Metric Embedding into the Hamming Space with the n-Simplex Projection

Lucia VADICAMO Fabrizio FALCHI

Institute of Information Science and Technologies, CNR, Pisa, Italy <u>Vladimir MIC</u> Pavel ZEZULA

Faculty of Informatics Masaryk University Brno, Czech Republic

2nd October 2019

- An efficient similarity search is nowadays necessary to process big volumes of complex data
- The similarity model: metric space (D, d)
- Transformations of the space (D, d) to Hamming space $(\{0, 1\}^{\lambda}, h)$ are suitable to facilitate searching in big volumes of data
- Notation:
 - bit-strings are *sketches*
 - techniques transforming metric spaces to Hamming spaces are *sketching techniques*

- Many sketching techniques were proposed
- No generally best sketching technique exists

- Many sketching techniques were proposed
- No generally best sketching technique exists
 - their quality is data dependent

- Many sketching techniques were proposed
- No generally best sketching technique exists
 - their quality is data dependent
 - they are of a different applicability
 - limit the metric space (D, d) to be e.g. the Euclidean space, vector space, arbitrary metric space, ...

- Many sketching techniques were proposed
- No generally best sketching technique exists
 - their quality is data dependent
 - they are of a different applicability
 - limit the metric space (*D*, *d*) to be e.g. the Euclidean space, vector space, arbitrary metric space, ...
 - they require various costs of
 - transformation learning (before the search)
 - transformation of objects $o \in D$ to sketches
 - pre-processing of the searched dataset (before the search)
 - transformation of the query object $q \in D$ to the query sketch sk(q) (during the search)

- Many sketching techniques were proposed
- No generally best sketching technique exists
 - their quality is data dependent
 - they are of a different applicability
 - limit the metric space (*D*, *d*) to be e.g. the Euclidean space, vector space, arbitrary metric space, ...
 - they require various costs of
 - transformation learning (before the search)
 - transformation of objects $o \in D$ to sketches
 - pre-processing of the searched dataset (before the search)
 - transformation of the query object $q \in D$ to the query sketch sk(q) (during the search)

Motivation to Propose Transformation Technique

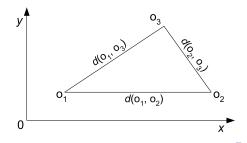
- We propose a novel sketching technique, and we want to achieve a good trade-off between:
 - **quality** of the space approximation
 - applicability of technique
 - O cost of the transformation learning
 - G cost of the object transformation

- Proposed *NSP_50* sketching technique:
 - exploits the *n-Simplex projection* to transform the given metric space to the Euclidean vector space

• binarizes the Euclidean space to Hamming space

n-Simplex Property

- the n-Simplex projection is applicable to spaces with *n*-point property:
- the n-point property:
 - ,,any n points $o_1, ..., o_n \in D$ can be isometrically embedded into the (n-1)-dimensional Euclidean vector space"
 - example: each metric space meets the 3-point property (due to the triangle inequality)



- n-Simplex projection exploits the n-point property:
 - *n* pivots *p_i* ∈ *D* can be isometrically embedded into (*n* − 1)-dimensional Euclidean space

• n-Simplex projection exploits the n-point property:

n pivots *p_i* ∈ *D* can be isometrically embedded into (*n* − 1)-dimensional Euclidean space

• Example for n = 7: each p_i transformed to the 6-dimens. vector v_{pi} : 6-dimensional Euclidean space (... as You can see) that preserves all pairwise distances between 7 vectors v_{ni} $V_{n1} = (V_{11}; V_{12}; V_{13}; V_{14}; V_{15}; V_{16})$ V_{p3} $V_{p2} = (v_{21}; v_{22}; v_{23}; v_{24}; v_{25}; v_{26})$ $V_{p3} = (V_{31}; V_{32}; V_{33}; V_{34}; V_{35}; V_{36})$ $V_{p4} = (v_{41}; v_{42}; v_{43}; v_{44}; v_{45}; v_{46})$ V_{p1} $V_{p5} = (V_{51}; V_{52}; V_{53}; V_{54}; V_{55}; V_{56})$ V_{p2} $V_{p6} = (v_{61}; v_{62}; v_{63}; v_{64}; v_{65}; v_{66})$ $V_{p7} = (V_{71}; V_{72}; V_{73}; V_{74}; V_{75}; V_{76})$ V_{p6} V_{p7}

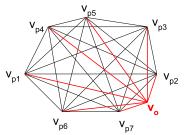
Figure: 7 pivots isometrically embedded into 6-dimensional Euclidean vector space

7 / 17

- (n+1)-point property guarantees it is possible to isometrically embed next object o ∈ D while adding a dimension to the Euclidean space:
 - o is transformed to vector v_o
 - a new coordinate is added to all v_{pi} vectors
 - both is done in a way that all pairwise distances are still preserved

- (n+1)-point property guarantees it is possible to isometrically embed next object o ∈ D while adding a dimension to the Euclidean space:
 - o is transformed to vector vo
 - a new coordinate is added to all v_{pi} vectors
 - both is done in a way that all pairwise distances are still preserved

