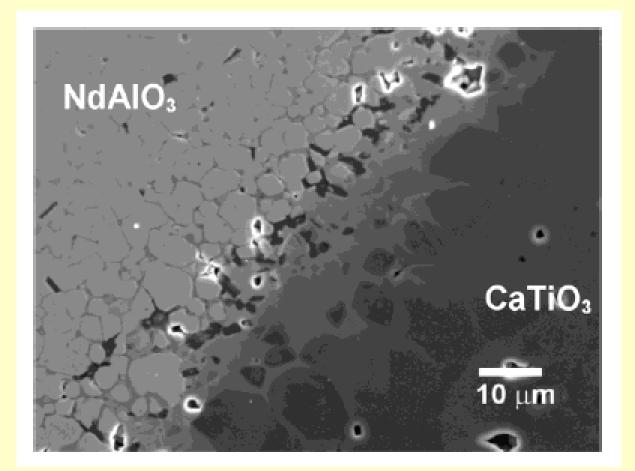
Diffusion Couple Experiments



Experimental conditions:

T = 1370 – 1673 K pO₂ = 40 Pa – 50 kPa

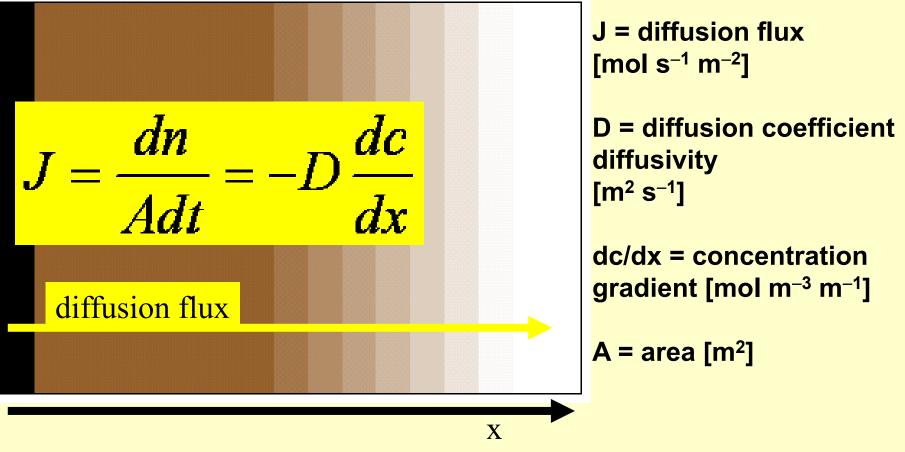
Diffusion Couple Experiments



CaTiO₃-NdAlO₃ diffusion couple fired at 1350 °C/ 6 h

Diffusion - Fick's First Law

Fick's first law describes steady-state diffusion



Velocity of diffusion of particles (ions, atoms ...) in a solid mass transport and concentration gradient for a given point in a solid

Mechanisms of Diffusion

Diffusion = the mechanism by which matter is transported into or through matter

Diffusion at the atomic level is a step-wise migration of atoms from lattice site to lattice site

Conditions for diffusion:

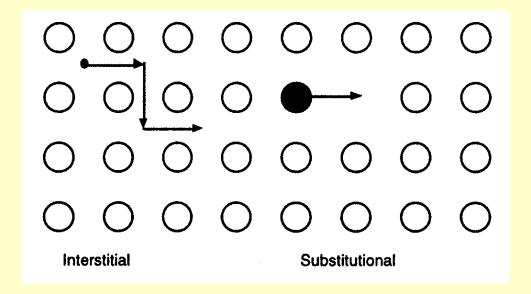
- an adjacent empty site
- atom possesses sufficient energy to break bonds with its neighbors and migrate to adjacent site (activation energy)

The higher the temperature, the higher is the probability that an atom will have sufficient energy

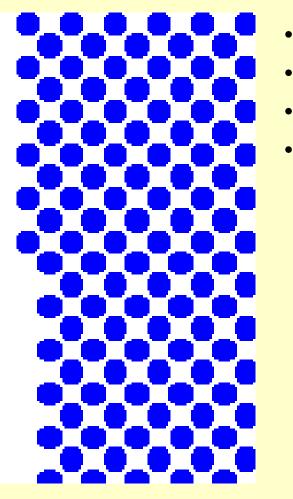
Diffusion rates increase with temperature

Mechanisms of Diffusion

- Along Defects = Vacancy (or Substitutional) mechanism
 - Point Defects
 - Line Defects
- Through Interstitial Spaces = Interstitial mechanism
- Along Grain Boundaries
- On the Surface



Vacancy Mechanisms of Diffusion



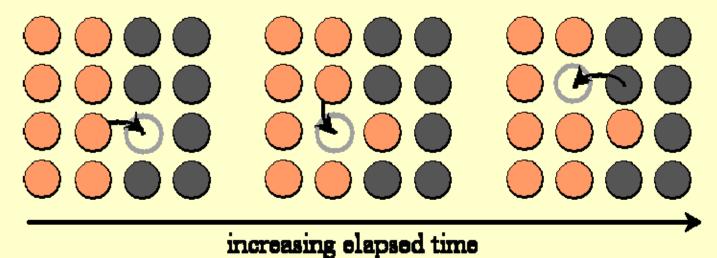
- Vacancies are holes in the matrix
- Vacancies are always moving
- An impurity can move into the vacancy
- Diffuse through the material



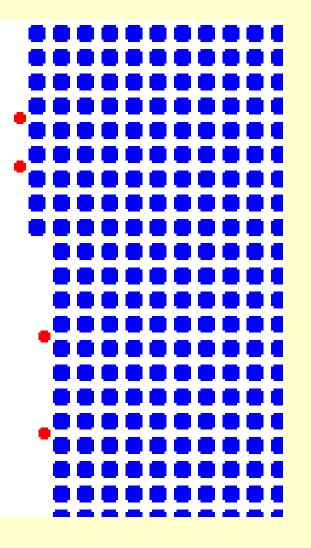
Vacancy Mechanisms of Diffusion

Atoms can move from one site to another if there is sufficient energy present for the atoms to overcome a local activation energy barrier and if there are vacancies present for the atoms to move into

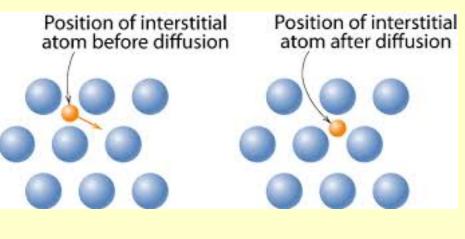
The activation energy for diffusion is the sum of the energy required to form a vacancy and the energy to move the vacancy