7-dimensional Euclidean space that preserves pairwise distances



$$V_{p1} = (v_{11}; v_{12}; v_{13}; v_{14}; v_{15}; v_{16}; 0)$$

$$V_{p2} = (v_{21}; v_{22}; v_{23}; v_{24}; v_{25}; v_{26}; 0)$$

$$V_{p3} = (v_{31}; v_{32}; v_{33}; v_{34}; v_{35}; v_{36}; 0)$$

$$V_{p4} = (v_{41}; v_{42}; v_{43}; v_{44}; v_{45}; v_{46}; 0)$$

$$V_{p5} = (v_{51}; v_{52}; v_{53}; v_{54}; v_{55}; v_{56}; 0)$$

$$V_{p6} = (v_{61}; v_{62}; v_{63}; v_{64}; v_{65}; v_{66}; 0)$$

$$V_{p7} = (v_{71}; v_{72}; v_{73}; v_{74}; v_{75}; v_{76}; 0)$$

$$V_{p} = (v_{11}; v_{2}; v_{3}; v_{4}; v_{5}; v_{5}; v_{5}; v_{5})$$

Please notice values added to vectors v_{pi} must be the same to preserve distances between these vectors

Vadicamo, <u>Mic</u>, Falchi, Zezula Hamming

Contribution: NSP_50 Sketching Technique

- We propose the *NSP_50* sketching technique that transforms metric spaces with the *n*-point property to Hamming space:
 - It selects *n* pivots
 - transforms all data-objects to *n*-dimensional Euclidean space by the n-Simplex projection
 - ¹ evaluates the median value for each coordinate of vectors *v_o*, and binarize them:
 - sets 0 iff the value in the vector is smaller then the median
 - number of pivots *n* thus also defines the length of produced sketches

ELE NOR

¹before this step, we randomly rotate the Euclidean space to distribute the information over coordinates a = b + a

Compared Sketching Techniques

- We compare the *NSP_50* technique experimentally and theoretically with other sketching techniques:
 - The *GHP*_50 uses the *generalyzed hyperplane partitioning* (GHP) to split dataset into approx. halves. Each instance of the GHP determines the value of one bit in all sketches. The *GHP*_50 produces sketches with low correlated bits.
 - The *BP_50* uses the *ball partitioning* (BP) to split data into halves to set values in a bit of all sketches. Also aims to produce sketches with low correlated bits.
 - The *PCA_50* use the principal component analysis to shorten vectors in the Euclidean space. Then it binarizes the vectors in a same way as *NSP_50*.

ELE NOR

Properties of Sketching Techniques

- Proper analysis is in the paper
- The main features of sketching techniques:

*NSP*_50

- 🙂 wide applicability
- good quality of space approximation
- cheap transformation learning
- ${\color{black} \bullet} \lambda$ distance computations and λ^2 flops to transform object

*BP_*50

- 🙂 very wide applicability
- very poor approximation quality when applied to complex spaces
- expectable transformation learning cost
- λ distance computations to transform object

*GHP*_50

- 🙂 very wide applicability
- still a good space approximation
- 😕 expensive transformation learning
- 2λ distance computations to transform object

PCA_50

- narrow applicability to Euclidean spaces (could be partially extended)
- very good space approximation
- 🙂 cheap transformation learning
- $\textcircled{o} \lambda \cdot "$ *space dim*" flops to transform object

= 900

- We search for 100 nearest neighbours in 1 million datasets of image visual descriptors
 - *DeCAF* descriptors: Euclidean space of 4,096 dim. vectors extracted from the *Profiset image collection* using the Deep Convolutional Neural Network
 - SIFT descriptors from the ANN dataset that form the Euclidean space with 128 dimensions
 - Adaptive-binning feature histograms compared by the Signature Quadratic Form Distance (SQFD), extracted from the *Profiset image collection*. Each signature consists of, on average, 60 cluster centroids in a 7-dimensional space.

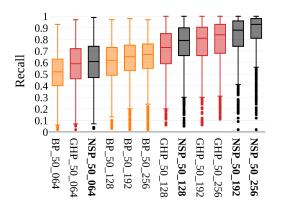
ELE NOR

Experiments – Setup

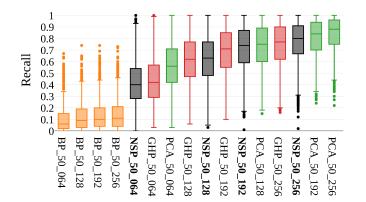
- We randomly select 1,000 query objects *q* for each dataset, and we compare the precise query answer with the approximate one:
- Approximate evaluation based on sketches:
 - For each q, we pre-select the *candidate set candSet(q)* of 2,000 descriptors from the dataset (0.2%) with the most similar sketches *sk(o)* to the sketch of the query object *sk(q)*
 - We evaluate the distances d(q, o), o ∈ candSet(q) to return 100 most similar objects from the candidate set
- Precise query answer:
 - 100 objects *o* from the dataset with minimum distances *d*(*q*, *o*) to the query object *q*
- Comparison:
 - the recall expresses the relative size of the intersection of the approximate and the precise query answer

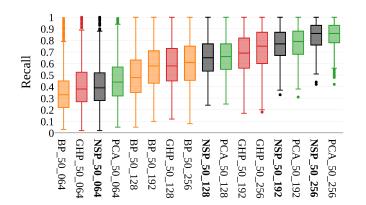
Experiments – Results SQFD dataset

- Box-plots express the distribution of the recall values per query objects
- Suffix in the name of the sketching technique expresses the length of sketches (in bits)



Experiments – Results DeCAF dataset





• We have proposed a novel sketching technique NSP_50

• based on the n-Simplex projection

 provides a good trade-off between applicability, quality and costs of transformation Comparison table: http://www.nmis.isti.cnr.it/falchi/SISAP19SM.pdf