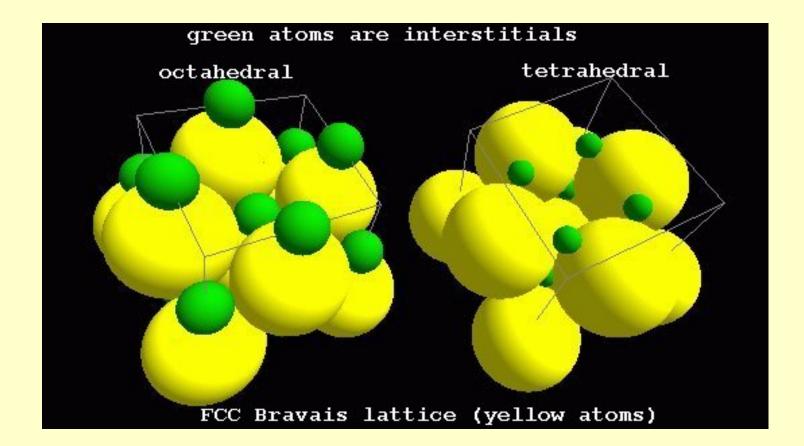
Interstitial Mechanisms of Diffusion

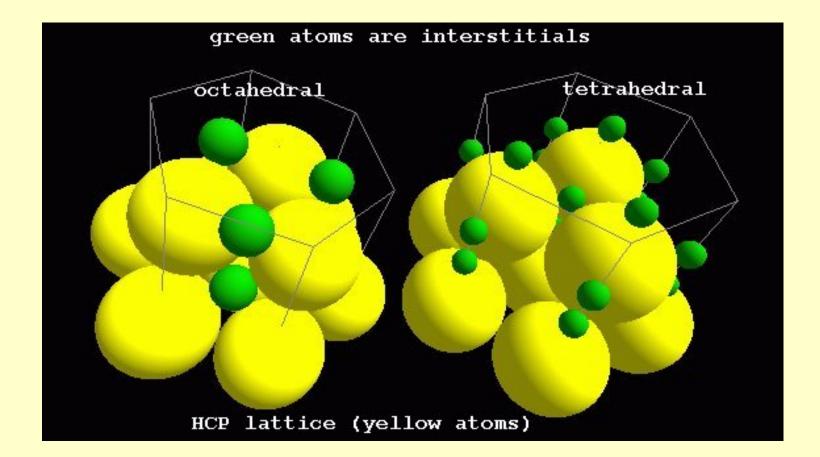


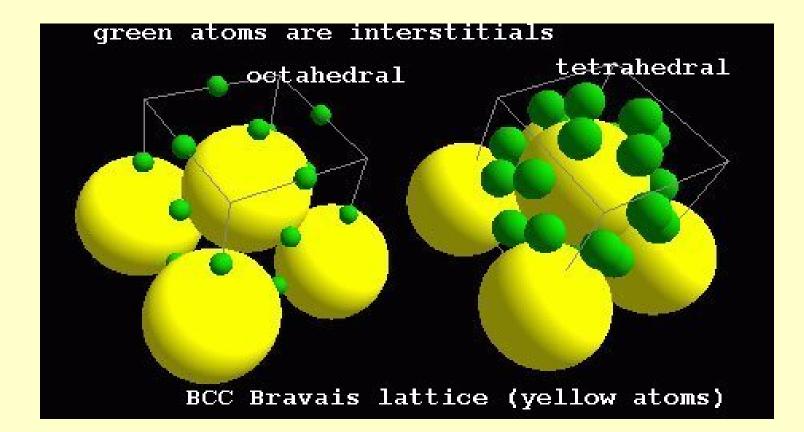
- There are holes between the atoms in the matrix
- If the atoms are small enough, they can diffuse through the interstitial holes
- Fast diffusion



- An atom must be small to fit into the interstitial voids
- H and He can diffuse rapidly through metals by moving through the interstitial voids
- Interstitial atoms like hydrogen, helium, carbon, nitrogen, etc. must squeeze through openings between interstitial sites to diffuse around in a crystal
- The activation energy for diffusion is the energy required for these atoms to squeeze through the small openings between the host lattice atoms
- Interstitial C is used to strengthen Fe = steel, it distorts the matrix
- The ratio of r/R is 0.57 needs an octahedral hole
- Octahedral and tetrahedral holes in both FCC and BCC however the holes in BCC are not regular polyhedra
- The solubility of C in FCC-Fe is much higher than in BCC-Fe



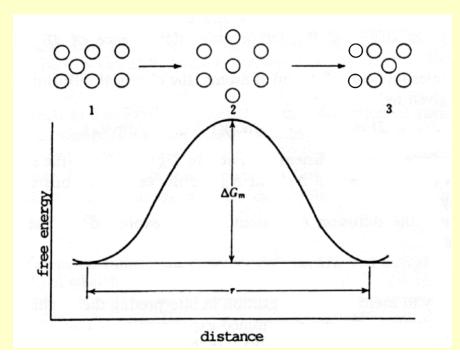




Activation Energy

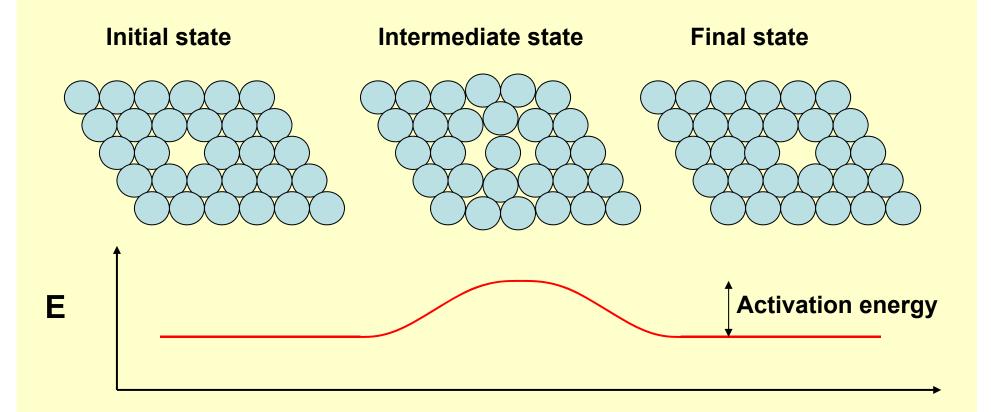
- All the diffusion mechanisms require a certain minimum energy to occur - the activation energy
- The higher the activation energy, the harder it is for diffusion to occur
- The order of energy for diffusion types:

Volume (Vacancy, Interstitial) > Grain Boundary > Surface



The activation energy = Energy barrier for diffusion

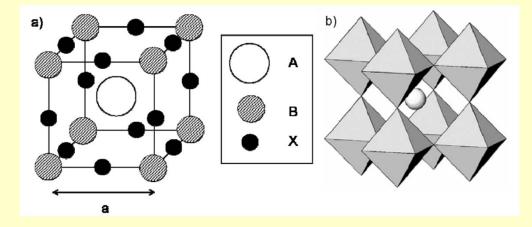
Activation Energy



Energy barrier for diffusion

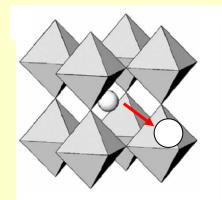
43

Diffusion in Perovskites ABX₃

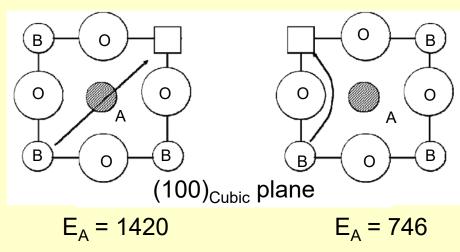


A cation diffusion

B cation diffusion



The A cation diffusion is easier



Activation energies (kJ mol⁻¹)

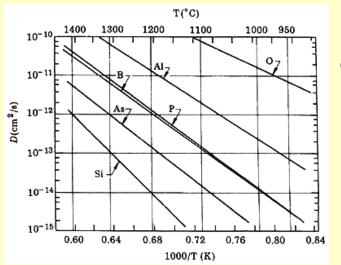
Diffusion Rate

$$D = D_{\infty} \exp\left(-\frac{Q}{RT}\right)$$

Diffusion coefficients show an exponential temperature dependence (Arrhenius type)

D = the diffusivity, which is proportional to the diffusion rate

 $D_{\infty} = D$ for $T \rightarrow \infty$ Q = the activation energy R = the gas constant T = the absolute temperature

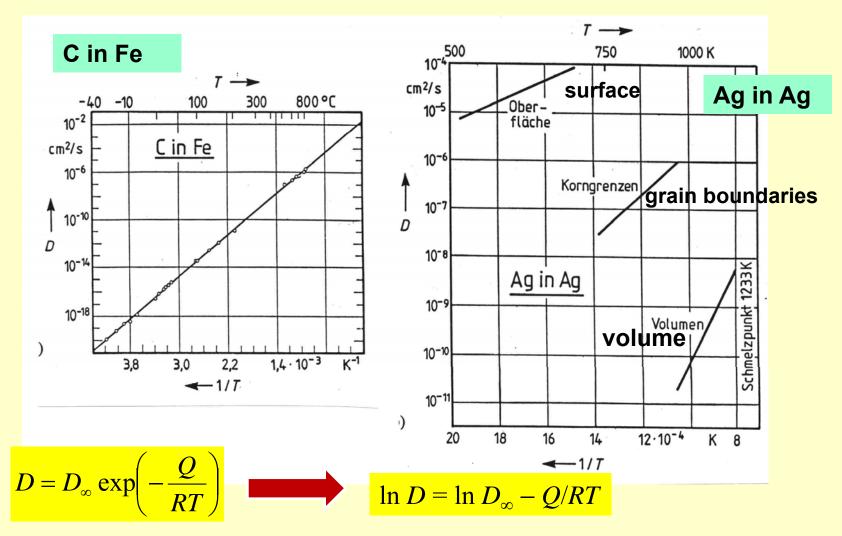


Diffusion coefficients for impurities in Si

D is a function of temperature

Thus the flux (J) is also a function of temperature High activation energy corresponds to low diffusion rates The logarithmic representation of D verus 1/T is linear, the slope corresponds to the activation energy and the intercept to D_{∞}

Diffusion Coefficients



46

Diffusion

Velocity of diffusion of particles (ions, atoms ...) in a solid

mass transport and concentration gradient for a given point in a solid

$$J = \frac{dn}{Adt} = -D\frac{dc}{dx}$$
 [mol cm⁻² s⁻¹] (const. T)

J_i: flow of diffusion (mol s⁻¹ cm⁻²); D_i: diffusion coefficient (cm² s⁻¹) $\delta c_i / \delta x$: concentration gradient (mol cm⁻³ cm⁻¹) (i.e. change of concentration along a line in the solid)

Knowledge of D allows an estimation of the average diffusion length for the migrating particles:

 $\langle x^2 \rangle = 2Dt$ ($\langle x^2 \rangle$: average square of diffusion area; t: time)

Diffusion

Diffusion FASTER for:

- open crystal structures
- lower melting T materials
- materials w/secondary bonding
- smaller diffusing atoms
- lower density materials

Diffusion SLOWER for:

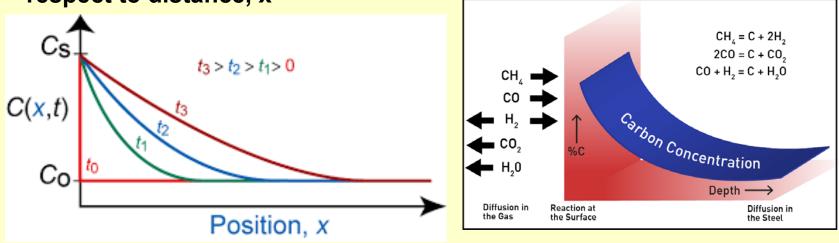
- close-packed structures
- higher melting T materials
- materials w/covalent bonding
- larger diffusing atoms
- higher density materials

Non-Steady-State Diffusion

Fick's Second Law of Diffusion

$$\frac{d C_x}{d t} = \frac{d}{d x} \left(D \frac{d C_x}{d x} \right)$$

The rate of change of composition at position x with time, t, is equal to the rate of change of the product of the diffusivity, D, times the rate of change of the concentration gradient, dC_x/dx , with respect to distance, x



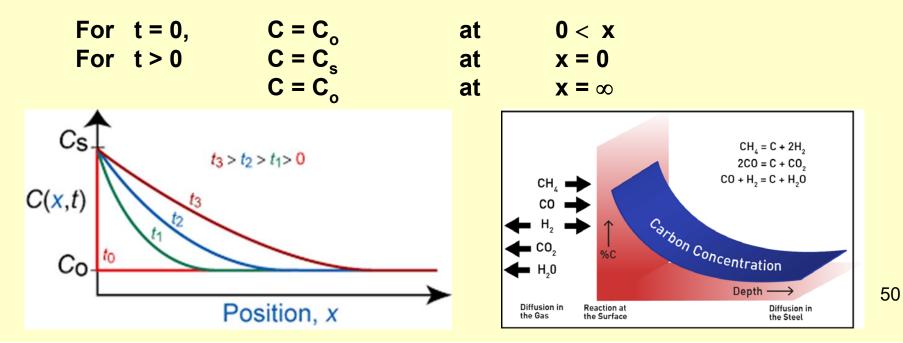
Fick's Second Law of Diffusion

Second order differential equations are nontrivial

Diffusion in from a surface where the concentration of diffusing species is always constant, e.g. :

- gas diffusion into a solid as in carburization of steels
- doping of semiconductors

Boundary Conditions



Fick's Second Law of Diffusion

The solution to Fick's second law is the relationship between the concentration C_x at a distance x below the surface at time t

$$\frac{C_x - C_o}{C_s - C_o} = 1 - erf\left(\frac{x}{2\sqrt{Dt}}\right)$$

 C_s = surface concentration C_o = initial uniform bulk concentration C_x = concentration of element at distance x from surface at time t x = distance from surface D = diffusivity of diffusing species in host lattice t = time erf = error function

